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(12) **United States Patent**
McLean

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(45) **Date of Patent:** **Jun. 11, 2019**

(54) **INSERTER FOR EXPANDING AN EXPANDABLE DEVICE**
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Related U.S. Application Data

(63) Continuation of application No. 14/736,689, filed on Jun. 11, 2015, now Pat. No. 9,445,921, which is a (Continued)
(51) **Int. Cl.**
A61B 17/70 (2006.01)
A61F 2/46 (2006.01)
(Continued)
(52) **U.S. Cl.**
CPC *A61F 2/4611* (2013.01); *A61B 17/8858* (2013.01); *A61F 2/447* (2013.01);
(Continued)
(58) **Field of Classification Search**
CPC *A61F 2/44*; *A61F 2/442*; *A61F 2002/4435*; *A61F 2/445*; *A61F 2/4475*; *A61F 2/4465*;
(Continued)

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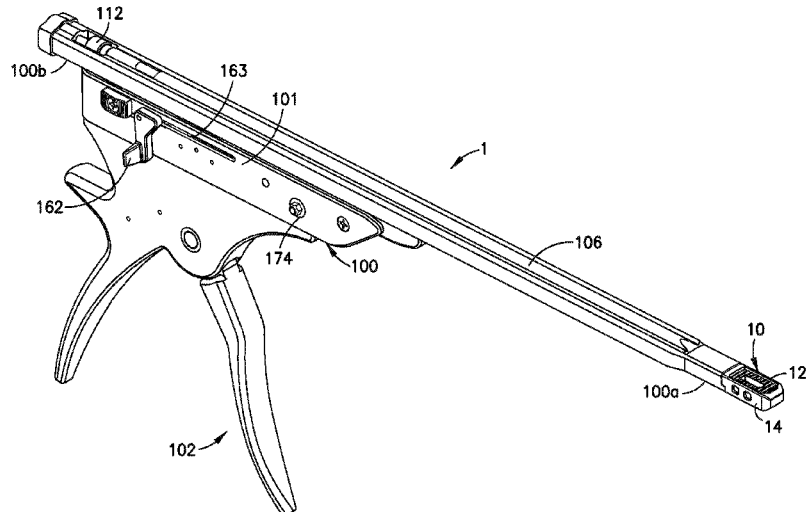
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(57) **ABSTRACT**
An expandable device for expanding and supporting body tissue comprises an inferior endplate having an outer surface configured to contact one body tissue surface and a superior endplate having an outer surface configured to contact an opposing body tissue surface. The inferior endplate and the superior endplate are movable relative to each other in a direction of expansion. The device includes an elevator captively supported between the inferior endplate and the superior endplate for independent movement along the direction of expansion. In the first direction the elevator is moved toward said superior endplate to lift the superior endplate and expand the device. In the second direction the elevator moves away from said superior endplate toward said inferior endplate to create a space for insertion of an insert into the expanded device.

20 Claims, 30 Drawing Sheets



Related U.S. Application Data

- continuation-in-part of application No. 14/474,555, filed on Sep. 2, 2014, now Pat. No. 9,078,767.
- (60) Provisional application No. 61/948,645, filed on Mar. 6, 2014.
- (51) **Int. Cl.**
A61F 2/44 (2006.01)
A61B 17/88 (2006.01)
A61F 2/30 (2006.01)
- (52) **U.S. Cl.**
 CPC *A61F 2/4455* (2013.01); *A61F 2002/3008* (2013.01); *A61F 2002/30131* (2013.01); *A61F 2002/30166* (2013.01); *A61F 2002/30401* (2013.01); *A61F 2002/30556* (2013.01); *A61F 2002/30579* (2013.01); *A61F 2002/30599* (2013.01); *A61F 2002/30601* (2013.01); *A61F 2002/30604* (2013.01); *A61F 2002/30622* (2013.01); *A61F 2002/30784* (2013.01); *A61F 2002/30797* (2013.01); *A61F 2002/30904* (2013.01); *A61F 2002/4475* (2013.01); *A61F 2002/4615* (2013.01); *A61F 2002/4623* (2013.01); *A61F 2002/4627* (2013.01); *A61F 2310/00017* (2013.01); *A61F 2310/00023* (2013.01); *A61F 2310/00029* (2013.01); *A61F 2310/00047* (2013.01); *A61F 2310/00101* (2013.01); *A61F 2310/00239* (2013.01); *A61F 2310/00317* (2013.01)
- (58) **Field of Classification Search**
 CPC *A61F 2/4611*; *A61B 2017/0256*; *A61B 17/885*; *A61B 17/8852*; *A61B 17/8858*
 USPC 606/246–249, 90, 99, 104, 105, 86 A; 623/17.11–17.16
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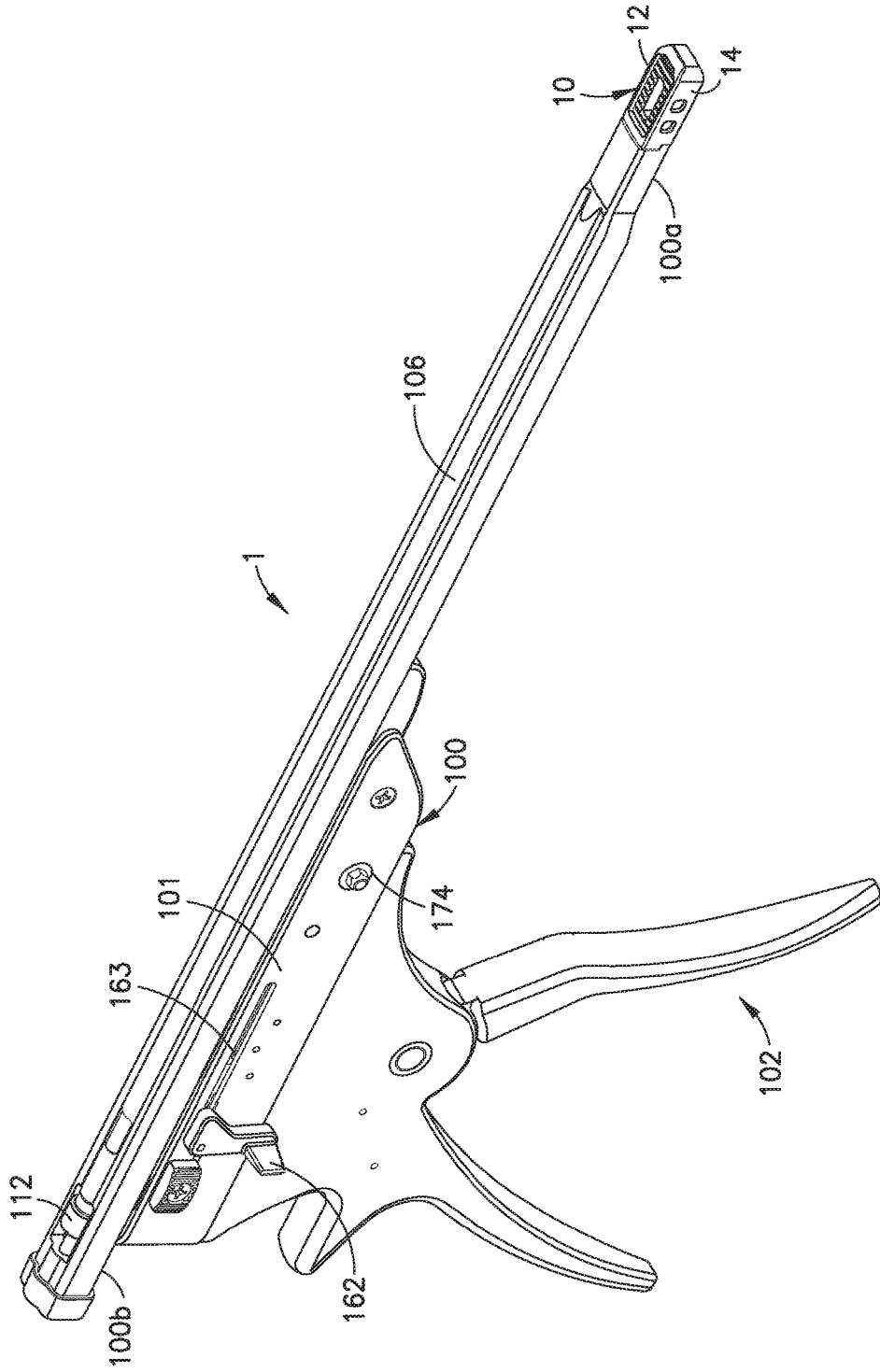


FIG.1a

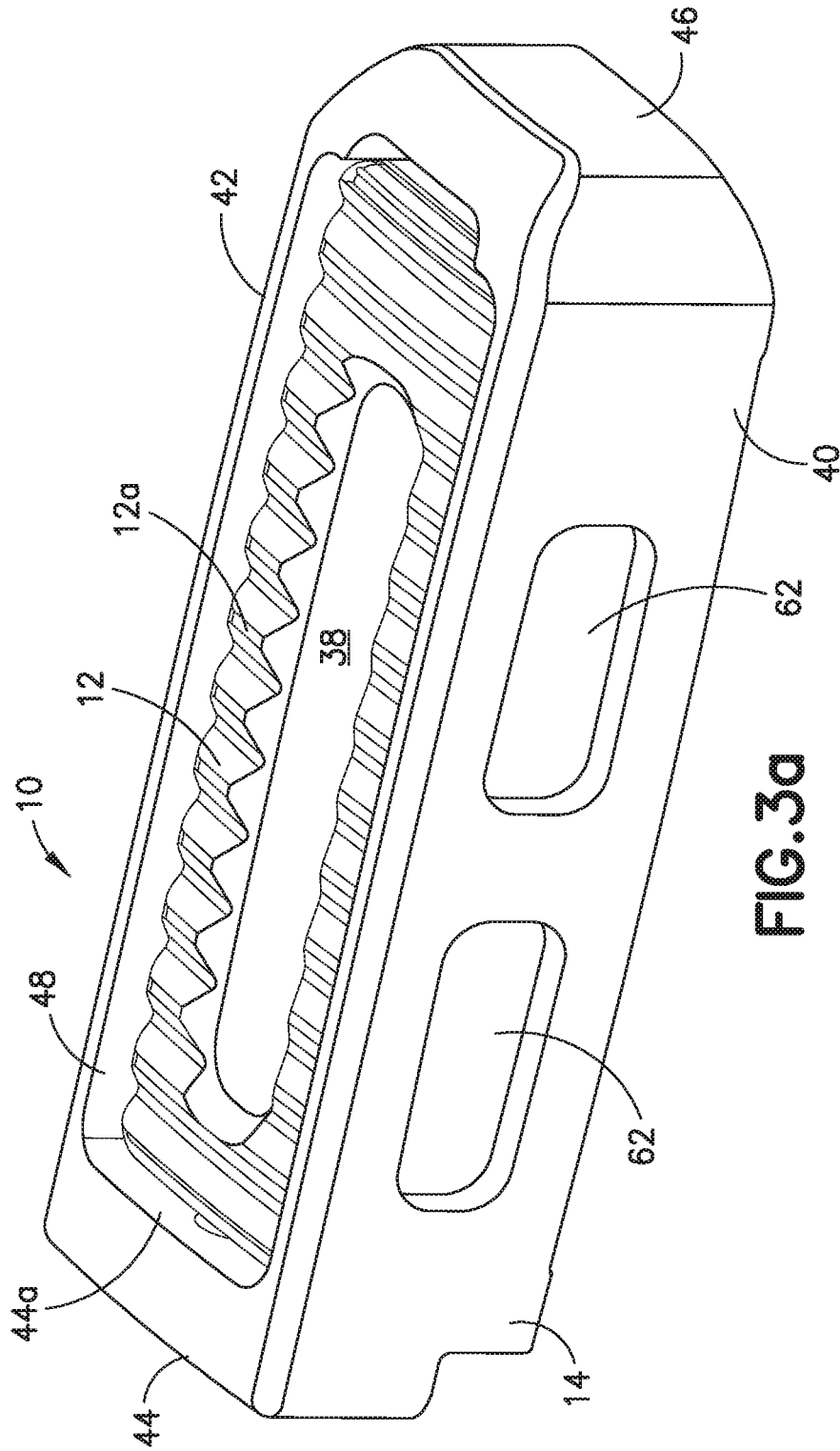
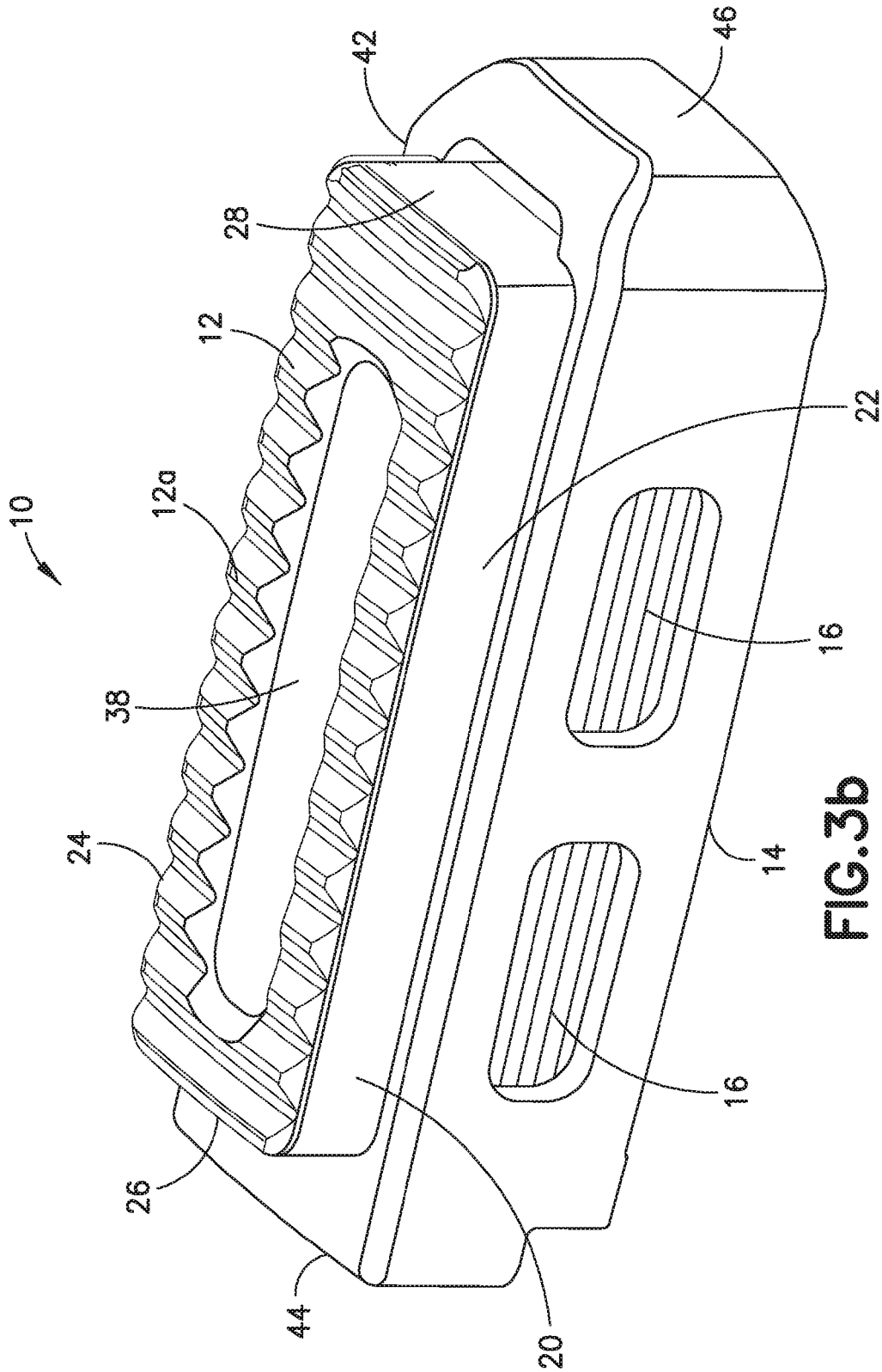


FIG. 3a



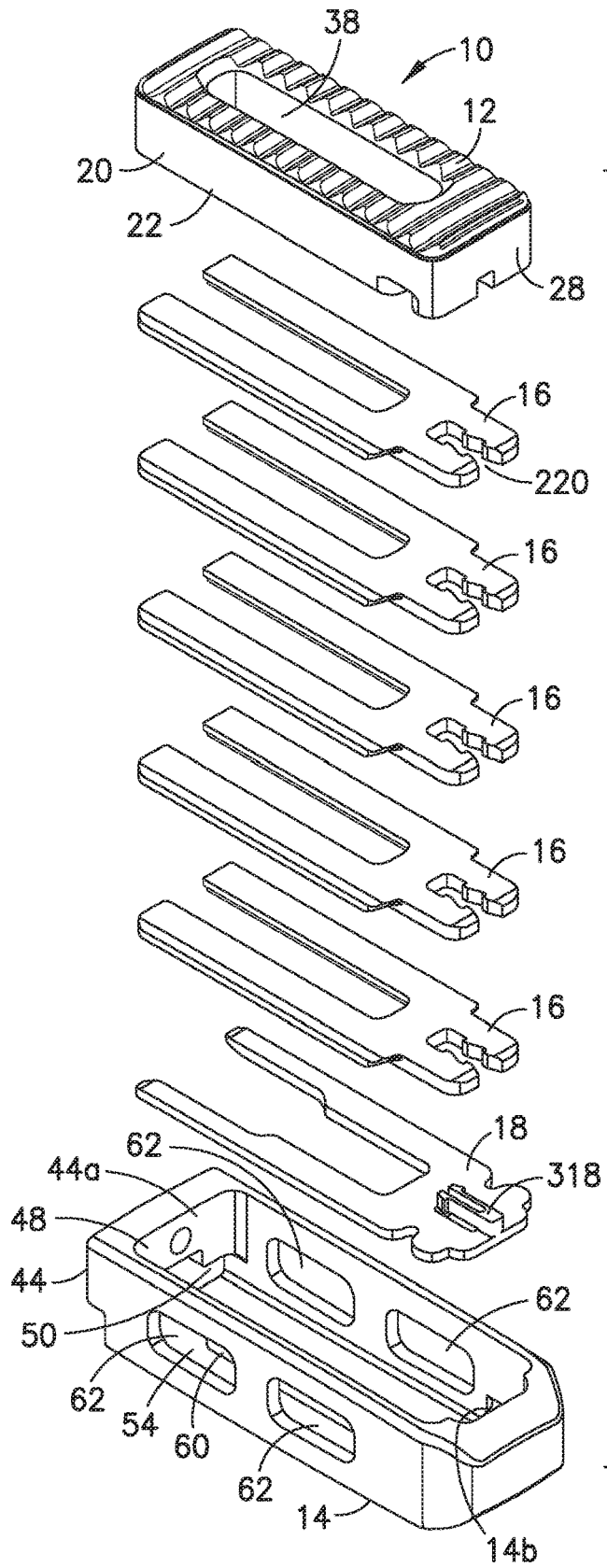


FIG. 4

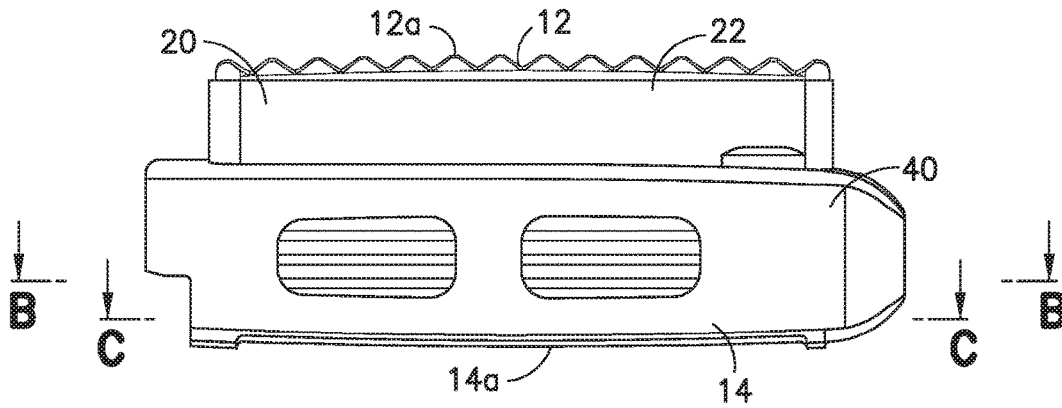


FIG. 5a

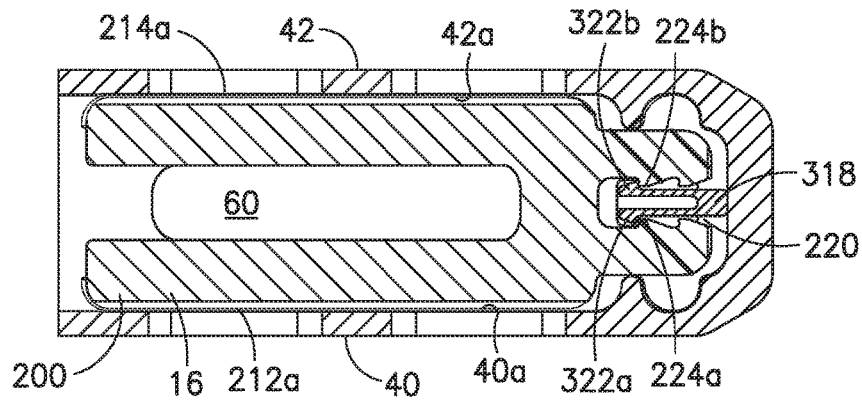


FIG. 5b

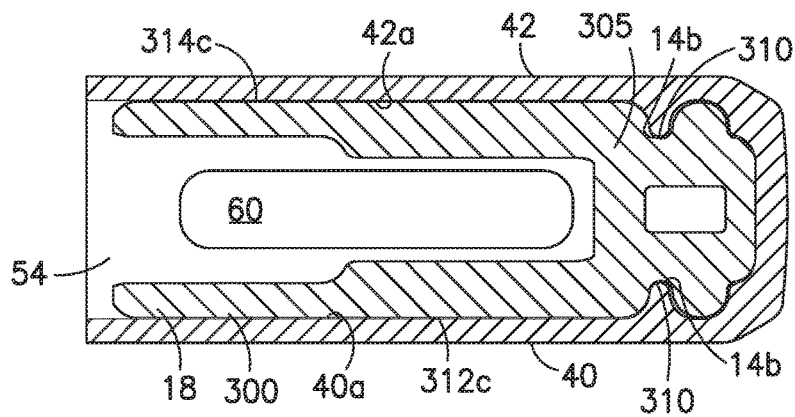
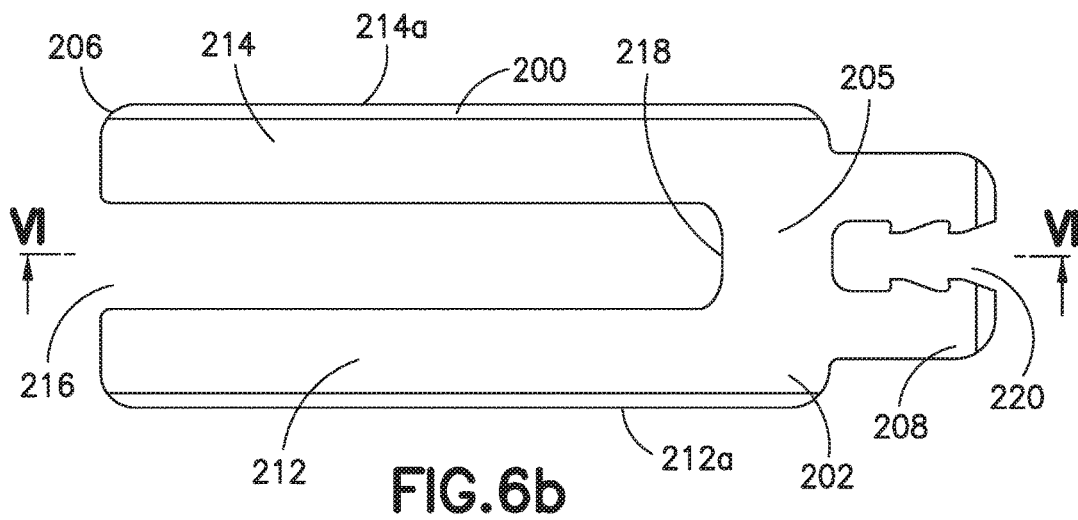
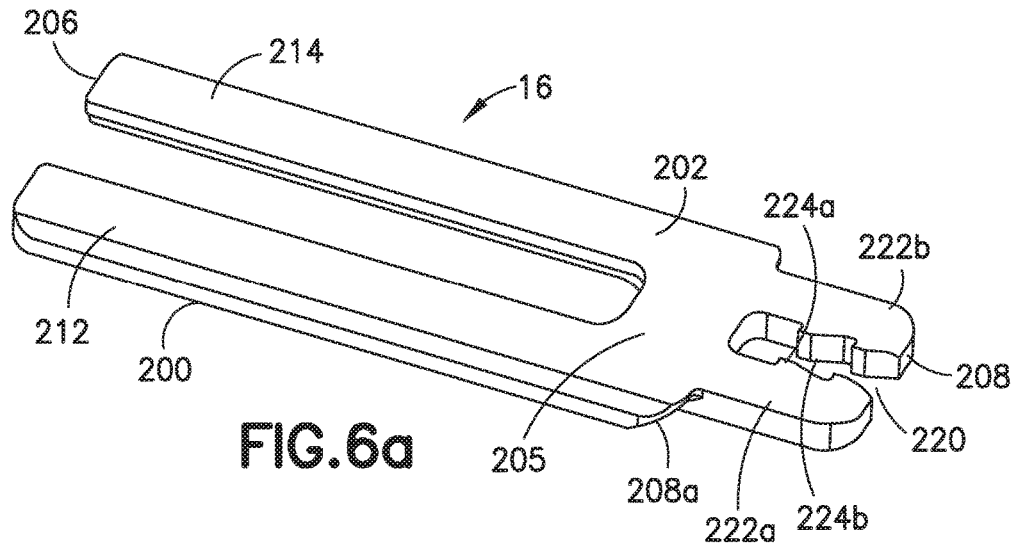


FIG. 5c



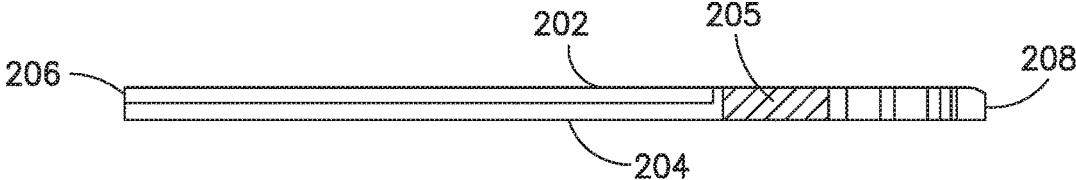


FIG. 6c

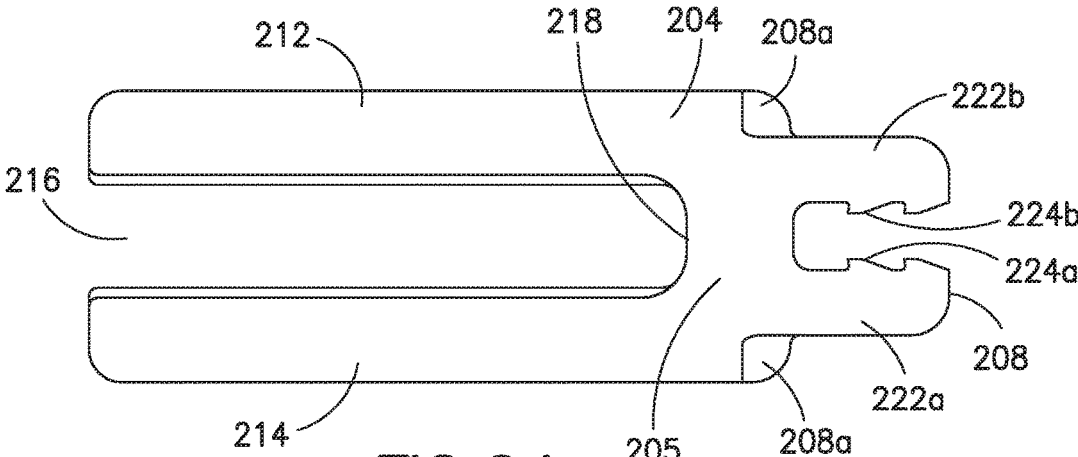


FIG. 6d

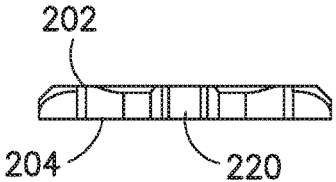


FIG. 6e

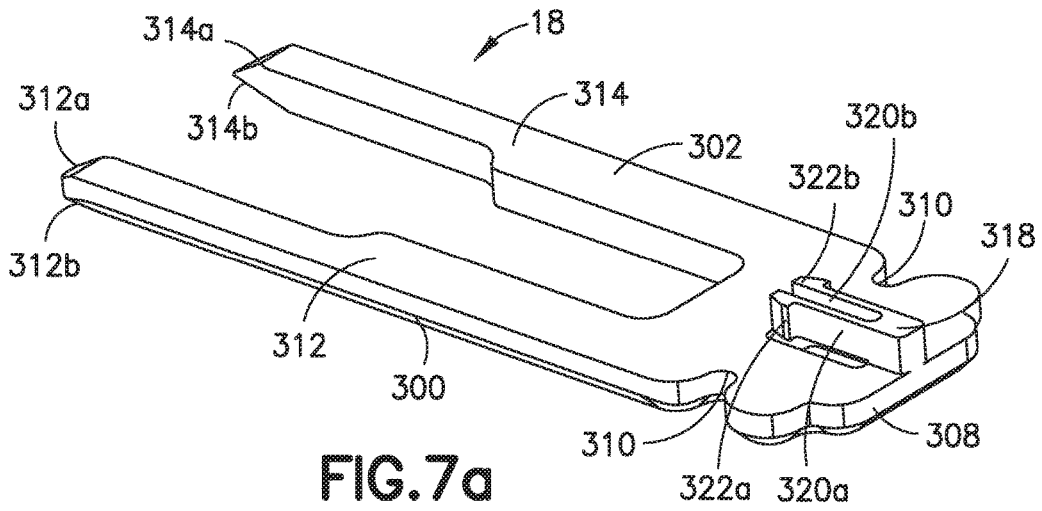


FIG. 7a

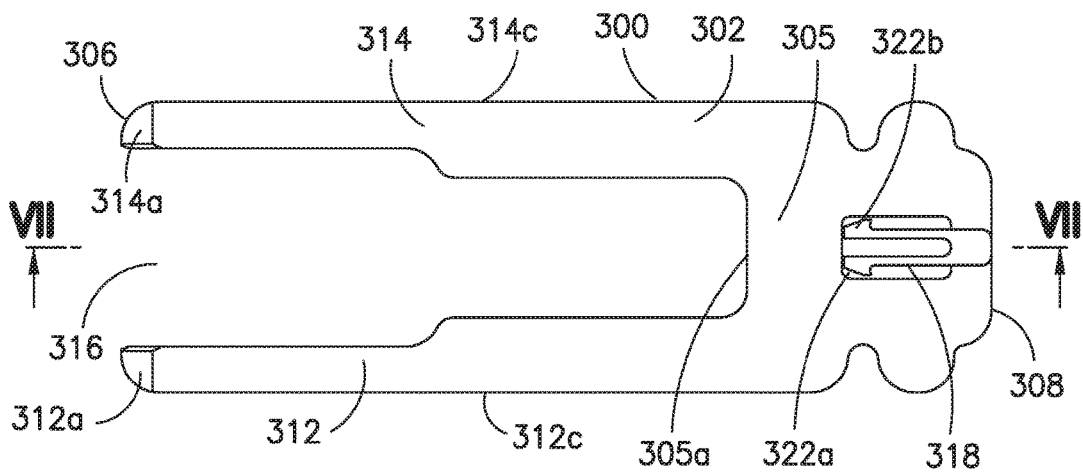


FIG. 7b

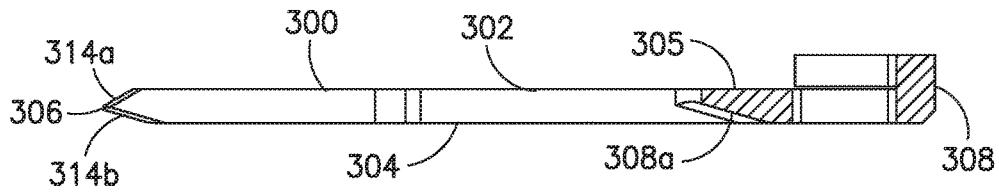


FIG. 7c

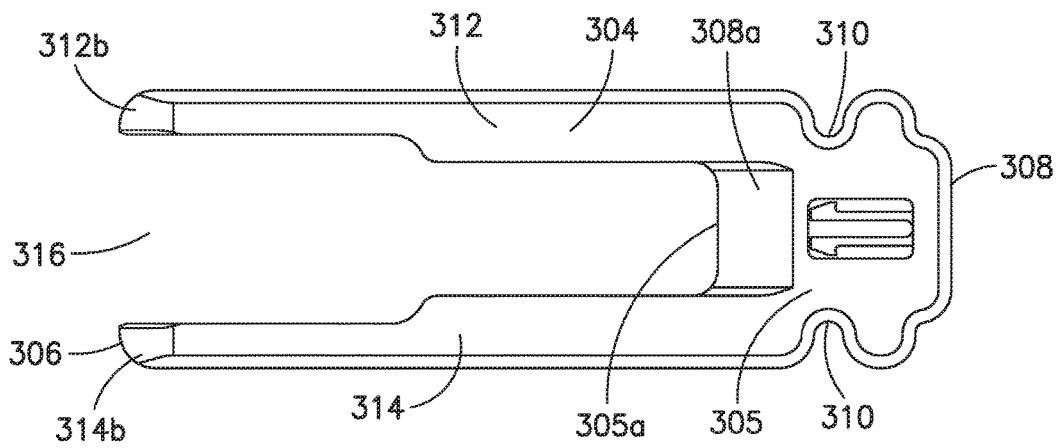


FIG. 7d

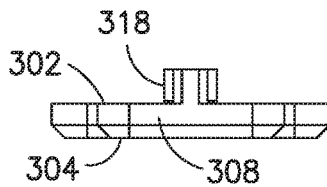


FIG. 7e

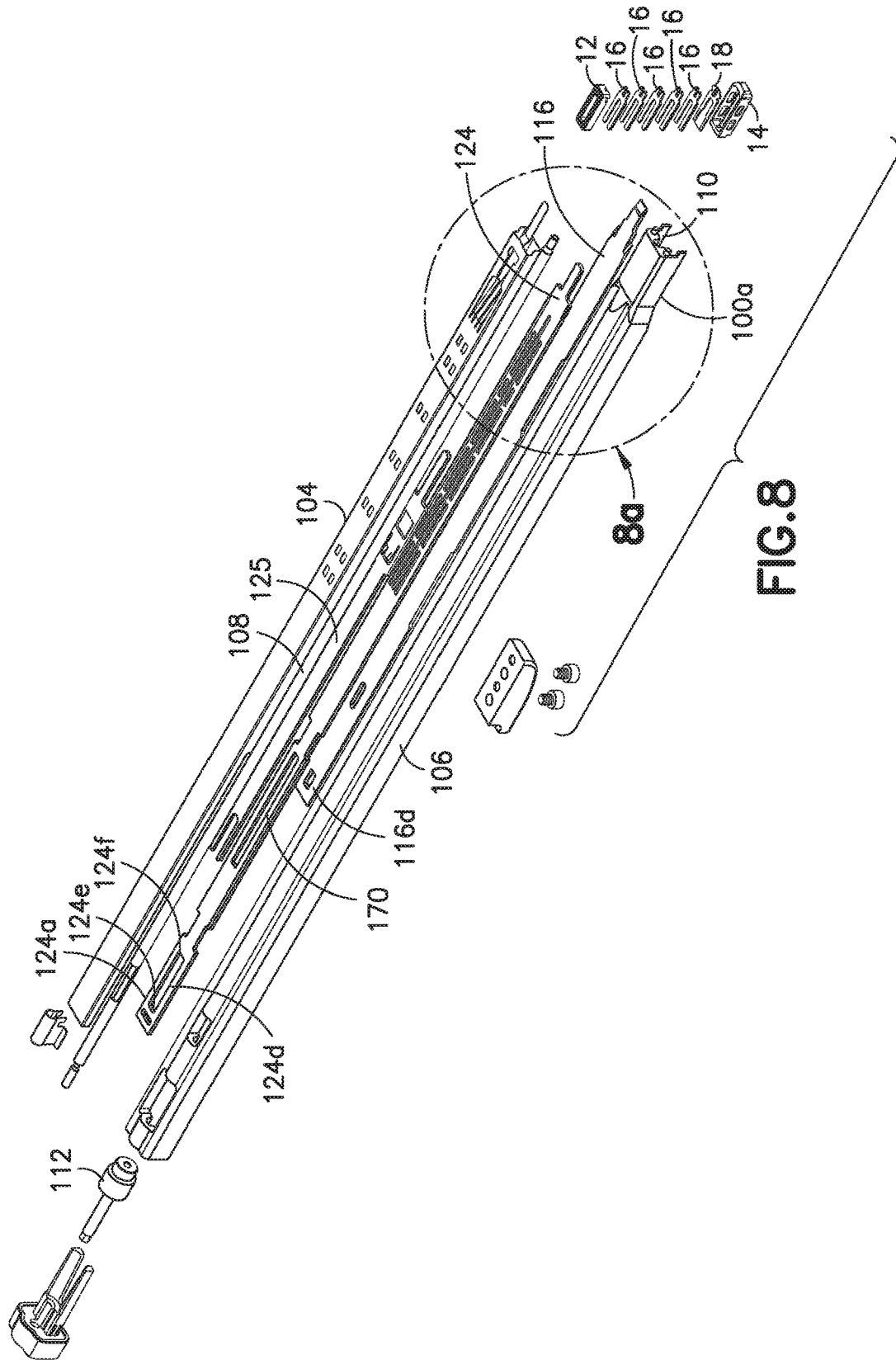


FIG. 8

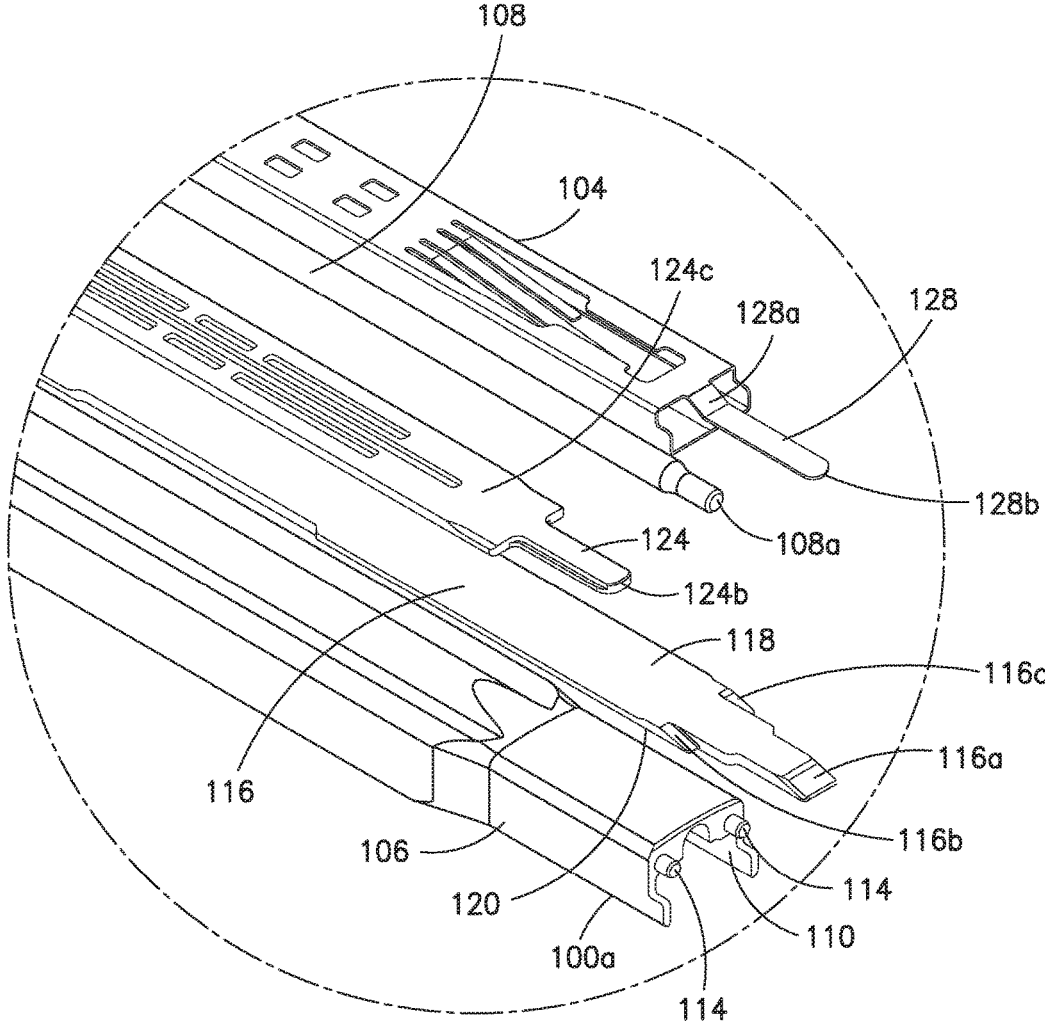


FIG.8a

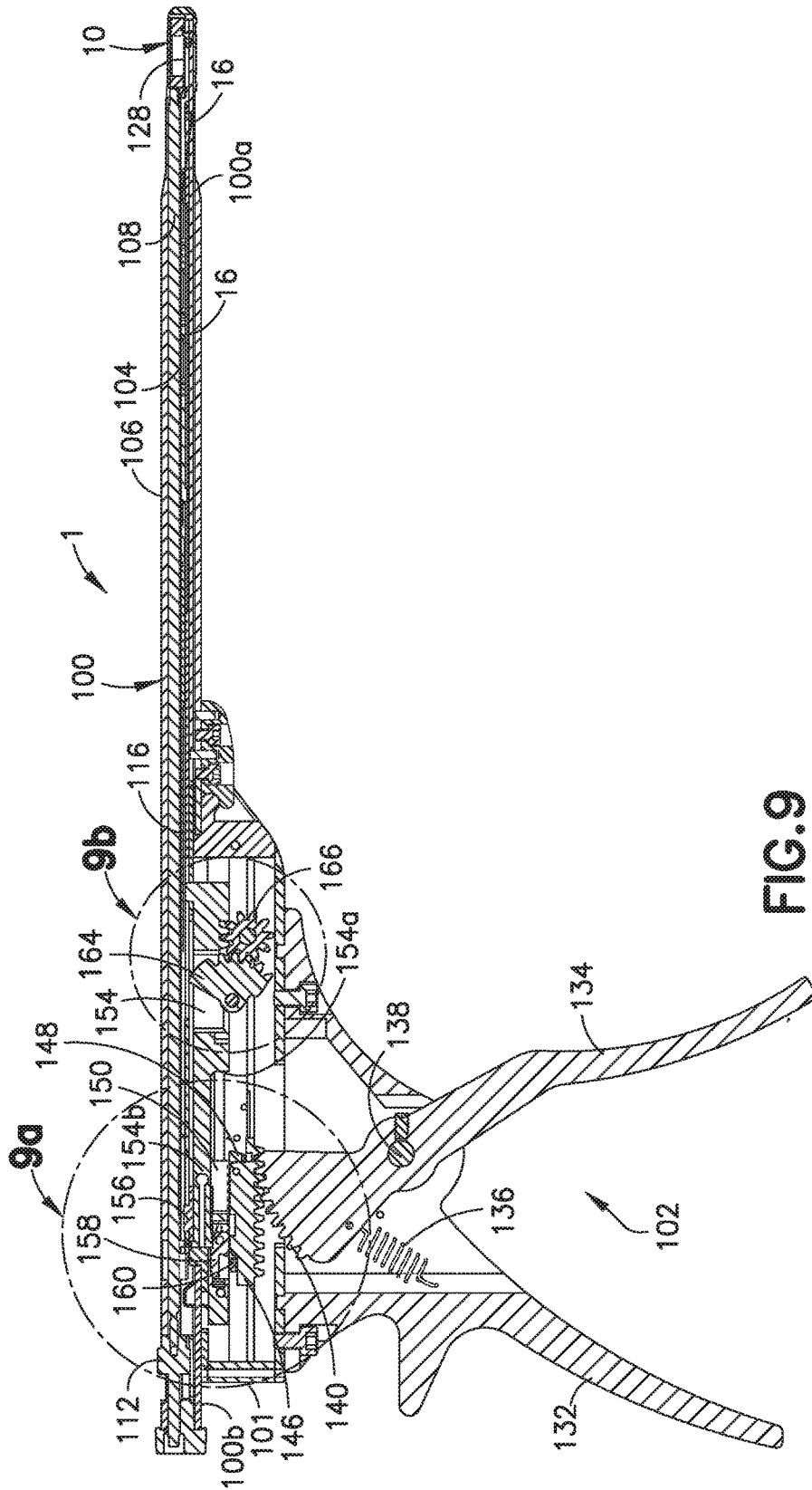


FIG. 9

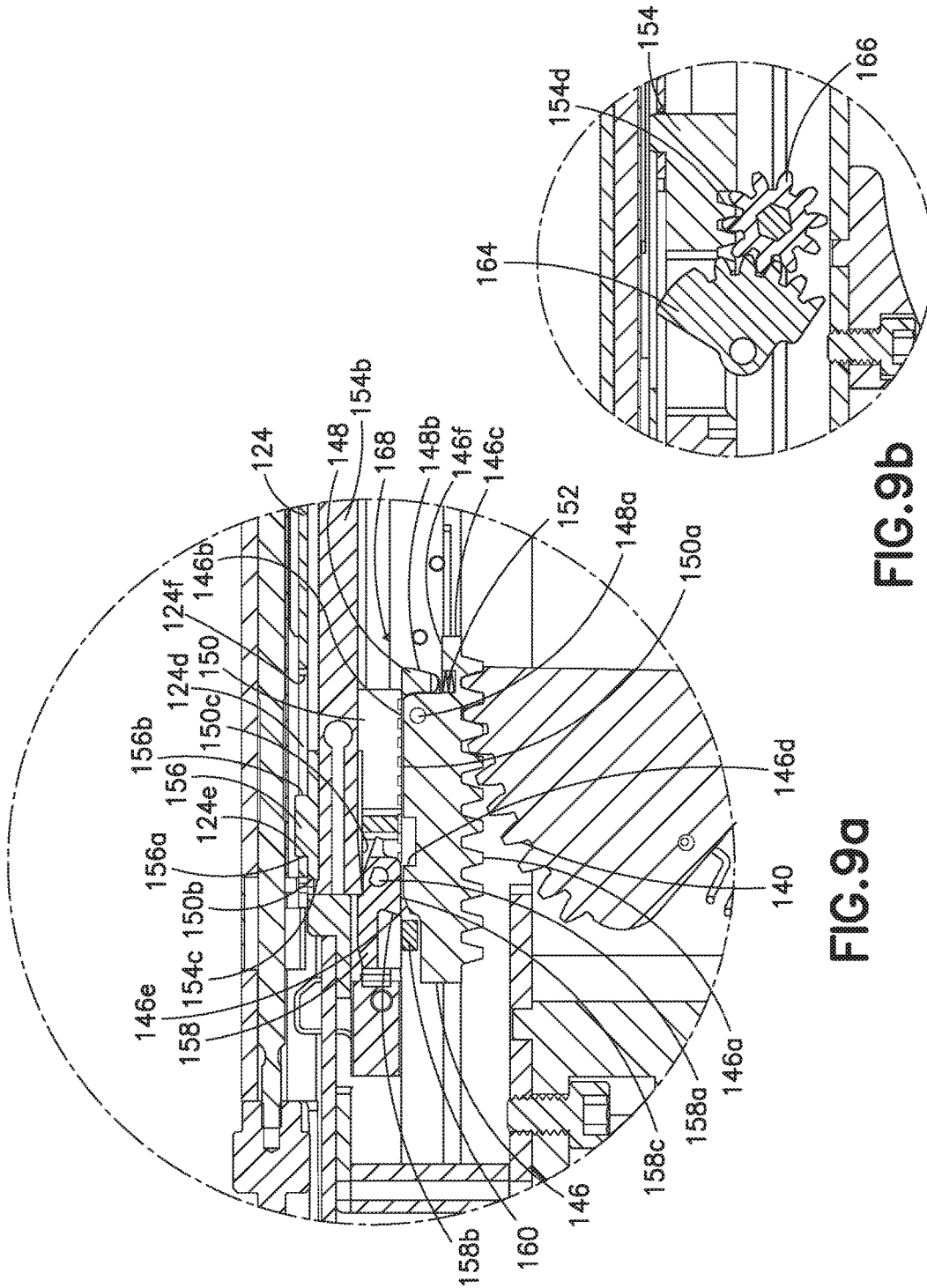


FIG. 9a

FIG. 9b

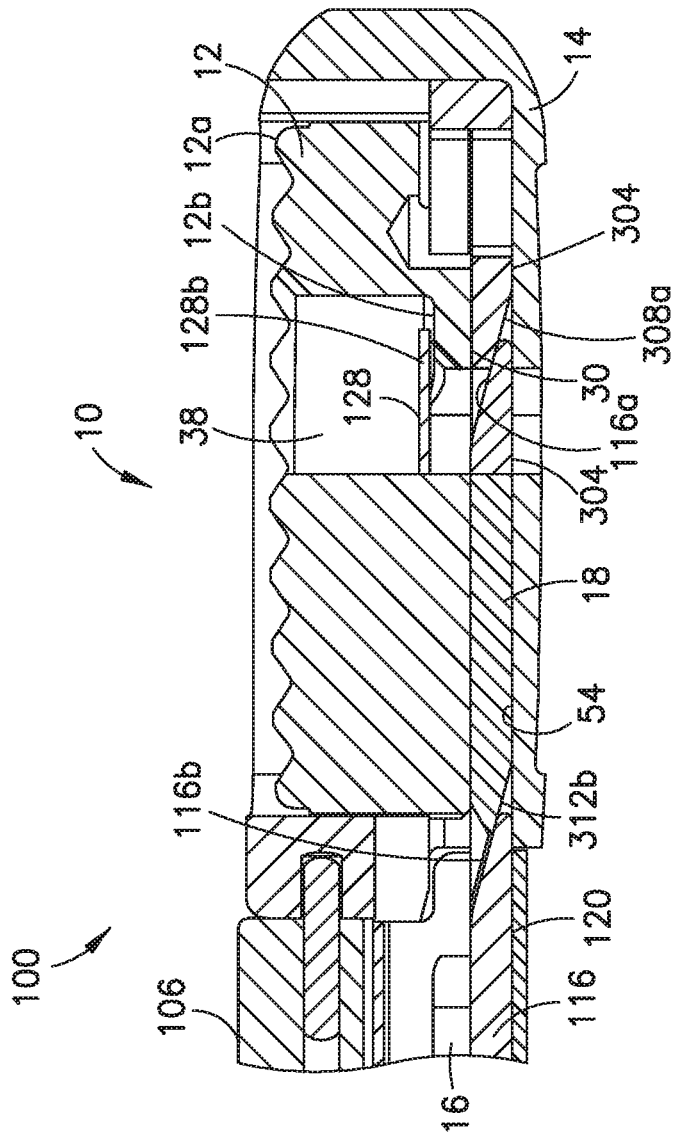


FIG.10b

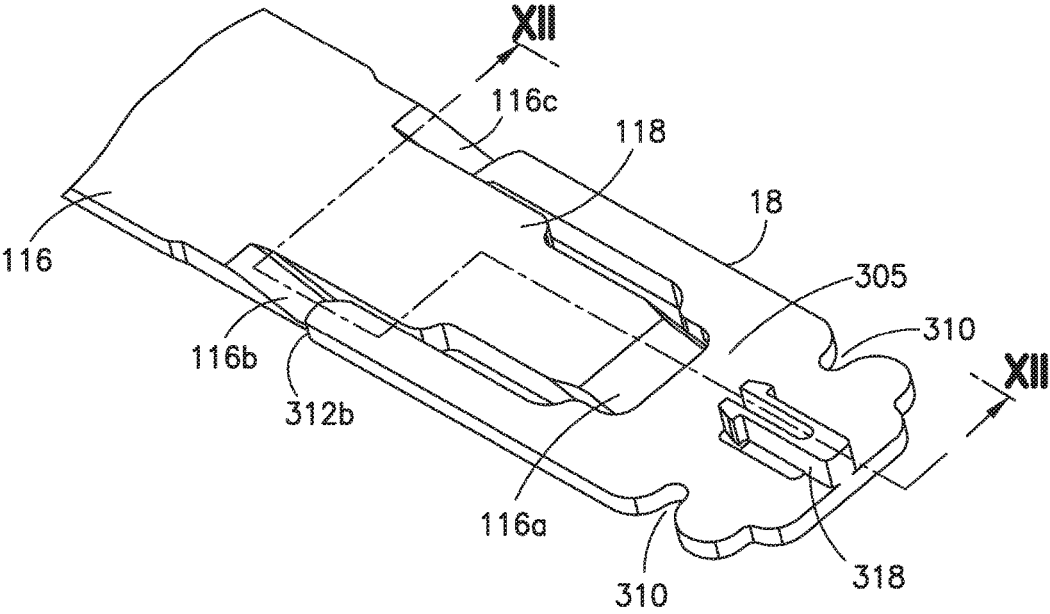


FIG. 11

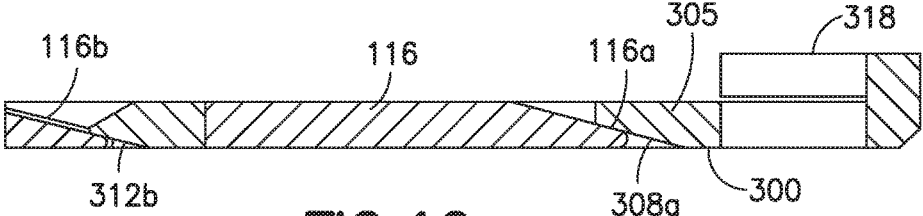


FIG. 12

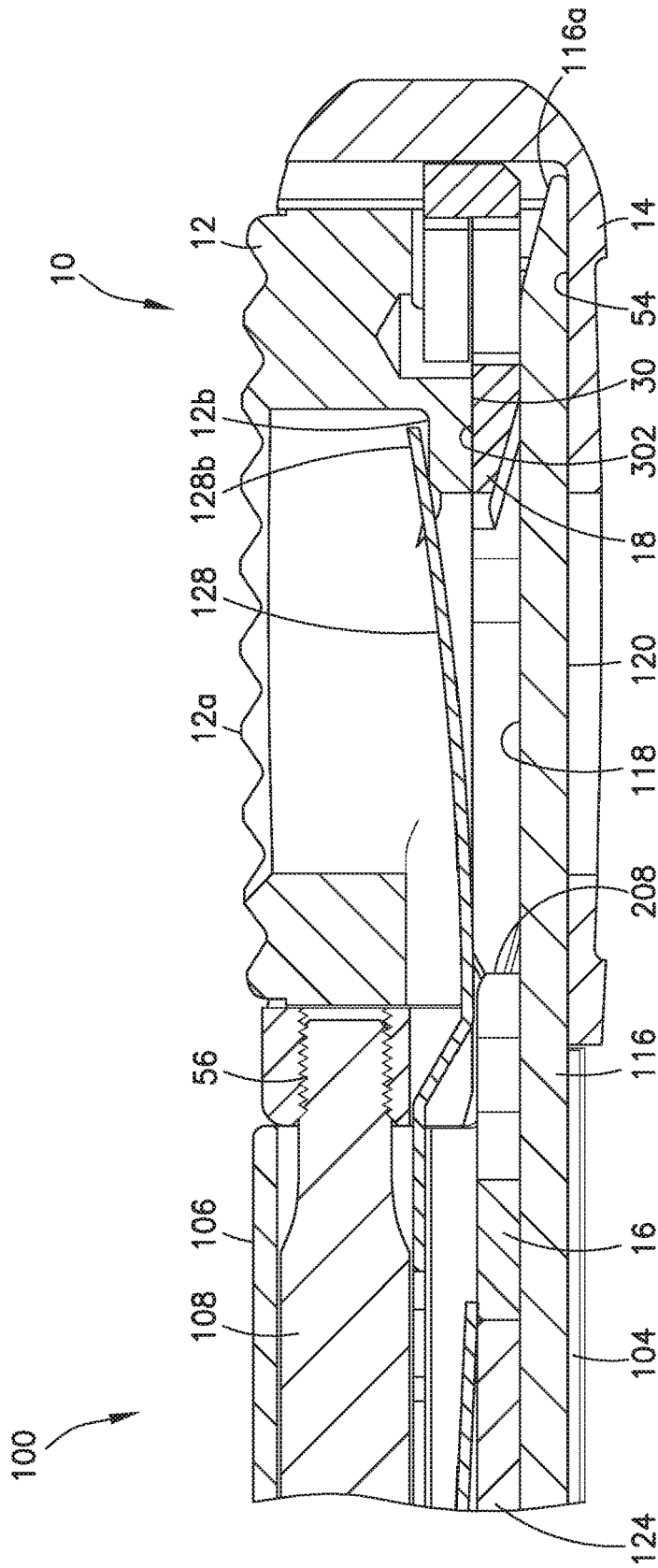


FIG. 13a

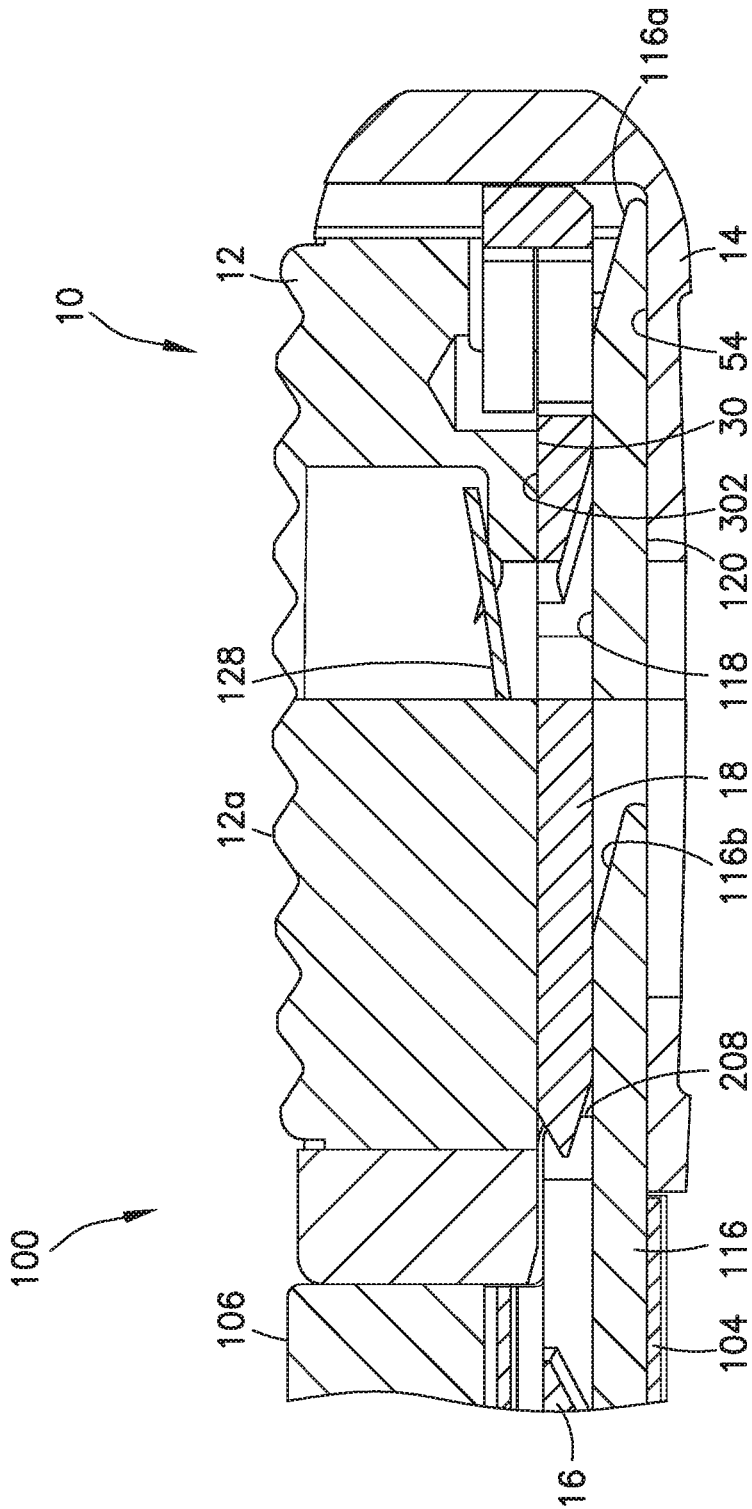


FIG.13b

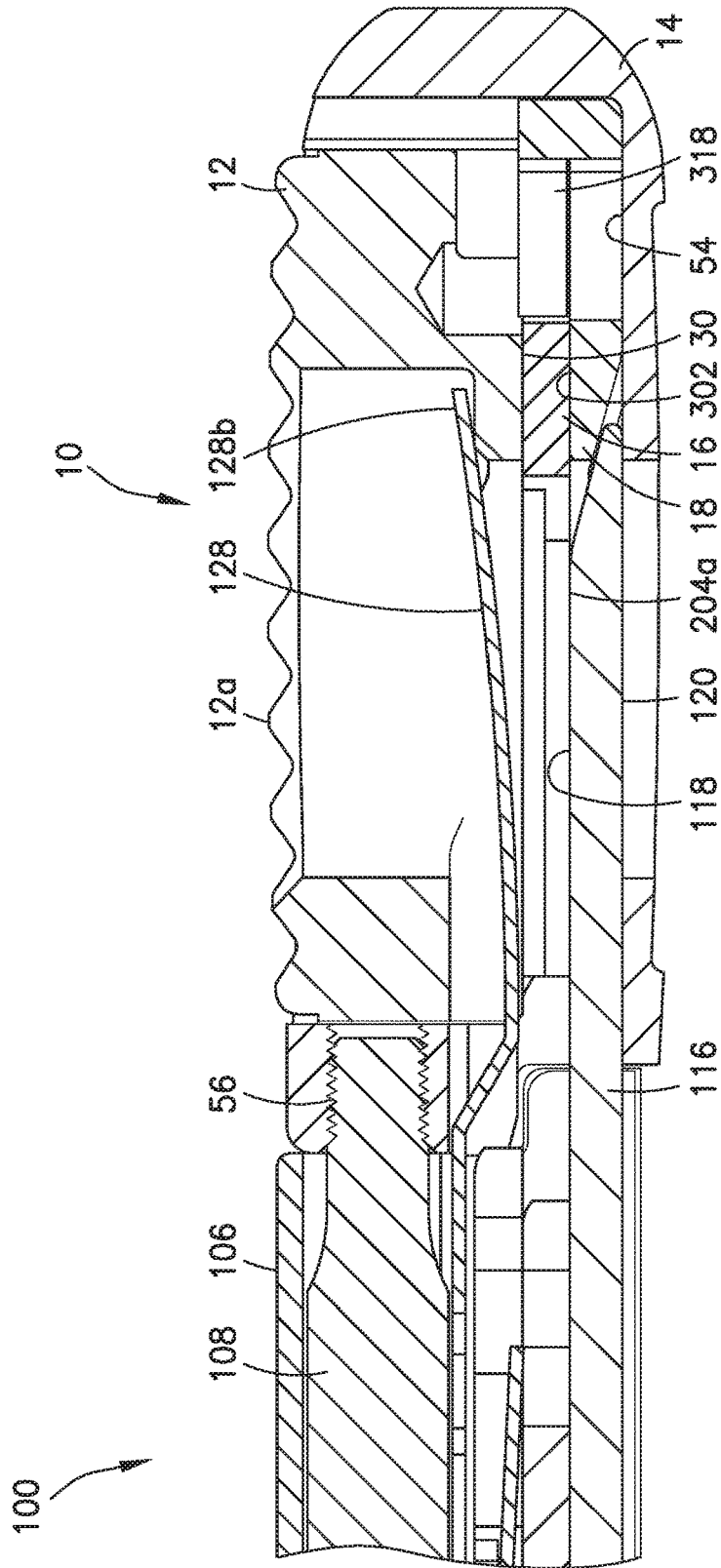


FIG.14

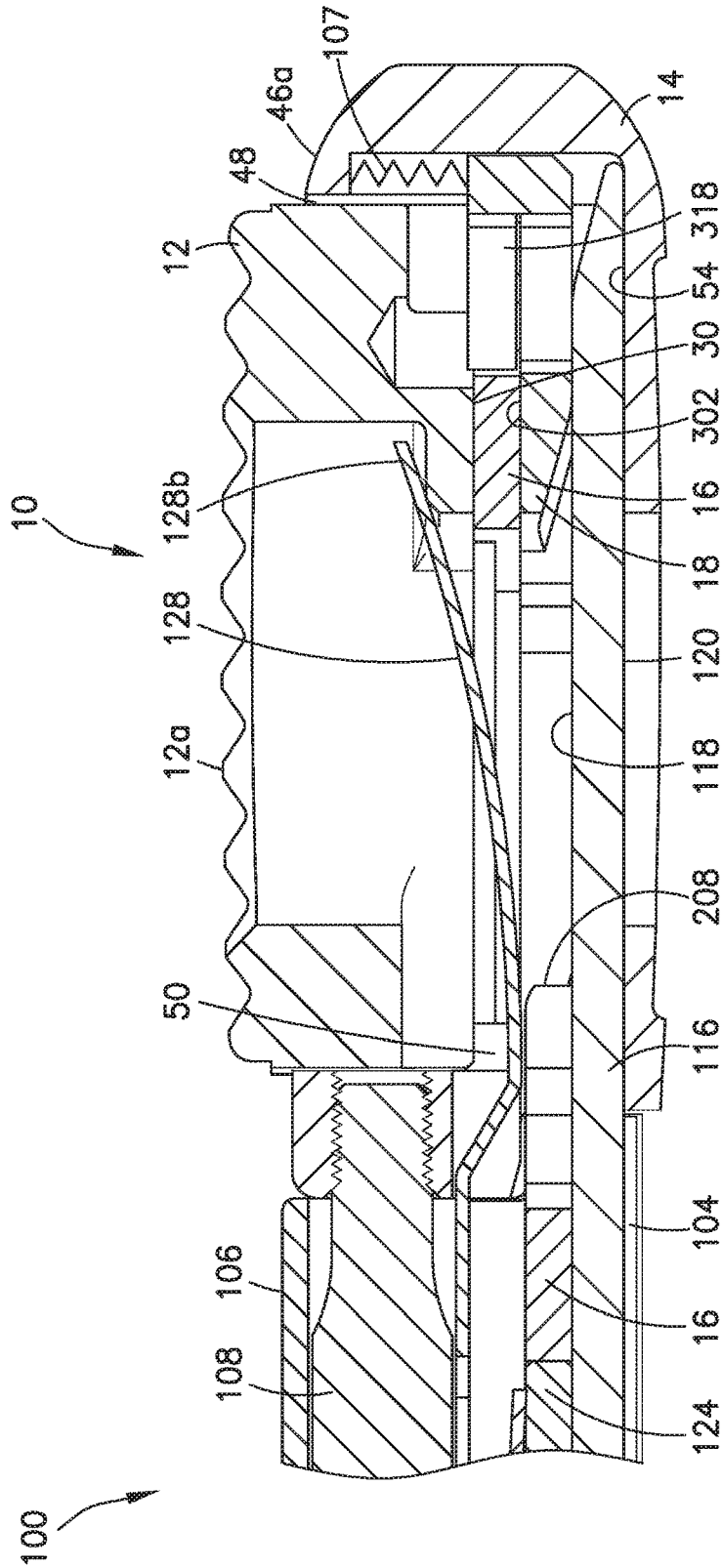


FIG.15a

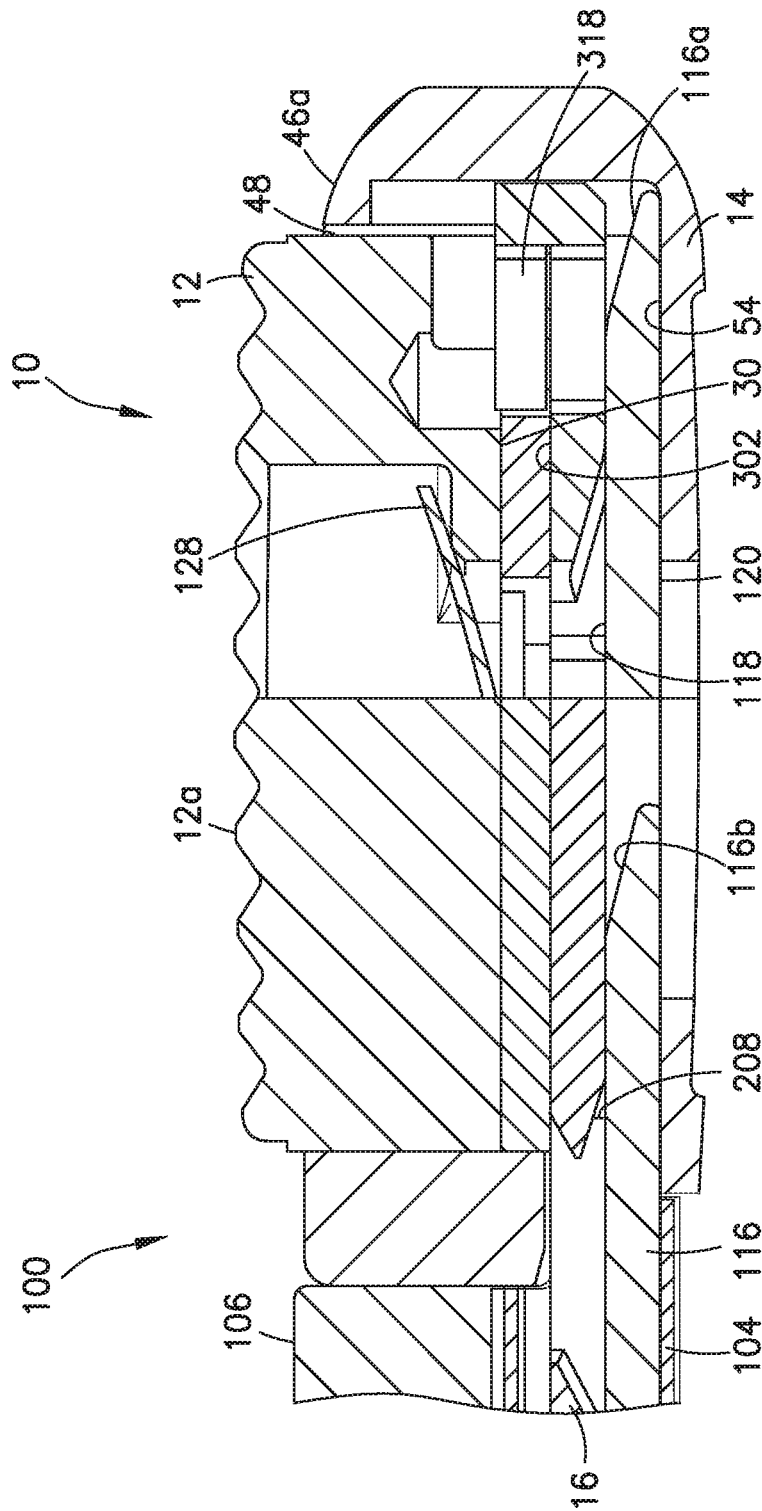


FIG.15b

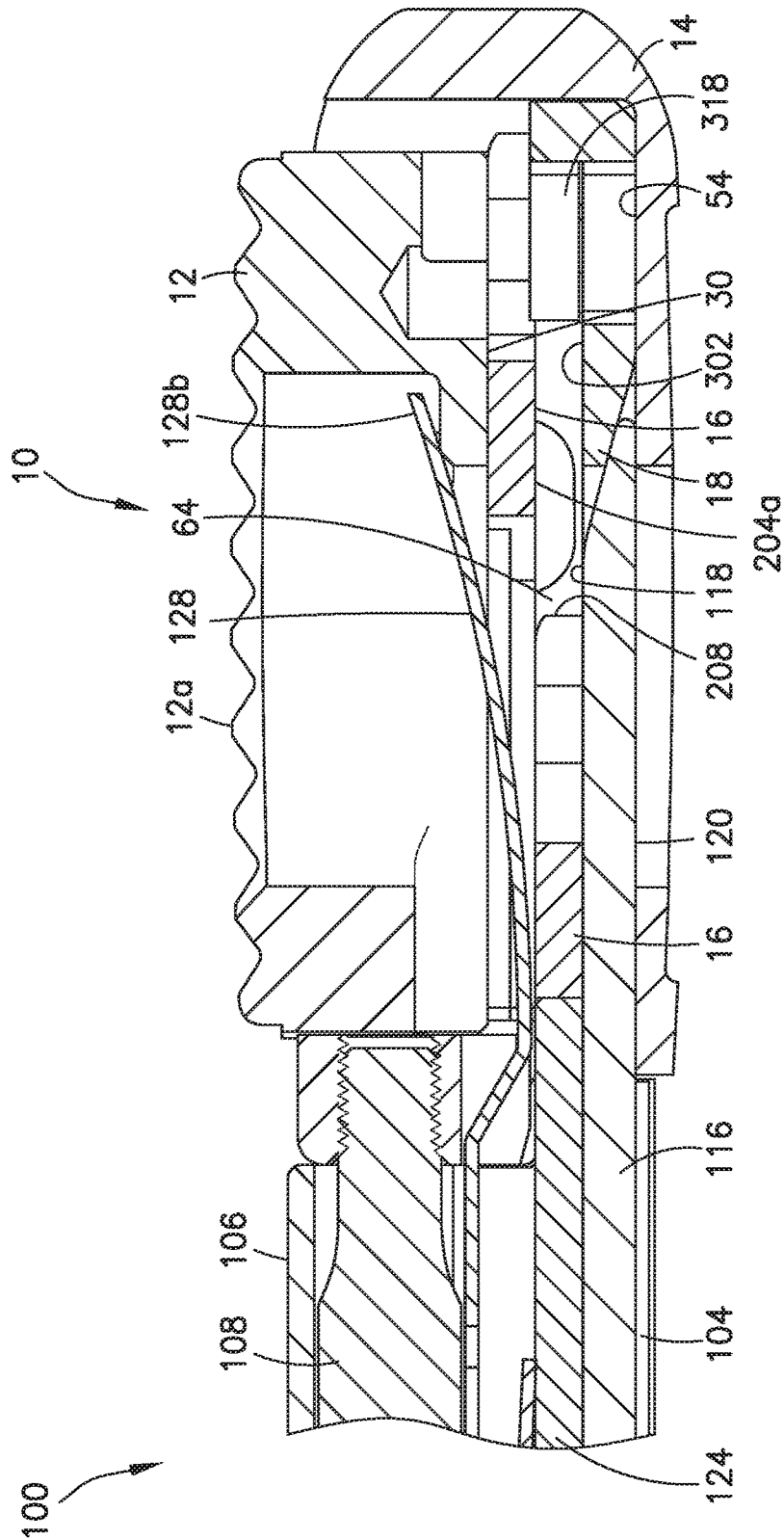


FIG. 16a

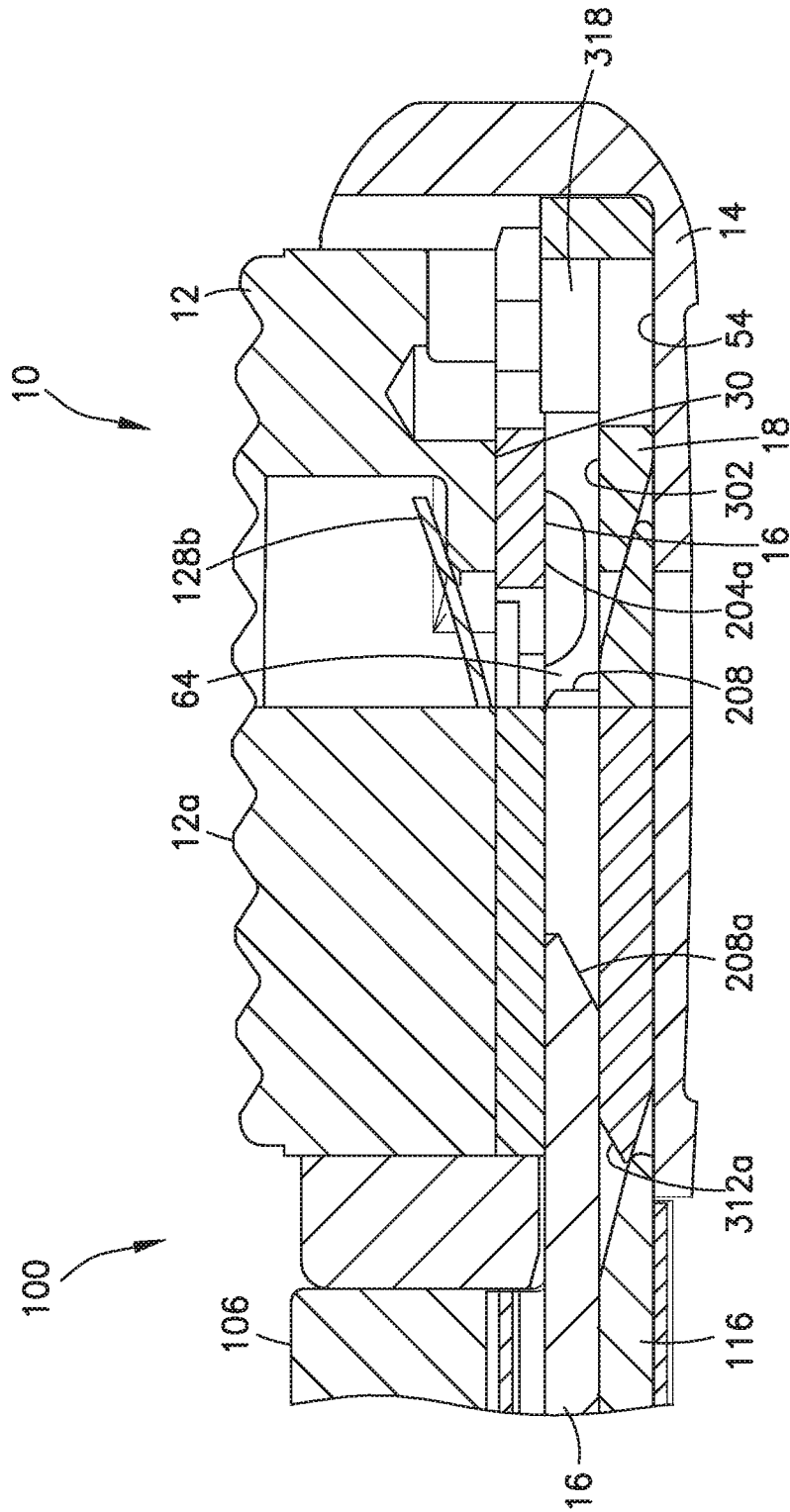


FIG.16b

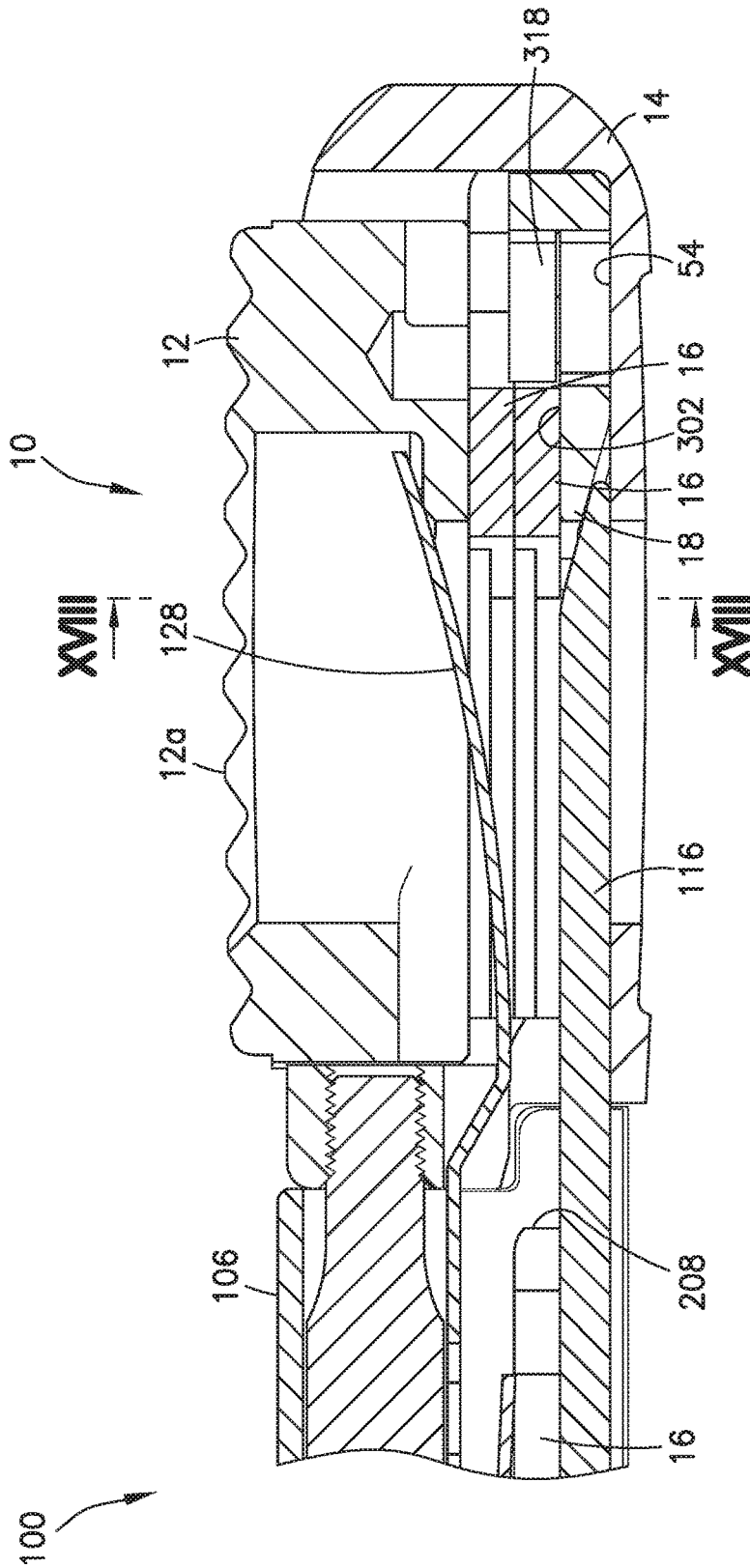


FIG.17

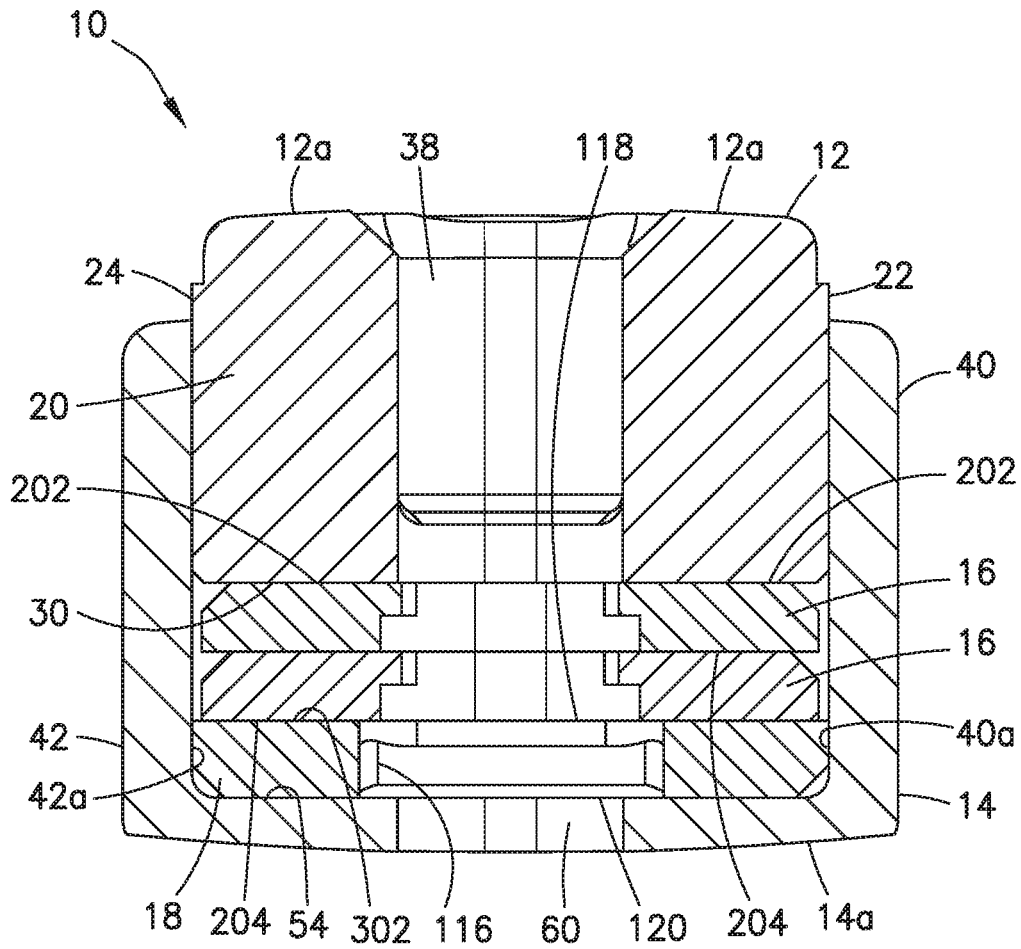


FIG.18

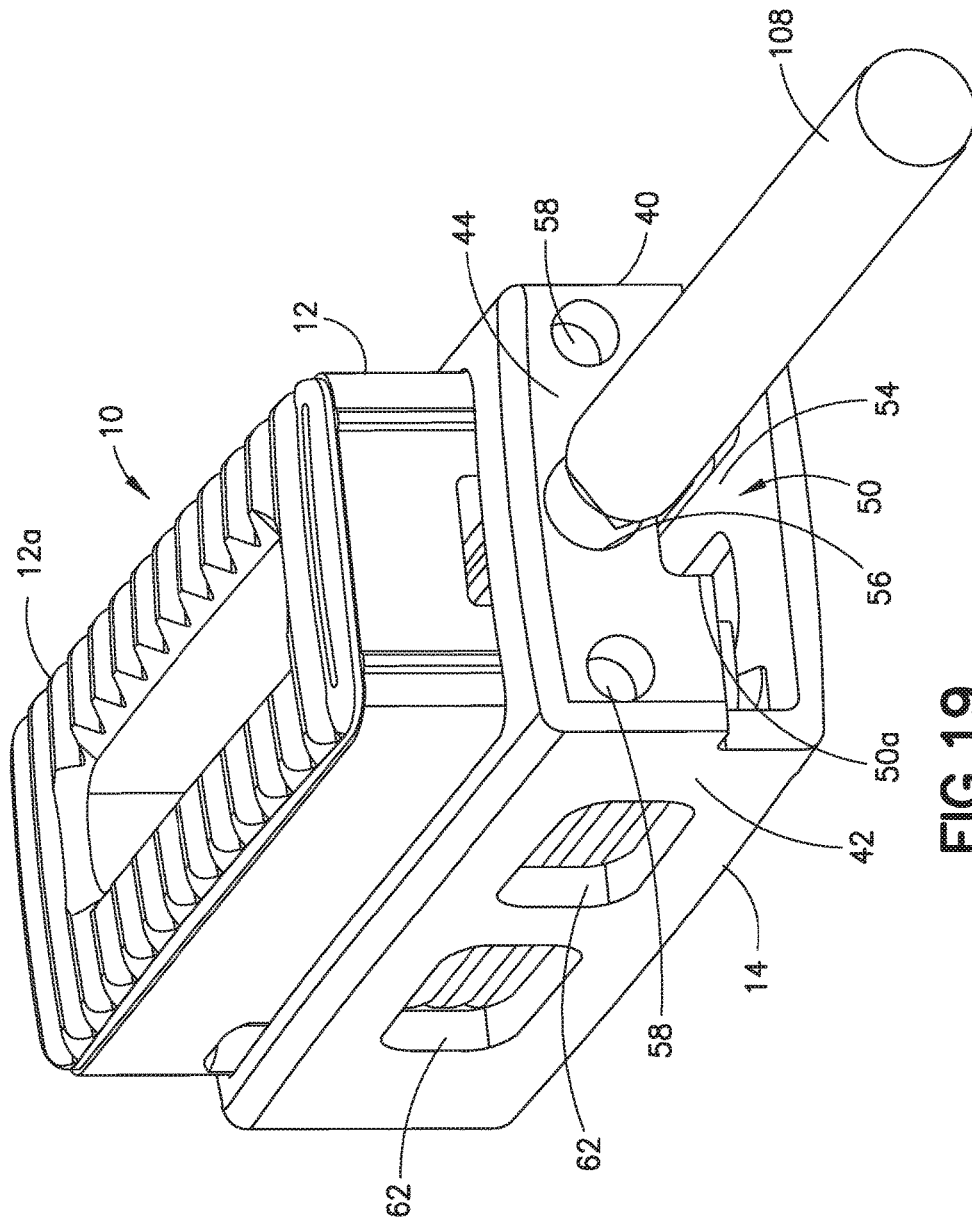


FIG. 19

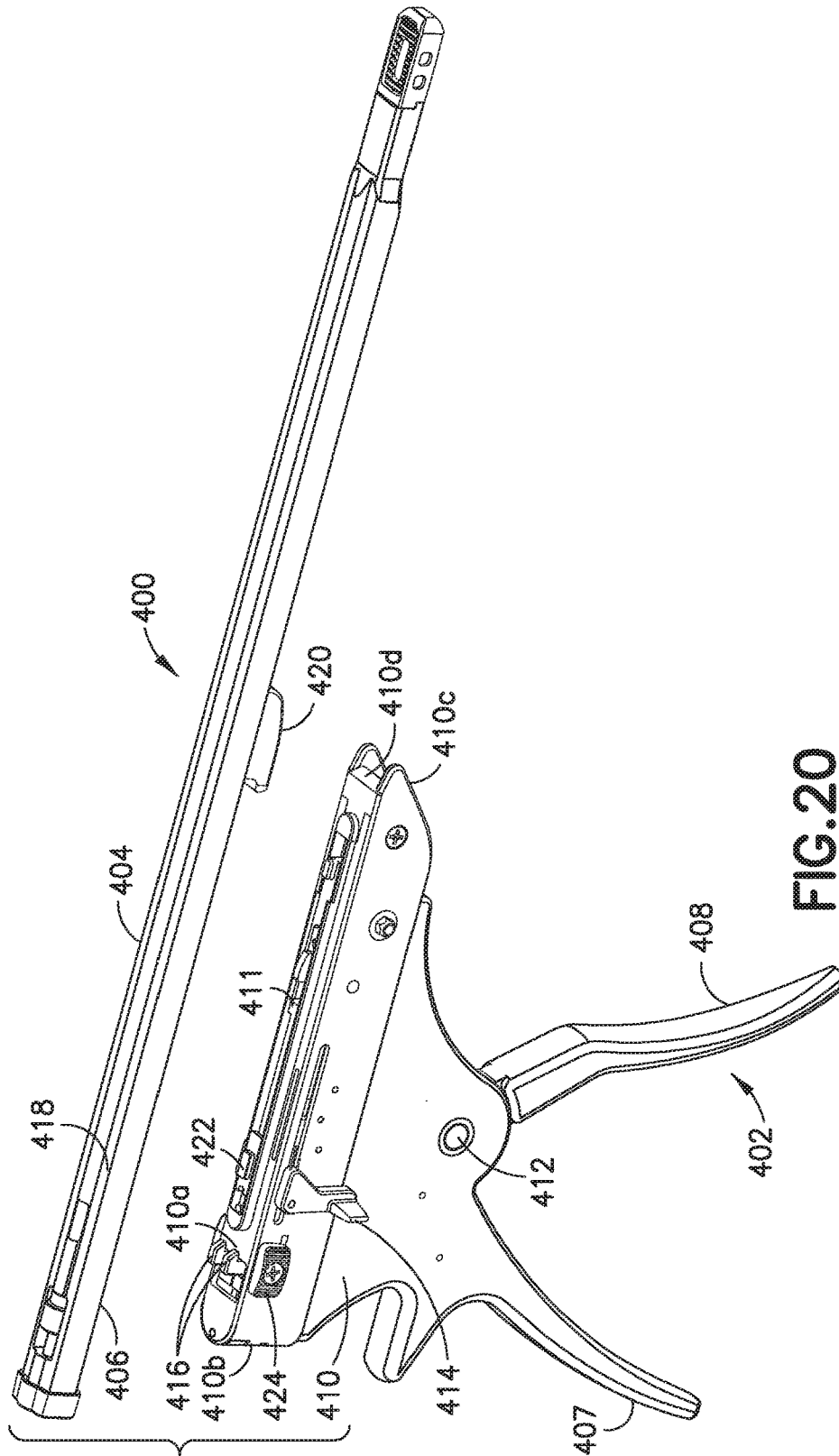


FIG.20

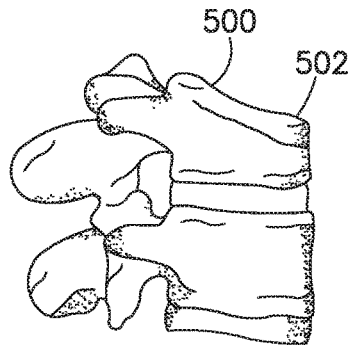


FIG. 21

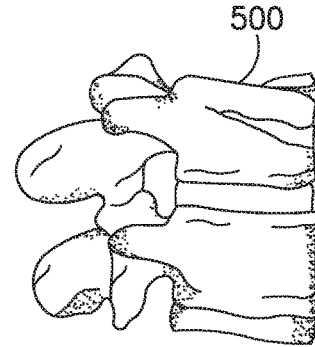


FIG. 22

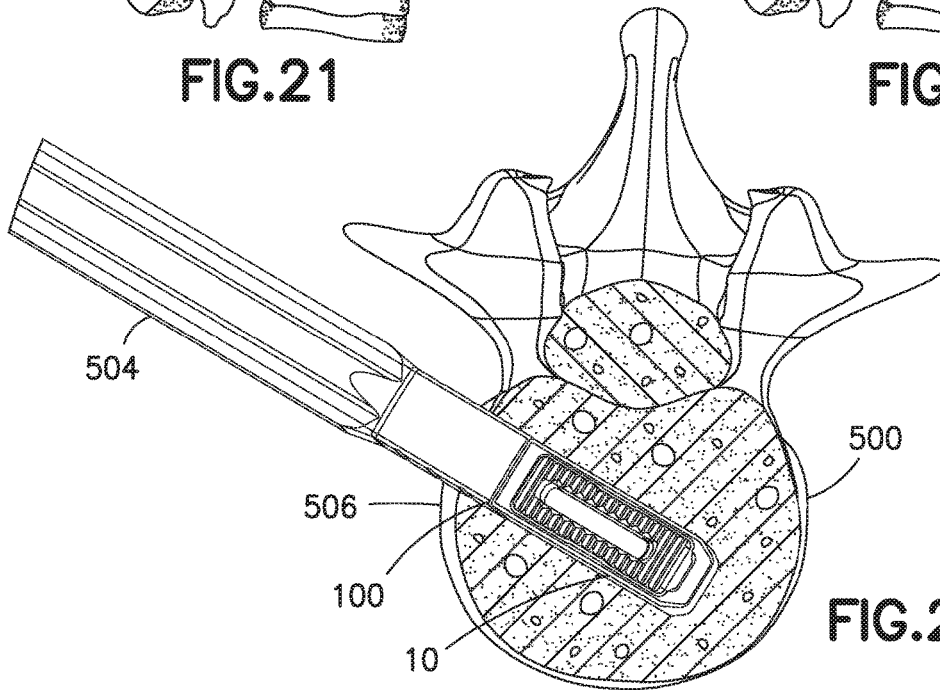


FIG. 23

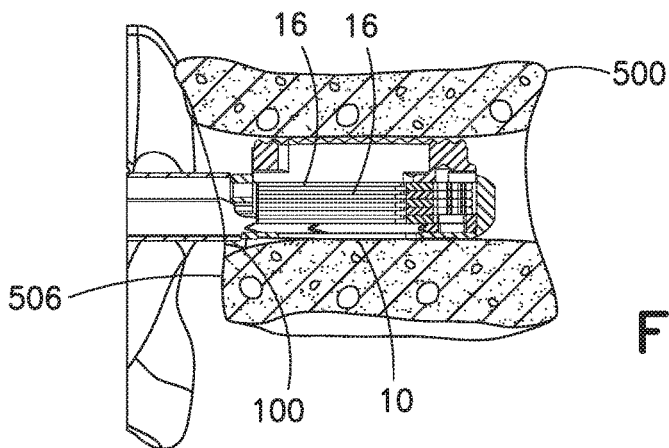


FIG. 24

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INSERTER FOR EXPANDING AN EXPANDABLE DEVICE

CROSS-REFERENCES TO RELATED APPLICATIONS

This application is a continuation of U.S. application Ser. No. 14/736,689, filed Jun. 11, 2015, now U.S. Pat. No. 9,445,921, which is a continuation-in-part application of U.S. application Ser. No. 14/474,555, filed Sep. 2, 2014, now U.S. Pat. No. 9,078,767, which claims the benefit of U.S. Provisional Patent Application No. 61/948,645, filed Mar. 6, 2014, each of which is herein incorporated by reference in its entirety.

FIELD OF THE INVENTION

The subject invention relates generally to the field of surgery, and particularly to surgical devices, instruments and methods of using the same.

BACKGROUND OF THE INVENTION

A variety of physical conditions involves two bodily tissue surfaces that, for treatment of the condition, need to be separated from one another and supported away from one another. Such tissue expansion may be to gain exposure to select tissue structures, to apply a therapeutic pressure to select tissues, to return tissue structures to their anatomic position and form, or in some cases to deliver a drug or growth factor to alter, influence or deter further growth of select tissues. Depending on the condition being treated, the tissue surfaces may be opposed or contiguous and may be bone, skin, soft tissue, or a combination thereof.

One particular device for treating these conditions by distracting and supporting tissue surfaces simultaneously is described in U.S. Pat. No. 6,595,998, entitled "Tissue Distraction Device", which issued on Jul. 22, 2003 (the '998 Patent). Other examples of such tissue distracting and supporting devices that are used for achieving spinal interbody fusion are described in U.S. Pat. No. 7,931,688 entitled "Expandable Interbody Fusion Device", which issued on Apr. 26, 2011 (the '688 Patent), and U.S. Pat. No. 7,967,867 entitled "Expandable Interbody Fusion Device", which issued on Jun. 28, 2011 (the '867 Patent). The '998 Patent, the '688 Patent and the '867 Patent each discloses sequentially introducing in situ a series of elongate inserts referred to as wafers in a percutaneous approach to incrementally distract opposing vertebral bodies to stabilize the spine and correct spinal height, the wafers including features that allow adjacent wafers to interlock in multiple degrees of freedom. The '998 Patent, the '688 Patent and the '867 Patent are assigned to the same assignee as the present invention, the disclosures of these patents being incorporated herein by reference in their entirety.

An issue that has arisen regarding such interbody fusion devices that use inserts or wafers to incrementally expand such devices is the determination of when full expansion has been achieved as a result of ligamentotaxis and no further inserts may be inserted. It is therefore desirable for a surgeon to know when a sufficient number of inserts has been introduced to stabilize the spine and correct spinal height and whether any additional inserts may be introduced. One approach addressing this issue is described in commonly assigned U.S. Pat. No. 8,828,019, entitled "Inserter for

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Expanding an Expandable Interbody Fusion Device", issued on Sep. 9, 2014 ("the '019 Patent") and incorporated herein by reference in its entirety.

Accordingly, in addition to interbody fusion applications, there is a similar need for other applications that use an expandable device and inserter to insert such a device into body tissue and expand the device in situ, including the capability to determine when proper expansion of the device has been achieved and no further inserts may be introduced.

SUMMARY OF THE INVENTION

It is an object of the invention to provide an improved device to expand body tissue and to introduce inserts after the device has been expanded. A further object is to provide an inserter that has the capability of allowing a surgeon to determine that suitable expansion has been reached and no additional inserts may be inserted.

DESCRIPTION OF THE FIGURES

FIG. 1a is a top perspective of an apparatus including an inserter releasably attached to an expandable spinal interbody fusion device in accordance with an embodiment of the present invention, the expandable interbody fusion device being unexpanded.

FIG. 1b is a side elevation view of the apparatus of FIG. 1a.

FIG. 1c is a top plan view of the apparatus of FIG. 1a.

FIG. 2 is an enlarged view of the distal portion of the apparatus as circled in FIG. 1c.

FIG. 3a is top perspective view of the unexpanded fusion device of FIG. 1a.

FIG. 3b is top perspective view of the fusion device of FIG. 3 after being expanded.

FIG. 4 is an exploded top perspective view of the expanded device of FIG. 3b.

FIG. 5a is a side elevation view of the expanded device of FIG. 3b.

FIG. 5b is a sectional view of the device of FIG. 5a as seen along viewing lines B-B of FIG. 5a.

FIG. 5c is a sectional view of the device of FIG. 5a as seen along viewing lines C-C of FIG. 5a.

FIG. 6a is a top perspective view of an insert used in the expandable spinal interbody fusion device of FIG. 3a.

FIG. 6b is a top plan view of the insert of FIG. 6a.

FIG. 6c is a longitudinal cross-sectional view of the insert as seen along viewing lines VI-VI of FIG. 6b.

FIG. 6d is a bottom plan view of the insert of FIG. 6a.

FIG. 6e is a distal end elevation view of the insert of FIG. 6a.

FIG. 7a is a top perspective view of an elevator used in the expandable spinal interbody fusion device of FIG. 3a.

FIG. 7b is a top plan view of the elevator of FIG. 7a.

FIG. 7c is a longitudinal cross-sectional view of the elevator as seen along viewing lines VII-VII of FIG. 7b.

FIG. 7d is a bottom plan view of the elevator of FIG. 7a.

FIG. 7e is a distal end elevation view of the elevator of FIG. 7a.

FIG. 8 is an exploded top perspective view of the track and components of the inserter of FIG. 1a, including the translatable lifting platform and translatable driver.

FIG. 8a is an enlarged view of the distal portion of the inserter track and components as circled in FIG. 8.

FIG. 9 is a cross-sectional view of the inserter and device of FIG. 1a as seen along viewing lines IX-IX of FIG. c.

FIG. 9a is an enlarged view of the encircled portion A of FIG. 9.

FIG. 9b is an enlarged view of the encircled portion B of FIG. 9.

FIG. 10a is a cross-sectional view of the distal end of the inserter and device as seen along viewing lines A-A of FIG. 2 with the expandable device unexpanded.

FIG. 10b is a cross-sectional view of the distal end of the inserter and device as seen along viewing lines B-B of FIG. 2 with the expandable device unexpanded.

FIG. 11 is a top partial perspective view of the distal end of the lifting platform and the elevator of the expandable device in the position depicted in FIGS. 10a and 10b.

FIG. 12 is a cross-sectional view of the lifting platform and elevator as seen along viewing lines XII-XII of FIG. 11.

FIGS. 13a and 13b are views similar to FIGS. 10a and 10b with the lifting platform having been distally moved to a position lifting the elevator and expanding the expandable device and a first insert partially entering the expanded device.

FIG. 14 is a view similar to FIG. 10a showing the first insert inserted into the expanded expandable device.

FIGS. 15a and 15b are views similar to FIGS. 13a and 13b with the lifting platform having been moved distally to a position lifting the elevator and the first insert to further expand the expandable device with a second insert partially entering the expanded device.

FIGS. 16a and 16b are views of the expandable device expanded as shown in the views of FIGS. 15a and 15b with the second insert having been further distally moved to a position moving the elevator away from the first insert and creating a space for the insertion of the second insert.

FIG. 17 is a view similar to the view of FIG. 14 showing the first and second inserts inserted into the expanded expandable device.

FIG. 18 is a cross-sectional view as seen along the viewing lines XVIII-XVIII of FIG. 17.

FIG. 19 is a proximal perspective view of the expanded spinal interbody fusion device with a guide pin releasably connected thereto subsequent to the inserter having been detached from the guide pin with inserts not being shown for clarity.

FIG. 20 is a top perspective of an apparatus including an inserter releasably attached to an expandable spinal interbody fusion device in accordance with a further embodiment of the present invention with the inserter being modular.

FIG. 21 shows a vertebral body having a compression fracture displacing its superior and anterior edge.

FIG. 22 shows a vertebral body, following treatment of a compression fracture.

FIG. 23 illustrates a plan view of an insertion apparatus according to another embodiment of the invention, placed within a vertebral body of FIG. 21, shown in cross-section.

FIG. 24 shows a side view of the insertion apparatus of FIG. 23 being deployed within a vertebral body, shown in sectional view.

DESCRIPTION OF THE EMBODIMENTS

For the purposes of promoting and understanding of the principles of the invention, reference will now be made to the embodiments illustrated in the drawings and described in the following written specification. It is understood that no limitation to the scope of the invention is thereby intended. It is further understood that the present invention includes any alterations and modifications to the illustrated embodiments and includes further applications of the principles of

the invention as would normally occur to one skilled in the art to which this invention pertains.

The invention provides a combination of an implantable expansion and support device and instrumentation to place the device into body tissue. The application of the invention as a spinal implant in spinal interbody fusion is detailed initially. Turning now to FIGS. 1a-c, 2, 3a-b and 4, an apparatus 1 for use in spinal interbody fusion is shown. Apparatus 1 comprises an expandable spinal interbody fusion device 10 and an inserter 100. The inserter 100 is an instrument used for inserting the device 10 into an intradiscal space between opposing vertebral bodies of a spine, expanding the device in situ and for inserting inserts into the expanded device 100. The expandable interbody fusion device 10 includes a first element, such as superior endplate 12, a second element, such as inferior endplate 14, at least one insert 16 and expansion structure including an elevator 18, as will be detailed hereinbelow. The height, H, across the superior and inferior endplates 12, 14 in the unexpanded condition as illustrated in FIG. 1b is less than the normal anatomic height of a typical intradiscal space. The invention contemplates expanding the interbody fusion device 10 by the inserter 100 from an unexpanded condition as shown in FIG. 3a to the expanded height as shown in FIG. 3b to ultimately restore the normal anatomic height of the disc space and thereafter inserting one or more inserts, such as inserts 16, as will be described, to form a stack of inserts 16 between the expanded superior endplate 12 and inferior endplate 14. In the particular arrangement being described, fusion device 10 is configured and sized for implantation into the spine from the posterior approach. In the unexpanded state as shown in FIG. 3a, device 10 has a length of approximately 25 mm, a width of approximately 10 mm, and an unexpanded height H of approximately 7 mm. Fusion device 10 may also be configured and sized for implantation into the spine using posteriolateral, anterior or lateral approaches, as will be described.

The superior endplate 12 as shown in FIGS. 3a-b and 18 is elongate and comprises a hub 20 having pair of side surfaces 22 and 24 extending longitudinally on each side of the hub 20 and a pair of end surfaces 26 and 28 extending respectively at the proximal rear end and the distal front end of the superior endplate 12. The hub 20 is sized and configured to fit within a cavity 48 of the inferior endplate 14 for telescoping movement therewithin, as will be described. The lower surface 30 of the hub 20 (FIG. 18) is generally flat and planar. Suitable friction or crush ribs may be provided between the hub 20 and cavity 48 of inferior endplate 14 at inner surface 44a to temporarily hold the superior and inferior endplates 12, 14 together in the direction of expansion as the device 10 is introduced into the intradiscal space to be distracted.

With continued reference to FIGS. 3a-b and 18, the superior endplate 12 includes a graft chamber defined by an opening 38 extending through the upper outer surface 12a and the lower surface 30. In accordance with one arrangement, the superior endplate 12 is formed of a biocompatible polymer such as polyethylethylketone (PEEK). PEEK is used in fusion applications for its combination of strength, biocompatibility, and elasticity which is similar to human bone. Other composites may include derivatives of PEEK such as carbon fiber reinforced PEEK and PEKK, respectively. In a particular aspect, the superior endplate 12 may further include an upper endcap that defines the outer surface 12a. The endcap may be a separate plate formed of material for the promotion of bone growth, such as titanium, and may be attached to the endplate 12 with suitable

conventional techniques. As an alternative, the upper surface **12a** may be defined by a coating of a suitable layer of bone growth promotion material, such as titanium, which may be deposited by conventional techniques.

The inferior endplate **14** of the interbody fusion device **10** as shown in FIGS. **3a-b** and **18** is elongate and comprises a pair of opposing spaced apart sidewalls **40** and **42** extending along the longitudinal direction and projecting upwardly from the lower outer surface **14a**. A pair of spaced apart end walls **44** and **46** extend laterally across the device **10** and project upwardly from outer surface **14a**. Rear end wall **44** is disposed at the rear or proximal end of the device **10** and front end wall **46** is disposed at the front or distal end of the device **10**. The side walls **40**, **42** together with rear end wall **44** and front end wall **46** form an open, upwardly facing fully bounded interior cavity **48** as shown in FIGS. **3a** and **4**. The interior cavity **48** is sized and configured to receive the superior endplate **12** including the hub **20** in relatively close fit between the side walls **40** and **42** and the end walls **44** and **46** of the inferior endplate **14** in a non-expanded condition as shown in FIGS. **1a-b**. The hub **20** of superior endplate **12**, as well as the entire stack of inserts **16**, remains fully contained within the inferior endplate **14** during telescoping expansion of the device **10** as shown in FIGS. **18** and **19**, contributing to the torsional strength of the expanded device **10**.

The inferior plate **14** as shown in FIGS. **4** and **19** includes a lower inner support surface **54** on which elevator **18** is supported. Inner surface **54** defines the bottom surface of the cavity **48**. Inferior endplate **14** further defines a fully bounded insert channel **50** extending through the rear end wall **44** in communication with interior cavity **48** and through which one or more inserts **16** are introduced. The height of channel **50** as measured vertically from inner surface **54** is slightly greater than the combined thicknesses of insert **16** and elevator **18**. With insert **16** being slidably received through channel **50** on top of elevator **18**, as will be described, only one insert **16** may be introduced at a time. As device **10** is expanded and further inserts **16** are sequentially introduced, all inserts **16** lying above the lowermost insert **16**, which would be situated on top of elevator **18**, will be prevented from backing out of the device **10** by the interior surface **44a** of rear end wall **44** (FIG. **4**). The rear end wall **44** further defines a threaded connection opening **56** (FIG. **10a**) for threaded releasable receipt of a guide pin **108** for use in the introduction of inserts **16** and in the delivery of bone graft material into the device **10**, as will also be described. Rear end wall **44** may also additionally include a pair of bilateral openings, such as holes **58**, adjacent the sidewalls **40** and **42** for use in releasably attaching the inserter **100** to the device **10** for the establishment of a rigid connection to the device **10** for insertion into the intradiscal space.

Elevator **18** is supported on inner surface **54** of inferior endplate **14** with the lateral width of elevator **18** being dimensioned for relatively close sliding fit between opposite interior surfaces **40a** and **42a** of side walls **40** and **42**, as shown in FIGS. **5c** and **18**. As such, lateral movement of elevator **18** in directions transverse to the direction of expansion is substantially constrained. In addition, inferior endplate **14** includes a rail **14b** projecting inwardly from each interior surface **40a** and **42a** and upwardly from lower inner surface **54** toward superior endplate **12**. The upward projection of each rail **14b** from inner surface **54** is slightly greater than twice the thickness of elevator **18**. Rails **14b** slidably project into recesses **310** extending into the base **305** of elevator **18** at each lateral side. Rails **14b** substan-

tially constrain movement of elevator **18** in the axial direction while the clearance in recesses **310** allows free movement of elevator **18** in the direction of expansion along rails **14b** as shown by the arrow **130** in FIG. **10a**. As such, elevator **18** is captively supported within inferior endplate **14** and is independently movable along the direction of expansion toward and away from each of the superior endplate **12** and the inferior endplate **14**.

As shown particularly in FIGS. **4**, **5a-b** and **18**, the inferior endplate **14** includes a graft chamber defined by an opening **60** extending through the lower outer surface **14a** and the lower inner surface **54** in communication with cavity **48**. In accordance with one arrangement, the inferior endplate **14** is formed of a material different from the material of the superior endplate **12**. In this aspect, the inferior endplate **14** may be formed of a biocompatible metal, such as titanium, for its strength properties. Titanium is chosen for strength, biocompatibility, processing capability, and fluoroscopic imaging properties (radiolucency). Other alternative materials include cobalt chrome, stainless steel (both stronger than titanium but much less radiolucent), or biocompatible ceramics such as silicon nitride or zirconia, which are radiolucent. Titanium and silicon nitride have demonstrated good apposition to bone and superiority to PEEK. In this regard where inferior endplate **14** is formed of titanium, the lower outer surface **14a** would provide for the promotion of bone growth. Lower outer surface **14a** may also, however, be coated with a suitable layer of bone growth promotion material, such as titanium, and deposited in a conventional manner so as to match the roughness/porosity of the superior endplate outer surface **12a**.

Where inferior endplate **14** is formed of titanium or other suitable metal that is radiopaque, windows **62** may be formed through sidewalls **40** and **42** as shown in FIGS. **3a-b** and **19** so as to allow visual observation of bony growth through growth by suitable imaging techniques, such as fluoroscopy. Further details of interbody fusion device **10** are described in commonly assigned U.S. Pat. No. 8,900,312, patent application Ser. No. 13/795,054 entitled "Expandable Interbody Fusion Device with Graft Chambers", filed on Mar. 12, 2013 ("the '312 Patent") and incorporated herein by reference in its entirety.

Details of insert **16** are shown in FIGS. **6a-e**. The insert **16** comprises an elongate and generally flat body **200** having an upper surface **202** and a lower surface **204**, both of which are generally planar and substantially parallel so that the inserts **16** can form a stable stack within the interbody fusion device **10** upon expansion. Insert **16** includes a trailing rear proximal end **206** and a leading front distal end **208**. The body **200** is formed to have a generally U-shaped, horseshoe configuration, with a pair of spaced opposing arms **212** and **214** projecting rearwardly from a base **205** and defining a rearwardly facing generally U-shaped opening **216** extending through the rear end **206** and through upper surface **202** and lower surface **204**. The lateral width of body **200** between side surfaces **212a** and **214a** is dimensioned for a relatively close sliding fit between interior surfaces **40a** and **42a** of side walls **40** and **42** of inferior endplate **14**, as shown in FIG. **5b**. Such close dimensioning reduces the potential of lateral movement of insert **16** during insert introduction and within cavity **48** of inferior endplate **14**. A surface **218** between the upper surface **202** and the lower surface **204** at the base **205** of opening **216** defines a pushing surface for receipt of a driver of inserter **10**, as will be described. The opening **216** at the rear end of each insert **200** is provided to allow bone graft material to flow into the device **10** through the insert openings **216** and into the openings **38** and **60**

extending through the superior endplate **12** and the inferior endplate **14**, respectively. A pair of inclined surfaces **208a** extends upwardly from and communicating with lower surface **204** on each lateral side the insert **16** adjacent the front distal end **208**.

The insert **16** includes a feature for interlocking engagement with elevator **18** in a complementary cooperative connection. Distal front end **208** of insert body **200** includes therein a latching receptacle **220** defined by a pair of spaced opposing arms **222a** and **222b** for receipt therein of a flexible latch **318** (FIG. *7a-e*) on elevator **18**, as will be described. Arms **222a** and **222b** include inwardly projecting locking surfaces **224a** and **224b** respectively for cooperative locking engagement with elevator latch **318**. Unlike the inserts described in the '312 Patent, the inserts **16** described herein do not function to assist in the separation of superior endplate **12** and inferior endplate **14** or any subsequent inserts **16** inserted into interbody fusion device **16**, as that lifting function is provided herein by inserter **100** in conjunction with elevator **18**. It is contemplated that the inserts **16** described herein be formed of a biocompatible material that is sufficiently rigid to form a solid stack as the successive inserts are inserted into the device. Thus, in one specific embodiment, the inserts **16** are formed of PEEK or a carbon-fiber reinforced PEEK, or similar polymeric material.

Turning now to FIGS. *7a-e*, details of the elevator **18** are shown. The elevator **18** comprises an elongate and generally flat body **300** having an upper surface **302** and a lower surface **304**, both of which are generally planar and substantially parallel. The elevator **18** has a thickness between upper surface **302** and lower surface **304** that is slightly greater than the thickness of insert **16**. As such, when as noted below the thickness of an insert **16** is, for example, 1.0 mm, the thickness of elevator **18** may be 1.03 mm. Elevator **18** includes a trailing rear proximal end **306** and a leading front distal end **308**. The elevator body **300** is formed to have a generally U-shaped, horseshoe configuration similar to the configuration of insert **16**. Elevator body **300** includes a pair of spaced opposing arms **312** and **314** projecting rearwardly from a base **305** and defining a rearwardly facing generally U-shaped opening **316** extending through the rear end **306** and through upper surface **302** and lower surface **304**. Base **305** has a rearwardly facing surface **305a** that communicates with opening **316**. The opening **316** at the rear end of elevator **18** is provided to allow bone graft material introduced into the device **10** to flow through the insert openings **216** of inserts **16** and into the openings **38** and **60** extending through the superior endplate **12** and the inferior endplate **14**, respectively. The rear proximal end **306** includes an inclined surface **312a** and **314a**, respectively at the free end of each arm **312** and **314** extending downwardly from and communicating with the upper surface **302**. The rear proximal end **306** further includes an inclined lifting surface **312b** and **314b**, respectively at the free end of each arm **312** and **314** extending upwardly from and communicating with the lower surface **304**. The front distal end **308** includes adjacent base surface **305a** an inclined lifting surface **308a** extending upwardly from and communicating with lower surface **304**. The inclined lifting surfaces **312b**, **314b** and **308a** are angled in the same direction with approximately equal angles. The lifting surfaces **312b**, **314b** and **308a** define inclined ramps with multiple points of contact for cooperative contact with complementary surfaces of an expansion component on the inserter **100** for lifting elevator **18**, as will be described. Inclined surface **308a** is generally centrally located along the elongate axis of elevator, while surfaces **312b** and **314b** are

spaced bilaterally. Thus, lifting surfaces **308a**, **312b** and **314b** define three triangulated points of contact. Elevator has a recess **310** extending into the elevator base **305** at each lateral side thereof. Recesses **310** are sized to receive rails **14b** on the interior surfaces of inferior endplate **14**, as described. In one specific embodiment, the elevator **18** is formed of titanium alloy, type 2, which may be anodized for lubricity. Other materials, such as PEEK, may also be used as the material for elevator **18**.

Distal front end of elevator body **300** includes a flexible latch **318** projecting upwardly from upper surface **302**. Latch **318** comprises a pair of spaced opposing flexible arms **320a** and **320b** that are configured to flex toward each other. Flexible arms **320a** and **320b** include outwardly directed locking surfaces **322a** and **322b** respectively, for cooperative receipt within receptacle **220** of each insert **16**, as shown in FIG. *5b*. Upon receipt of latch **318** into receptacle **220**, locking surfaces **224a** and **224b** resiliently engage locking surfaces **322a** and **322b**, respectively. Latch **318** projects above the upper surface **302** and a height slightly greater than the thickness of an insert **16**. The lateral width of elevator body **300** between the side surfaces **312c** and **314c**, respectively of arms **312** and **314** is dimensioned for a relatively close sliding fit as noted hereinabove between interior surfaces **40a** and **42a** of inferior endplate **14**, as shown in FIG. *5c*.

Turning again now to FIGS. *1a-c* and FIGS. **8** and **8a**, details of the inserter **100** are described. Inserter **100** is elongate having a distal end **100a** and at a proximal end **100b** a frame **101**. A trigger actuator **102** to effect expansion of device **10** and insertion of inserts **16** into device **10** after expansion includes a frame **101** at the proximal end **100b** of inserter. A plurality of inserts **16** are movably supported in a linear array on an elongate track **104** for individual successive insertion into device **10**. Track **104** supports at least one insert **16** and may, for example, support an array of five inserts **16**, although fewer or more inserts **16** may be supported as desired.

The distal end **100a** is shown in exploded detail in FIGS. **8** and **8a**. The inserter **100** includes elongate track **104** and an outer elongate track cover **106**, the cover **106** being substantially rigidly joined to track **104**. Track **104** is configured as a closed channel and is supported within outer track cover **106**. Cover **106** is fixedly secured to frame **101**, although in a particular arrangement as will be described, cover **106** may be removably attached to frame **101**. An elongate guide pin **108** is supported within an opening **110** extending lengthwise through the cover **106**. The distal end **108a** of the guide pin **108** is threaded for releasable threaded engagement into opening **56** in the proximal rear end wall **44** of the inferior endplate **14**. The proximal end of guide pin **108** is provided with a threaded knob **112** for compressing and releasably attaching the cover **106**, and thereby the track **104** to the device **10**. The track cover **106**, in one arrangement, includes a pair of opposing pins **114** that engage corresponding holes **58** in rear wall **44** of inferior endplate **14** (FIG. *19*) to assist in rigidly securing the inserter **100** to the device **10**. It should be appreciated that other securement structure may be used to releasably attach the inserter **100** to the device **10**. Track **104**, in one embodiment, is formed of stamped stainless steel and cover **106** is an extruded aluminum alloy. Stainless steel or strong reinforced plastic could also be used for cover **106**.

The track **104** at the distal end **100a** of the inserter **100** supports an expansion component defined by an axially translatable lifting platform **116** movably supported on track **104** for relative axial movement thereto to cooperatively

slidably contact elevator 18 for expanding the device 10. The lifting platform 116 is elongate and generally flat having an upper surface 118 and a lower surface 120, both of which are generally planar and substantially parallel (FIG. 18). The lifting platform 116 has a thickness between upper surface 118 and lower surface 120 that is dimensioned to be the same as the thickness of elevator 18, i.e., slightly greater than the thickness of an insert 16. Lifting platform 116 is supported by the inserter 100 for reciprocating axial movement in projecting and retracting directions. The proximal end of the lifting platform 116d is coupled to the trigger actuator 102 to effect such projecting and retracting directions, as will be described.

Lifting platform 116 projects slidably axially outwardly from track 104 and includes at its free distal end an inclined lifting surface 116a extending downwardly from and communicating with upper surface 118. At a location spaced proximally of lifting surface 116a, lifting platform further includes a pair of laterally spaced inclined surfaces 116b and 116c. The inclined lifting surfaces 116a, 116b and 116c are angled in the same direction with angles approximately equal to the angles respectively of inclined lifting surfaces 312b, 314b and 308a of elevator body 300. Inclined surfaces 116a, 116b and 116c define inclined ramps with multiple complementary points of contact for cooperative contact with elevator 18. Inclined surface 116a is generally centrally located along the elongate axis of lifting platform 116, while surfaces 116b and 116c are spaced bilaterally. Thus, lifting surfaces 116a, 116b and 116c define three triangulated points of contact that are located and spaced to cooperatively contact lifting surfaces 308a, 312b, and 314b, respectively during movement of lifting platform 116 in the projecting direction. Lifting platform 116, particularly inclined surfaces 116a, 116b and 116c, may be coated or otherwise include a suitable lubricant to facilitate sliding contact with elevator 18 for expansion of device 10. Where lifting platform 116 is made of stainless steel, for example, such lubricant may include a molybdenum disulfide (MoS₂) material.

Still referring to FIGS. 8 and 8a, inserter 100 further supports at its distal end 100a a driver 124 for axial translational movement within track 104. The proximal end 124a (FIG. 8) of driver 124 is coupled to trigger actuator 102 to effect translational movement of the driver 124, as will be described. The distal end of driver 124 comprises a pushing surface 124b sized and configured to enter into the opening 216 of an insert body 200 to engage pushing surface 218 and push the insert 16 from track 104 into the device 10 upon axial distal movement of driver 124. Furthermore, driver 124 includes an upper surface 124c on which inserts 16 are movably supported in a linear array. Also included as shown in FIG. 8 is an indexing member 125 that cooperates with driver 124 to distally incrementally move inserts 16 in the projecting direction to be positioned for individual contact with driver pushing surface 124b while preventing retrograde movement of inserts 16 as they are positioned.

With further reference still to FIG. 8a, inserter 100 comprises a flexible graft shield 128 projecting distally from inner track 104. Graft shield 128 is supported at one end 128a in a cantilevered manner with an opposite end 128b being unsupported and free to flex. Graft shield 128 is elongate and generally flat and is sized and configured to substantially block communication between the opening 38 through the superior endplate 12 and inserts 16 slidably inserted into device 10. As will be described, graft shield 128 is configured to extend into device 10 through channel 50

between the superior endplate 12 and the expansion structure adjacent the lower surface 30 of the superior endplate 12.

Turning now to FIGS. 9 and 9a-b, the details of the trigger actuator 102 of the inserter 100 and its operating mechanism and function are described. Trigger actuator 102 comprises a pair of hand grips 132 and 134 biased apart by an extension spring 136. Hand grip 132 is fixedly secured to frame 101 of inserter 100. Hand grip 134 is pivotally connected to frame 101 at pivot point 138 and is movable toward hand grip 132 against the bias of extension spring 136 by manual pressure. Hand grip 134 has gear teeth 140 that interface with a gear rack 146 slidably coupled to the frame 101. The gear mechanism is sized to provide the appropriate translation of the gear rack 146 in the projecting direction as trigger actuator 102 is actuated. Also slidably coupled to the frame 101 are a driving slide 150 that is configured for relative and joint movement with driver 124, and a lifting slide 154 that is configured for joint movement with lifting platform 116. Gear rack 146 includes a lower surface 146a defining a tooth pattern, an upper surface 146b defining a pushing surface 146d, a ramp surface 146e, and a distal end 146c. Distal end 146c includes a pawl 148 configured for limited rotation about pivot point 148a, the distal end of pawl 148 being biased toward the driving slide 150 by a compression spring 152. Prior to actuation of trigger 102 the pawl 148 is constrained from rotation about pivot point 148a by the lower surface 150a of driving slide 150. Upon a first actuation of trigger 102, and therefore translation of the gear rack 146 in the projecting direction, the pawl 148, under bias of compression spring 152, slides along lower surface 150a. When sufficient translation of gear rack 146 has occurred such that the pawl 148 has passed the distal end of driving slide 150, pawl 148 rotates counterclockwise as viewed in FIG. 9a about pivot point 148a to a position limited by contact with upper surface 146f of gear rack 146.

Pawl 148 includes a pushing surface 148b sized to engage pushing surface 154a at proximal end of lifting slide 154. Further actuation of the trigger 102 promotes contact of pushing surfaces 148b and 154a and therefore movement of the lifting slide 154 and lifting platform 116 in the projecting direction causing expansion of the device 10.

Lifting slide 154 further includes a proximal elongate tethering portion 154b with pushing surface 154c sized to engage pushing surface 150b at proximal end of driving slide 150. Upon translation of lifting slide 154 in the projecting direction, pushing surface 154c engages pushing surface 150b for joint translation therebetween.

Driving slide 150 further includes an upper boss feature 156 defining pushing surfaces 156a and 156b sized to fit within slot a 124d (FIG. 8) of driver 124. Slot 124d comprises complementary axially spaced apart pushing surfaces 124e and 124f, respectively. The length of slot 124d is sized such that translation of driving slide 150 during first actuation of trigger 102 does not induce contact between pushing surfaces 156b and 124f and therefore does not impart translation of driver 124.

Driving slide 150 further includes a pawl 158 configured for limited rotation about pivot point 158a, the proximal end of pawl being biased toward the gear rack 146 by bilateral torsion springs (not shown). Prior to actuation of trigger 102 the pawl 148 is constrained from rotation about pivot point 158a by a ledge surface 160 rigidly coupled to frame 101. Upon translation of the driving slide 150 in the projecting direction, the pawl 158, under bias of the torsion springs, slides along upper ledge surface 160. When sufficient translation of driving slide 150 has occurred such that the pawl

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158 has passed the distal end of ledge surface 160, pawl 158 rotates counterclockwise as viewed in FIG. 9a about pivot point 158a to a position limited by contact with lower surface 150c of driving slide 150. Such translation is configured to be slightly longer than the translation required by the lifting platform 116 to achieve full expansion of device 10 such that rotation of pawl 158 will not occur in the absence of full expansion of device 10. Further, rigidly coupled to pawl 158 for rotation therewith are bilateral flags 162 positioned in slots 163 in frame 101 (FIG. 1a), the flags 162 projecting laterally outwardly of both sides of frame 101. Upon joint rotation of pawl 158 and flags 162 the user is visually alerted to the position of the driving slide 150 and lifting slide 154 thereby indicating to the user that full expansion of device 10 has been achieved and that no further inserts can be introduced.

Pawl 158 further comprises a pushing surface 158b sized to engage pushing surface 146d of gear rack 146 and a ramp surface 158c sized to engage ramp surface 146e of gear rack 146. After full actuation and a complete stroke of trigger 102 and release of grip pressure, the gear rack 146 and hand grips 132/134 are returned under the bias of the extension spring 136. During retraction of the gear rack 146, cooperative ramp surfaces 146e and 158c collide inducing pawl 158 to rotate clockwise thereby allowing passage of the gear rack 146. Upon sufficient translation of the gear rack 146 in the retracting direction such that the ramp surface 146e has passed the proximal edge of ramp 158c, pawl 158 rotates counterclockwise about pivot point 158a back to a position limited by contact with lower surface 150c of driving slide 150.

It should be appreciated that upon completion of first actuation of trigger 102 and completion of the first stroke, lifting platform 116 remains projected maintaining the expanded state of device 10 and that driving slide 150 remains in a partially projected state due to tether 154b of lifting slide 154. It should also be noted that pawl 158 remains in a rotated state limited by contact with driving slide 150 while pawl 148 is returned to its original collapsed state limited by lower surface 150a of driving slide 150.

Upon a second actuation of trigger 102 gear rack 146 translates again in the projecting direction such that pushing surface 146d contacts pushing surface 158b of pawl 158 causing joint translation of gear rack 146 and driving slide 150. Upon further actuation, pushing surface 156b of driving slide 150 contacts pushing surface 124f of driver 124 causing joint translation therebetween, thereby engaging pushing surface 218 of insert 16 and pushing the insert 16 from track 104 into the device 10 during completion of the second stroke of trigger actuator 102.

For the purpose of returning the track lifting platform 116 to its original position in the retracting direction a cam 164 and gear 166 are provided. The gear 166 interfaces with a second gear rack 154d rigidly connected to the lower surface of lifting slide 154. The cam 164 is coupled to gear 166 for opposite rotation therebetween and is positioned to contact a notch 170 (FIG. 8a) in the driver 124 after an insert 16 has been partially inserted into the device 10. Further trigger actuation returns the lifting platform 116 to its original position while the driver further inserts the insert 16. When full trigger actuation is achieved, the gear rack 146 and hand grips 132/134 are returned under the bias of the extension spring 136. To reset the position of driving slide 150 manually, the user pulls up on bilateral tabs 162b rigidly coupled to flags 162 thereby imparting rotation of pawl 158 and translation of driving slide 150 in the retracting direction. Due to the rotated state of flags 162 and pawl 158,

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driver slide 150 can be returned to its original retracted position with pawl 158 rotation limited by ledge 160 surface. A two way ratchet mechanism 168 prevents unwanted motion of driving slide 150 in the wrong direction. In the event full expansion of device 10 is achieved and the surgeon prefers to abort the procedure without further introduction of an insert 16, hex fitting 174 (FIG. 1a) coupled to gear 166 may be actuated by a hex wrench or other suitable tool. Rotation of fitting 174 rotates gear 166 which directly translates lifting slide 154 and hence lifting platform 116 proximally to release the expansion of device 10 with no insert 16 introduced.

It should now be understood how the trigger actuator 102 operates to expand device 10 and introduce one or more inserts 16. During the first stroke, only lifting platform 116 is translated in the projecting direction to cause expansion of device 10. Driver 124 remains stationary during the entire first stroke. After the hand grips 132/134 are returned to the starting position under the bias of extension spring 136 upon completion of the first stroke, lifting platform 116 remains stationary in the projecting position maintaining the expanded state of device 10 as hand grips 132/134 return. During the second stroke of trigger actuator 102, driver 124 is translated in the projecting direction while the lifting platform 116 is initially stationary in the projecting direction. When driver 124 has inserted an insert 16 partially into the expanded device 10 continued operation of trigger actuator 102 retracts lifting platform 116 in the retracting direction. As lifting platform 116 retracts, driver 124 continues to advance in the projecting direction to push insert 16 fully into position upon completion of the second stroke.

Thus, for the particular device being described for insertion into the intradiscal space in the posterior approach, expansion of device 10 is achieved during the first stroke of trigger actuator 102 and full insertion of an insert 16 during completion the second stroke. For longer devices, such as those insertable from the lateral approach, the mechanism of inserter 100 may be adjusted such that the longer device is expanded in a first stroke, the inserts 16 inserted partially into the expanded device during a second stroke, and fully inserted in the third stroke. It should thus be appreciated by those skilled in the art that the number of strokes employed for expansion of device 10 and insertion of an insert 16 into the expanded device 10 may be varied by suitable adjustment of the operating mechanism of trigger actuator 102. Such adjustment may include, for example, varying the number of pushing surfaces 146d that are provided on gear rack 146 for engagement with pawl 158.

Turning now to FIGS. 10a-b and 11-12 the assembly of the device 10 and the inserter 100 is described. The superior endplate 12 and the inferior endplate 14 are assembled in an unexpanded condition to the inserter 100 with the superior endplate 12 residing fully within cavity 48 of inferior endplate 14. In such condition elevator 18 is captively retained between superior endplate 12 and inferior endplate 14 as described above and shown in FIG. 5c for independent movement along the direction of expansion 130. The inserter 100 is releasably attached to the device 10 upon threaded engagement of the guide pin 108 into threaded opening 56 in the proximal rear end wall 44 of the inferior endplate 14. Graft shield 128 extends into device 10 through channel 50 between the superior endplate 12 and the elevator 18 adjacent the lower surface 30 of the superior endplate 12. With the inserter 100 fixed to the device 10, lifting platform 116 and driver 124 are axially translatable relative to the device 10 in the projecting and retracting directions. In this unexpanded condition, there are no inserts 16 in the device 10. In

the arrangement being described, there are five inserts 16 supported in a linear array on track 104.

In the position illustrated in FIGS. 10a-b and 11-12 lifting platform 116 is in a retracted position relative to device 10 and elevator 18. Insert 16, as seen in FIG. 10a, is disposed on track 104 exteriorly of and ready for insertion into device 10. In this position the lower surface 120 of lifting platform 116 is situated on lower inner surface 54 of inferior endplate 14. Likewise lower surface 304 of elevator 18 is supported by lower inner surface 54 of inferior endplate 14. As such, lifting platform 116 and elevator 18 are on substantially the same plane, with the upper surface 118 of lifting platform 116 being substantially coplanar with the upper surface 302 of elevator 18. With the inserter 100 attached to the device 10, elevator 18 is fixed in the axial direction relative to axial movement of lifting platform 116.

In the condition shown in FIGS. 10a-b, apparatus 1 comprising unexpanded device 10 releasably attached to inserter 100 is ready for use in inserting device 10 into an intradiscal space between two opposing vertebral bodies. Prior to insertion, opening 38 through superior endplate 12 may be pre-packed with a suitable bone graft material for the promotion of fusion through device 10 to the opposing vertebral bodies. Graft shield 128 extends into device 10 through channel 50 between the superior endplate 12 and the elevator 18 adjacent the lower surface 30 of the superior endplate 12 defining a pocket for receipt of the graft material. The free end 128b of graft shield 128 rests unattached on an interior ledge 12b of superior endplate 12 adjacent the distal end thereof. Opening 38 is therefore open adjacent outer surface 12a of superior endplate 12 and closed by graft shield 128 adjacent lower surface 30. As such, graft shield 128 provides a barrier between the graft material and the elevator 18 and inserts 16 inserted into device 10 during expansion. Pre-packing of bone graft material in opening 38 on graft shield 128 advantageously allows for less introduction of graft material in situ and provides more assurance that sufficient graft material will be contained throughout device 10 and into openings 38 and 60 through superior endplate 12 and inferior endplates 14 and in a stress-loaded condition against opposing vertebral bodies. In addition, graft shield 128 provides a barrier substantially preventing graft material within opening 38 from being disturbed during expansion and by substantially blocking graft material from interfering with the expansion of device 10 or with the slidable insertion of inserts 16 which may be impeded by graft material on the sliding interfacing surfaces.

At this point in the surgical procedure, inserter 100 is used to insert unexpanded device 10 into the intradiscal space. Device 10 may be implanted as explained hereinabove into the spine posteriorly or posteriolaterally, either bilaterally or unilaterally, or in an anterior or lateral approach depending upon the surgical indication and the surgeons preference. Once device 10 is inserted in the intradiscal space in a suitable location, actuator 102 as described hereinabove is then operated in a first actuation. Initially during the first stroke lifting platform 116 is translated axially while driver 124 remains stationary. Lifting platform 116 is moved from the retracted position of FIGS. 10a-b to a projecting direction whereby lifting platform 116 is moved further into device 10. During movement in the projecting direction, lifting surfaces 116a, 116b and 116c of lifting platform 116 contact cooperative lifting surfaces 308a, 312b, and 314b, respectively of elevator 18. The cooperative engagement causes elevator 18 to move in the direction of expansion away from lower inner surface 54 of inferior endplate 14 and toward superior endplate 12. The upper surface 302 of

elevator 18 contacts lower surface 30 of superior endplate 12 and elevator 18 slidably moves in the direction of expansion along rails 14b toward superior endplate 12 and away from inferior endplate 14 as shown in FIGS. 13a-b, thereby expanding device 10.

When complete expansion of device 10 is achieved the first stroke of trigger actuator 102 is completed and hand grips 132/134 are returned to the original starting position, as described above. Trigger actuator 102 is then operated in a second actuation to start a second stroke. As the second stroke commences, lifting platform 116 remains stationary holding device 10 in the expanded condition while axial translation of driver 124 begins. Continued operation of actuator 102 pushes insert 16 distally so that the distal front end 208 moves freely into expanded device 10 through channel 50 until the distal front end 208 of insert 16 is partially inserted into expanded device 10 between superior endplate 12 and inferior endplate 14 adjacent the proximal end of device 10, as illustrated in FIGS. 13a-b.

With insert 16 partially inserted in device 10, continued operation of the actuator 102 during the second stroke causes lifting platform 116 to move proximally thereby moving lifting platform 116 in a retracting direction. With distal front end 208 of insert 16 supporting superior endplate 12, continued proximal movement of lifting platform 116 causes lifting surfaces 116a, 116b and 116c of lifting platform 116 to sufficiently disengage cooperative lifting surfaces 308a, 312b, and 314b, respectively of elevator 18 to allow elevator 18 to move away in the direction of expansion from superior endplate 12 and toward inferior endplate 14 along rails 14b and return to the position of elevator 18 shown in FIGS. 10a-b. As elevator 18 returns to the position whereby the lower surface 120 of lifting platform 116 is situated on lower inner surface 54 of inferior endplate 14, a space like the space 64 as described hereinbelow with reference to FIG. 16b, is created between lower surface 30 of superior endplate 12 and upper surface 302 of elevator 18. Such space between the superior endplate 12 and the elevator 18 is slightly greater than the thickness of an insert 16 and is in direct communication with lower surface 30 of superior endplate 12 and upper surface 302 of elevator 18. During completion of the second stroke of actuator 102 driver 124 continues to move axially distally slidably pushing insert 16 fully into such space of expanded device 10, as shown in FIG. 14, with lower surface 204 of insert 16 facing and being in slidable contact with upper surface 302 of elevator 18. Driver 124 is retracted proximally to the original position shown in FIGS. 10a-b when the hand grip 134 of actuator 102 is released.

During insertion of insert 16 into device 10, receptacle 220 described hereinabove at the distal end 208 of insert 16 cooperatively receives complementary flexible latch 318 on the upper surface 302 of elevator 18 such that locking surfaces 224a, 224b and 322a, 322b resiliently interlock, as shown in FIG. 5b. Such interlocking substantially resists any back out of the insert 16 through channel 50 as driver 124 is withdrawn away from insert 16 in the retracted position. In the event device 10 is further expanded, as described hereinbelow, the initial insert 16 is moved upwardly with superior endplate 12 by elevator 18. As elevator 18 then returns downwardly toward inferior endplate 14 as will be explained, latch 318 is separated from receptacle 220 as space 64 is created. With the initial insert 16 moved upwardly, it is situated above channel 50 and held captive by the interior surfaces of inferior endplate 14, including interior surface 44a of rear end wall 44. It should be appreciated that while insert 16 is held in position within device 10 by

interlocking of receptacle 220 and latch 318, other structure to resist back out movement of insert 16 may be provided, such as interlocking structure between insert 16 and one or more interior surfaces of the inferior endplate 14, or interlocking structure between adjacent inserts 16. Upon completion of insertion of insert 16, opening 216 of insert 16 is at least partially aligned with opening 316 of elevator 18, opening 38 of superior endplate 12 and opening 60 of inferior endplate 14. Once inserter 100 is removed from the expanded device upon completion of the surgical procedure, insert opening 216, elevator opening 316 and graft chambers 38 and 60, respectively, will all be in at least partial alignment and communication with each other.

In the event the surgeon determines that additional inserts 16 are required in order to provide proper correction of the height of the intradiscal space, actuator 102 may be operated to insert one or more additional inserts 16 in the same manner as described with respect to the insertion of first insert 16. FIGS. 15a-b show device 10 with one insert 16 having been inserted and a second insert 16 partially introduced after device 10 has been further expanded during a first stroke of actuator 102 by elevator 18 upon lifting by the lifting platform 116 in the same process as described with respect to FIGS. 13a-b. As the second insert 16 enters the further expanded device 10 during the second stroke, lifting platform 116 is pulled proximally in a retracting direction, sufficiently disengaging lifting surfaces 116a, 116b and 116c of lifting platform 116 from cooperative lifting surfaces 308a, 312b, and 314b, respectively of elevator 18 to allow elevator 18 to freely return to inner surface 54 of inferior endplate 14. However, in the event elevator 18 fails to fully or partially return to such position, during pushing of second insert 16 into device 10 by driver 124, the inclined surfaces 208a adjacent the front distal end 208 of second insert 16 contacts inclined surfaces 312a and 314a, respectively at the upper free end of each arm 312 and 314 of elevator 18, as shown in FIGS. 16a-b, to urge elevator 18 toward and against lower surface 54 of the inferior endplate 14 creating a space 64 between lower surface 204 of the first insert 16 and upper surface 302 of elevator 18. Alternatively, or in addition, a suitable biasing element may be included to normally urge elevator 18 toward inner surface 54 of inferior endplate 14. Inferior endplate 14 may be formed to include a lip 46a on the front end wall 46 adjacent the distal end of cavity 48 to contain a spring 107 which would serve as the biasing element, as shown, for example, in FIG. 15a. It should be understood that the features urging elevator 18 toward lower inner surface 54 of inferior endplate 14 function during the insertion of first insert 16 as well as with all subsequently inserted inserts 16.

Continued operation of actuator 102 during the second stroke will continue to move second insert 16 until fully inserted shown in FIG. 17. During insertion of second insert 16 into device 10, the resilient interlocking features of receptacle 220 described hereinabove of the second insert 16 cooperatively interlock with the complementary interlocking features of flexible latch 318 on the distal end of elevator 18. Upon completion of insertion of second insert 16, opening 216 of insert 16 is at least partially aligned with opening 216 of the first insert, opening 38 of superior endplate 12 and opening 60 of inferior endplate 14, all of which will be in communication upon removal of inserter 100. The second insert 16 is the lowermost insert and resides on upper surface 302 of elevator 18 directly below and in contact with first insert 16, as shown in FIGS. 17 and 18.

Driver 124 is then again retracted proximally to the original position shown in FIGS. 10a-b when the hand grip 134 of actuator 102 is released.

When the intradiscal space has been expanded to its maximum anatomic extent as the spine reaches ligamentotaxis and the device 10 cannot be further expanded, the surgeon will be able to determine such condition by tactile feedback. Insertion of an insert 16 into device 10 can only be achieved after elevator 18 reaches its ultimate movement in the direction of expansion toward superior endplate 12. As such, failure to compress hand grips 132/134 in a manner to complete the first stroke of actuator 102 will allow the surgeon to recognize that ligamentotaxis has been reached and the proper intradiscal height has been restored. Inasmuch as the insertion of an insert 16 follows the expansion of device 10 upon full movement of elevator 18 in the direction of expansion toward inferior endplate 14, incomplete insertion of an insert 16 may be avoided. An indication that full expansion of device 10 has been reached may also be determined visually as described hereinabove by observation that flags 162 on actuator 102 have rotated relative to frame 101. The surgeon would then terminate the procedure by actuating hex fitting 174, as described hereinabove. Inserter 100 would then be removed from the expanded device 10 by rotatably removing knob 112 from the proximal end of guide pin 108. As shown in FIG. 19, the guide pin 108 may remain releasably connected to expanded device 10 to serve as a locator for subsequent attachment to an apparatus containing suitable bone graft to assist in the delivery of such material into channel 50 of inferior endplate 14 through which inserts 16 were inserted. As such, upon removal of inserter 100 from expanded device 10, a substantially unobstructed path exists from channel 50 through opening 316 of elevator 18 and openings 216 of inserts 16 and into openings 38 and 60 extending through the superior endplate 12 and the inferior endplate 14, respectively, to allow bone graft material introduced into expanded device 10 through channel 50 to flow fully through device 10.

In accordance with certain specific applications of device 10 for posterior implantation as described hereinabove, the overall length of the device 10 as defined by the length of the inferior endplate 14 is about 25 mm. The width of the device 10 is approximately 10 mm. The height of the unexpanded device 10 of FIGS. 1a-c with the superior endplate 12 fully nested within the inferior endplate 14 is approximately 7 mm. With the introduction of five inserts 16, each of which has a thickness of approximately 1.0 mm, the height of device 10 may be expanded from an unexpanded height of approximately 7 mm to an expanded height of approximately 12 mm. It should be appreciated that these dimensions are only illustrative and the number of inserts 16 as well as the dimensions of device 10 may vary depending upon the particular surgery and application. For example, device 10 for posterior implantation may have an initial unexpanded height in the range of approximately 7-10 mm, a width in the range of approximately 10-14 mm, and a length in the range of approximately 20-35 mm, with up to eight inserts 16 for the taller sizes. For implementing such posterior-size devices 10, trigger actuator 102 may have an operating mechanism as described herein for expanding device 10 in a first stroke and fully inserting an insert 16 in a second stroke.

For certain applications of device 10 that may be implanted from a lateral approach, device 10 may have an unexpanded height in the range of approximately 8-10 mm, a width in the range of approximately 14-26 mm, and a length in the range of approximately 35-60 mm. To implant

such devices **10** from the lateral approach, trigger actuator **102** may have an operating mechanism adjusted to expand device **10** in a first stroke, partially insert an insert **16** in a second stroke, and fully insert an insert **16** in a third stroke.

Channel **50**, extending through the rear end wall **44**, is sized and configured to facilitate the introduction of a suitable bone graft material by a graft delivery apparatus that may use guide pin **108** as a locator, as shown in FIG. **19**. Such a graft delivery apparatus may have an entry tip sized and configured for entry into channel **50**. In a particular arrangement, it may be desirable to increase the entry opening to further ease the delivery of graft material. In such instance, a portion of rear end wall **44** may be notched out to form a channel portion **50a** of increased height directly below threaded opening **56**. Channel portion **50a** situated below threading opening **56** would direct the entry flow of bone graft material into the center of expanded device **10**. Channel portion **50a** may be suitably configured to cooperatively receive the entry tip of the graft delivery apparatus, with such channel portion **50a** being rectangular, square or arcuate. In the example of device **10** for posterior applications, channel portion **50a** may be particularly configured to be square. Where such device **10** has an initial unexpanded height of 7 mm and a width of 10 mm, channel portion **50a** may have a width of 3 mm and a height of 3 mm as measured vertically from inner surface **54**. In the example of device **10** for lateral applications, channel portion **50a** may be particularly configured to be generally rectangular. Where such device **10** has an initial unexpanded height of 8 mm and a width of 16 mm, channel portion **50a** may have a height of 3 mm as measured vertically from inner surface **54**, and a width of 6 mm. For purposes of delivering bone graft material in the form of autograft, it is desirable that the minimum dimension of channel portion **50a**, or any portion of channel **50** used as an entry port for such autograft material be no less than about 2 mm. It should be appreciated, however, that depending upon the viscosity of bone graft material to be delivered, such minimum dimension may vary.

Turning now to FIG. **20**, an alternative inserter **400** embodying a modular construction is described. Inserter **400** comprises an actuator **402** and a releasable cartridge **404**. Actuator **402** includes a pair of hand grips **407** and **408** that are biased apart by an extension spring in the same manner as in trigger actuator **102** described hereinabove. Actuator **402** includes a frame **410** housing an operating mechanism **411** substantially the same as the operating mechanism of trigger actuator **102**. Grip **407** is fixedly secured to frame **410** while grip **408** is pivotally connected to frame **410** by a pivot pin **412**. Frame **410** supports a rotatable flag **414** that is coupled to the operating mechanism **411** as in trigger actuator **102**. Frame **410** includes a pair of spring-loaded flexible latches **416** projecting upwardly from an interface surface **410a** adjacent the proximal end **410b** of frame **410**. Adjacent the distal end **410c** of frame **410** a support surface **410d** is provided. Actuator **402** in a particular embodiment is reusable. Frame **410**, as well as frame **101**, and hand grips **407**, **408**, as well as hand grips **132**, **134** are all formed of stainless steel in a particular arrangement, although other materials, such as aluminum alloys and plastics may also be used.

Cartridge **404** comprises a track **406** contained within an outer cover **418** similar to track **104** and cover **106** of trigger actuator **102**. Cartridge **404** likewise houses a translatable lifting platform, a translatable driver and an indexing member (all not shown) that are constructed the same as lifting platform **116**, driver **124** and indexing member **125** of

trigger actuator **102**, and that function in the same manner. A support **420** comparable to support **172** is secured to the bottom of cover **418**. Cartridge **404** supports a plurality of inserts **16** in a linear array for insertion into the expandable device **10**. Cooperative latching structure is provided at the bottom surface of cover **418** for releasable engagement with latches **416** of actuator **402**. In a particular embodiment, cartridge **404** is disposable.

Cartridge **404** is releasably attached to frame **410** by initially engaging support **420** with support surface **410d** on frame **410** and then rotating cartridge down toward proximal end **410b** until latches **416** releasably attach to the cooperative latching structure at the bottom of cartridge **404**. Upon attachment of cartridge **404** with actuator **402**, components of operating mechanism **411** interface with the driver and the lifting mechanism within track **406** in a manner comparable to actuator **102**, including the receipt of boss feature **422** (the same as boss feature **156**) into a slot that is the same as slot **124d** of driver **124**. Cartridge **404** may be released from actuator **402** by actuation of release levers **424** supported by frame **410** on both sides thereof and movably coupled to latches **416**. In all other respects, modular inserter **400** operates the same as trigger actuator **102** described hereinabove.

While the invention has been illustrated and described in detail in the drawings and foregoing description, the same should be considered as illustrative and not restrictive in character. It is understood that only the preferred embodiments have been presented and that all changes, modifications and further applications that come within the spirit of the invention are desired to be protected. For instance, an inserter with a graft shield, such as shield **128**, may be used with expandable spinal interbody fusion devices having an expansion structure without an elevator **18** as described hereinabove. For example, an inserter with a graft shield **128** may be used with the expandable interbody fusion device shown and described in the '312 Patent referenced hereinabove wherein the device is expanded upon introduction of a series of wafers. Shield **128** may be used similarly as described herein to provide a barrier between a graft opening through one of the endplates, such as the superior endplate, and the wafers. Such a barrier would substantially prevent bone graft material pre-packed into such opening from interfering with sliding receipt of such wafers during insertion and expansion of the device. In addition, it should also be appreciated that actuators other than trigger actuators, such as with threaded rotary mechanisms, may be used with the inserter **100** described herein.

While one use of the invention as described herein is as an expandable spinal interbody fusion device, the invention may also be used in any situation where it is desirable to expand two tissue surfaces and to support such tissue surfaces after they have been separated. The tissue may be bone, skin, soft tissue, or combinations thereof. Further, the surfaces may be opposed surfaces of contiguous elements or surfaces of opposed elements. Thus, in addition to being used as a spinal interbody fusion device as set forth herein, the invention may also be used to treat vertebral compression fractures, for replacement of vertebral bodies (VBR), as a wedge opening high tibial osteotomy, tibial tuberosity elevation, as well as for treating other compression fractures including, but not limited to tibia plateau fractures, calcaneus, distal tibial fractures, or distal radius (wrist) fractures. One method for treating these conditions includes distracting and supporting the tissue surfaces simultaneously, as described in the '998 Patent. The approach described herein, which includes expanding the tissue and then supporting the

expanded tissue, may be used to treat these same conditions. Such procedures may be performed percutaneously through a cannula or other minimally invasive instrument or in an open procedure.

The expansion device is now described in this section by its application as a spinal implant to vertebral compression fractures. FIG. 21 shows a vertebral body 500 having a compression fracture displacing its superior and anterior edge 502. FIG. 22 shows vertebral body 500 wherein the height has been restored. FIG. 23 illustrates an extrapedicular approach to vertebral body 500 wherein an access cannula 504 is placed through the posterolateral wall 506 of vertebral body 500. Other approaches may optionally be used for placing a cannula into a vertebral body such as a transpedicular approach to the vertebral body wherein an access cannula may be placed through the pedicle. In the extrapedicular approach, two cannulae 504 may be placed bilaterally, one on each side.

The procedure for the placement of access cannula 504 into vertebral body 500 is more fully described in the '998 Patent, incorporated herein by reference. Cannula 504 in this particular arrangement is preferably rectangular in cross-section, although cannulae of other cross-sections, such as circular may be used. Further, cannula 504 may be of fixed configuration or expandable. Once access cannula 504 is in place, an expandable device 10 supported by inserter 100 may be introduced into vertebral body 500 through cannula 504. This application of the invention contemplates expanding expandable device 10 by the inserter 100 from an unexpanded condition as shown, for example in FIG. 3a to the expanded height as shown in FIG. 24 to ultimately reduce the vertebral compression fracture and substantially restore the normal anatomic height of vertebral body 500, inserting one or more inserts, such as inserts 16, as described herein, to form a stack of inserts 16 between the expanded superior endplate 12 and inferior endplate 14 of expandable device 10. In the particular arrangement being described for vertebral compression fracture reduction, expandable device 10 may have a length of approximately 25 mm, a width of approximately 10 mm, and an unexpanded height H of approximately 7 mm. The height H may be expanded by 5 mm and supported by the introduction of five inserts 16, as shown in FIG. 24, each insert 16 as described herein having a thickness of 1 mm. It should be appreciated that the height H may be increased by other amounts and more or less than five inserts used, and that device 10 may be configured in other dimensions as set forth in the '998 Patent.

When the fracture is reduced as depicted in FIG. 22, or when the physician determines that an adequate number of inserts 16 has been inserted, the inserter 100 may be separated from device 10 and removed from cannula 504 while expanded device 10 remains within vertebral body 500. Access cannula 504 is left in place. Suitable bone filler may be injected into vertebral body 500 through cannula 504 to encapsulate device 10, provide weight bearing structure and increase stability of vertebral body 500. Bone filler may flow through device 10 and the insert column and out to the surrounding bone to interdigitate with cancellous bone.

It should therefore be understood that while various embodiments of the invention have been presented herein, various changes, modifications and further applications may be made without departing from the spirit of the invention and the scope of the appended claims.

What is claimed is:

1. An inserter for expanding an expandable device for expanding body tissue and inserting an insert into said device, comprising:

an elongate frame;

an elongate lifting platform supported by said frame for axial movement thereon for expanding said device, said lifting platform including a lifting surface for engaging a cooperatively configured receiving surface of said device to expand said device;

an elongate driver movably supported by said frame for axial movement thereon for inserting said insert into said device;

an actuator supported by said frame and operably coupled to said lifting platform and said driver to cause axial movement of said driver and said lifting platform upon operation of said actuator; and

a movable indicator coupled to said elongate driver for movement therewith and exteriorly supported by said frame for movement thereon, movement of said indicator providing a visual indication of expansion of said device.

2. The inserter of claim 1, wherein said driver moves at least partially independently of axial movement of said elongate lifting platform upon operation of said actuator.

3. The inserter of claim 1, wherein said indicator comprises a flag that is rotatable relative to said frame, rotation of said flag indicating expansion of said device.

4. The inserter of claim 1, wherein said indicator is operable independently of said actuator to move said driver in a retracting direction to a reset position relative to said frame.

5. The inserter of claim 1, further including an elongate track having a distal end and a proximal end, said driver being supported by said track for axial movement for contacting and driving said insert into said device.

6. The inserter of claim 5, wherein said track is configured to linearly support a plurality of inserts for sequential individual insertion into said device by said driver.

7. The inserter of claim 1, further comprising a guide pin releasably connectable to said device and detachably connected to said frame.

8. The inserter of claim 1, wherein said inserter further comprises a graft shield projecting from the distal end of said inserter and being of size and configuration to extend into said device.

9. The inserter of claim 1, wherein said actuator comprises a pair of hand grips, one of which is fixedly secured to said frame and the other of which is pivotally connected to said frame.

10. An inserter for expanding an expandable device for expanding body tissue and inserting an insert into said device, comprising:

an actuator including a frame and an operating mechanism, said frame comprising a flexible latch; and

an elongate cartridge releasably connected to said frame by said flexible latch, said cartridge including an elongate track movably supporting an elongate lifting platform for expanding said device and supporting for movement at least partially independently of said lifting platform an elongate driver for inserting an insert into said device, and a plurality of inserts in a linear array, said cartridge being disposed on said frame such that said lifting platform and said driver are operably separably connected to said operating mechanism.

11. The inserter of claim 10, wherein said cartridge is disposable.

12. The inserter of claim 11, wherein said actuator is reusable.

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13. The inserter of claim 10, wherein said frame includes a movable lever for actuation of said flexible latch and release of said cartridge from said frame.

14. The inserter of claim 10, wherein said actuator comprises a pair of hand grips, one grip being fixedly secured to said frame and the other grip being pivotally connected to said frame and spring-loaded relative to said one grip.

15. The inserter of claim 10, further comprising a movable indicator coupled to said operating mechanism and exteriorly supported by said frame for movement thereon with said

driver, movement of said indicator providing a visual indication of expansion of said device.

16. The inserter of claim 15, wherein said indicator comprises a flag that is rotatable relative to said frame, rotation of said flag indicating expansion of said device.

17. An inserter for expanding an expandable device for expanding body tissue and inserting an insert into said device, comprising:

an elongate frame;

an elongate lifting platform supported by said frame for axial movement thereon for expanding said device, said lifting platform including a lifting surface for engaging a cooperatively configured receiving surface of said device to expand said device;

an elongate driver movably supported by said frame for axial movement thereon for inserting said insert into said device;

an actuator supported by said frame and operably coupled to said lifting platform and said driver to cause axial

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movement of said driver and said lifting platform upon operation of said actuator; and

an expansion release member coupled to said lifting platform and operable independently of said actuator to move said lifting platform in a retracting direction.

18. The inserter of claim 17, wherein said expansion release member is a fitting exteriorly supported by said frame.

19. The inserter of claim 18, wherein said fitting is rotatable.

20. An inserter for expanding an expandable device for expanding body tissue and inserting an insert into said device, comprising:

an actuator including a frame and an operating mechanism, said operating mechanism comprising a movable expansion element movable upon operation of said actuator and engageable with said device for expanding said device; and a movable indicator exteriorly supported by said frame for movement thereon and responsive to the movement of said expansion element for providing a visual indication of expansion of said device; and

an expansion release member exteriorly supported by said frame, said expansion release member being coupled to said expansion element and operable to move said expansion element independently of operation of said actuator.

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