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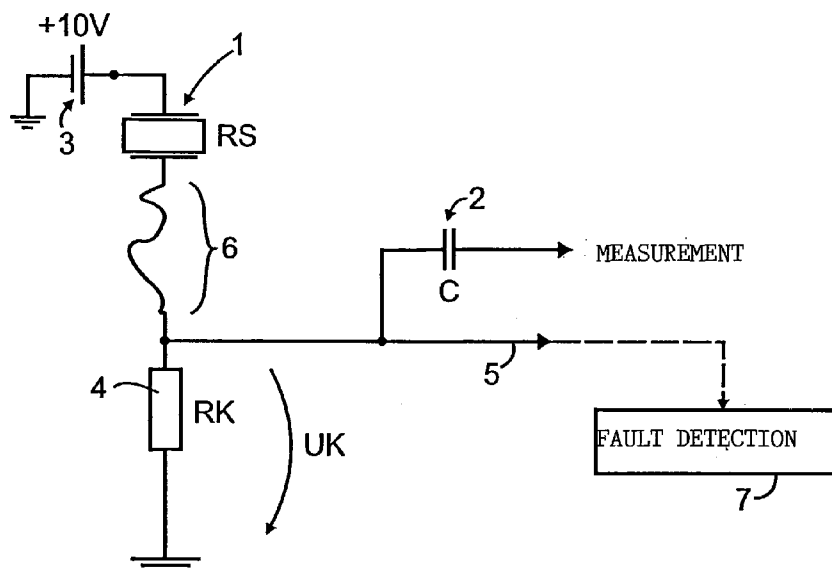


FIG. 1

(57) Abstract: An indicator arrangement according to the invention also comprises a resistor (4) the first end of which is connected to between a passive acceleration sensor (1) and a filtering means (2) and the other end is connected to a basic voltage level. An output (5) is also connected to the connection of the first end of the resistor. The indicator arrangement also comprises a direct voltage source (3) the first end of which is connected to a passive acceleration sensor (1) while the other end is connected to a basic voltage level. Voltage can be detected from the output (5) of the indicator arrangement for detecting a fault in the indicator arrangement.

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INDICATOR ARRANGEMENT

Field of invention

The present invention relates to indicators used in piston-operated internal
5 combustion engines, such as diesel engines or gas engines. The invention especially
relates to knock indicators.

Background art

Many kinds of different indicators are used in piston engines for observing different
10 units and states in engines. The temperature of a cylinder can be measured, the fuel
flow to be supplied can be monitored; the engine running speed can be measured
and so on. The knocking occurring in a cylinder of an engine can also be monitored.

A cylinder knocks when the air-fuel mixture introduced therein is ignited in an
undesired manner. Typically knocking occurs when the air-fuel mixture or the fuel
15 used separately for ignition is ignited too early. Knocking stresses the engine and can
damage the engine. Knock control is used to avoid engine knock by controlling the
ignition timing and/or fuel injection for each cylinder. Knock control can reduce the
engine load. The last alternative is to even turn the engine off in case deemed
necessary. It is also possible to recycle exhaust gas back to the engine, whereby the
20 so-called knock margin is increased. Knock margin means the difference between
the units of the operating state of the cylinder and the state causing the knock. The
larger the margin is, the smaller the probability of the cylinder turning into the knock-
causing state.

It is nowadays common to measure the knock by means of an acceleration sensor
25 from the cylinder head, cylinder sleeve or the engine block. The acceleration sensor
is typically a piezoresistive crystal. The signal emitted by the sensor is measured at
the correct moment (i.e. when the crank rotation angle is suitable) at the time knock

most likely occurs. Noise and excess frequencies are filtered from the signal. The processed signal is compared with the reference value, whereby it is possible to deduce whether the cylinder is in a knock state.

If the knock-indicating sensor and the cables connected thereto are not damaged, knocking can be reliably observed. However, if the sensor or the cables connected thereto are damaged, the signal emitted by the sensor can be incorrect. The engine can be incorrectly controlled on the basis of the incorrect signal whereby there is a great risk of damaging the engine. The engine causes vibration that can in the long run damage the sensor, the cables connected thereto or the connections of the cable.

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Brief description of the invention

An aim of the present invention is to reduce the above-mentioned disadvantages. The aim is achieved as described in the main claim. The dependent claims describe the various embodiments of the invention.

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The embodiment according to the invention comprises a passive acceleration sensor 1 for forming a voltage signal and filtering means 2 for filtering the said voltage signal. Such an indicator arrangement is for piston engines – usually for detecting knocking in the cylinder of the engine. The indicator arrangement according to the invention also comprises a resistor 4, the first end of which is connected to between the passive acceleration sensor 1 and the filtering means 2 and the other end is connected to the basic voltage level. The connection of the first end of the resistor is also connected to output 5. The indicator arrangement also comprises a direct voltage source 3, the first end of which is connected to a passive acceleration sensor 1 while the second end is connected to the basic voltage level. Voltage can be detected from the output of the indicator arrangement for detecting a fault in the indicator arrangement.

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List of figures

In the following the invention is described in more detail by reference to the figures in the drawing, in which

Figure 1 illustrates an example of the indicator arrangement according to the invention. **Description of the invention**

Figure 1 illustrates an example of an embodiment of the indicator arrangement according to the invention as a simple circuit diagram. It will be obvious to one skilled in the art to carry the apparatus according to the invention out based on the circuit diagram. As has been mentioned above, the indicator arrangement is used in piston-operated internal combustion engines, usually for indicating knocking taking place in the cylinder. The indicator arrangement comprises a passive acceleration sensor 1 for forming a voltage signal and filtering means 2 for filtering the said voltage signal.

In the mode of carrying out of this example, when the indicator arrangement is installed in a piston-operated internal combustion engine, the acceleration sensor is arranged in the cylinder head where it can detect a knocking phenomenon should one occur. The signal sent by the sensor is measured at a suitable moment when knocking is most probable to occur. At this time an undesired force component resulting from burning of fuel and causing knocking has an effect on the cylinder head, which can be detected with an acceleration sensor.

The indicator arrangement also comprises a resistor 4, an output 5 and a DC voltage source 3. The first end of the resistor 4 is connected to between the passive acceleration sensor 1 and the filtering means 2 and the other end is connected to the basic voltage level. The connection of the first end of the resistor (i.e. the node of the electric circuit) is also connected to output 5. The first end of the direct voltage source 3 is connected to the passive acceleration sensor 1 while the second end is connected to the basic voltage level. Voltage can be detected from the output of the indicator arrangement for detecting a fault in the indicator arrangement. A detection

apparatus 7 can be connected to the output 5 for detecting a fault in the indicator arrangement.

The example of figure 1 illustrates that there is a connection between the connection of the first end of the resistor 4 and the passive acceleration sensor 1.

5 This connection can be a connection lead 6, which is very descriptive of a real installation. Both the acceleration sensor 1 and the connection lead 6 can be damaged. For example, the vibration of the engine can stress the sensor and/or the connection lead. The connection lead can be metres in length. The connections of the connection lead are also exposed to stresses caused by the vibration of the
10 engine.

In the example of figure 1 the direct voltage source is +10V. The voltage of the direct voltage source is (mainly) divided over the internal resistance R_S of the acceleration sensor 1 and the resistance R_K of the resistor 4. In this case voltage U_K is formed between the first end of the resistor and the basic voltage level, i.e. over the
15 resistor 4. The acceleration sensor has a slight effect on the voltage level U_K that is monitored via the output 5. It should be mentioned that the U_K direct voltage is monitored at the output.

When the acceleration sensor and the connection lead (with its connections) are operational, the U_K direct voltage is on a certain voltage level. For example, if the
20 resistance R_S of the acceleration sensor is $4.88 \text{ M}\Omega$ and the resistance R_K of the resistor is $1 \text{ M}\Omega$, the voltage U_K is in normal state 1.7 V . This voltage level fluctuates in normal state according to the normal operation of the acceleration sensor.

Let's examine a fault situation in which the connection lead 6 is broken so that the lead is in connection with the environment normally having a zero voltage, i.e. in the
25 basic voltage level shown in the figure. In such a case the U_K voltage level is reduced even to nearly zero depending on the resistance between the breakage point of the lead and the environment. Another exemplary situation is the internal

breakage of the acceleration sensor so that its internal resistance is reduced. Thus the UK voltage level increases.

When certain limit values are set as the lower and upper limit of the UK voltage, the voltage level at the output 5 can be used for deducing whether the indicator arrangement is working correctly or whether there is a fault. The limit value of the lower voltage can be, for example, 1.2 V with a voltage lower than that being considered a fault. The limit value of the upper voltage can be, for example, 2.2 V with a voltage higher than that being considered a fault. The voltage range between the higher and lower voltages is the range of normal operation on which there is no fault. In practice the detection apparatus 7 follows whether values exceed or fall below the limit values on the basis of which a fault alarm can be given. The voltage source, voltage values and resistor values shown here can also differ from what is described here. The choice of suitable values depends, for example, on how high the desired direct voltage is supposed to be.

The passive acceleration sensor 1 can, for example, be a piezoelectric crystal or an inductive sensor. Filtering means 2 are used for filtering the noise and excess frequencies interfering with the measurement of the knocking from the signal 1 of the acceleration sensor. In the figure the filtering means 2 are illustrated simply as a capacitor, but the filtering means can also comprise other parts, such as resistors.

In the figure, the basic voltage level is shown as zero voltage level, but it will also be possible to use another voltage level as the basic voltage level.

As can be seen, the embodiment according to the invention can be carried out by means of a number of solutions. Thus, it will be apparent that the invention is not limited to the examples mentioned in this text. Thus, any inventive embodiment can be carried out within the scope of the invention.

Claims

1. An indicator arrangement for piston-operated internal combustion engines comprising a passive acceleration sensor (1) for forming a voltage signal and a filtering means (2) for filtering the said voltage signal.

5 **characterized** in that the indicator arrangement comprises a resistor (4) the first end of which is connected between a passive acceleration sensor (1) and a filtering means (2) and the other end is connected to a basic voltage level, the connection of the first end of the resistor being also connected to an output (5), the indicator arrangement also comprising a direct voltage source (3) the first end of which is
10 connected to the passive acceleration sensor (1) and the other end of which is connected to a basic voltage level, the voltage at the output (5) of the indicator arrangement enabling detection of a fault in the indicator arrangement.

2. An arrangement according to claim 1, **characterized** in that a detection apparatus (7) is connected to the output (5) for detecting a fault in the indicator
15 arrangement.

3. An arrangement according to claim 1 or 2, **characterized** in that the passive acceleration sensor is a piezoelectric crystal.

4. An arrangement according to claim 1 or 2, **characterized** in that the passive acceleration sensor is an inductive sensor.

20 5. An arrangement according to claim 3 or 4, **characterized** in that there is a connection lead (6) between the connection of the first end of the resistor and the passive acceleration sensor.

6. An arrangement according to claim 5, **characterized** in that the basic voltage level is zero voltage level.

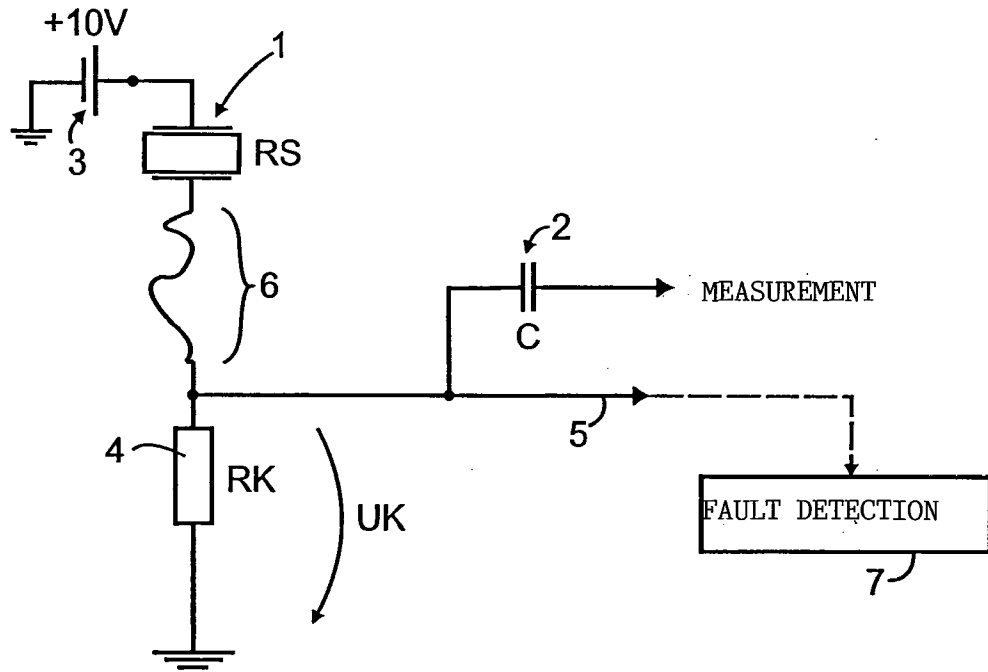


FIG. 1