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Simpson et al.

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(54) **PARALLEL PROCESSING TECHNIQUES FOR EXPEDITING RECONCILIATION FOR A HIERARCHY OF FORECASTS ON A COMPUTER SYSTEM**

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(*) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 0 days.

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(21) Appl. No.: **18/229,333**

(22) Filed: **Aug. 2, 2023**

(57) **ABSTRACT**

Related U.S. Application Data

(60) Provisional application No. 63/461,208, filed on Apr. 21, 2023, provisional application No. 63/457,391, filed on Apr. 5, 2023.

A parallel processing technique can be used to expedite reconciliation of a hierarchy of forecasts on a computer system. As one example, the computer system can receive forecasts that have a hierarchical relationship with respect to one another. The computer system can distribute the forecasts among a group of computing nodes by time point, so that all data points corresponding to the same time point in the forecasts are assigned to the same computing node. The computing nodes can receive the datasets corresponding to the time points, organize the data points in each of the datasets by forecast to generate ordered datasets, and assign the ordered datasets to processing threads. The processing threads (across the computing nodes) can then execute a reconciliation process in parallel to one another to generate reconciled values, which can be output by the computing nodes.

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G06F 9/46 (2006.01)
G06F 9/52 (2006.01)

(52) **U.S. Cl.**
CPC **G06F 9/52** (2013.01)

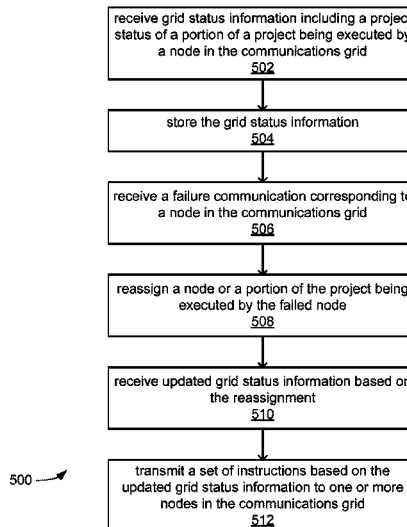
(58) **Field of Classification Search**
CPC G06F 9/52
See application file for complete search history.

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30 Claims, 25 Drawing Sheets



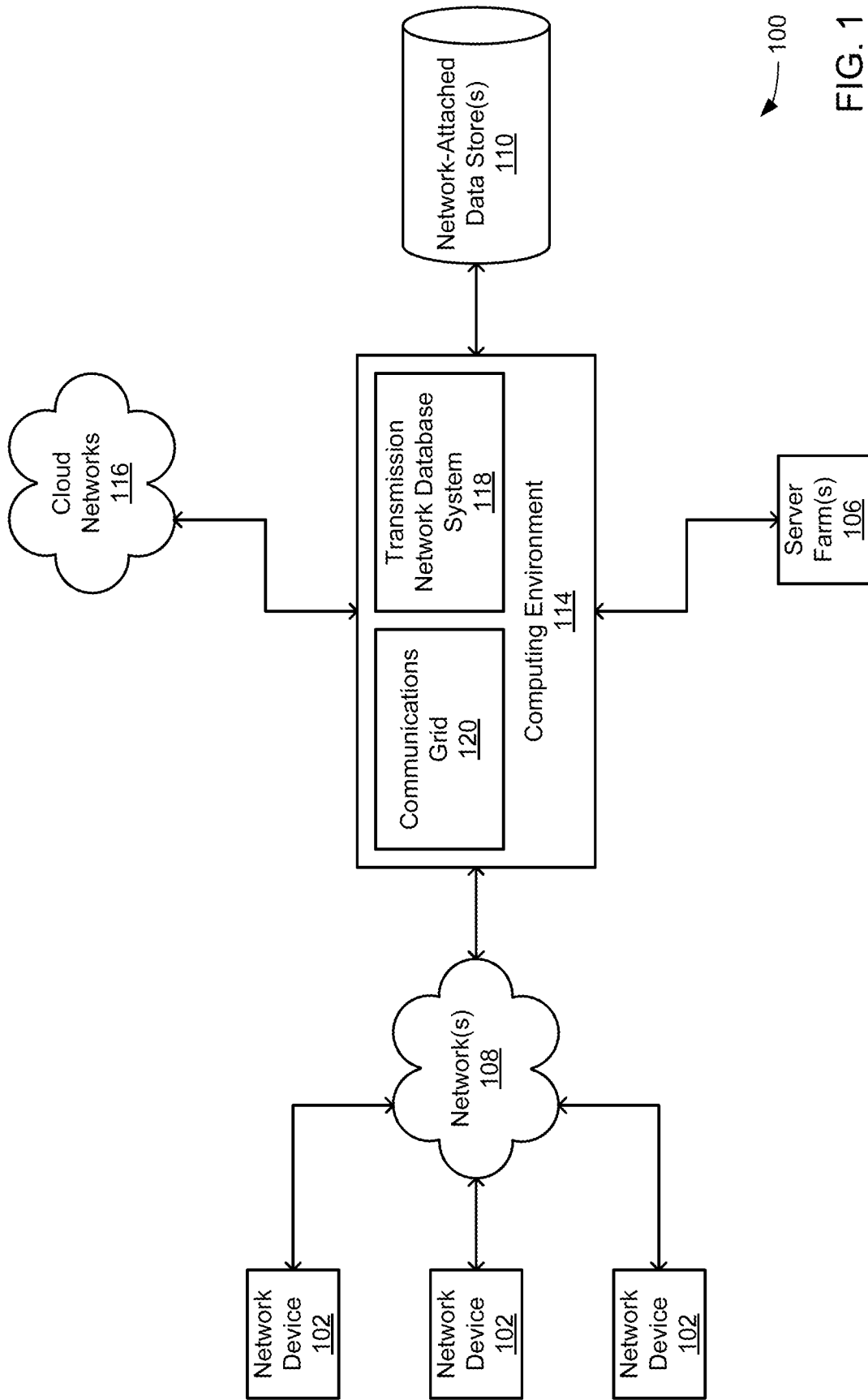


FIG. 1

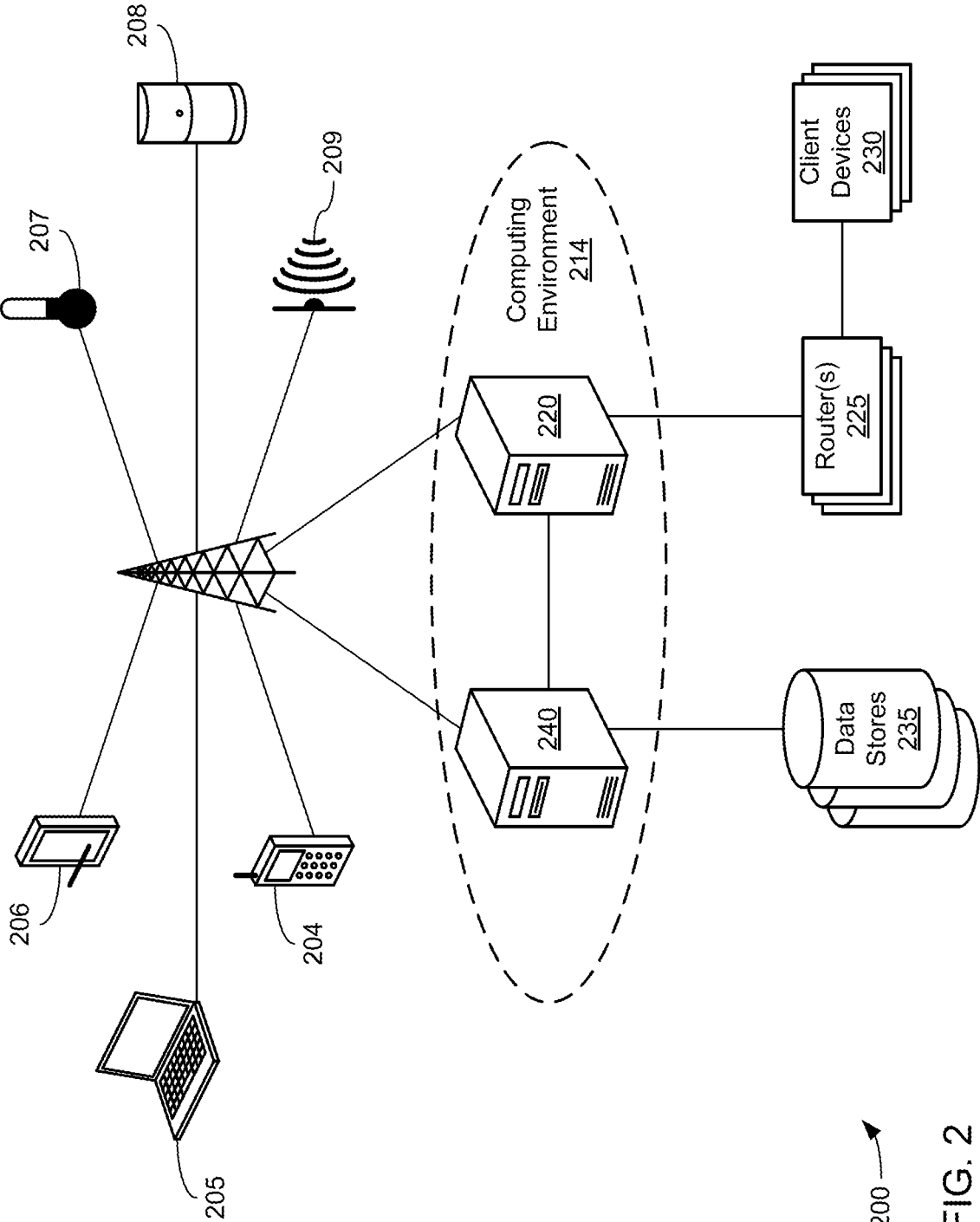


FIG. 2

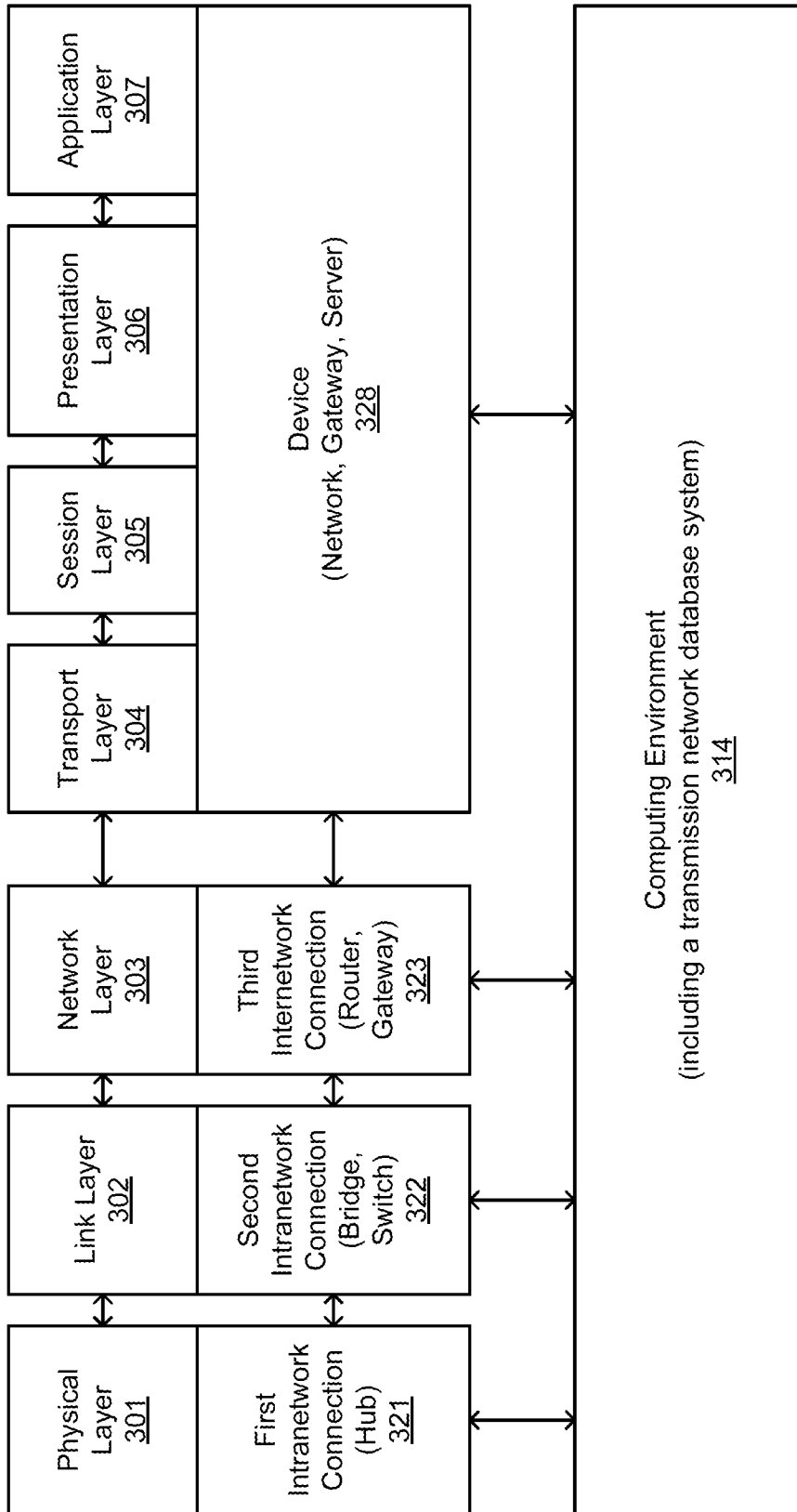


FIG. 3

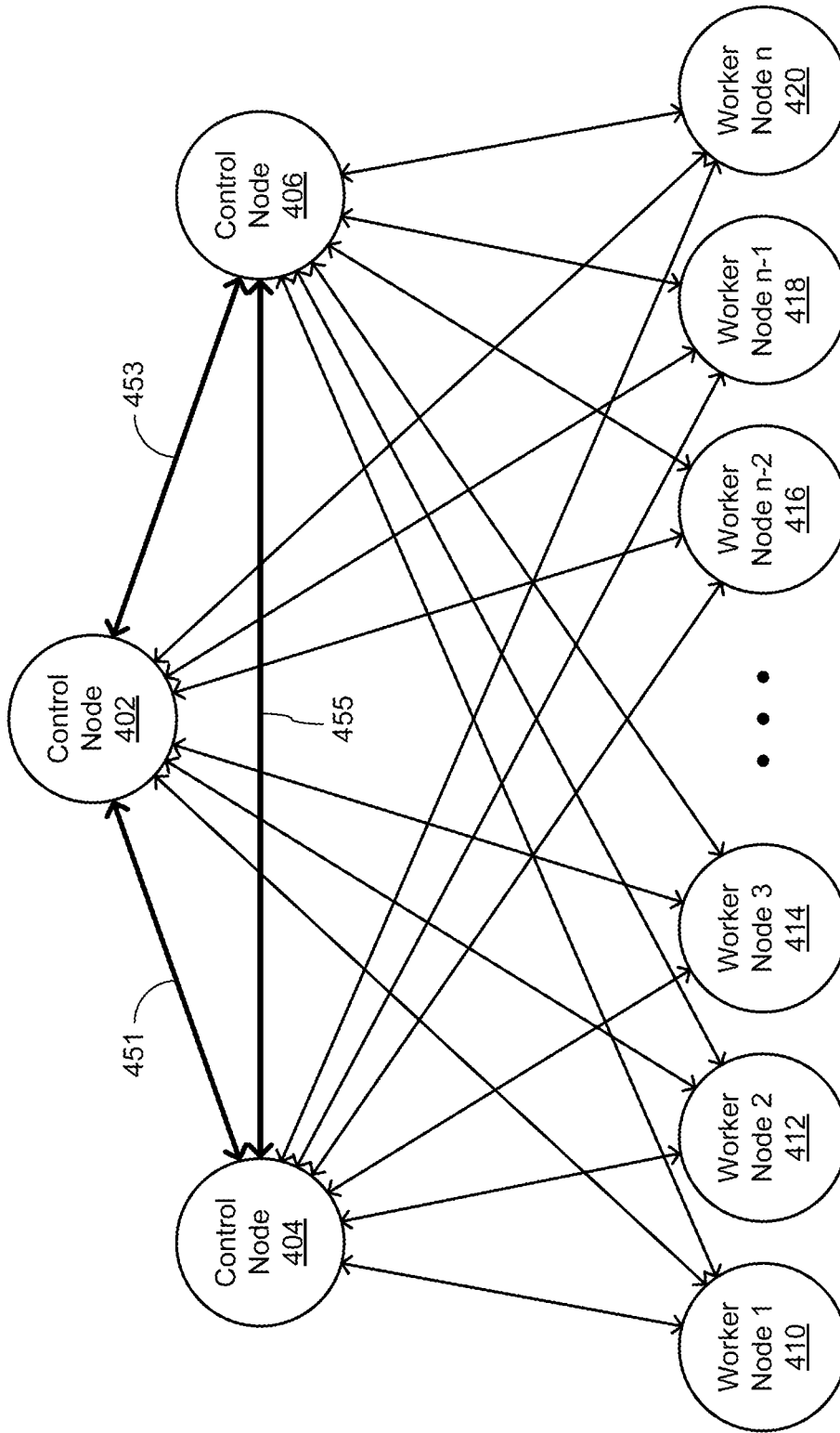
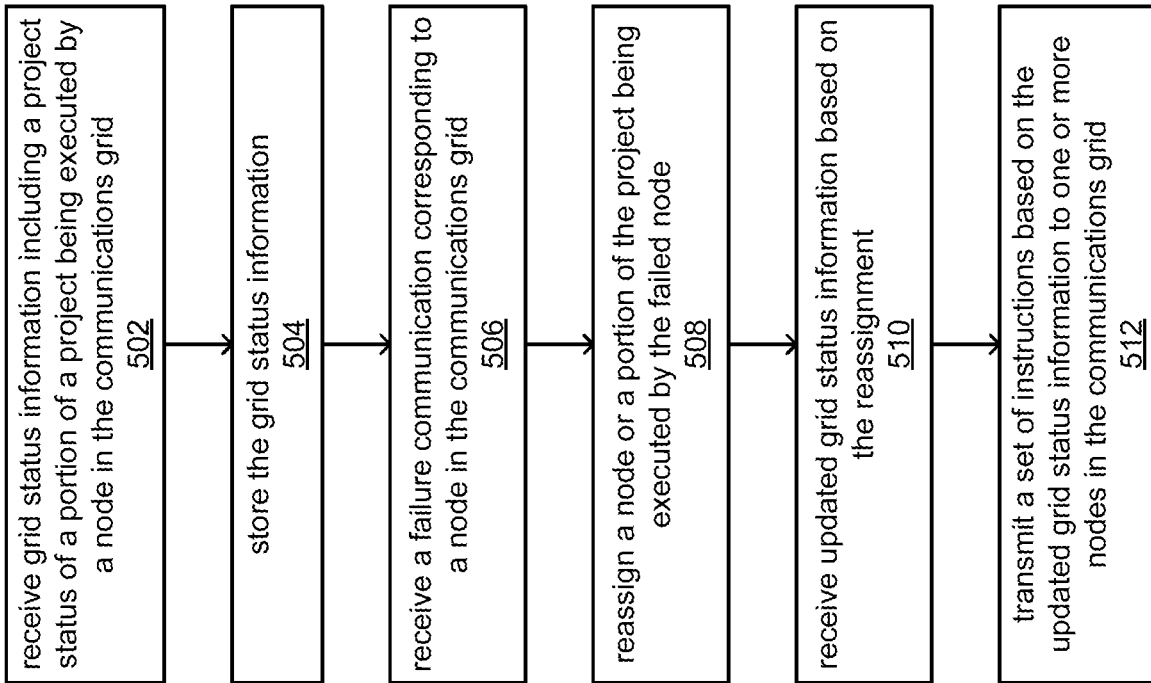


FIG. 4

400 →



500 →

FIG. 5

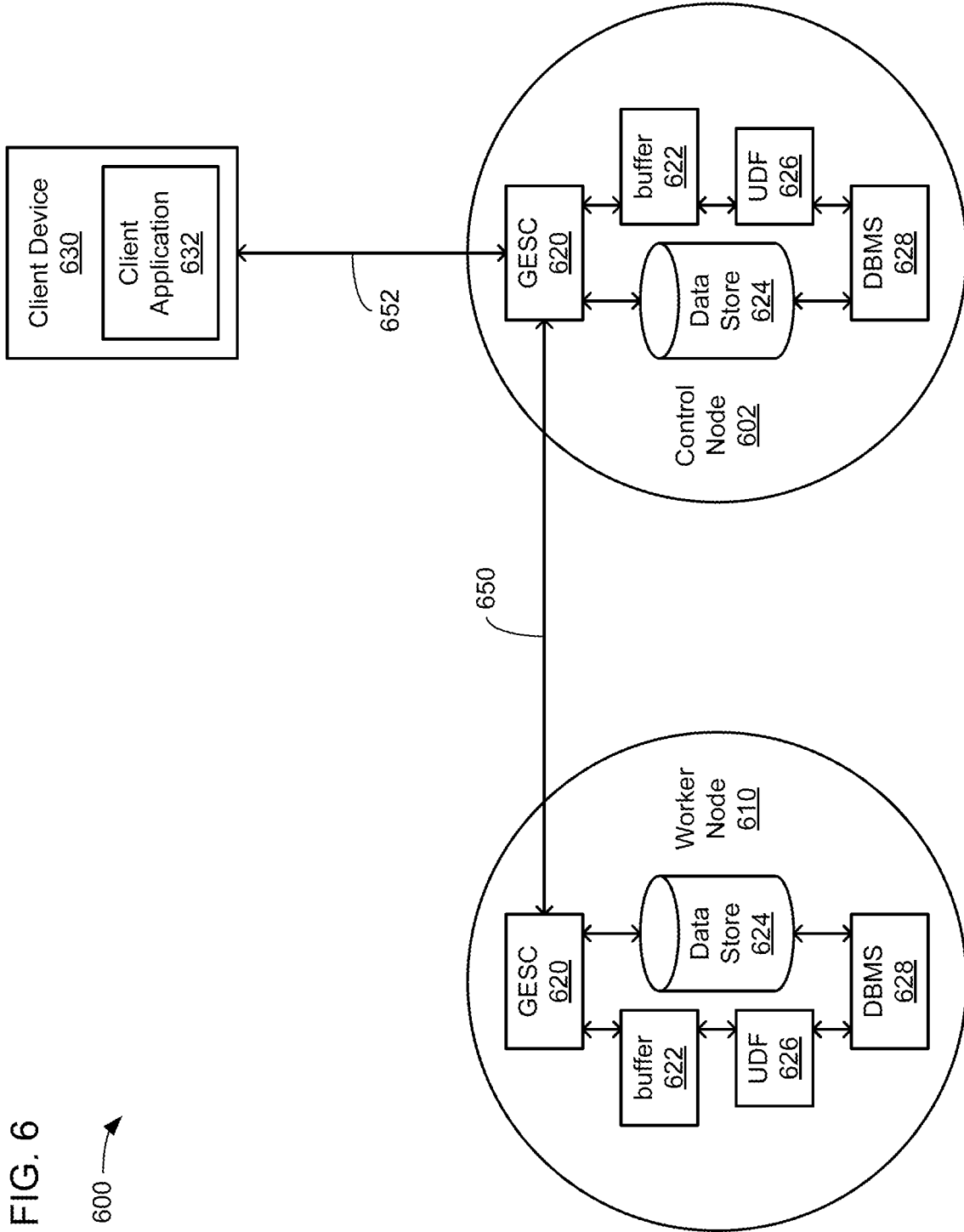
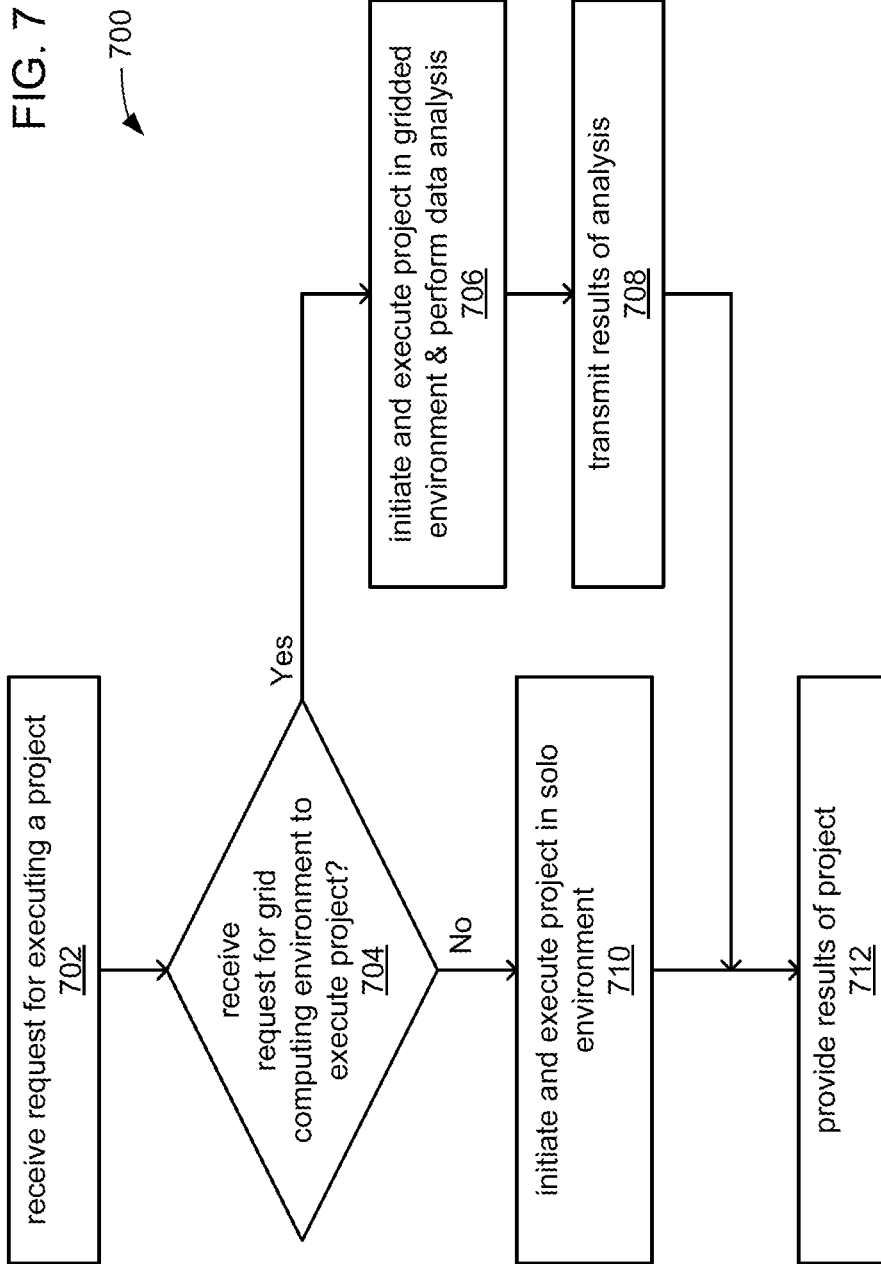


FIG. 6

600



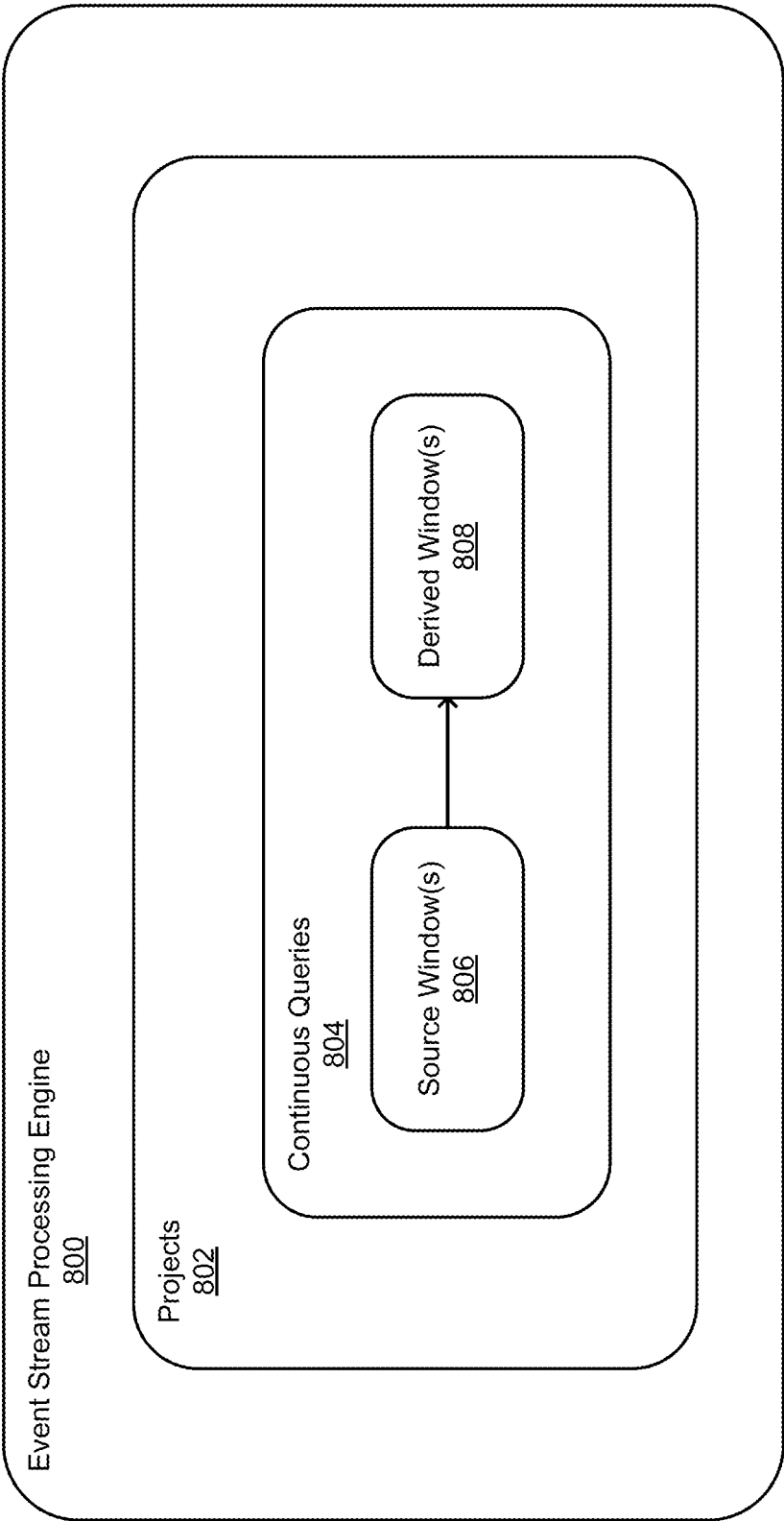
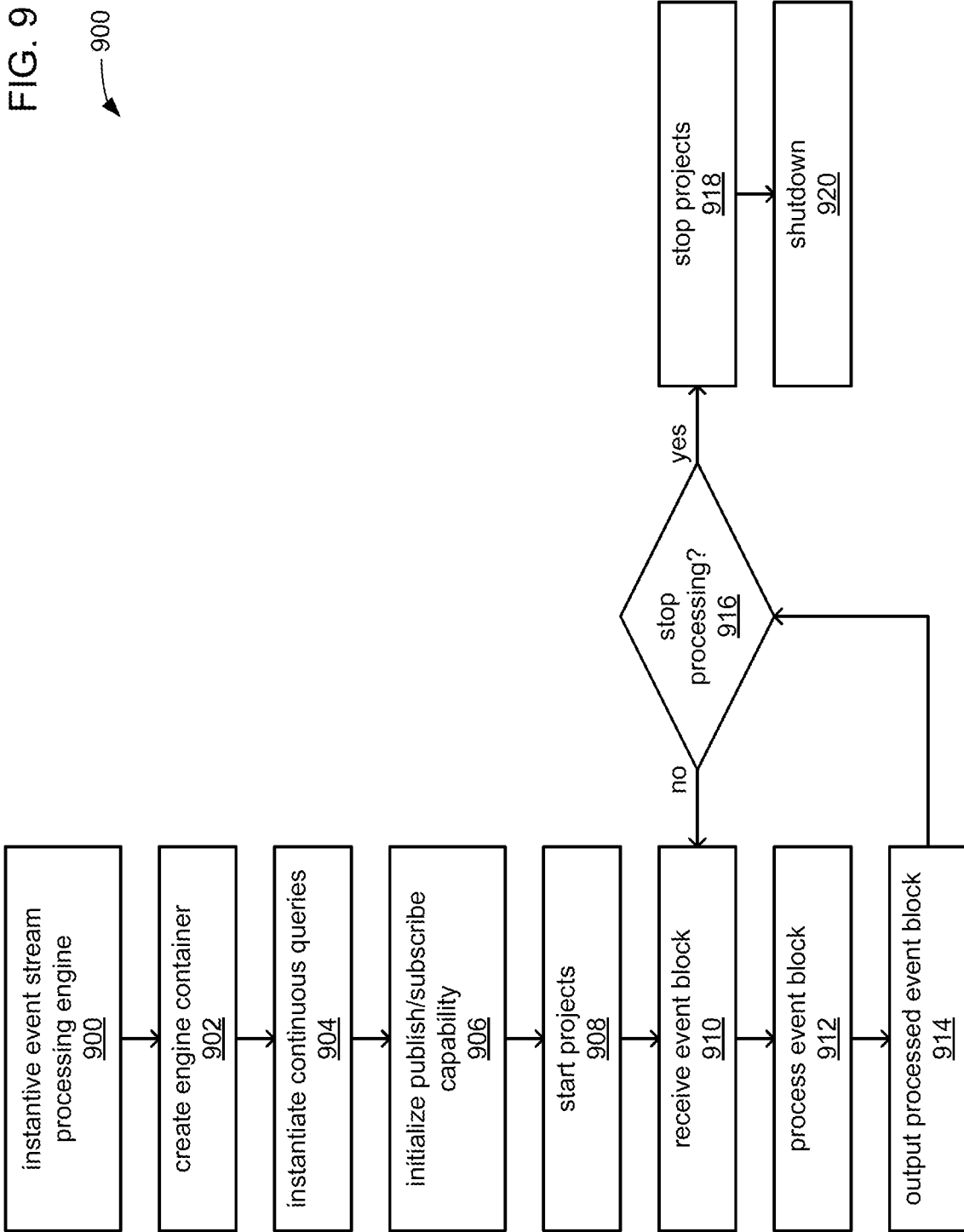
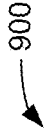


FIG. 8

FIG. 9



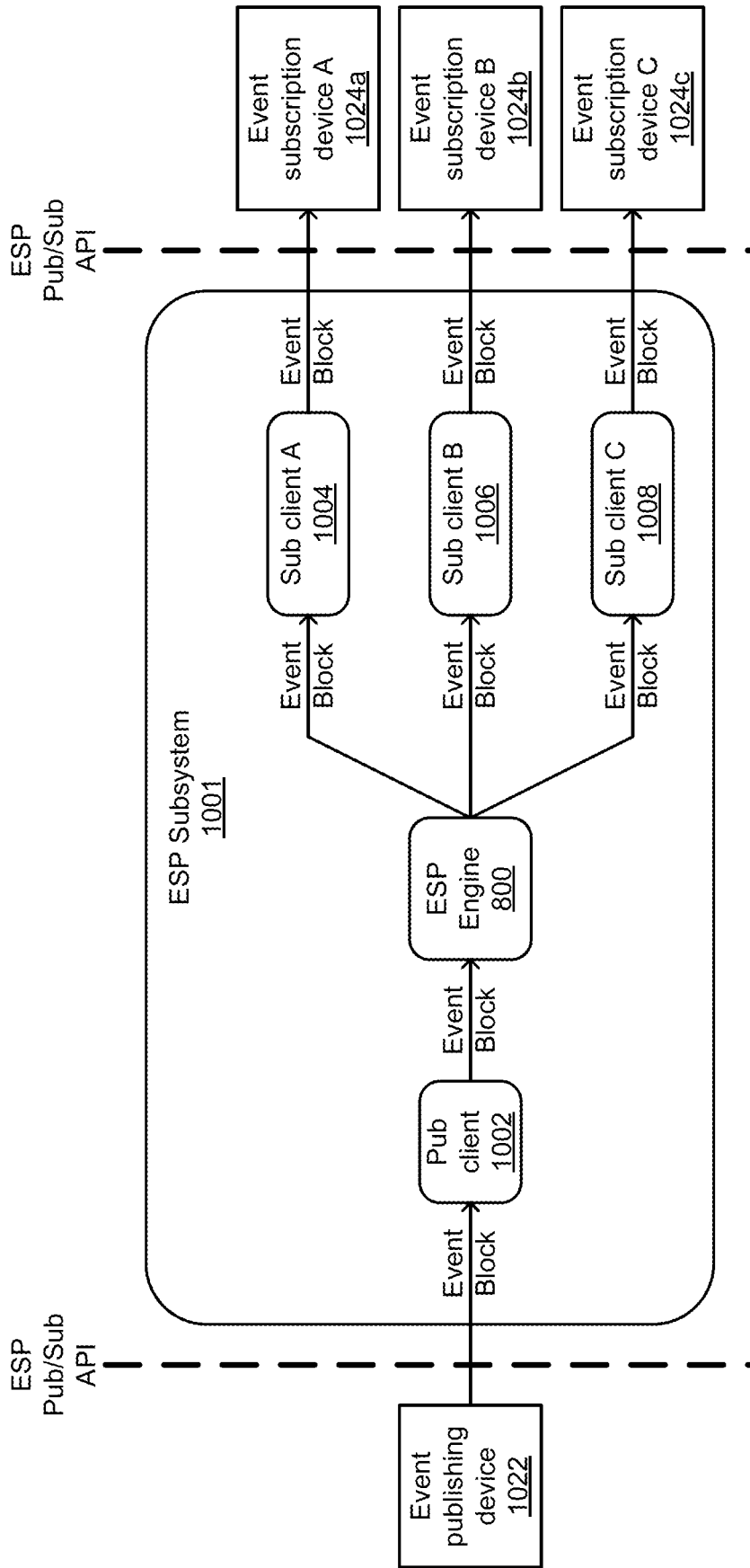
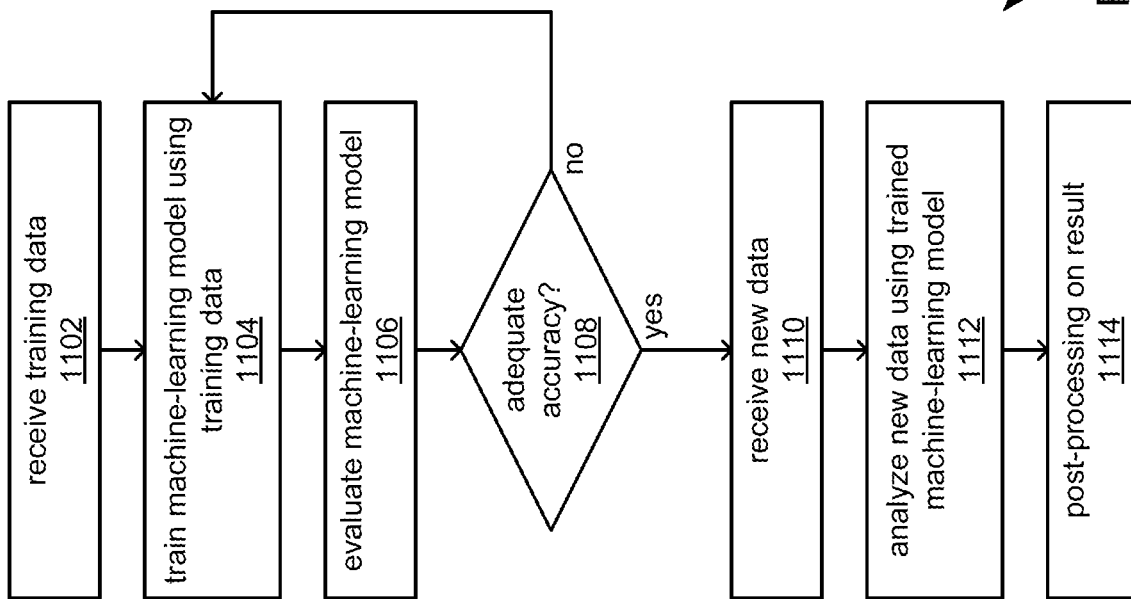


FIG. 10

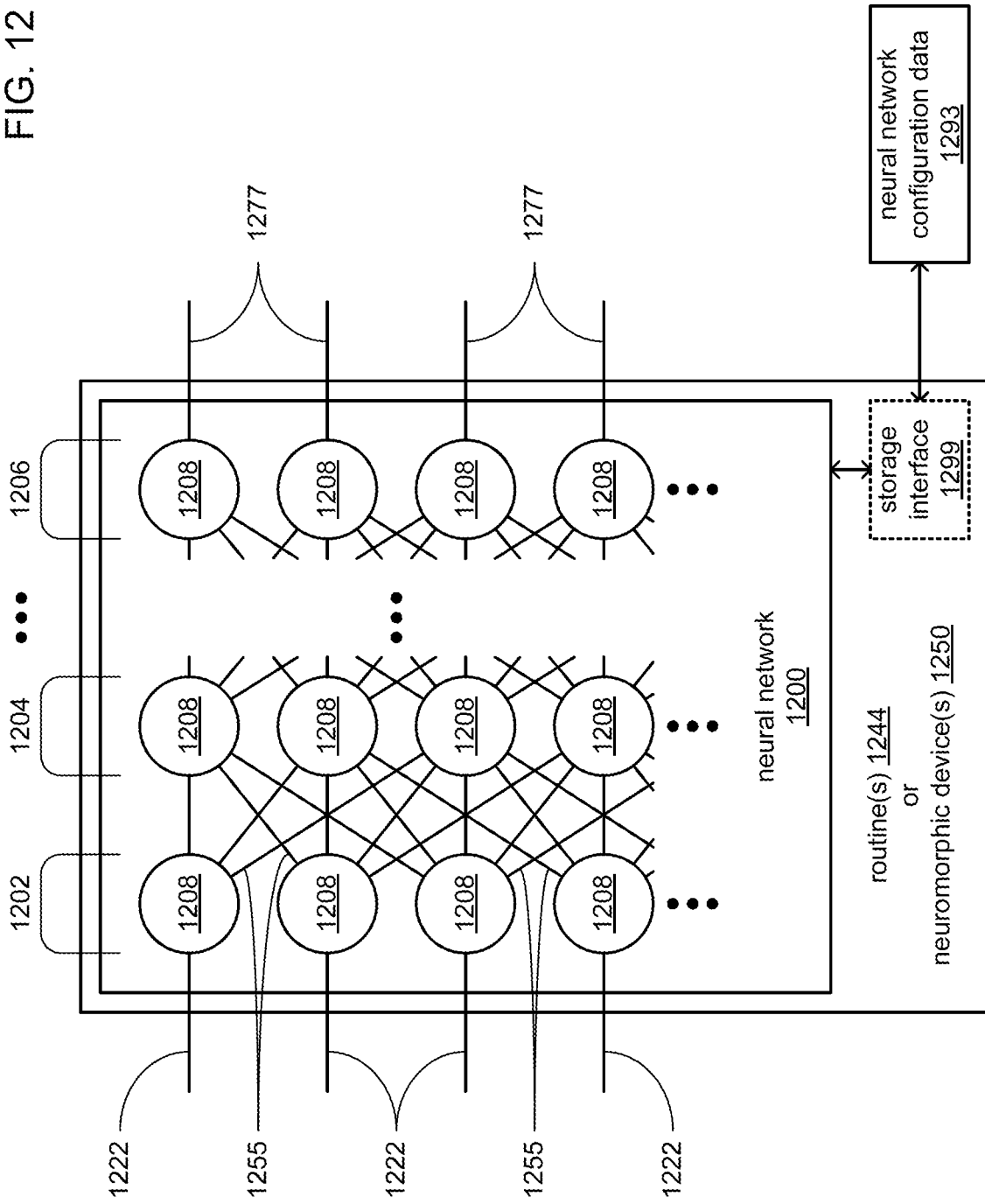
1000



1100

FIG. 11

FIG. 12



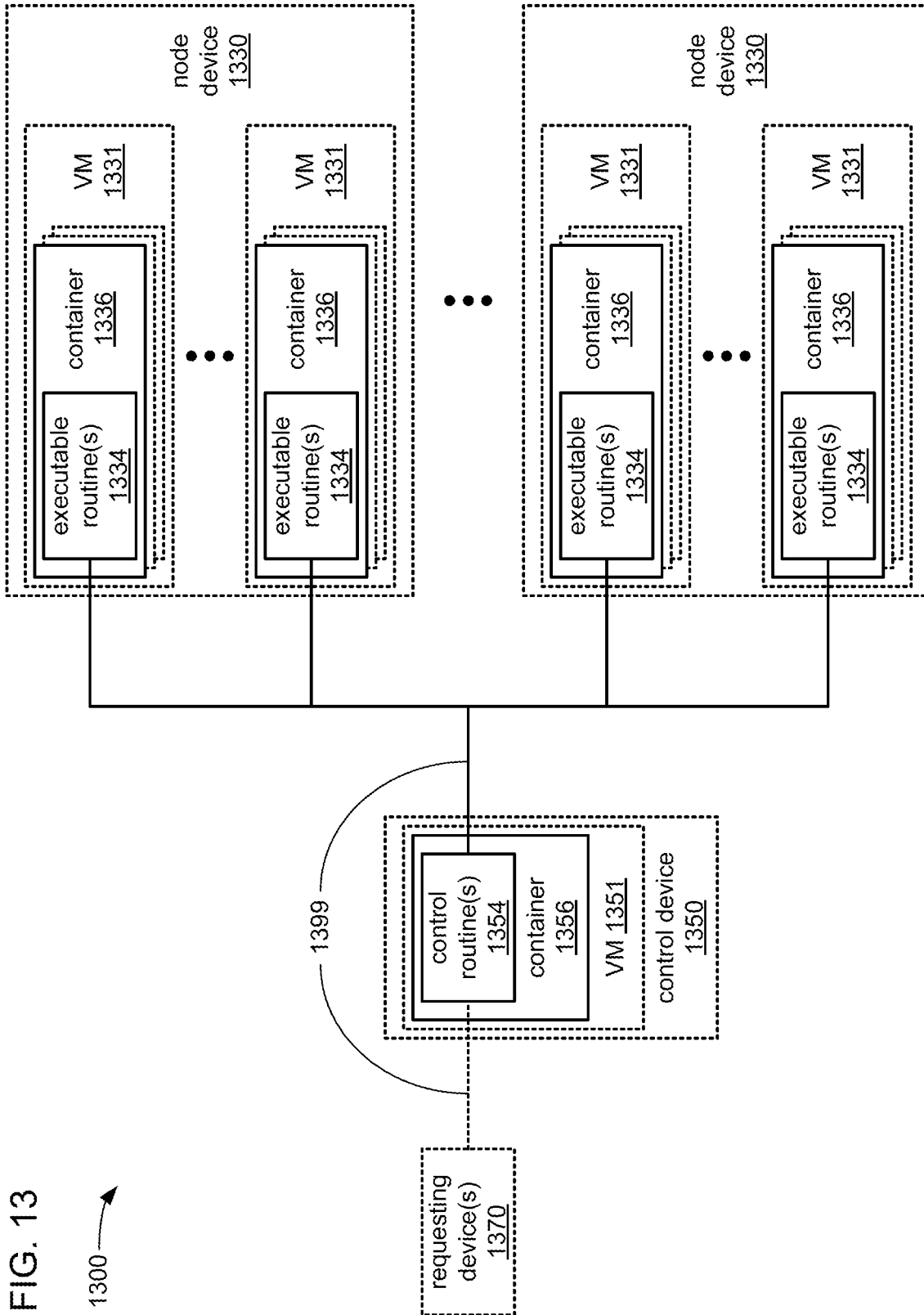


FIG. 13

1400

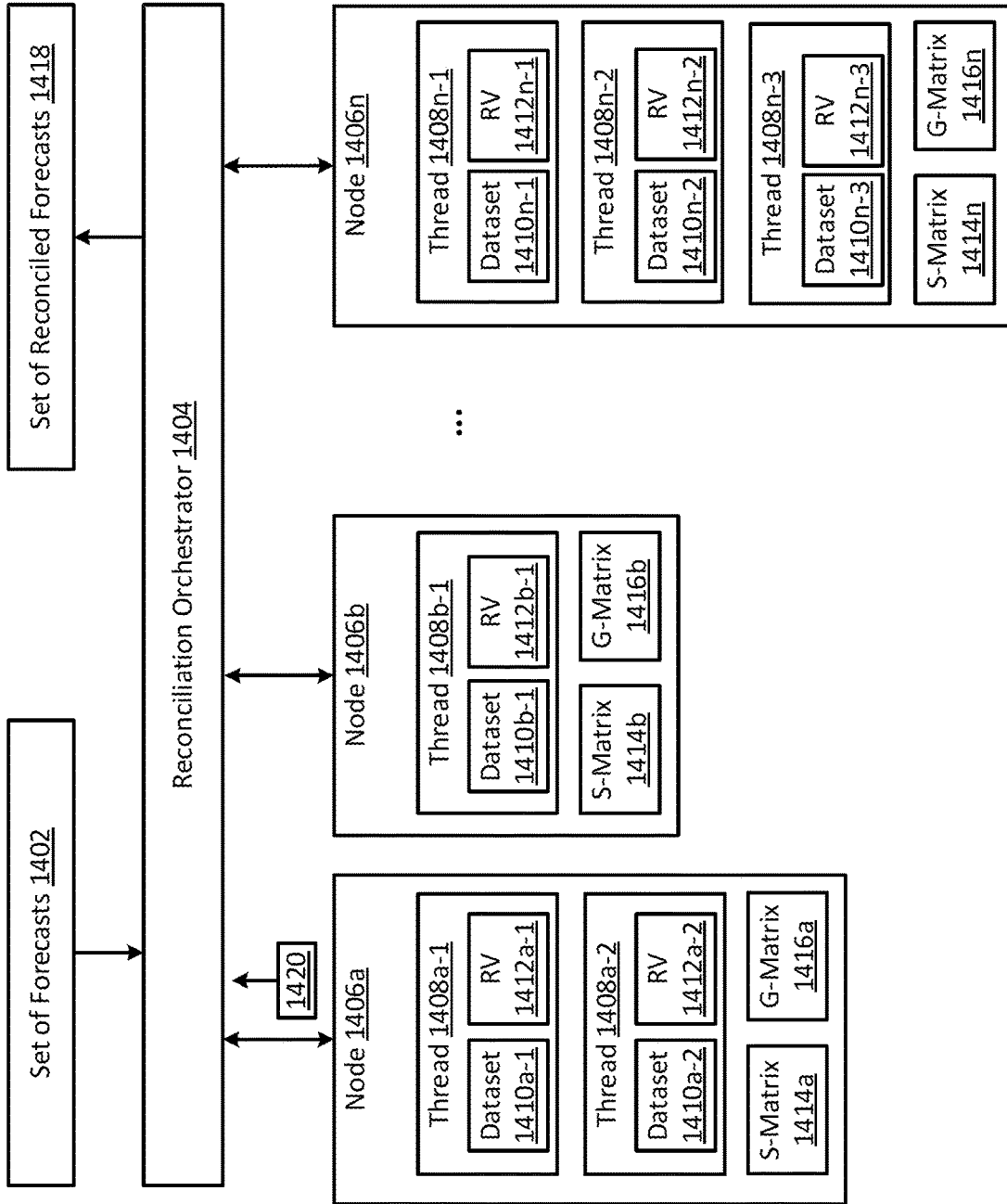
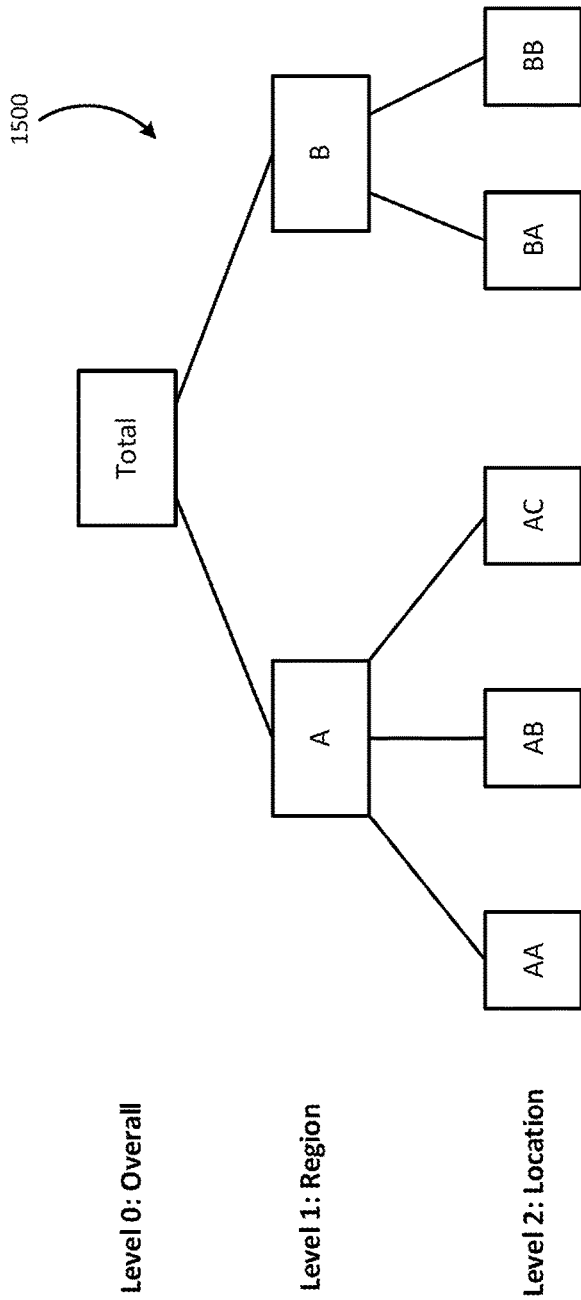


FIG. 14



1502

$$Y_{total,t} = Y_{A,t} + Y_{B,t}$$
$$Y_{A,t} = Y_{AA,t} + Y_{AB,t} + Y_{AC,t}$$
$$Y_{B,t} = Y_{BA,t} + Y_{BB,t}$$

FIG. 15

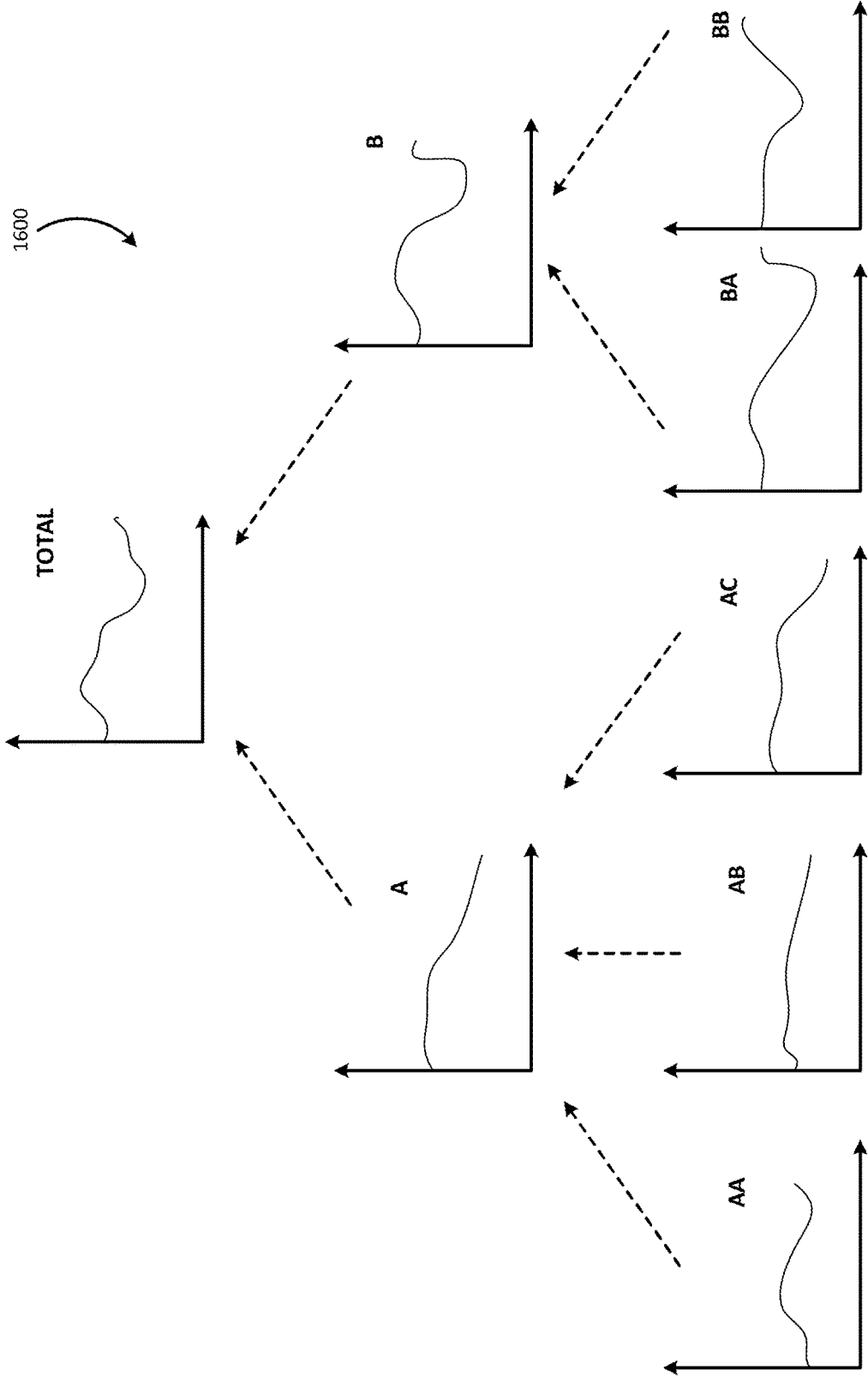


FIG. 16

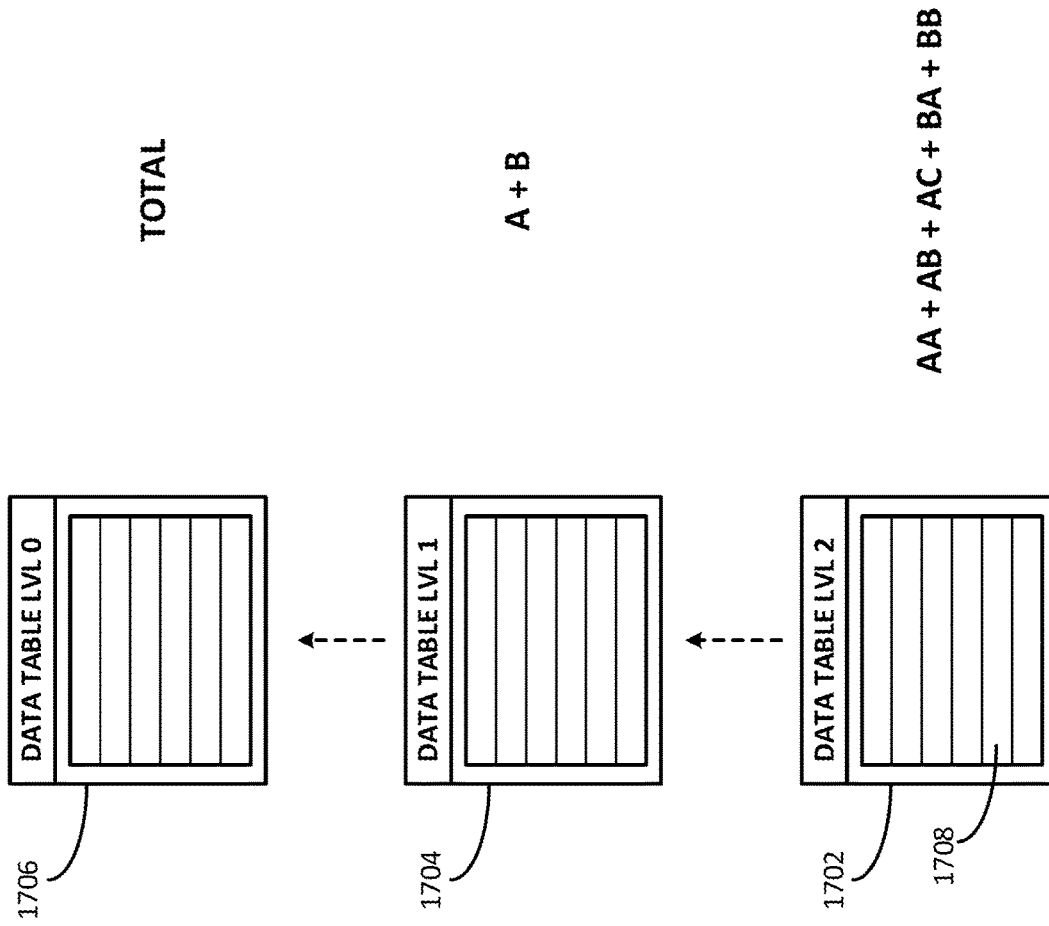


FIG. 17

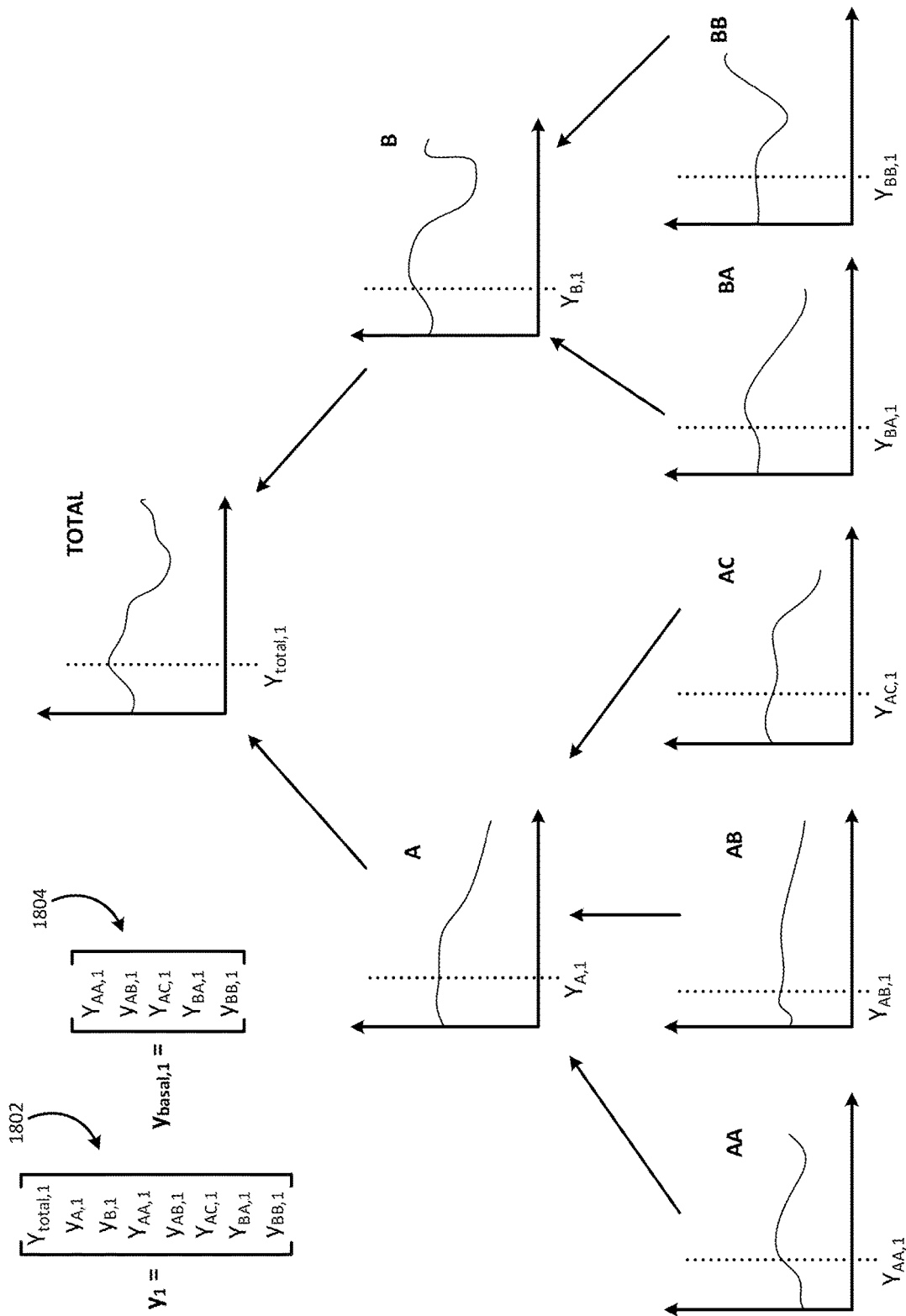


FIG. 18

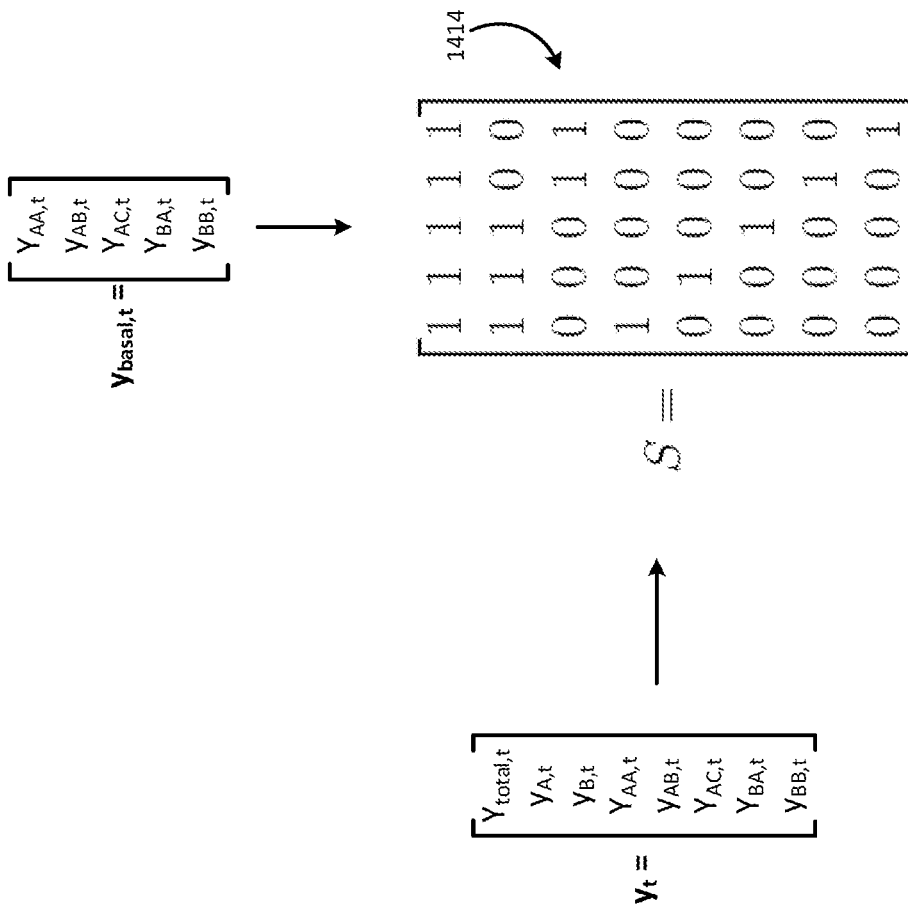


FIG. 19

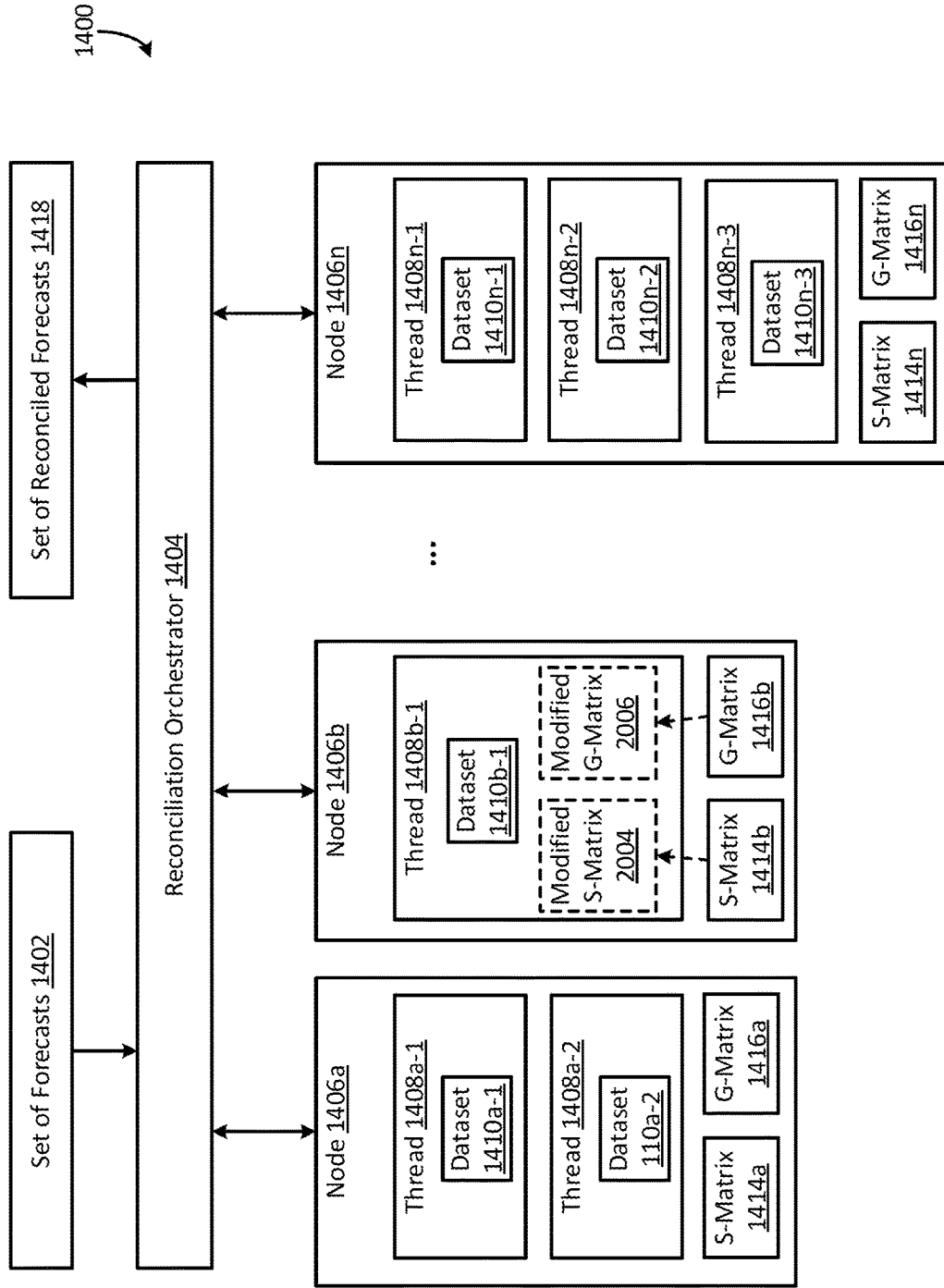


FIG. 20

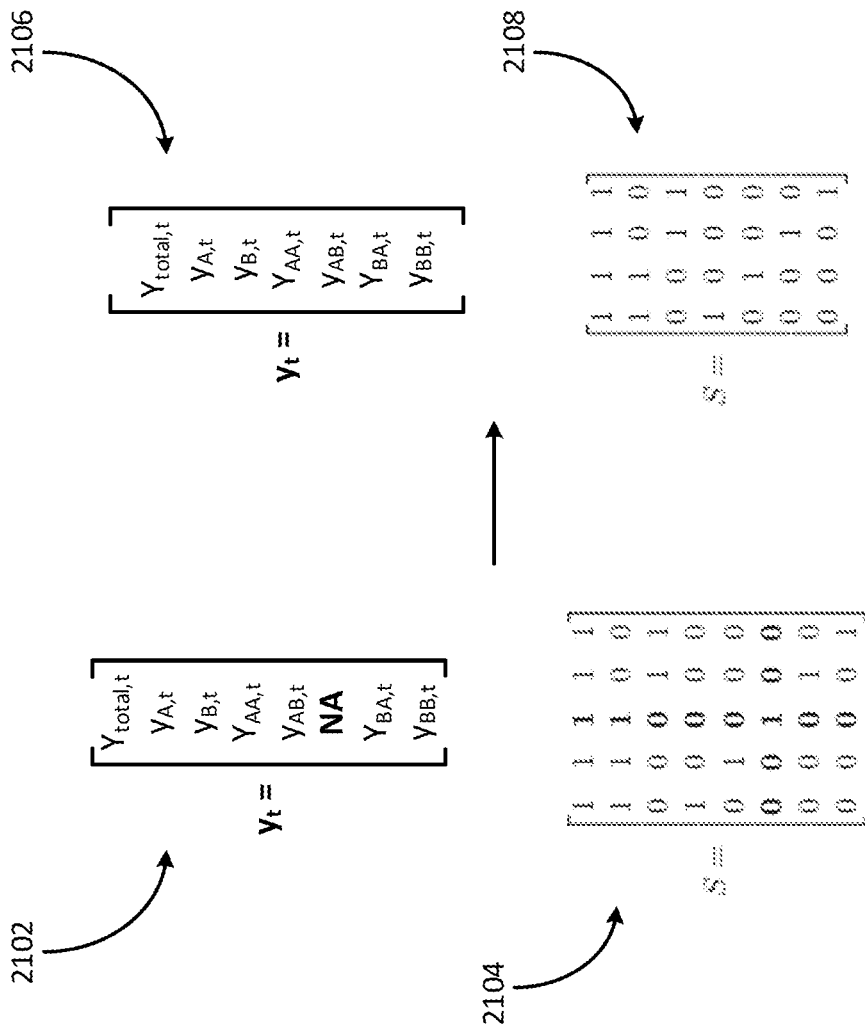


FIG. 21

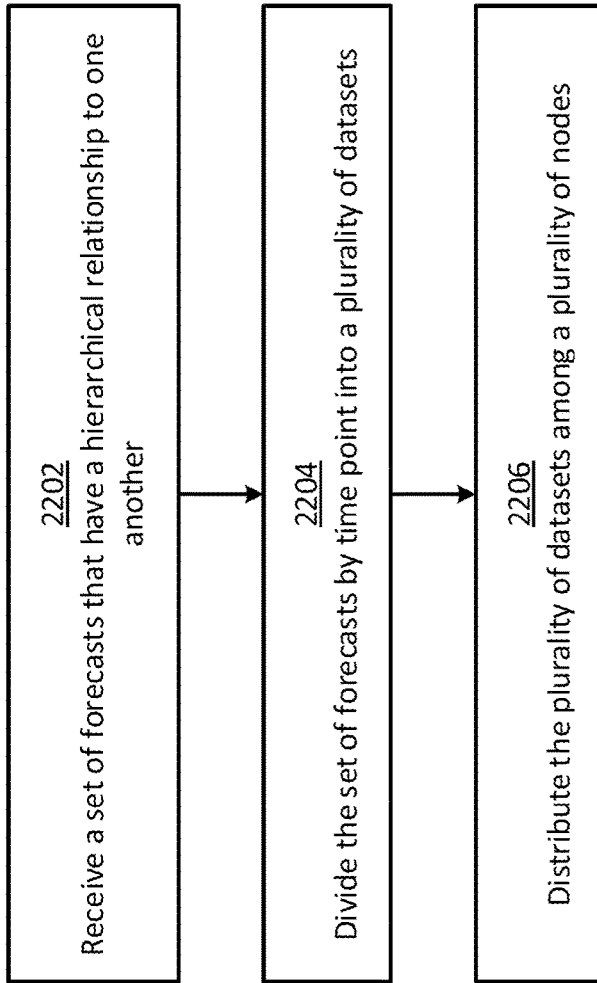


FIG. 22

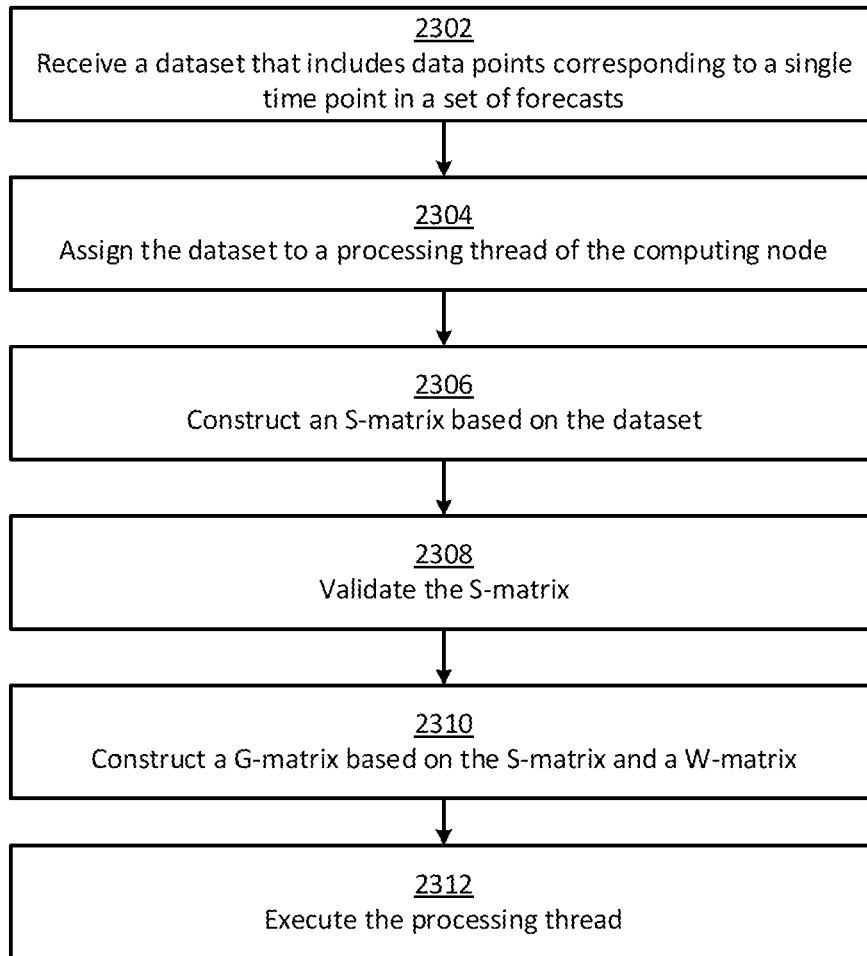


FIG. 23

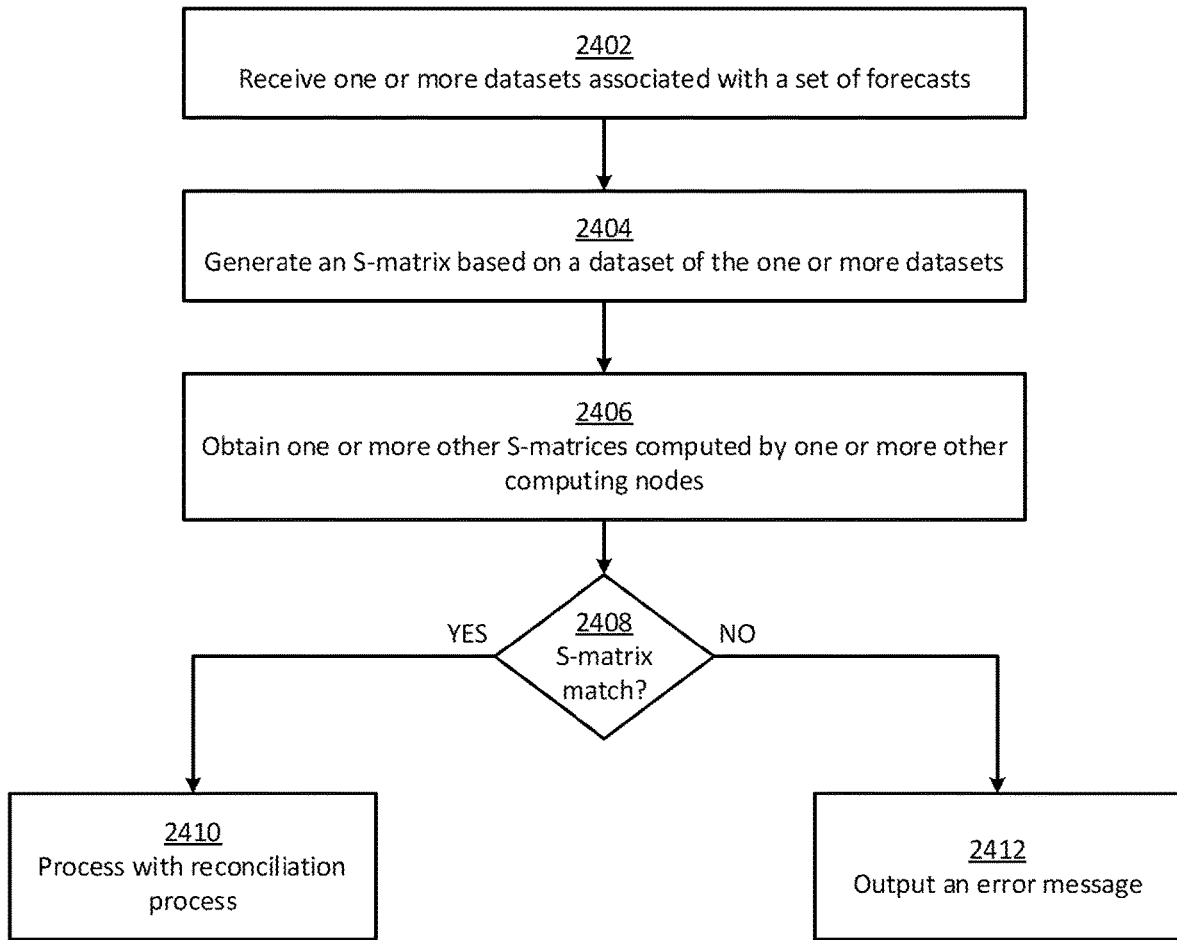


FIG. 24

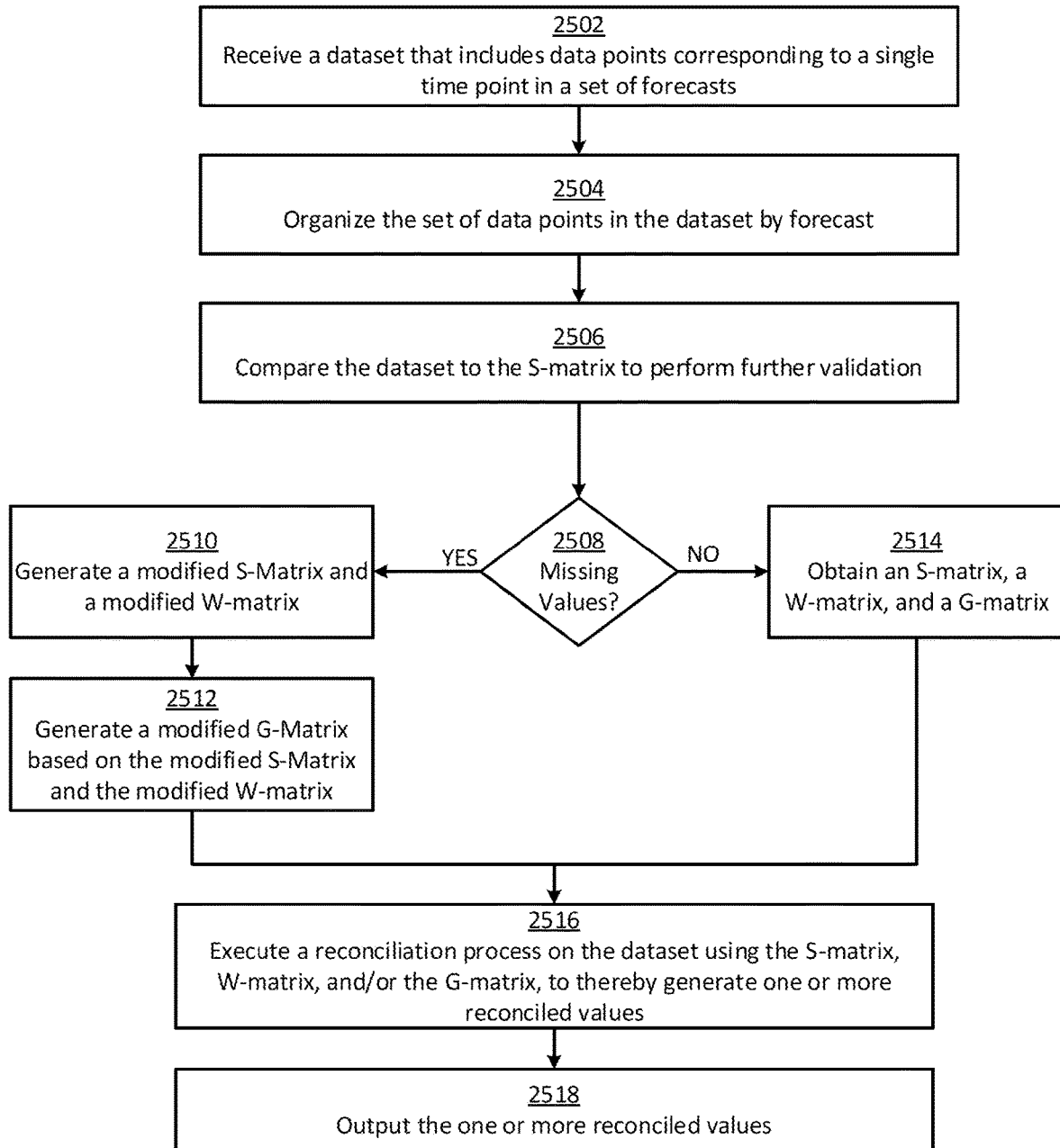


FIG. 25

**PARALLEL PROCESSING TECHNIQUES
FOR EXPEDITING RECONCILIATION FOR
A HIERARCHY OF FORECASTS ON A
COMPUTER SYSTEM**

REFERENCE TO RELATED APPLICATION

This claims the benefit of priority under 35 U.S.C. § 119(e) to U.S. Provisional Patent Application No. 63/457,391 filed May 5, 2023, and to U.S. Provisional Patent Application No. 63/461,208, filed Apr. 21, 2023, the entirety of each of which is hereby incorporated by reference herein.

TECHNICAL FIELD

The present disclosure relates generally to parallel processing in a computing cluster. More specifically, but not by way of limitation, this disclosure relates to a parallel processing technique for expediting reconciliation of a hierarchy of forecasts on a computer system.

BACKGROUND

In some situations, time series data can be organized hierarchically. For example, an administrator of a network can receive a set of time series indicating the total number of packets flowing through the network's servers over a given time window, such as one month. Each time series can correspond to an individual server and each data point in the time series can indicate the total number of packets flowing through that server at a particular point in time, such as on a given day. The data points can be collected daily or at another frequency. The servers can be geographically distributed across a country, such as the United States. The time series may be organized hierarchically by geographical region, such as by states, counties, and cities within the country. When time series data is organized in a hierarchical fashion, there are often constraints that link the time series together at different levels of the hierarchy. For example, the total packet flow through the entire network should be the sum of all of the packet flow through all of the states covered by the network. While these constraints may be inherently satisfied by actual time-series data, it can be more challenging to meet these constraints in the context of predictive forecasting.

Forecasting can involve generating time-stamped data (e.g., a time series) with predicted values over a future time window. Such forecasts are normally generated using models, such as machine-learning models. In some cases, the forecasts can have a hierarchical relationship with respect to one another. For example, the forecasts can be generated to predict the packet flow through the network at the state level, the county level, and the city level over a future time window. But imposing the abovementioned constraints during a forecasting process may be challenging, because the forecasts are often individually generated by the models, without regard for the other levels of the hierarchy. As a result, such forecasts often do not respect the constraints. To resolve this problem, after the forecasts have been generated, a reconciliation process may be applied to the forecasts to adjust the forecasts so that they adhere to those constraints.

SUMMARY

One example of the present disclosure includes a system comprising one or more processors and one or more memo-

ries. The one or more memories can include program code that is executable by the one or more processors for causing the one or more processors to perform operations. The operations can include receiving a plurality of forecasts that have a hierarchical relationship with respect to one another, wherein each forecast among the plurality of forecasts corresponds to a respective level of a hierarchy, and wherein at least one forecast in the plurality of forecasts corresponds to a higher level of the hierarchy than at least one other forecast of the plurality of forecasts. The operations can include distributing the plurality of forecasts among a plurality of computing nodes of a distributed computing environment by time point, such that all data points corresponding to a same time point in the plurality of forecasts are assigned to a same computing node of the plurality of computing nodes. The plurality of computing nodes can be configured to collectively process the plurality of forecasts in parallel to implement a reconciliation process that involves adjusting the plurality of forecasts subject to an aggregation constraint. The plurality of computing nodes can be further configured to: receive a plurality of datasets corresponding to a plurality of time points, each dataset of the plurality of datasets including a respective set of data points from the plurality of forecasts corresponding to a single time point; organize the respective set of data points in each of the plurality of datasets by forecast to generate a plurality of ordered datasets; assign the plurality of ordered datasets to a plurality of processing threads on the plurality of computing nodes, the plurality of processing threads being executable in parallel to implement respective portions of the reconciliation process using the plurality of ordered datasets; execute the plurality of processing threads to implement the reconciliation process on the plurality of forecasts, to thereby generate a plurality of reconciled values; and output the plurality of reconciled values.

Another example of the present disclosure includes a method of operations. The operations can include receiving a plurality of forecasts that have a hierarchical relationship with respect to one another, wherein each forecast among the plurality of forecasts corresponds to a respective level of a hierarchy, and wherein at least one forecast in the plurality of forecasts corresponds to a higher level of the hierarchy than at least one other forecast of the plurality of forecasts. The operations can include distributing the plurality of forecasts among a plurality of computing nodes of a distributed computing environment by time point, such that all data points corresponding to a same time point in the plurality of forecasts are assigned to a same computing node of the plurality of computing nodes. The plurality of computing nodes can be configured to collectively process the plurality of forecasts in parallel to implement a reconciliation process that involves adjusting the plurality of forecasts subject to an aggregation constraint. The plurality of computing nodes can be further configured to: receive a plurality of datasets corresponding to a plurality of time points, each dataset of the plurality of datasets including a respective set of data points from the plurality of forecasts corresponding to a single time point; organize the respective set of data points in each of the plurality of datasets by forecast to generate a plurality of ordered datasets; assign the plurality of ordered datasets to a plurality of processing threads on the plurality of computing nodes, the plurality of processing threads being executable in parallel to implement respective portions of the reconciliation process using the plurality of ordered datasets; execute the plurality of processing threads to implement the reconciliation process on the plurality of forecasts, to thereby generate a plurality of reconciled val-

ues; and output the plurality of reconciled values. The operations can be implemented by one or more processors.

Yet another example of the present disclosure includes a non-transitory computer-readable medium comprising program code that is executable by one or more processors for causing the one or more processors to perform operations. The operations can include receiving a plurality of forecasts that have a hierarchical relationship with respect to one another, wherein each forecast among the plurality of forecasts corresponds to a respective level of a hierarchy, and wherein at least one forecast in the plurality of forecasts corresponds to a higher level of the hierarchy than at least one other forecast of the plurality of forecasts. The operations can include distributing the plurality of forecasts among a plurality of computing nodes of a distributed computing environment by time point, such that all data points corresponding to a same time point in the plurality of forecasts are assigned to a same computing node of the plurality of computing nodes. The plurality of computing nodes can be configured to collectively process the plurality of forecasts in parallel to implement a reconciliation process that involves adjusting the plurality of forecasts subject to an aggregation constraint. The plurality of computing nodes can be further configured to: receive a plurality of datasets corresponding to a plurality of time points, each dataset of the plurality of datasets including a respective set of data points from the plurality of forecasts corresponding to a single time point; organize the respective set of data points in each of the plurality of datasets by forecast to generate a plurality of ordered datasets; assign the plurality of ordered datasets to a plurality of processing threads on the plurality of computing nodes, the plurality of processing threads being executable in parallel to implement respective portions of the reconciliation process using the plurality of ordered datasets; execute the plurality of processing threads to implement the reconciliation process on the plurality of forecasts, to thereby generate a plurality of reconciled values; and output the plurality of reconciled values.

This summary is not intended to identify key or essential features of the claimed subject matter, nor is it intended to be used in isolation to determine the scope of the claimed subject matter. The subject matter should be understood by reference to appropriate portions of the entire specification, any or all drawings, and each claim.

The foregoing, together with other features and examples, will become more apparent upon referring to the following specification, claims, and accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

The present disclosure is described in conjunction with the appended FIGURES:

FIG. 1 shows an example of the hardware components of a data transmission network according to some aspects of the present disclosure.

FIG. 2 shows an example network including an example set of devices communicating with each other over an exchange system according to some aspects of the present disclosure.

FIG. 3 shows an example representation of a conceptual model of a communications protocol system according to some aspects of the present disclosure.

FIG. 4 shows a communications grid computing system including a variety of control and worker nodes according to some aspects of the present disclosure.

FIG. 5 shows a flow chart showing an example process for adjusting a communications grid or a work project in a

communications grid after a failure of a node according to some aspects of the present disclosure.

FIG. 6 shows a portion of a communications grid computing system including a control node and a worker node according to some aspects of the present disclosure.

FIG. 7 shows a flow chart showing an example method 700 for executing a project within a grid computing system according to some aspects of the present disclosure.

FIG. 8 shows a block diagram including components of an Event Stream Processing Engine (ESPE) according to some aspects of the present disclosure.

FIG. 9 shows a flow chart of an example process including operations performed by an event stream processing engine according to some aspects of the present disclosure.

FIG. 10 shows an ESP system interfacing between publishing device and event subscribing devices according to some aspects of the present disclosure.

FIG. 11 shows a flow chart of an example of a process for generating and using a machine-learning model according to some aspects of the present disclosure.

FIG. 12 shows a node-link diagram of an example of a neural network according to some aspects of the present disclosure.

FIG. 13 shows various aspects of the use of containers as a mechanism to allocate processing, storage and/or other resources of a processing system to the performance of various analyses according to some aspects of the present disclosure.

FIG. 14 shows a block diagram of an example of a computer system for expediting reconciliation of a hierarchy of forecasts according to some aspects of the present disclosure.

FIG. 15 shows a block diagram of an example of a hierarchy of forecasts according to some aspects of the present disclosure.

FIG. 16 shows an example of a hierarchy of forecasts according to some aspects of the present disclosure.

FIG. 17 shows an example of a hierarchy of data tables according to some aspects of the present disclosure.

FIG. 18 shows an example of a dataset corresponding to a particular time point in a set of forecasts according to some aspects of the present disclosure.

FIG. 19 shows an example of an S-matrix according to some aspects of the present disclosure.

FIG. 20 shows a block diagram of an example of a computer system with a modified S-matrix and a modified G-matrix according to some aspects of the present disclosure.

FIG. 21 shows an example of a dataset, an S-matrix, a modified dataset, and a modified S-matrix according to some aspects of the present disclosure.

FIG. 22 shows a flowchart of an example of a process for dividing and distributing forecast data among a group of nodes according to some aspects of the present disclosure.

FIG. 23 shows a flowchart of an example of a process for performing reconciliation on a computing node according to some aspects of the present disclosure.

FIG. 24 shows a flowchart of an example of a process for S-matrix validation according to some aspects of the present disclosure.

FIG. 25 shows a flowchart of an example of a process for performing reconciliation on a processing thread of a computing node according to some aspects of the present disclosure.

In the appended FIGURES, similar components or features can have the same reference number. Further, various components of the same type may be distinguished by

following the reference number with a lowercase letter that distinguishes among the similar components. If only the first reference number is used in the specification, the description is applicable to any one of the similar components having the same first reference number irrespective of the lowercase letter.

DETAILED DESCRIPTION

Computerized forecasting can involve a computer system executing a model (e.g., a machine-learning model) to generate a forecast, which can include time-stamped data of predicted values over a future time window. In some cases, the computer system can generate multiple forecasts that have a hierarchical relationship with respect to one another. For example, a first forecast in the hierarchy may be considered a parent and a second forecast in the hierarchy may be considered a child of the parent. Given that the forecasts have a hierarchical relationship with respect to one another, it may be desirable to impose certain constraints such as an aggregation constraint on the forecasts. An aggregation constraint may be a requirement that values at a lower level of the hierarchy sum up to values at a higher level of the hierarchy. For instance, the total of all packet flow through a state at any given point in time should be the sum of all packet flow through all regions of the state at that point in time. But imposing such constraints during a forecasting process may be challenging for a variety of reasons. To help resolve this problem, after the forecasts have been generated, the computer system may perform a reconciliation process on the forecasts to adjust the forecasts so that they adhere to those constraints.

Existing reconciliation processes are technically complex. They normally involve computationally intensive matrix operations with high computational overhead. As a result, reconciliation can be slow, inefficient, and resource intensive (e.g., it can consume a significant amount of processing power, memory, and storage) when performed in conventional ways on a computer. This can prevent the computer from performing other tasks and may introduce latency in forecasting applications.

Existing reconciliation processes may also only handle two forecasts of a hierarchy at a time. For example, if the reconciliation process is to be applied to a four level hierarchy, it may reconcile levels one and two, and then levels two and three, and then levels three and four. This pairwise reconciliation process can be difficult to implement and may be computationally intensive.

Some examples of the present disclosure can overcome one or more of the abovementioned problems by performing reconciliation on a set of hierarchical forecasts (e.g., forecasts having a hierarchical relationship to one another) using two levels of parallel processing on a computing cluster. The two levels of parallel processing can include a first level of parallelism in which the computing cluster divides the set of forecasts by time point into datasets. Each dataset may correspond to a single time point. For example, each dataset may only consist of the data points related to that single time point in the forecasts. After dividing the forecasts into the datasets by time point, the computing cluster can distribute the datasets among its computing nodes to be processed in parallel by the computing nodes. The two levels of parallel processing can also include a second level of parallelism. The second level of parallelism can be applied at each individual computing node. In particular, each individual computing node can process its assigned datasets in parallel using multiple threads (processing threads). For example, if

five datasets are assigned to a single node, those five datasets can be processed on that single node in parallel using five threads, where each dataset is processed by one of the threads. This can involve the thread executing a reconciliation process on the data points in its assigned dataset. Using these techniques, the reconciliation process can be distributed among multiple nodes of a computing cluster and parallelized in two ways. This can significantly expedite the reconciliation process and reduce latency.

The techniques described herein can also perform reconciliation simultaneously across any number of levels of a hierarchy. For example, by dividing and distributing all levels of the hierarchy across the computing nodes for parallel processing, as described above, the system can simultaneously reconcile all levels of an N-level hierarchy (e.g., rather than performing pairwise reconciliation on two levels at a time). This may lead to improved accuracy as compared to conventional approaches.

As noted above, an overall reconciliation process for the set of forecasts can be divided up and distributed among multiple threads of multiple computing nodes. Each thread can execute a respective reconciliation process on its assigned dataset to generate one or more reconciled values for the corresponding time point. The computing cluster can then collect the reconciled values for some or all of the time points and use them to generate reconciled forecasts (e.g., reconciled versions of the original set of forecasts) that satisfy one or more predefined constraints.

In some examples, each computing node can inspect one of its assigned datasets to construct a summing matrix (“S-matrix”) to be used by its threads in its reconciliation processes. The S-matrix can encode the aggregation constraints between the levels of the hierarchy. The computing nodes can then compare their S-matrices to one another to check whether they match. This check can be performed prior to the computing nodes executing their respective reconciliation processes on their assigned datasets. If the check succeeds, the computing nodes can proceed to execute their respective reconciliation processes. If the check fails, for example because at least two of the nodes have different S-matrices, it may mean that the nodes disagree about the aggregation constraints, so the computing cluster can issue an error notification. By performing this validation prior to executing the reconciliation processes, the computing cluster can help avoid wasting computing resources by performing the reconciliation processes in situations that would yield inaccurate results, because the S-matrices are used in the reconciliation computations.

In some examples, each thread can check whether its assigned dataset has any missing values. For example, there can be a dataset that is assigned to a thread on a computing node. The dataset can correspond to a time point in a set of three forecasts. In the dataset, there can be three data points—one data point extracted from each of the three forecasts. The thread can analyze the three data points to determine if any of them have missing values (e.g., an empty or NULL value for a data point). A data point may have a missing value for any number of reasons, such as a problem with the forecasting model that produced the corresponding forecast. If the thread determines that a data point is missing a value, the thread can execute a missing-value handling process. This can involve dynamically modifying the S-matrix that it previously computed, for example, to remove a row and/or column related to the missing value from the S-matrix. The thread can then use the dynamically modified S-matrix to perform its reconciliation process. In this way, each thread can perform a missing value check on each of its

assigned datasets and dynamically adjust the pre-computed S-matrix upon detecting a missing value in a dataset, so that the missing value does not negatively affect the reconciliation process for that dataset.

Because of some or all of the features described above, the techniques described herein can be more stable and hundreds or thousands of times faster than conventional reconciliation approaches. For example, existing reconciliation libraries such as HTS and Fabletools either cannot perform any parallelization at all or can only performed limited parallel processing on a single computer, not a cluster of distributed nodes. The inability to perform parallel reconciliation or distributed reconciliation significantly limits the speed and abilities of these libraries. This can result in memory errors and scalability problems when applied to larger datasets. Some existing reconciliation libraries, such as existing Python packages, also do not compute an S-matrix or organize the forecast data. Thus, the techniques described herein can provide numerous technical improvements over existing reconciliation approaches.

These illustrative examples are given to introduce the reader to the general subject matter discussed here and are not intended to limit the scope of the disclosed concepts. The following sections describe various additional features and examples with reference to the drawings in which like numerals indicate like elements but, like the illustrative examples, should not be used to limit the present disclosure.

FIG. 1 is a block diagram that provides an illustration of the hardware components of a data transmission network 100, according to embodiments of the present technology. Data transmission network 100 is a specialized computer system that may be used for processing large amounts of data where a large number of computer processing cycles are required.

Data transmission network 100 may also include computing environment 114. Computing environment 114 may be a specialized computer or other machine that processes the data received within the data transmission network 100. Data transmission network 100 also includes one or more network devices 102. Network devices 102 may include client devices that attempt to communicate with computing environment 114. For example, network devices 102 may send data to the computing environment 114 to be processed, may send signals to the computing environment 114 to control different aspects of the computing environment or the data it is processing, among other reasons. Network devices 102 may interact with the computing environment 114 through a number of ways, such as, for example, over one or more networks 108. As shown in FIG. 1, computing environment 114 may include one or more other systems. For example, computing environment 114 may include a database system 118 and/or a communications grid 120.

In other embodiments, network devices 102 may provide a large amount of data, either all at once or streaming over a period of time (e.g., using event stream processing (ESP), described further with respect to FIGS. 8-10), to the computing environment 114 via networks 108. For example, network devices 102 may include network computers, sensors, databases, or other devices that may transmit or otherwise provide data to computing environment 114. For example, network devices 102 may include local area network devices, such as routers, hubs, switches, or other computer networking devices. These devices may provide a variety of stored or generated data, such as network data or data specific to the network devices themselves. Network devices 102 may also include sensors that monitor their environment or other devices to collect data regarding that

environment or those devices, and such network devices may provide data they collect over time. Network devices 102 may also include devices within the internet of things, such as devices within a home automation network. Some of these devices may be referred to as edge devices, and may involve edge computing circuitry. Data may be transmitted by network devices 102 directly to computing environment 114 or to network-attached data stores, such as network-attached data stores 110 for storage so that the data may be retrieved later by the computing environment 114 or other portions of data transmission network 100.

Data transmission network 100 may also include one or more network-attached data stores 110. Network-attached data stores 110 are used to store data to be processed by the computing environment 114 as well as any intermediate or final data generated by the computing system in non-volatile memory. However, in certain embodiments, the configuration of the computing environment 114 allows its operations to be performed such that intermediate and final data results can be stored solely in volatile memory (e.g., RAM), without a requirement that intermediate or final data results be stored to non-volatile types of memory (e.g., disk). This can be useful in certain situations, such as when the computing environment 114 receives ad hoc queries from a user and when responses, which are generated by processing large amounts of data, need to be generated on-the-fly. In this non-limiting situation, the computing environment 114 may be configured to retain the processed information within memory so that responses can be generated for the user at different levels of detail as well as allow a user to interactively query against this information.

Network-attached data stores 110 may store a variety of different types of data organized in a variety of different ways and from a variety of different sources. For example, network-attached data storage may include storage other than primary storage located within computing environment 114 that is directly accessible by processors located therein. Network-attached data storage may include secondary, tertiary or auxiliary storage, such as large hard drives, servers, virtual memory, among other types. Storage devices may include portable or non-portable storage devices, optical storage devices, and various other mediums capable of storing or containing data. A machine-readable storage medium or computer-readable storage medium may include a non-transitory medium in which data can be stored and that does not include carrier waves and/or transitory electronic signals. Examples of a non-transitory medium may include, for example, a magnetic disk or tape, optical storage media such as compact disk or digital versatile disk, flash memory, memory or memory devices. A computer-program product may include code and/or machine-executable instructions that may represent a procedure, a function, a subprogram, a program, a routine, a subroutine, a module, a software package, a class, or any combination of instructions, data structures, or program statements. A code segment may be coupled to another code segment or a hardware circuit by passing and/or receiving information, data, arguments, parameters, or memory contents. Information, arguments, parameters, data, etc. may be passed, forwarded, or transmitted via any suitable means including memory sharing, message passing, token passing, and network transmission, among others. Furthermore, the data stores may hold a variety of different types of data. For example, network-attached data stores 110 may hold unstructured (e.g., raw) data, such as manufacturing data (e.g., a database containing records identifying products being manufactured with parameter data for each product, such as colors and models)

or product sales databases (e.g., a database containing individual data records identifying details of individual product sales).

The unstructured data may be presented to the computing environment **114** in different forms such as a flat file or a conglomerate of data records, and may have data values and accompanying time stamps. The computing environment **114** may be used to analyze the unstructured data in a variety of ways to determine the best way to structure (e.g., hierarchically) that data, such that the structured data is tailored to a type of further analysis that a user wishes to perform on the data. For example, after being processed, the unstructured time stamped data may be aggregated by time (e.g., into daily time period units) to generate time series data and/or structured hierarchically according to one or more dimensions (e.g., parameters, attributes, and/or variables). For example, data may be stored in a hierarchical data structure, such as a ROLAP OR MOLAP database, or may be stored in another tabular form, such as in a flat-hierarchy form.

Data transmission network **100** may also include one or more server farms **106**. Computing environment **114** may route select communications or data to the one or more server farms **106** or one or more servers within the server farms. Server farms **106** can be configured to provide information in a predetermined manner. For example, server farms **106** may access data to transmit in response to a communication. Server farms **106** may be separately housed from each other device within data transmission network **100**, such as computing environment **114**, and/or may be part of a device or system.

Server farms **106** may host a variety of different types of data processing as part of data transmission network **100**. Server farms **106** may receive a variety of different data from network devices **102**, from computing environment **114**, from cloud network **116**, or from other sources. The data may have been obtained or collected from one or more sensors, as inputs from a control database, or may have been received as inputs from an external system or device. Server farms **106** may assist in processing the data by turning raw data into processed data based on one or more rules implemented by the server farms. For example, sensor data may be analyzed to determine changes in an environment over time or in real-time.

Data transmission network **100** may also include one or more cloud networks **116**. Cloud network **116** may include a cloud infrastructure system that provides cloud services. In certain embodiments, services provided by the cloud network **116** may include a host of services that are made available to users of the cloud infrastructure system on demand. Cloud network **116** is shown in FIG. **1** as being connected to computing environment **114** (and therefore having computing environment **114** as its client or user), but cloud network **116** may be connected to or utilized by any of the devices in FIG. **1**. Services provided by the cloud network can dynamically scale to meet the needs of its users. The cloud network **116** may include one or more computers, servers, and/or systems. In some embodiments, the computers, servers, and/or systems that make up the cloud network **116** are different from the user's own on-premises computers, servers, and/or systems. For example, the cloud network **116** may host an application, and a user may, via a communication network such as the Internet, on demand, order and use the application.

While each device, server and system in FIG. **1** is shown as a single device, it will be appreciated that multiple devices may instead be used. For example, a set of network

devices can be used to transmit various communications from a single user, or remote server may include a server stack. As another example, data may be processed as part of computing environment **114**.

Each communication within data transmission network **100** (e.g., between client devices, between servers **106** and computing environment **114** or between a server and a device) may occur over one or more networks **108**. Networks **108** may include one or more of a variety of different types of networks, including a wireless network, a wired network, or a combination of a wired and wireless network. Examples of suitable networks include the Internet, a personal area network, a local area network (LAN), a wide area network (WAN), or a wireless local area network (WLAN). A wireless network may include a wireless interface or combination of wireless interfaces. As an example, a network in the one or more networks **108** may include a short-range communication channel, such as a BLUETOOTH® communication channel or a BLUETOOTH® Low Energy communication channel. A wired network may include a wired interface. The wired and/or wireless networks may be implemented using routers, access points, bridges, gateways, or the like, to connect devices in the network **108**, as will be further described with respect to FIG. **2**. The one or more networks **108** can be incorporated entirely within or can include an intranet, an extranet, or a combination thereof. In one embodiment, communications between two or more systems and/or devices can be achieved by a secure communications protocol, such as secure sockets layer (SSL) or transport layer security (TLS). In addition, data and/or transactional details may be encrypted.

Some aspects may utilize the Internet of Things (IoT), where things (e.g., machines, devices, phones, sensors) can be connected to networks and the data from these things can be collected and processed within the things and/or external to the things. For example, the IoT can include sensors in many different devices, and high value analytics can be applied to identify hidden relationships and drive increased efficiencies. This can apply to both big data analytics and real-time (e.g., ESP) analytics. This will be described further below with respect to FIG. **2**.

As noted, computing environment **114** may include a communications grid **120** and a transmission network database system **118**. Communications grid **120** may be a grid-based computing system for processing large amounts of data. The transmission network database system **118** may be for managing, storing, and retrieving large amounts of data that are distributed to and stored in the one or more network-attached data stores **110** or other data stores that reside at different locations within the transmission network database system **118**. The compute nodes in the grid-based computing system **120** and the transmission network database system **118** may share the same processor hardware, such as processors that are located within computing environment **114**.

FIG. **2** illustrates an example network including an example set of devices communicating with each other over an exchange system and via a network, according to embodiments of the present technology. As noted, each communication within data transmission network **100** may occur over one or more networks. System **200** includes a network device **204** configured to communicate with a variety of types of client devices, for example client devices **230**, over a variety of types of communication channels.

As shown in FIG. **2**, network device **204** can transmit a communication over a network (e.g., a cellular network via

a base station). The communication can be routed to another network device, such as network devices **205-209**, via base station. The communication can also be routed to computing environment **214** via base station. For example, network device **204** may collect data either from its surrounding environment or from other network devices (such as network devices **205-209**) and transmit that data to computing environment **214**.

Although network devices **204-209** are shown in FIG. 2 as a mobile phone, laptop computer, tablet computer, temperature sensor, motion sensor, and audio sensor respectively, the network devices may be or include sensors that are sensitive to detecting characteristics of their environment. For example, the network devices may include sensors such as water sensors, power sensors, electrical current sensors, chemical sensors, optical sensors, pressure sensors, geographic or position sensors (e.g., GPS), velocity sensors, acceleration sensors, flow rate sensors, among others. Examples of characteristics that may be sensed include force, torque, load, strain, position, temperature, air pressure, fluid flow, chemical properties, resistance, electromagnetic fields, radiation, irradiance, proximity, acoustics, moisture, distance, speed, vibrations, acceleration, electrical potential, and electrical current, among others. The sensors may be mounted to various components used as part of a variety of different types of systems (e.g., an oil drilling operation). The network devices may detect and record data related to the environment that it monitors, and transmit that data to computing environment **214**.

As noted, one type of system that may include various sensors that collect data to be processed and/or transmitted to a computing environment according to certain embodiments includes an oil drilling system. For example, the one or more drilling operation sensors may include surface sensors that measure a hook load, a fluid rate, a temperature and a density in and out of the wellbore, a standpipe pressure, a surface torque, a rotation speed of a drill pipe, a rate of penetration, a mechanical specific energy, etc., and downhole sensors that measure a rotation speed of a bit, fluid densities, downhole torque, downhole vibration (axial, tangential, lateral), a weight applied at a drill bit, an annular pressure, a differential pressure, an azimuth, an inclination, a dog leg severity, a measured depth, a vertical depth, a downhole temperature, etc. Besides the raw data collected directly by the sensors, other data may include parameters either developed by the sensors or assigned to the system by a client or other controlling device. For example, one or more drilling operation control parameters may control settings such as a mud motor speed to flow ratio, a bit diameter, a predicted formation top, seismic data, weather data, etc. Other data may be generated using physical models such as an earth model, a weather model, a seismic model, a bottom hole assembly model, a well plan model, an annular friction model, etc. In addition to sensor and control settings, predicted outputs, of for example, the rate of penetration, mechanical specific energy, hook load, flow in fluid rate, flow out fluid rate, pump pressure, surface torque, rotation speed of the drill pipe, annular pressure, annular friction pressure, annular temperature, equivalent circulating density, etc. may also be stored in the data warehouse.

In another example, another type of system that may include various sensors that collect data to be processed and/or transmitted to a computing environment according to certain embodiments includes a home automation or similar automated network in a different environment, such as an office space, school, public space, sports venue, or a variety of other locations. Network devices in such an automated

network may include network devices that allow a user to access, control, and/or configure various home appliances located within the user's home (e.g., a television, radio, light, fan, humidifier, sensor, microwave, iron, and/or the like), or outside of the user's home (e.g., exterior motion sensors, exterior lighting, garage door openers, sprinkler systems, or the like). For example, network device **102** may include a home automation switch that may be coupled with a home appliance. In another embodiment, a network device can allow a user to access, control, and/or configure devices, such as office-related devices (e.g., copy machine, printer, or fax machine), audio and/or video related devices (e.g., a receiver, a speaker, a projector, a DVD player, or a television), media-playback devices (e.g., a compact disc player, a CD player, or the like), computing devices (e.g., a home computer, a laptop computer, a tablet, a personal digital assistant (PDA), a computing device, or a wearable device), lighting devices (e.g., a lamp or recessed lighting), devices associated with a security system, devices associated with an alarm system, devices that can be operated in an automobile (e.g., radio devices, navigation devices), and/or the like. Data may be collected from such various sensors in raw form, or data may be processed by the sensors to create parameters or other data either developed by the sensors based on the raw data or assigned to the system by a client or other controlling device.

In another example, another type of system that may include various sensors that collect data to be processed and/or transmitted to a computing environment according to certain embodiments includes a power or energy grid. A variety of different network devices may be included in an energy grid, such as various devices within one or more power plants, energy farms (e.g., wind farm, solar farm, among others) energy storage facilities, factories, homes and businesses of consumers, among others. One or more of such devices may include one or more sensors that detect energy gain or loss, electrical input or output or loss, and a variety of other efficiencies. These sensors may collect data to inform users of how the energy grid, and individual devices within the grid, may be functioning and how they may be made more efficient.

Network device sensors may also perform processing on data they collect before transmitting the data to the computing environment **114**, or before deciding whether to transmit data to the computing environment **114**. For example, network devices may determine whether data collected meets certain rules, for example by comparing data or values calculated from the data and comparing that data to one or more thresholds. The network device may use this data and/or comparisons to determine if the data should be transmitted to the computing environment **214** for further use or processing.

Computing environment **214** may include machines **220** and **240**. Although computing environment **214** is shown in FIG. 2 as having two machines, **220** and **240**, computing environment **214** may have only one machine or may have more than two machines. The machines that make up computing environment **214** may include specialized computers, servers, or other machines that are configured to individually and/or collectively process large amounts of data. The computing environment **214** may also include storage devices that include one or more databases of structured data, such as data organized in one or more hierarchies, or unstructured data. The databases may communicate with the processing devices within computing environment **214** to distribute data to them. Since network devices may transmit data to computing environment **214**,

that data may be received by the computing environment **214** and subsequently stored within those storage devices. Data used by computing environment **214** may also be stored in data stores **235**, which may also be a part of or connected to computing environment **214**.

Computing environment **214** can communicate with various devices via one or more routers **225** or other inter-network or intra-network connection components. For example, computing environment **214** may communicate with client devices **230** via one or more routers **225**. Computing environment **214** may collect, analyze and/or store data from or pertaining to communications, client device operations, client rules, and/or user-associated actions stored at one or more data stores **235**. Such data may influence communication routing to the devices within computing environment **214**, how data is stored or processed within computing environment **214**, among other actions.

Notably, various other devices can further be used to influence communication routing and/or processing between devices within computing environment **214** and with devices outside of computing environment **214**. For example, as shown in FIG. 2, computing environment **214** may include a machine **240** that is a web server. Thus, computing environment **214** can retrieve data of interest, such as client information (e.g., product information, client rules, etc.), technical product details, news, current or predicted weather, and so on.

In addition to computing environment **214** collecting data (e.g., as received from network devices, such as sensors, and client devices or other sources) to be processed as part of a big data analytics project, it may also receive data in real time as part of a streaming analytics environment. As noted, data may be collected using a variety of sources as communicated via different kinds of networks or locally. Such data may be received on a real-time streaming basis. For example, network devices may receive data periodically from network device sensors as the sensors continuously sense, monitor and track changes in their environments. Devices within computing environment **214** may also perform pre-analysis on data it receives to determine if the data received should be processed as part of an ongoing project. The data received and collected by computing environment **214**, no matter what the source or method or timing of receipt, may be processed over a period of time for a client to determine results data based on the client's needs and rules.

FIG. 3 illustrates a representation of a conceptual model of a communications protocol system, according to embodiments of the present technology. More specifically, FIG. 3 identifies operation of a computing environment in an Open Systems Interaction model that corresponds to various connection components. The model **300** shows, for example, how a computing environment, such as computing environment **314** (or computing environment **214** in FIG. 2) may communicate with other devices in its network, and control how communications between the computing environment and other devices are executed and under what conditions.

The model can include layers **301-307**. The layers are arranged in a stack. Each layer in the stack serves the layer one level higher than it (except for the application layer, which is the highest layer), and is served by the layer one level below it (except for the physical layer, which is the lowest layer). The physical layer is the lowest layer because it receives and transmits raw bites of data, and is the farthest layer from the user in a communications system. On the other hand, the application layer is the highest layer because it interacts directly with a software application.

As noted, the model includes a physical layer **301**. Physical layer **301** represents physical communication, and can define parameters of that physical communication. For example, such physical communication may come in the form of electrical, optical, or electromagnetic signals. Physical layer **301** also defines protocols that may control communications within a data transmission network.

Link layer **302** defines links and mechanisms used to transmit (i.e., move) data across a network. The link layer **302** manages node-to-node communications, such as within a grid computing environment. Link layer **302** can detect and correct errors (e.g., transmission errors in the physical layer **301**). Link layer **302** can also include a media access control (MAC) layer and logical link control (LLC) layer.

Network layer **303** defines the protocol for routing within a network. In other words, the network layer coordinates transferring data across nodes in a same network (e.g., such as a grid computing environment). Network layer **303** can also define the processes used to structure local addressing within the network.

Transport layer **304** can manage the transmission of data and the quality of the transmission and/or receipt of that data. Transport layer **304** can provide a protocol for transferring data, such as, for example, a Transmission Control Protocol (TCP). Transport layer **304** can assemble and disassemble data frames for transmission. The transport layer can also detect transmission errors occurring in the layers below it.

Session layer **305** can establish, maintain, and manage communication connections between devices on a network. In other words, the session layer controls the dialogues or nature of communications between network devices on the network. The session layer may also establish checkpointing, adjournment, termination, and restart procedures.

Presentation layer **306** can provide translation for communications between the application and network layers. In other words, this layer may encrypt, decrypt and/or format data based on data types and/or encodings known to be accepted by an application or network layer.

Application layer **307** interacts directly with software applications and end users, and manages communications between them. Application layer **307** can identify destinations, local resource states or availability and/or communication content or formatting using the applications.

Intra-network connection components **321** and **322** are shown to operate in lower levels, such as physical layer **301** and link layer **302**, respectively. For example, a hub can operate in the physical layer, a switch can operate in the link layer, and a router can operate in the network layer. Inter-network connection components **323** and **328** are shown to operate on higher levels, such as layers **303-307**. For example, routers can operate in the network layer and network devices can operate in the transport, session, presentation, and application layers.

As noted, a computing environment **314** can interact with and/or operate on, in various embodiments, one, more, all or any of the various layers. For example, computing environment **314** can interact with a hub (e.g., via the link layer) so as to adjust which devices the hub communicates with. The physical layer may be served by the link layer, so it may implement such data from the link layer. For example, the computing environment **314** may control which devices it will receive data from. For example, if the computing environment **314** knows that a certain network device has turned off, broken, or otherwise become unavailable or unreliable, the computing environment **314** may instruct the hub to prevent any data from being transmitted to the

computing environment **314** from that network device. Such a process may be beneficial to avoid receiving data that is inaccurate or that has been influenced by an uncontrolled environment. As another example, computing environment **314** can communicate with a bridge, switch, router or gateway and influence which device within the system (e.g., system **200**) the component selects as a destination. In some embodiments, computing environment **314** can interact with various layers by exchanging communications with equipment operating on a particular layer by routing or modifying existing communications. In another embodiment, such as in a grid computing environment, a node may determine how data within the environment should be routed (e.g., which node should receive certain data) based on certain parameters or information provided by other layers within the model.

As noted, the computing environment **314** may be a part of a communications grid environment, the communications of which may be implemented as shown in the protocol of FIG. 3. For example, referring back to FIG. 2, one or more of machines **220** and **240** may be part of a communications grid computing environment. A gridded computing environment may be employed in a distributed system with non-interactive workloads where data resides in memory on the machines, or compute nodes. In such an environment, analytic code, instead of a database management system, controls the processing performed by the nodes. Data is collocated by pre-distributing it to the grid nodes, and the analytic code on each node loads the local data into memory. Each node may be assigned a particular task such as a portion of a processing project, or to organize or control other nodes within the grid.

FIG. 4 illustrates a communications grid computing system **400** including a variety of control and worker nodes, according to embodiments of the present technology. Communications grid computing system **400** includes three control nodes and one or more worker nodes. Communications grid computing system **400** includes control nodes **402**, **404**, and **406**. The control nodes are communicatively connected via communication paths **451**, **453**, and **455**. Therefore, the control nodes may transmit information (e.g., related to the communications grid or notifications), to and receive information from each other. Although communications grid computing system **400** is shown in FIG. 4 as including three control nodes, the communications grid may include more or less than three control nodes.

Communications grid computing system (or just “communications grid”) **400** also includes one or more worker nodes. Shown in FIG. 4 are six worker nodes **410-420**. Although FIG. 4 shows six worker nodes, a communications grid according to embodiments of the present technology may include more or less than six worker nodes. The number of worker nodes included in a communications grid may be dependent upon how large the project or data set is being processed by the communications grid, the capacity of each worker node, the time designated for the communications grid to complete the project, among others. Each worker node within the communications grid **400** may be connected (wired or wirelessly, and directly or indirectly) to control nodes **402-406**. Therefore, each worker node may receive information from the control nodes (e.g., an instruction to perform work on a project) and may transmit information to the control nodes (e.g., a result from work performed on a project). Furthermore, worker nodes may communicate with each other (either directly or indirectly). For example, worker nodes may transmit data between each other related to a job being performed or an individual task within a job

being performed by that worker node. However, in certain embodiments, worker nodes may not, for example, be connected (communicatively or otherwise) to certain other worker nodes. In an embodiment, worker nodes may only be able to communicate with the control node that controls it, and may not be able to communicate with other worker nodes in the communications grid, whether they are other worker nodes controlled by the control node that controls the worker node, or worker nodes that are controlled by other control nodes in the communications grid.

A control node may connect with an external device with which the control node may communicate (e.g., a grid user, such as a server or computer, may connect to a controller of the grid). For example, a server or computer may connect to control nodes and may transmit a project or job to the node. The project may include a data set. The data set may be of any size. Once the control node receives such a project including a large data set, the control node may distribute the data set or projects related to the data set to be performed by worker nodes. Alternatively, for a project including a large data set, the data set may be received or stored by a machine other than a control node (e.g., a HADOOP® standard-compliant data node employing the HADOOP® Distributed File System, or HDFS).

Control nodes may maintain knowledge of the status of the nodes in the grid (i.e., grid status information), accept work requests from clients, subdivide the work across worker nodes, and coordinate the worker nodes, among other responsibilities. Worker nodes may accept work requests from a control node and provide the control node with results of the work performed by the worker node. A grid may be started from a single node (e.g., a machine, computer, server, etc.). This first node may be assigned or may start as the primary control node that will control any additional nodes that enter the grid.

When a project is submitted for execution (e.g., by a client or a controller of the grid) it may be assigned to a set of nodes. After the nodes are assigned to a project, a data structure (i.e., a communicator) may be created. The communicator may be used by the project for information to be shared between the project codes running on each node. A communication handle may be created on each node. A handle, for example, is a reference to the communicator that is valid within a single process on a single node, and the handle may be used when requesting communications between nodes.

A control node, such as control node **402**, may be designated as the primary control node. A server, computer or other external device may connect to the primary control node. Once the control node receives a project, the primary control node may distribute portions of the project to its worker nodes for execution. For example, when a project is initiated on communications grid **400**, primary control node **402** controls the work to be performed for the project in order to complete the project as requested or instructed. The primary control node may distribute work to the worker nodes based on various factors, such as which subsets or portions of projects may be completed most efficiently and in the correct amount of time. For example, a worker node may perform analysis on a portion of data that is already local to (e.g., stored on) the worker node. The primary control node also coordinates and processes the results of the work performed by each worker node after each worker node executes and completes its job. For example, the primary control node may receive a result from one or more worker nodes, and the control node may organize (e.g.,

collect and assemble) the results received and compile them to produce a complete result for the project received from the end user.

Any remaining control nodes, such as control nodes **404** and **406**, may be assigned as backup control nodes for the project. In an embodiment, backup control nodes may not control any portion of the project. Instead, backup control nodes may serve as a backup for the primary control node and take over as primary control node if the primary control node were to fail. If a communications grid were to include only a single control node, and the control node were to fail (e.g., the control node is shut off or breaks), then the communications grid as a whole may fail and any project or job being run on the communications grid may fail and may not complete. While the project may be run again, such a failure may cause a delay (severe delay in some cases, such as overnight delay) in completion of the project. Therefore, a grid with multiple control nodes, including a backup control node, may be beneficial.

To add another node or machine to the grid, the primary control node may open a pair of listening sockets, for example. A socket may be used to accept work requests from clients, and the second socket may be used to accept connections from other grid nodes. The primary control node may be provided with a list of other nodes (e.g., other machines, computers, servers) that will participate in the grid, and the role that each node will fill in the grid. Upon startup of the primary control node (e.g., the first node on the grid), the primary control node may use a network protocol to start the server process on every other node in the grid. Command line parameters, for example, may inform each node of one or more pieces of information, such as: the role that the node will have in the grid, the host name of the primary control node, and the port number on which the primary control node is accepting connections from peer nodes, among others. The information may also be provided in a configuration file, transmitted over a secure shell tunnel, or received from a configuration server, among others. While the other machines in the grid may not initially know about the configuration of the grid, that information may also be sent to each other node by the primary control node. Updates of the grid information may also be subsequently sent to those nodes.

For any control node other than the primary control node added to the grid, the control node may open three sockets. The first socket may accept work requests from clients, the second socket may accept connections from other grid members, and the third socket may connect (e.g., permanently) to the primary control node. When a control node (e.g., primary control node) receives a connection from another control node, it first checks to see if the peer node is in the list of configured nodes in the grid. If it is not on the list, the control node may clear the connection. If it is on the list, it may then attempt to authenticate the connection. If authentication is successful, the authenticating node may transmit information to its peer, such as the port number on which a node is listening for connections, the host name of the node, and information about how to authenticate the node, among other information. When a node, such as the new control node, receives information about another active node, it will check to see if it already has a connection to that other node. If it does not have a connection to that node, it may then establish a connection to that control node.

Any worker node added to the grid may establish a connection to the primary control node and any other control nodes on the grid. After establishing the connection, it may authenticate itself to the grid (e.g., any control nodes,

including both primary and backup, or a server or user controlling the grid). After successful authentication, the worker node may accept configuration information from the control node.

When a node joins a communications grid (e.g., when the node is powered on or connected to an existing node on the grid or both), the node is assigned (e.g., by an operating system of the grid) a universally unique identifier (UUID). This unique identifier may help other nodes and external entities (devices, users, etc.) to identify the node and distinguish it from other nodes. When a node is connected to the grid, the node may share its unique identifier with the other nodes in the grid. Since each node may share its unique identifier, each node may know the unique identifier of every other node on the grid. Unique identifiers may also designate a hierarchy of each of the nodes (e.g., backup control nodes) within the grid. For example, the unique identifiers of each of the backup control nodes may be stored in a list of backup control nodes to indicate an order in which the backup control nodes will take over for a failed primary control node to become a new primary control node. However, a hierarchy of nodes may also be determined using methods other than using the unique identifiers of the nodes. For example, the hierarchy may be predetermined, or may be assigned based on other predetermined factors.

The grid may add new machines at any time (e.g., initiated from any control node). Upon adding a new node to the grid, the control node may first add the new node to its table of grid nodes. The control node may also then notify every other control node about the new node. The nodes receiving the notification may acknowledge that they have updated their configuration information.

Primary control node **402** may, for example, transmit one or more communications to backup control nodes **404** and **406** (and, for example, to other control or worker nodes within the communications grid). Such communications may be sent periodically, at fixed time intervals, between known fixed stages of the project's execution, among other protocols. The communications transmitted by primary control node **402** may be of varied types and may include a variety of types of information. For example, primary control node **402** may transmit snapshots (e.g., status information) of the communications grid so that backup control node **404** always has a recent snapshot of the communications grid. The snapshot or grid status may include, for example, the structure of the grid (including, for example, the worker nodes in the grid, unique identifiers of the nodes, or their relationships with the primary control node) and the status of a project (including, for example, the status of each worker node's portion of the project). The snapshot may also include analysis or results received from worker nodes in the communications grid. The backup control nodes may receive and store the backup data received from the primary control node. The backup control nodes may transmit a request for such a snapshot (or other information) from the primary control node, or the primary control node may send such information periodically to the backup control nodes.

As noted, the backup data may allow the backup control node to take over as primary control node if the primary control node fails without requiring the grid to start the project over from scratch. If the primary control node fails, the backup control node that will take over as primary control node may retrieve the most recent version of the snapshot received from the primary control node and use the snapshot to continue the project from the stage of the project indicated by the backup data. This may prevent failure of the project as a whole.

A backup control node may use various methods to determine that the primary control node has failed. In one example of such a method, the primary control node may transmit (e.g., periodically) a communication to the backup control node that indicates that the primary control node is working and has not failed, such as a heartbeat communication. The backup control node may determine that the primary control node has failed if the backup control node has not received a heartbeat communication for a certain predetermined period of time. Alternatively, a backup control node may also receive a communication from the primary control node itself (before it failed) or from a worker node that the primary control node has failed, for example because the primary control node has failed to communicate with the worker node.

Different methods may be performed to determine which backup control node of a set of backup control nodes (e.g., backup control nodes **404** and **406**) will take over for failed primary control node **402** and become the new primary control node. For example, the new primary control node may be chosen based on a ranking or "hierarchy" of backup control nodes based on their unique identifiers. In an alternative embodiment, a backup control node may be assigned to be the new primary control node by another device in the communications grid or from an external device (e.g., a system infrastructure or an end user, such as a server or computer, controlling the communications grid). In another alternative embodiment, the backup control node that takes over as the new primary control node may be designated based on bandwidth or other statistics about the communications grid.

A worker node within the communications grid may also fail. If a worker node fails, work being performed by the failed worker node may be redistributed amongst the operational worker nodes. In an alternative embodiment, the primary control node may transmit a communication to each of the operable worker nodes still on the communications grid that each of the worker nodes should purposefully fail also. After each of the worker nodes fail, they may each retrieve their most recent saved checkpoint of their status and re-start the project from that checkpoint to minimize lost progress on the project being executed.

FIG. 5 illustrates a flow chart showing an example process **500** for adjusting a communications grid or a work project in a communications grid after a failure of a node, according to embodiments of the present technology. The process may include, for example, receiving grid status information including a project status of a portion of a project being executed by a node in the communications grid, as described in operation **502**. For example, a control node (e.g., a backup control node connected to a primary control node and a worker node on a communications grid) may receive grid status information, where the grid status information includes a project status of the primary control node or a project status of the worker node. The project status of the primary control node and the project status of the worker node may include a status of one or more portions of a project being executed by the primary and worker nodes in the communications grid. The process may also include storing the grid status information, as described in operation **504**. For example, a control node (e.g., a backup control node) may store the received grid status information locally within the control node. Alternatively, the grid status information may be sent to another device for storage where the control node may have access to the information.

The process may also include receiving a failure communication corresponding to a node in the communications grid

in operation **506**. For example, a node may receive a failure communication including an indication that the primary control node has failed, prompting a backup control node to take over for the primary control node. In an alternative embodiment, a node may receive a failure that a worker node has failed, prompting a control node to reassign the work being performed by the worker node. The process may also include reassigning a node or a portion of the project being executed by the failed node, as described in operation **508**. For example, a control node may designate the backup control node as a new primary control node based on the failure communication upon receiving the failure communication. If the failed node is a worker node, a control node may identify a project status of the failed worker node using the snapshot of the communications grid, where the project status of the failed worker node includes a status of a portion of the project being executed by the failed worker node at the failure time.

The process may also include receiving updated grid status information based on the reassignment, as described in operation **510**, and transmitting a set of instructions based on the updated grid status information to one or more nodes in the communications grid, as described in operation **512**. The updated grid status information may include an updated project status of the primary control node or an updated project status of the worker node. The updated information may be transmitted to the other nodes in the grid to update their stale stored information.

FIG. 6 illustrates a portion of a communications grid computing system **600** including a control node and a worker node, according to embodiments of the present technology. Communications grid computing system **600** includes one control node (control node **602**) and one worker node (worker node **610**) for purposes of illustration, but may include more worker and/or control nodes. The control node **602** is communicatively connected to worker node **610** via communication path **650**. Therefore, control node **602** may transmit information (e.g., related to the communications grid or notifications), to and receive information from worker node **610** via path **650**.

Similar to in FIG. 4, communications grid computing system (or just "communications grid") **600** includes data processing nodes (control node **602** and worker node **610**). Nodes **602** and **610** include multi-core data processors. Each node **602** and **610** includes a grid-enabled software component (GES) **620** that executes on the data processor associated with that node and interfaces with buffer memory **622** also associated with that node. Each node **602** and **610** includes database management software (DBMS) **628** that executes on a database server (not shown) at control node **602** and on a database server (not shown) at worker node **610**.

Each node also includes a data store **624**. Data stores **624**, similar to network-attached data stores **110** in FIG. 1 and data stores **235** in FIG. 2, are used to store data to be processed by the nodes in the computing environment. Data stores **624** may also store any intermediate or final data generated by the computing system after being processed, for example in non-volatile memory. However in certain embodiments, the configuration of the grid computing environment allows its operations to be performed such that intermediate and final data results can be stored solely in volatile memory (e.g., RAM), without a requirement that intermediate or final data results be stored to non-volatile types of memory. Storing such data in volatile memory may be useful in certain situations, such as when the grid receives queries (e.g., ad hoc) from a client and when responses,

which are generated by processing large amounts of data, need to be generated quickly or on-the-fly. In such a situation, the grid may be configured to retain the data within memory so that responses can be generated at different levels of detail and so that a client may interactively query against this information.

Each node also includes a user-defined function (UDF) **626**. The UDF provides a mechanism for the DBMS **628** to transfer data to or receive data from the database stored in the data stores **624** that are managed by the DBMS **628**. For example, UDF **626** can be invoked by the DBMS **628** to provide data to the GESC **620** for processing. The UDF **626** may establish a socket connection (not shown) with the GESC **620** to transfer the data. Alternatively, the UDF **626** can transfer data to the GESC **620** by writing data to shared memory accessible by both the UDF **626** and the GESC **620**.

The GESC **620** at the nodes **602** and **610** may be connected via a network, such as network **108** shown in FIG. 1. Therefore, nodes **602** and **610** can communicate with each other via the network using a predetermined communication protocol such as, for example, the Message Passing Interface (MPI). Each GESC **620** can engage in point-to-point communication with the GESC at another node or in collective communication with multiple GESCs via the network. The GESC **620** at each node may contain identical (or nearly identical) software instructions. Each node may be capable of operating as either a control node or a worker node. The GESC at the control node **602** can communicate, over a communication path **652**, with a client device **630**. More specifically, control node **602** may communicate with client application **632** hosted by the client device **630** to receive queries and to respond to those queries after processing large amounts of data.

DBMS **628** may control the creation, maintenance, and use of database or data structure (not shown) within a nodes **602** or **610**. The database may organize data stored in data stores **624**. The DBMS **628** at control node **602** may accept requests for data and transfer the appropriate data for the request. With such a process, collections of data may be distributed across multiple physical locations. In this example, each node **602** and **610** stores a portion of the total data managed by the management system in its associated data store **624**.

Furthermore, the DBMS may be responsible for protecting against data loss using replication techniques. Replication includes providing a backup copy of data stored on one node on one or more other nodes. Therefore, if one node fails, the data from the failed node can be recovered from a replicated copy residing at another node. However, as described herein with respect to FIG. 4, data or status information for each node in the communications grid may also be shared with each node on the grid.

FIG. 7 illustrates a flow chart showing an example method **700** for executing a project within a grid computing system, according to embodiments of the present technology. As described with respect to FIG. 6, the GESC at the control node may transmit data with a client device (e.g., client device **630**) to receive queries for executing a project and to respond to those queries after large amounts of data have been processed. The query may be transmitted to the control node, where the query may include a request for executing a project, as described in operation **702**. The query can contain instructions on the type of data analysis to be performed in the project and whether the project should be executed using the grid-based computing environment, as shown in operation **704**.

To initiate the project, the control node may determine if the query requests use of the grid-based computing environment to execute the project. If the determination is no, then the control node initiates execution of the project in a solo environment (e.g., at the control node), as described in operation **710**. If the determination is yes, the control node may initiate execution of the project in the grid-based computing environment, as described in operation **706**. In such a situation, the request may include a requested configuration of the grid. For example, the request may include a number of control nodes and a number of worker nodes to be used in the grid when executing the project. After the project has been completed, the control node may transmit results of the analysis yielded by the grid, as described in operation **708**. Whether the project is executed in a solo or grid-based environment, the control node provides the results of the project, as described in operation **712**.

As noted with respect to FIG. 2, the computing environments described herein may collect data (e.g., as received from network devices, such as sensors, such as network devices **204-209** in FIG. 2, and client devices or other sources) to be processed as part of a data analytics project, and data may be received in real time as part of a streaming analytics environment (e.g., ESP). Data may be collected using a variety of sources as communicated via different kinds of networks or locally, such as on a real-time streaming basis. For example, network devices may receive data periodically from network device sensors as the sensors continuously sense, monitor and track changes in their environments. More specifically, an increasing number of distributed applications develop or produce continuously flowing data from distributed sources by applying queries to the data before distributing the data to geographically distributed recipients. An event stream processing engine (ESPE) may continuously apply the queries to the data as it is received and determines which entities should receive the data. Client or other devices may also subscribe to the ESPE or other devices processing ESP data so that they can receive data after processing, based on for example the entities determined by the processing engine. For example, client devices **230** in FIG. 2 may subscribe to the ESPE in computing environment **214**. In another example, event subscription devices **1024a-c**, described further with respect to FIG. 10, may also subscribe to the ESPE. The ESPE may determine or define how input data or event streams from network devices or other publishers (e.g., network devices **204-209** in FIG. 2) are transformed into meaningful output data to be consumed by subscribers, such as for example client devices **230** in FIG. 2.

FIG. 8 illustrates a block diagram including components of an Event Stream Processing Engine (ESPE), according to embodiments of the present technology. ESPE **800** may include one or more projects **802**. A project may be described as a second-level container in an engine model managed by ESPE **800** where a thread pool size for the project may be defined by a user. Each project of the one or more projects **802** may include one or more continuous queries **804** that contain data flows, which are data transformations of incoming event streams. The one or more continuous queries **804** may include one or more source windows **806** and one or more derived windows **808**.

The ESPE may receive streaming data over a period of time related to certain events, such as events or other data sensed by one or more network devices. The ESPE may perform operations associated with processing data created by the one or more devices. For example, the ESPE may receive data from the one or more network devices **204-209**

shown in FIG. 2. As noted, the network devices may include sensors that sense different aspects of their environments, and may collect data over time based on those sensed observations. For example, the ESPE may be implemented within one or more of machines 220 and 240 shown in FIG. 2. The ESPE may be implemented within such a machine by an ESP application. An ESP application may embed an ESPE with its own dedicated thread pool or pools into its application space where the main application thread can do application-specific work and the ESPE processes event streams at least by creating an instance of a model into processing objects.

The engine container is the top-level container in a model that manages the resources of the one or more projects 802. In an illustrative embodiment, for example, there may be only one ESPE 800 for each instance of the ESP application, and ESPE 800 may have a unique engine name. Additionally, the one or more projects 802 may each have unique project names, and each query may have a unique continuous query name and begin with a uniquely named source window of the one or more source windows 806. ESPE 800 may or may not be persistent.

Continuous query modeling involves defining directed graphs of windows for event stream manipulation and transformation. A window in the context of event stream manipulation and transformation is a processing node in an event stream processing model. A window in a continuous query can perform aggregations, computations, pattern-matching, and other operations on data flowing through the window. A continuous query may be described as a directed graph of source, relational, pattern matching, and procedural windows. The one or more source windows 806 and the one or more derived windows 808 represent continuously executing queries that generate updates to a query result set as new event blocks stream through ESPE 800. A directed graph, for example, is a set of nodes connected by edges, where the edges have a direction associated with them.

An event object may be described as a packet of data accessible as a collection of fields, with at least one of the fields defined as a key or unique identifier (ID). The event object may be created using a variety of formats including binary, alphanumeric, XML, etc. Each event object may include one or more fields designated as a primary identifier (ID) for the event so ESPE 800 can support operation codes (opcodes) for events including insert, update, upsert, and delete. Upsert opcodes update the event if the key field already exists; otherwise, the event is inserted. For illustration, an event object may be a packed binary representation of a set of field values and include both metadata and field data associated with an event. The metadata may include an opcode indicating if the event represents an insert, update, delete, or upsert, a set of flags indicating if the event is a normal, partial-update, or a retention generated event from retention policy management, and a set of microsecond timestamps that can be used for latency measurements.

An event block object may be described as a grouping or package of event objects. An event stream may be described as a flow of event block objects. A continuous query of the one or more continuous queries 804 transforms a source event stream made up of streaming event block objects published into ESPE 800 into one or more output event streams using the one or more source windows 806 and the one or more derived windows 808. A continuous query can also be thought of as data flow modeling.

The one or more source windows 806 are at the top of the directed graph and have no windows feeding into them. Event streams are published into the one or more source

windows 806, and from there, the event streams may be directed to the next set of connected windows as defined by the directed graph. The one or more derived windows 808 are all instantiated windows that are not source windows and that have other windows streaming events into them. The one or more derived windows 808 may perform computations or transformations on the incoming event streams. The one or more derived windows 808 transform event streams based on the window type (that is operators such as join, filter, compute, aggregate, copy, pattern match, procedural, union, etc.) and window settings. As event streams are published into ESPE 800, they are continuously queried, and the resulting sets of derived windows in these queries are continuously updated.

FIG. 9 illustrates a flow chart showing an example process including operations performed by an event stream processing engine, according to some embodiments of the present technology. As noted, the ESPE 800 (or an associated ESP application) defines how input event streams are transformed into meaningful output event streams. More specifically, the ESP application may define how input event streams from publishers (e.g., network devices providing sensed data) are transformed into meaningful output event streams consumed by subscribers (e.g., a data analytics project being executed by a machine or set of machines).

Within the application, a user may interact with one or more user interface windows presented to the user in a display under control of the ESPE independently or through a browser application in an order selectable by the user. For example, a user may execute an ESP application, which causes presentation of a first user interface window, which may include a plurality of menus and selectors such as drop down menus, buttons, text boxes, hyperlinks, etc. associated with the ESP application as understood by a person of skill in the art. As further understood by a person of skill in the art, various operations may be performed in parallel, for example, using a plurality of threads.

At operation 900, an ESP application may define and start an ESPE, thereby instantiating an ESPE at a device, such as machine 220 and/or 240. In an operation 902, the engine container is created. For illustration, ESPE 800 may be instantiated using a function call that specifies the engine container as a manager for the model.

In an operation 904, the one or more continuous queries 804 are instantiated by ESPE 800 as a model. The one or more continuous queries 804 may be instantiated with a dedicated thread pool or pools that generate updates as new events stream through ESPE 800. For illustration, the one or more continuous queries 804 may be created to model business processing logic within ESPE 800, to predict events within ESPE 800, to model a physical system within ESPE 800, to predict the physical system state within ESPE 800, etc. For example, as noted, ESPE 800 may be used to support sensor data monitoring and management (e.g., sensing may include force, torque, load, strain, position, temperature, air pressure, fluid flow, chemical properties, resistance, electromagnetic fields, radiation, irradiance, proximity, acoustics, moisture, distance, speed, vibrations, acceleration, electrical potential, or electrical current, etc.).

ESPE 800 may analyze and process events in motion or "event streams." Instead of storing data and running queries against the stored data, ESPE 800 may store queries and stream data through them to allow continuous analysis of data as it is received. The one or more source windows 806 and the one or more derived windows 808 may be created based on the relational, pattern matching, and procedural algorithms that transform the input event streams into the

output event streams to model, simulate, score, test, predict, etc. based on the continuous query model defined and application to the streamed data.

In an operation **906**, a publish/subscribe (pub/sub) capability is initialized for ESPE **800**. In an illustrative embodiment, a pub/sub capability is initialized for each project of the one or more projects **802**. To initialize and enable pub/sub capability for ESPE **800**, a port number may be provided. Pub/sub clients can use a host name of an ESP device running the ESPE and the port number to establish pub/sub connections to ESPE **800**.

FIG. **10** illustrates an ESP system **1000** interfacing between publishing device **1022** and event subscribing devices **1024a-c**, according to embodiments of the present technology. ESP system **1000** may include ESP device or subsystem **1001**, event publishing device **1022**, an event subscribing device A **1024a**, an event subscribing device B **1024b**, and an event subscribing device C **1024c**. Input event streams are output to ESP subsystem **1001** by publishing device **1022**. In alternative embodiments, the input event streams may be created by a plurality of publishing devices. The plurality of publishing devices further may publish event streams to other ESP devices. The one or more continuous queries instantiated by ESPE **800** may analyze and process the input event streams to form output event streams output to event subscribing device A **1024a**, event subscribing device B **1024b**, and event subscribing device C **1024c**. ESP system **1000** may include a greater or a fewer number of event subscribing devices of event subscribing devices.

Publish-subscribe is a message-oriented interaction paradigm based on indirect addressing. Processed data recipients specify their interest in receiving information from ESPE **800** by subscribing to specific classes of events, while information sources publish events to ESPE **800** without directly addressing the receiving parties. ESPE **800** coordinates the interactions and processes the data. In some cases, the data source receives confirmation that the published information has been received by a data recipient.

A publish/subscribe API may be described as a library that enables an event publisher, such as publishing device **1022**, to publish event streams into ESPE **800** or an event subscriber, such as event subscribing device A **1024a**, event subscribing device B **1024b**, and event subscribing device C **1024c**, to subscribe to event streams from ESPE **800**. For illustration, one or more publish/subscribe APIs may be defined. Using the publish/subscribe API, an event publishing application may publish event streams into a running event stream processor project source window of ESPE **800**, and the event subscription application may subscribe to an event stream processor project source window of ESPE **800**.

The publish/subscribe API provides cross-platform connectivity and endianness compatibility between ESP application and other networked applications, such as event publishing applications instantiated at publishing device **1022**, and event subscription applications instantiated at one or more of event subscribing device A **1024a**, event subscribing device B **1024b**, and event subscribing device C **1024c**.

Referring back to FIG. **9**, operation **906** initializes the publish/subscribe capability of ESPE **800**. In an operation **908**, the one or more projects **802** are started. The one or more started projects may run in the background on an ESP device. In an operation **910**, an event block object is received from one or more computing device of the event publishing device **1022**.

ESP subsystem **1001** may include a publishing client **1002**, ESPE **800**, a subscribing client A **1004**, a subscribing client B **1006**, and a subscribing client C **1008**. Publishing client **1002** may be started by an event publishing application executing at publishing device **1022** using the publish/subscribe API. Subscribing client A **1004** may be started by an event subscription application A, executing at event subscribing device A **1024a** using the publish/subscribe API. Subscribing client B **1006** may be started by an event subscription application B executing at event subscribing device B **1024b** using the publish/subscribe API. Subscribing client C **1008** may be started by an event subscription application C executing at event subscribing device C **1024c** using the publish/subscribe API.

An event block object containing one or more event objects is injected into a source window of the one or more source windows **806** from an instance of an event publishing application on event publishing device **1022**. The event block object may be generated, for example, by the event publishing application and may be received by publishing client **1002**. A unique ID may be maintained as the event block object is passed between the one or more source windows **806** and/or the one or more derived windows **808** of ESPE **800**, and to subscribing client A **1004**, subscribing client B **1006**, and subscribing client C **1008** and to event subscription device A **1024a**, event subscription device B **1024b**, and event subscription device C **1024c**. Publishing client **1002** may further generate and include a unique embedded transaction ID in the event block object as the event block object is processed by a continuous query, as well as the unique ID that publishing device **1022** assigned to the event block object.

In an operation **912**, the event block object is processed through the one or more continuous queries **804**. In an operation **914**, the processed event block object is output to one or more computing devices of the event subscribing devices **1024a-c**. For example, subscribing client A **1004**, subscribing client B **1006**, and subscribing client C **1008** may send the received event block object to event subscription device A **1024a**, event subscription device B **1024b**, and event subscription device C **1024c**, respectively.

ESPE **800** maintains the event block containership aspect of the received event blocks from when the event block is published into a source window and works its way through the directed graph defined by the one or more continuous queries **804** with the various event translations before being output to subscribers. Subscribers can correlate a group of subscribed events back to a group of published events by comparing the unique ID of the event block object that a publisher, such as publishing device **1022**, attached to the event block object with the event block ID received by the subscriber.

In an operation **916**, a determination is made concerning whether or not processing is stopped. If processing is not stopped, processing continues in operation **910** to continue receiving the one or more event streams containing event block objects from the, for example, one or more network devices. If processing is stopped, processing continues in an operation **918**. In operation **918**, the started projects are stopped. In operation **920**, the ESPE is shutdown.

As noted, in some embodiments, big data is processed for an analytics project after the data is received and stored. In other embodiments, distributed applications process continuously flowing data in real-time from distributed sources by applying queries to the data before distributing the data to geographically distributed recipients. As noted, an event stream processing engine (ESPE) may continuously apply

the queries to the data as it is received and determines which entities receive the processed data. This allows for large amounts of data being received and/or collected in a variety of environments to be processed and distributed in real time. For example, as shown with respect to FIG. 2, data may be collected from network devices that may include devices within the internet of things, such as devices within a home automation network. However, such data may be collected from a variety of different resources in a variety of different environments. In any such situation, embodiments of the present technology allow for real-time processing of such data.

Aspects of the current disclosure provide technical solutions to technical problems, such as computing problems that arise when an ESP device fails which results in a complete service interruption and potentially significant data loss. The data loss can be catastrophic when the streamed data is supporting mission critical operations such as those in support of an ongoing manufacturing or drilling operation. An embodiment of an ESP system achieves a rapid and seamless failover of ESPE running at the plurality of ESP devices without service interruption or data loss, thus significantly improving the reliability of an operational system that relies on the live or real-time processing of the data streams. The event publishing systems, the event subscribing systems, and each ESPE not executing at a failed ESP device are not aware of or effected by the failed ESP device. The ESP system may include thousands of event publishing systems and event subscribing systems. The ESP system keeps the failover logic and awareness within the boundaries of out-messaging network connector and out-messaging network device.

In one example embodiment, a system is provided to support a failover when event stream processing (ESP) event blocks. The system includes, but is not limited to, an out-messaging network device and a computing device. The computing device includes, but is not limited to, a processor and a computer-readable medium operably coupled to the processor. The processor is configured to execute an ESP engine (ESPE). The computer-readable medium has instructions stored thereon that, when executed by the processor, cause the computing device to support the failover. An event block object is received from the ESPE that includes a unique identifier. A first status of the computing device as active or standby is determined. When the first status is active, a second status of the computing device as newly active or not newly active is determined. Newly active is determined when the computing device is switched from a standby status to an active status. When the second status is newly active, a last published event block object identifier that uniquely identifies a last published event block object is determined. A next event block object is selected from a non-transitory computer-readable medium accessible by the computing device. The next event block object has an event block object identifier that is greater than the determined last published event block object identifier. The selected next event block object is published to an out-messaging network device. When the second status of the computing device is not newly active, the received event block object is published to the out-messaging network device. When the first status of the computing device is standby, the received event block object is stored in the non-transitory computer-readable medium.

FIG. 11 is a flow chart of an example of a process for generating and using a machine-learning model according to some aspects. Machine learning is a branch of artificial intelligence that relates to mathematical models that can

learn from, categorize, and make predictions about data. Such mathematical models, which can be referred to as machine-learning models, can classify input data among two or more classes; cluster input data among two or more groups; predict a result based on input data; identify patterns or trends in input data; identify a distribution of input data in a space; or any combination of these. Examples of machine-learning models can include (i) neural networks; (ii) decision trees, such as classification trees and regression trees; (iii) classifiers, such as Naïve bias classifiers, logistic regression classifiers, ridge regression classifiers, random forest classifiers, least absolute shrinkage and selector (LASSO) classifiers, and support vector machines; (iv) clusterers, such as k-means clusterers, mean-shift clusterers, and spectral clusterers; (v) factorizers, such as factorization machines, principal component analyzers and kernel principal component analyzers; and (vi) ensembles or other combinations of machine-learning models. In some examples, neural networks can include deep neural networks, feed-forward neural networks, recurrent neural networks, convolutional neural networks, radial basis function (RBF) neural networks, echo state neural networks, long short-term memory neural networks, bi-directional recurrent neural networks, gated neural networks, hierarchical recurrent neural networks, stochastic neural networks, modular neural networks, spiking neural networks, dynamic neural networks, cascading neural networks, neuro-fuzzy neural networks, or any combination of these.

Different machine-learning models may be used interchangeably to perform a task. Examples of tasks that can be performed at least partially using machine-learning models include various types of scoring; bioinformatics; cheminformatics; software engineering; fraud detection; customer segmentation; generating online recommendations; adaptive websites; determining customer lifetime value; search engines; placing advertisements in real time or near real time; classifying DNA sequences; affective computing; performing natural language processing and understanding; object recognition and computer vision; robotic locomotion; playing games; optimization and metaheuristics; detecting network intrusions; medical diagnosis and monitoring; or predicting when an asset, such as a machine, will need maintenance.

Any number and combination of tools can be used to create machine-learning models. Examples of tools for creating and managing machine-learning models can include SAS® Enterprise Miner, SAS® Rapid Predictive Modeler, and SAS® Model Manager, SAS Cloud Analytic Services (CAS)®, SAS Viya® of all which are by SAS Institute Inc. of Cary, North Carolina.

Machine-learning models can be constructed through an at least partially automated (e.g., with little or no human involvement) process called training. During training, input data can be iteratively supplied to a machine-learning model to enable the machine-learning model to identify patterns related to the input data or to identify relationships between the input data and output data. With training, the machine-learning model can be transformed from an untrained state to a trained state. Input data can be split into one or more training sets and one or more validation sets, and the training process may be repeated multiple times. The splitting may follow a k-fold cross-validation rule, a leave-one-out-rule, a leave-p-out rule, or a holdout rule. An overview of training and using a machine-learning model is described below with respect to the flow chart of FIG. 11.

In block 1102, training data is received. In some examples, the training data is received from a remote

database or a local database, constructed from various subsets of data, or input by a user. The training data can be used in its raw form for training a machine-learning model or pre-processed into another form, which can then be used for training the machine-learning model. For example, the raw form of the training data can be smoothed, truncated, aggregated, clustered, or otherwise manipulated into another form, which can then be used for training the machine-learning model.

In block 1104, a machine-learning model is trained using the training data. The machine-learning model can be trained in a supervised, unsupervised, or semi-supervised manner. In supervised training, each input in the training data is correlated to a desired output. This desired output may be a scalar, a vector, or a different type of data structure such as text or an image. This may enable the machine-learning model to learn a mapping between the inputs and desired outputs. In unsupervised training, the training data includes inputs, but not desired outputs, so that the machine-learning model has to find structure in the inputs on its own. In semi-supervised training, only some of the inputs in the training data are correlated to desired outputs.

In block 1106, the machine-learning model is evaluated. For example, an evaluation dataset can be obtained, for example, via user input or from a database. The evaluation dataset can include inputs correlated to desired outputs. The inputs can be provided to the machine-learning model and the outputs from the machine-learning model can be compared to the desired outputs. If the outputs from the machine-learning model closely correspond with the desired outputs, the machine-learning model may have a high degree of accuracy. For example, if 90% or more of the outputs from the machine-learning model are the same as the desired outputs in the evaluation dataset, the machine-learning model may have a high degree of accuracy. Otherwise, the machine-learning model may have a low degree of accuracy. The 90% number is an example only. A realistic and desirable accuracy percentage is dependent on the problem and the data.

In some examples, if, at block 1108, the machine-learning model has an inadequate degree of accuracy for a particular task, the process can return to block 1104, where the machine-learning model can be further trained using additional training data or otherwise modified to improve accuracy. However, if, at block 1108, the machine-learning model has an adequate degree of accuracy for the particular task, the process can continue to block 1110.

In block 1110, new data is received. In some examples, the new data is received from a remote database or a local database, constructed from various subsets of data, or input by a user. The new data may be unknown to the machine-learning model. For example, the machine-learning model may not have previously processed or analyzed the new data.

In block 1112, the trained machine-learning model is used to analyze the new data and provide a result. For example, the new data can be provided as input to the trained machine-learning model. The trained machine-learning model can analyze the new data and provide a result that includes a classification of the new data into a particular class, a clustering of the new data into a particular group, a prediction based on the new data, or any combination of these.

In block 1114, the result is post-processed. For example, the result can be added to, multiplied with, or otherwise combined with other data as part of a job. As another example, the result can be transformed from a first format,

such as a time series format, into another format, such as a count series format. Any number and combination of operations can be performed on the result during post-processing.

A more specific example of a machine-learning model is the neural network 1200 shown in FIG. 12. The neural network 1200 is represented as multiple layers of neurons 1208 that can exchange data between one another via connections 1255 that may be selectively instantiated thereamong. The layers include an input layer 1202 for receiving input data provided at inputs 1222, one or more hidden layers 1204, and an output layer 1206 for providing a result at outputs 1277. The hidden layer(s) 1204 are referred to as hidden because they may not be directly observable or have their inputs or outputs directly accessible during the normal functioning of the neural network 1200. Although the neural network 1200 is shown as having a specific number of layers and neurons for exemplary purposes, the neural network 1200 can have any number and combination of layers, and each layer can have any number and combination of neurons.

The neurons 1208 and connections 1255 thereamong may have numeric weights, which can be tuned during training of the neural network 1200. For example, training data can be provided to at least the inputs 1222 to the input layer 1202 of the neural network 1200, and the neural network 1200 can use the training data to tune one or more numeric weights of the neural network 1200. In some examples, the neural network 1200 can be trained using backpropagation. Backpropagation can include determining a gradient of a particular numeric weight based on a difference between an actual output of the neural network 1200 at the outputs 1277 and a desired output of the neural network 1200. Based on the gradient, one or more numeric weights of the neural network 1200 can be updated to reduce the difference therebetween, thereby increasing the accuracy of the neural network 1200. This process can be repeated multiple times to train the neural network 1200. For example, this process can be repeated hundreds or thousands of times to train the neural network 1200.

In some examples, the neural network 1200 is a feed-forward neural network. In a feed-forward neural network, the connections 1255 are instantiated and/or weighted so that every neuron 1208 only propagates an output value to a subsequent layer of the neural network 1200. For example, data may only move one direction (forward) from one neuron 1208 to the next neuron 1208 in a feed-forward neural network. Such a “forward” direction may be defined as proceeding from the input layer 1202 through the one or more hidden layers 1204, and toward the output layer 1206.

In other examples, the neural network 1200 may be a recurrent neural network. A recurrent neural network can include one or more feedback loops among the connections 1255, thereby allowing data to propagate in both forward and backward through the neural network 1200. Such a “backward” direction may be defined as proceeding in the opposite direction of forward, such as from the output layer 1206 through the one or more hidden layers 1204, and toward the input layer 1202. This can allow for information to persist within the recurrent neural network. For example, a recurrent neural network can determine an output based at least partially on information that the recurrent neural network has seen before, giving the recurrent neural network the ability to use previous input to inform the output.

In some examples, the neural network 1200 operates by receiving a vector of numbers from one layer; transforming the vector of numbers into a new vector of numbers using a matrix of numeric weights, a nonlinearity, or both; and

providing the new vector of numbers to a subsequent layer (“subsequent” in the sense of moving “forward”) of the neural network 1200. Each subsequent layer of the neural network 1200 can repeat this process until the neural network 1200 outputs a final result at the outputs 1277 of the output layer 1206. For example, the neural network 1200 can receive a vector of numbers at the inputs 1222 of the input layer 1202. The neural network 1200 can multiply the vector of numbers by a matrix of numeric weights to determine a weighted vector. The matrix of numeric weights can be tuned during the training of the neural network 1200. The neural network 1200 can transform the weighted vector using a nonlinearity, such as a sigmoid tangent or the hyperbolic tangent. In some examples, the nonlinearity can include a rectified linear unit, which can be expressed using the equation $y = \max(x, 0)$ where y is the output and x is an input value from the weighted vector. The transformed output can be supplied to a subsequent layer (e.g., a hidden layer 1204) of the neural network 1200. The subsequent layer of the neural network 1200 can receive the transformed output, multiply the transformed output by a matrix of numeric weights and a nonlinearity, and provide the result to yet another layer of the neural network 1200 (e.g., another, subsequent, hidden layer 1204). This process continues until the neural network 1200 outputs a final result at the outputs 1277 of the output layer 1206.

As also depicted in FIG. 12, the neural network 1200 may be implemented either through the execution of the instructions of one or more routines 1244 by central processing units (CPUs), or through the use of one or more neuromorphic devices 1250 that incorporate a set of memristors (or other similar components) that each function to implement one of the neurons 1208 in hardware. Where multiple neuromorphic devices 1250 are used, they may be interconnected in a depth-wise manner to enable implementing neural networks with greater quantities of layers, and/or in a width-wise manner to enable implementing neural networks having greater quantities of neurons 1208 per layer.

The neuromorphic device 1250 may incorporate a storage interface 1299 by which neural network configuration data 1293 that is descriptive of various parameters and hyperparameters of the neural network 1200 may be stored and/or retrieved. More specifically, the neural network configuration data 1293 may include such parameters as weighting and/or biasing values derived through the training of the neural network 1200, as has been described. Alternatively or additionally, the neural network configuration data 1293 may include such hyperparameters as the manner in which the neurons 1208 are to be interconnected (e.g., feed-forward or recurrent), the trigger function to be implemented within the neurons 1208, the quantity of layers and/or the overall quantity of the neurons 1208. The neural network configuration data 1293 may provide such information for more than one neuromorphic device 1250 where multiple ones have been interconnected to support larger neural networks.

Other examples of the present disclosure may include any number and combination of machine-learning models having any number and combination of characteristics. The machine-learning model(s) can be trained in a supervised, semi-supervised, or unsupervised manner, or any combination of these. The machine-learning model(s) can be implemented using a single computing device or multiple computing devices, such as the communications grid computing system 400 discussed above.

Implementing some examples of the present disclosure at least in part by using machine-learning models can reduce

the total number of processing iterations, time, memory, electrical power, or any combination of these consumed by a computing device when analyzing data. For example, a neural network may more readily identify patterns in data than other approaches. This may enable the neural network to analyze the data using fewer processing cycles and less memory than other approaches, while obtaining a similar or greater level of accuracy.

Some machine-learning approaches may be more efficiently and speedily executed and processed with machine-learning specific processors (e.g., not a generic CPU). Such processors may also provide an energy savings when compared to generic CPUs. For example, some of these processors can include a graphical processing unit (GPU), an application-specific integrated circuit (ASIC), a field-programmable gate array (FPGA), an artificial intelligence (AI) accelerator, a neural computing core, a neural computing engine, a neural processing unit, a purpose-built chip architecture for deep learning, and/or some other machine-learning specific processor that implements a machine learning approach or one or more neural networks using semiconductor (e.g., silicon (Si), gallium arsenide (GaAs)) devices. These processors may also be employed in heterogeneous computing architectures with a number of and/or a variety of different types of cores, engines, nodes, and/or layers to achieve various energy efficiencies, processing speed improvements, data communication speed improvements, and/or data efficiency targets and improvements throughout various parts of the system when compared to a homogeneous computing architecture that employs CPUs for general purpose computing.

FIG. 13 illustrates various aspects of the use of containers 1336 as a mechanism to allocate processing, storage and/or other resources of a processing system 1300 to the performance of various analyses. More specifically, in a processing system 1300 that includes one or more node devices 1330 (e.g., the aforementioned grid system 400), the processing, storage and/or other resources of each node device 1330 may be allocated through the instantiation and/or maintenance of multiple containers 1336 within the node devices 1330 to support the performance(s) of one or more analyses. As each container 1336 is instantiated, predetermined amounts of processing, storage and/or other resources may be allocated thereto as part of creating an execution environment therein in which one or more executable routines 1334 may be executed to cause the performance of part or all of each analysis that is requested to be performed.

It may be that at least a subset of the containers 1336 are each allocated a similar combination and amounts of resources so that each is of a similar configuration with a similar range of capabilities, and therefore, are interchangeable. This may be done in embodiments in which it is desired to have at least such a subset of the containers 1336 already instantiated prior to the receipt of requests to perform analyses, and thus, prior to the specific resource requirements of each of those analyses being known.

Alternatively or additionally, it may be that at least a subset of the containers 1336 are not instantiated until after the processing system 1300 receives requests to perform analyses where each request may include indications of the resources required for one of those analyses. Such information concerning resource requirements may then be used to guide the selection of resources and/or the amount of each resource allocated to each such container 1336. As a result, it may be that one or more of the containers 1336 are caused to have somewhat specialized configurations such that there

may be differing types of containers to support the performance of different analyses and/or different portions of analyses.

It may be that the entirety of the logic of a requested analysis is implemented within a single executable routine **1334**. In such embodiments, it may be that the entirety of that analysis is performed within a single container **1336** as that single executable routine **1334** is executed therein. However, it may be that such a single executable routine **1334**, when executed, is at least intended to cause the instantiation of multiple instances of itself that are intended to be executed at least partially in parallel. This may result in the execution of multiple instances of such an executable routine **1334** within a single container **1336** and/or across multiple containers **1336**.

Alternatively or additionally, it may be that the logic of a requested analysis is implemented with multiple differing executable routines **1334**. In such embodiments, it may be that at least a subset of such differing executable routines **1334** are executed within a single container **1336**. However, it may be that the execution of at least a subset of such differing executable routines **1334** is distributed across multiple containers **1336**.

Where an executable routine **1334** of an analysis is under development, and/or is under scrutiny to confirm its functionality, it may be that the container **1336** within which that executable routine **1334** is to be executed is additionally configured assist in limiting and/or monitoring aspects of the functionality of that executable routine **1334**. More specifically, the execution environment provided by such a container **1336** may be configured to enforce limitations on accesses that are allowed to be made to memory and/or I/O addresses to control what storage locations and/or I/O devices may be accessible to that executable routine **1334**. Such limitations may be derived based on comments within the programming code of the executable routine **1334** and/or other information that describes what functionality the executable routine **1334** is expected to have, including what memory and/or I/O accesses are expected to be made when the executable routine **1334** is executed. Then, when the executable routine **1334** is executed within such a container **1336**, the accesses that are attempted to be made by the executable routine **1334** may be monitored to identify any behavior that deviates from what is expected.

Where the possibility exists that different executable routines **1334** may be written in different programming languages, it may be that different subsets of containers **1336** are configured to support different programming languages. In such embodiments, it may be that each executable routine **1334** is analyzed to identify what programming language it is written in, and then what container **1336** is assigned to support the execution of that executable routine **1334** may be at least partially based on the identified programming language. Where the possibility exists that a single requested analysis may be based on the execution of multiple executable routines **1334** that may each be written in a different programming language, it may be that at least a subset of the containers **1336** are configured to support the performance of various data structure and/or data format conversion operations to enable a data object output by one executable routine **1334** written in one programming language to be accepted as an input to another executable routine **1334** written in another programming language.

As depicted, at least a subset of the containers **1336** may be instantiated within one or more VMs **1331** that may be instantiated within one or more node devices **1330**. Thus, in some embodiments, it may be that the processing, storage

and/or other resources of at least one node device **1330** may be partially allocated through the instantiation of one or more VMs **1331**, and then in turn, may be further allocated within at least one VM **1331** through the instantiation of one or more containers **1336**.

In some embodiments, it may be that such a nested allocation of resources may be carried out to effect an allocation of resources based on two differing criteria. By way of example, it may be that the instantiation of VMs **1331** is used to allocate the resources of a node device **1330** to multiple users or groups of users in accordance with any of a variety of service agreements by which amounts of processing, storage and/or other resources are paid for each such user or group of users. Then, within each VM **1331** or set of VMs **1331** that is allocated to a particular user or group of users, containers **1336** may be allocated to distribute the resources allocated to each VM **1331** among various analyses that are requested to be performed by that particular user or group of users.

As depicted, where the processing system **1300** includes more than one node device **1330**, the processing system **1300** may also include at least one control device **1350** within which one or more control routines **1354** may be executed to control various aspects of the use of the node device(s) **1330** to perform requested analyses. By way of example, it may be that at least one control routine **1354** implements logic to control the allocation of the processing, storage and/or other resources of each node device **1330** to each VM **1331** and/or container **1336** that is instantiated therein. Thus, it may be the control device(s) **1350** that effects a nested allocation of resources, such as the aforementioned example allocation of resources based on two differing criteria.

As also depicted, the processing system **1300** may also include one or more distinct requesting devices **1370** from which requests to perform analyses may be received by the control device(s) **1350**. Thus, and by way of example, it may be that at least one control routine **1354** implements logic to monitor for the receipt of requests from authorized users and/or groups of users for various analyses to be performed using the processing, storage and/or other resources of the node device(s) **1330** of the processing system **1300**. The control device(s) **1350** may receive indications of the availability of resources, the status of the performances of analyses that are already underway, and/or still other status information from the node device(s) **1330** in response to polling, at a recurring interval of time, and/or in response to the occurrence of various preselected events. More specifically, the control device(s) **1350** may receive indications of status for each container **1336**, each VM **1331** and/or each node device **1330**. At least one control routine **1354** may implement logic that may use such information to select container(s) **1336**, VM(s) **1331** and/or node device(s) **1330** that are to be used in the execution of the executable routine(s) **1334** associated with each requested analysis.

As further depicted, in some embodiments, the one or more control routines **1354** may be executed within one or more containers **1356** and/or within one or more VMs **1351** that may be instantiated within the one or more control devices **1350**. It may be that multiple instances of one or more varieties of control routine **1354** may be executed within separate containers **1356**, within separate VMs **1351** and/or within separate control devices **1350** to better enable parallelized control over parallel performances of requested analyses, to provide improved redundancy against failures for such control functions, and/or to separate differing ones of the control routines **1354** that perform different functions.

By way of example, it may be that multiple instances of a first variety of control routine **1354** that communicate with the requesting device(s) **1370** are executed in a first set of containers **1356** instantiated within a first VM **1351**, while multiple instances of a second variety of control routine **1354** that control the allocation of resources of the node device(s) **1330** are executed in a second set of containers **1356** instantiated within a second VM **1351**. It may be that the control of the allocation of resources for performing requested analyses may include deriving an order of performance of portions of each requested analysis based on such factors as data dependencies thereamong, as well as allocating the use of containers **1336** in a manner that effectuates such a derived order of performance.

Where multiple instances of control routine **1354** are used to control the allocation of resources for performing requested analyses, such as the assignment of individual ones of the containers **1336** to be used in executing executable routines **1334** of each of multiple requested analyses, it may be that each requested analysis is assigned to be controlled by just one of the instances of control routine **1354**. This may be done as part of treating each requested analysis as one or more “ACID transactions” that each have the four properties of atomicity, consistency, isolation and durability such that a single instance of control routine **1354** is given full control over the entirety of each such transaction to better ensure that all of each such transaction is either entirely performed or is entirely not performed. Allowing partial performances to occur may cause cache incoherencies and/or data corruption issues.

As additionally depicted, the control device(s) **1350** may communicate with the requesting device(s) **1370** and with the node device(s) **1330** through portions of a network **1399** extending thereamong. Again, such a network as the depicted network **1399** may be based on any of a variety of wired and/or wireless technologies, and may employ any of a variety of protocols by which commands, status, data and/or still other varieties of information may be exchanged. It may be that one or more instances of a control routine **1354** cause the instantiation and maintenance of a web portal or other variety of portal that is based on any of a variety of communication protocols, etc. (e.g., a restful API). Through such a portal, requests for the performance of various analyses may be received from requesting device(s) **1370**, and/or the results of such requested analyses may be provided thereto. Alternatively or additionally, it may be that one or more instances of a control routine **1354** cause the instantiation of and maintenance of a message passing interface and/or message queues. Through such an interface and/or queues, individual containers **1336** may each be assigned to execute at least one executable routine **1334** associated with a requested analysis to cause the performance of at least a portion of that analysis.

Although not specifically depicted, it may be that at least one control routine **1354** may include logic to implement a form of management of the containers **1336** based on the Kubernetes container management platform promulgated by Cloud Native Computing Foundation of San Francisco, CA, USA. In such embodiments, containers **1336** in which executable routines **1334** of requested analyses may be instantiated within “pods” (not specifically shown) in which other containers may also be instantiated for the execution of other supporting routines. Such supporting routines may cooperate with control routine(s) **1354** to implement a communications protocol with the control device(s) **1350** via the network **1399** (e.g., a message passing interface, one or more message queues, etc.). Alternatively or additionally,

such supporting routines may serve to provide access to one or more storage repositories (not specifically shown) in which at least data objects may be stored for use in performing the requested analyses.

FIG. **14** shows a block diagram of an example of a system **1400** according to some aspects of the present disclosure. The system **1400** is a distributed computing environment, such as a computing cluster, a data grid, or a cloud computing environment. The system **1400** can include any number of computing nodes (e.g., physical machines), such as nodes **1406a-n**. Examples of the nodes **1406a-n** can include servers, desktop computers, etc.

The system **1400** can include a reconciliation orchestrator **1404**. The reconciliation orchestrator **1404** can be any software that is configured to orchestrate a reconciliation process for a set of forecasts **1402** across some or all of the nodes **1406a-n**. The reconciliation orchestrator **1404** may also be configured to perform other tasks, such as job scheduling or workload balancing. In some examples, the set of forecasts **1402** may be time series that all span the same time period and may have the same time interval between data points. A time series can be a sequence of data points indexed in time order, where the data points are collected at uniform time intervals. The forecasts **1402** can have a hierarchical relationship to one another, such that some forecasts are children of other forecasts. The reconciliation process can be configured to adjust the set of forecasts **1402** to minimize a weighted sum of variances of reconciled forecast errors associated with all forecasts (e.g., time series) in the hierarchy.

More specifically, the reconciliation orchestrator **1404** can receive the set of forecasts **1402**. The forecasts **1402** may have been generated by a machine-learning model, such as an autoregressive integrated moving average (ARIMA) model or an exponential smoothing model (ESM). The set of forecasts **1402** may include any number of forecasts, such as three or more forecasts. The forecasts **1402** may each be time-stamped data (e.g., a time series) of predicted values over a future time window.

The forecasts **1402** can have a hierarchical relationship to one another. One example of such a hierarchy of forecasts is shown in FIGS. **15-16**. FIG. **15** shows a simplified representation of the forecasts as blocks. FIG. **16** shows the forecasts as time series graphs. In FIGS. **15-16**, there are three levels of forecasts in the hierarchies **1500**, **1600**. The basal level (e.g., Level 2) has five forecasts—AA, AB, AC, BA, and BB. The middle level (e.g., Level 1) has two forecasts—A and B. The top level (e.g., Level 0) has one forecast—Total.

Still referring to FIGS. **15-16**, it may be desirable for the forecasts to satisfy an aggregation constraint, for example so that the depicted conditions **1502** are satisfied at every time t . In particular, at a given time t , the value in the Total forecast should be the sum of the values in the intermediate forecasts A and B. Similarly, at that time t , the value in forecast A should be the sum of the values in the basal forecasts AA, AB, and AC. And, at that time t , the value in forecast B should be the sum of the values in the basal forecasts BA and BB. As one specific example, the forecasts may relate to a company’s sales. The sales in region A should be the sum of the sales in locations (e.g., stores) AA, AB, and AC. The sales in region B should be the sum of the sales in locations BA and BB. And the total sales should be the sum of the sales in regions A and B. Of course, other examples may involve other hierarchical arrangements of more or fewer forecasts.

In some examples, the reconciliation orchestrator **1404** can receive the set of forecasts **1402** in a data table format. For example, the forecasts **1402** can be stored in data tables that are arranged by level of the hierarchy. There can be one data table per level of the hierarchy, where the data table includes all of the data points associated with all of the forecasts at that level of the hierarchy. For instance, referring to FIG. 17, there can be a first data table **1702** that includes all of the data points in all of the forecasts at a first level of the hierarchy (e.g., AA, AB, AC, BA, and BB). There can be a second data table **1704** that includes all of the data points in all of the forecasts at a second level of the hierarchy (e.g., A and B). And there can be a third data table **1706** that includes all of the data points in all of the forecasts at a third level of the hierarchy (e.g., Total). Each row of each data table can correspond to a particular data point in a particular forecast covered by that data table. For example, row **1708** can correspond to a particular data point in forecast AA. Organizing the forecasts **1402** into data tables by level in the hierarchy can make it easier for the reconciliation orchestrator **1404** to divide the forecasts **1402** into datasets by timestamp, as described below.

Referring back to FIG. 14, after receiving the set of forecasts **1402**, the reconciliation orchestrator **1404** can determine how to divide and distribute the set of forecasts **1402** among the nodes **1406a-n** to implement the reconciliation process. In some examples, the reconciliation orchestrator **1404** can divide the set of forecasts **1402** into datasets **1410** by timestamp, where each dataset corresponds to a single time point in the set of forecasts **1402**. For example, the set of forecasts **1402** have a ten minute interval between data points. The reconciliation orchestrator **1404** can generate a first dataset **1410a-1** that consists of the data points from the set of forecasts **1402** corresponding to Jun. 22, 2024 at 1:00 PM. The reconciliation orchestrator **1404** can also generate a second dataset **1410a-2** that consists of the data points from the set of forecasts **1402** corresponding to Jun. 22, 2024 at 1:10 PM. And the reconciliation orchestrator **1404** can generate a third dataset **1410b-1** that consists of the data points from the set of forecasts **1402** corresponding to Jun. 22, 2024 at 1:20 PM. And so on for all of the data points in the set of forecasts **1402**. One specific example of this process is shown in FIG. 18. In FIG. 18, a data point at time **t1** is identified by a dotted line in each of the depicted forecasts. Those data points are collected into a dataset **1802** corresponding to time **t1**. That dataset **1802** can be referred to herein using the mathematical notation y_t , where **t** is a point in time. A basal dataset **1804** may also be determined. The basal dataset **1804** may only consist of the data points from the basal level forecasts (and not the higher-level forecasts). The basal dataset **1804** can be referred to herein using the mathematical notation $y_{basal,t}$.

After dividing the set of forecasts **1402** into the datasets **1410**, the reconciliation orchestrator **1404** can distribute the datasets **1410** among the nodes **1406a-n**. The reconciliation orchestrator **1404** can distribute the datasets **1410** among the nodes **1406a-n** in any suitable manner. For example, the reconciliation orchestrator **1404** can distribute the datasets **1410** substantially evenly among the nodes **1406a-n**, so that most or all of the nodes **1406a-n** have the same number of datasets. As another example, the reconciliation orchestrator **1404** can distribute the datasets **1410** based on the existing workloads of the nodes **1406a-n**, for example so that nodes with less available computing resources may receive fewer of the datasets **1410** than nodes with more available com-

puting resources. This can help prevent against overburdening a node that is already processing a large number of workloads.

The nodes **1406a-n** can each receive one or more of the datasets **1410** from the reconciliation orchestrator **1404**. After receiving the datasets **1410**, the nodes **1406a-n** can assign the datasets **1410** to separate processing threads **1408**. For example, node **1406a** can receive two datasets **1410a-1**, **1410a-2** from the reconciliation orchestrator **1404** and assign them to threads **1408a-1**, **1408a-2**. As another example, node **1406b** can receive one dataset **1410b-1** from the reconciliation orchestrator **1404** and assign it to thread **1408b-1**. As yet another example, node **1406n** can receive three datasets **1410n-1**, **1410n-2**, **1410n-3** from the reconciliation orchestrator **1404** and assign them to threads **1408n-1**, **1408n-2**, **1408n-3**. The nodes **1406a-n** may assign the datasets **1410** to threads **1408** that are not already processing any workloads, so that the threads **1408** are dedicated for the reconciliation process. In some examples, the nodes **1406a-n** may generate new threads **1408** that are solely dedicated to the reconciliation process and shut down those threads when the reconciliation process is complete. This may conserve computing resources.

The threads **1408** can each execute a respective reconciliation process on a respective dataset **1410** to produce one or more reconciled values **1412** (e.g., reconciled data points). The reconciled values **1412** are denoted as “RV” in FIG. 14. For example, thread **1408a-1** can execute a reconciliation process on dataset **1410a-1** to produce a reconciled value **1412a-1**. Thread **1408a-2** can execute a reconciliation process on dataset **1410a-2** to produce a reconciled value **1412a-2**. Thread **1408b-1** can execute a reconciliation process on dataset **1410b-1** to produce a reconciled value **1412b-1**. And so on through thread **1408n-3**. Some or all of the threads **1408** across some or all of the nodes **1406** can execute their reconciliation processes in parallel to one another, so that the reconciliation processes are performed concurrently (e.g., simultaneously). The nodes **1406a-n** can then transmit the reconciled values **1412** to the reconciliation orchestrator **1404**.

The reconciliation orchestrator **1404** can collect the reconciled values **1412** and generate a set of reconciled forecasts **1418** based on the reconciled values **1412**. The set of reconciled forecasts **1418** can be reconciled versions of the original set of forecasts **1402**. The reconciliation orchestrator **1404** can then provide the set of reconciled forecasts **1418** for subsequent use. For example, the reconciliation orchestrator **1404** can transmit the set of reconciled forecasts **1418** to a client device for use by an application executing on the client device. In some examples, the client device may have provided the original set of forecasts **1402** to the system **1400** for reconciliation and can receive the set of reconciled forecasts **1418** in return from the system **1400**.

Through the above process, the reconciliation orchestrator **1404** can divide and distribute the reconciliation process among the nodes **1406a-n**, which in turn can further distribute the reconciliation process among separate threads **1408**. This can result in two levels of parallelism that can improve the efficiency of the reconciliation process and significantly expedite the reconciliation process.

As noted above, the nodes **1406a-n** can each perform reconciliation processes on their assigned datasets **1410**. To perform the reconciliation processes, the nodes **1406a-n** may each compute a respective summation matrix (“S-matrix”) **1414** that can encode the aggregation (e.g., summation) constraints. To compute an S-matrix, a node **1406a** can access one of its assigned datasets and generate the

S-matrix based on that dataset. For example, node **1406a** can generate an S-matrix **1414a** based on dataset **1410a-1**, node **1406b** can generate an S-matrix **1414b** based on dataset **1410b-1**, and node **1406n** can generate the S-matrix **1414n** based on dataset **1410n-1**.

In some examples, the S-matrix **1414** can have as many rows as there are forecasts in the set of forecasts **1402**. The S-matrix **1414** may also have as many columns as there are basal level forecasts in the set of forecasts **1402**. One specific example is shown in FIG. **19**. As shown, if there are eight total forecasts in the set of forecasts **1402**, of which five are basal level forecasts, the S-matrix **1414** can be 8x5 in size. Of course, depending on the implementation, the number of the rows and columns can be swapped (e.g., so that the S-matrix is 5x8) in other examples. The S-matrix **1414** can include binary values that encode one or more aggregation constraints.

After generating the S-matrices **1414**, some or all of the nodes **1406a-n** can compare their computed S-matrices **1414** to one another to ensure that they match. For example, node **1406a** can request the S-matrix **1414b** from node **1406b**. Node **1406a** can then compare its S-matrix **1414a** to the other S-matrix **1414b**. If they do not match, it may signify a nonuniformity in the datasets **1410** that could lead to downstream errors and/or inaccuracies in the reconciliation process. So, the node **1406a** can transmit an error message **1420** to the reconciliation orchestrator **1404**. In some examples, the reconciliation orchestrator **1404** can receive the error message **1420** and responsively transmit an error notification to one or more client devices of one or more users. The users can include an administrator and/or the user that submitted the set of forecasts **1402** for reconciliation. The error notification can notify the one or more users of the problem. Additionally or alternatively, in response to receiving the error message **1420**, the reconciliation orchestrator **1404** may automatically perform one or more operations in an effort to resolve the problem. For example, the reconciliation orchestrator **1404** may identify the root cause of the problem, such as a missing value in the dataset **1410b-1**, and update the dataset **1410b-1** to include the missing value. This may involve generating a synthetic value to take the place of the missing value. The reconciliation orchestrator **1404** may then transmit the updated dataset to the node **1406b**, which can recompute the S-matrix **1414b** and perform the validation process again. This initial validation of the S-matrices **1414a-n** can help avoid downstream inaccuracies that could occur if different reconciliation processes are performed on different nodes using different S-matrices.

After generating the S-matrices **1414a-n**, the nodes **1406a-n** can each generate a respective reconciliation matrix, which is referred to herein as a "G-matrix". In some examples, the nodes **1406a-n** can generate the G-matrices **1416** based on the S-matrices **1414** and a weighting matrix. The weighting matrix can be a predefined matrix of weights. For instance, the nodes **1406a-n** can each generate a G-matrix **1416** according to the following equation:

$$G=(S^TWS)^{-1}S^TW$$

where G is the G-matrix, S is the S-matrix, and W is a predefined weighting matrix. Thus, the G-matrix on each of the nodes **1406a-n** can depend on the S-matrix **1414** computed by that node. For example, node **1406a** can generate a G-matrix **1416a** based on its S-matrix **1414a** and optionally the weighting matrix. Node **1406b** can generate a G-matrix **1416b** based on its S-matrix **1414b** and optionally

the weighting matrix. And node **1406n** can generate a G-matrix **1416n** based on its S-matrix **1414n** and optionally the weighting matrix.

After generating the G-matrices **1416**, the nodes **1406a-n** can use the G-matrices **1416** to perform their respective reconciliation processes. For example, the nodes **1406a-n** can compute the reconciled basal level forecasts according to the following equation:

$$Z_{basal,t}=Gy_t$$

where $Z_{basal,t}$ includes the reconciled basal level forecast values, G is the G-matrix, and y_t includes the original forecast values at all levels of the hierarchy. The nodes **1406a-n** can then compute the full reconciled forecasts according to the following equation:

$$Z_t=SZ_{basal,t}=SGy_t$$

where Z_t includes the full reconciled forecast values, $Z_{basal,t}$ includes the reconciled basal level forecast values, and S is the S-matrix. After generating the full reconciled forecast values (e.g., reconciled values **1412**), the nodes **1406a-n** can transmit them to the reconciliation orchestrator **1404** as described above.

In some examples, a thread **1408** may be assigned to process a dataset **1410** that is missing a value for a data point. For example, the dataset **1410b-1** may include a data point from a forecast, where the data point corresponds to Jun. 22, 2024 at 1:00 PM. But, the data point may be missing a value (e.g., the value may be NULL). This can happen for various reasons, for example if the forecasting model that generated the forecast experienced an error or did not have sufficient information to create a value for the data point. To prevent the missing value from causing a downstream error, in some examples the corresponding thread **1408b-1** can dynamically adjust the corresponding S-matrix **1414b** to account for the missing value. If there is a weighting matrix (W), the weighting matrix can also be dynamically adjusted to account for the missing value. One example of adjusting an S-matrix **2004** is shown in FIG. **20**. As shown in FIG. **20**, the thread **1408b-1** can dynamically create a modified S-matrix **2004** that accounts for the missing value. The thread **1408b-1** can also dynamically create a modified G-matrix **2006** based on the modified S-matrix **2004**, for example by recomputing the G-matrix using the equation described above. In some examples involving a weighting matrix (W), the W-matrix can also be dynamically adjusted to account for the missing value. The thread **1408b-1** can then dynamically create the modified G-matrix **2006** based on the modified S-matrix and the modified W-matrix. The modified S-matrix **2004**, the modified W-matrix, and the modified G-matrix may be new matrices created separately from the originals, so that other threads on the node **1406b** can still use the original S-matrix **1414b**, W-matrix, and G-matrix **1416b** in their reconciliation processes. The thread **1408b-1** can then use the modified S-matrix **2004**, the modified W-matrix, and the modified G-matrix **2006** in its reconciliation process.

FIG. **21** shows an example of a process for creating a modified S-matrix **2004**. In this example, the dataset **2102** can include data points from all of the forecasts shown in FIG. **15** for time t. If all of the data points had valid values, it could result in the S-matrix **2104**. But in this example, the data point value for forecast AC is missing (e.g., NULL). So, the data point with the missing value can be excluded from the dataset **2102** to produce a modified dataset **2106**. A modified S-matrix **2108** can then be generated based on the modified dataset **2106**. The modified S-matrix **2108** can

exclude a row and column corresponding to the missing value. For illustrative purposes, the excluded row and column is shown in bold in S-matrix 2104. In this way, a modified S-matrix 2108 can be generated to account for the missing value. A similar process can be applied to the W-matrix (e.g., excluding a row and column associated with the missing value). The modified S-matrix and/or W-matrix can then be used to compute a modified G-matrix, as described above, for use in the reconciliation process.

FIG. 22 shows a flowchart of an example of a process for dividing and distributing forecast data among a group of nodes according to some aspects of the present disclosure. Other examples may include more operations, fewer operations, different operations, or a different sequence of operations than is shown. The operations of FIG. 22 are described below with reference to the components of FIG. 14 described above.

In block 2202, a system 1400 (e.g., reconciliation orchestrator 1404) can receive a set of forecasts 1402 that have a hierarchical relationship to one another. The system 1400 may receive the set of forecasts 1402 from a client device, which can be internal or external to the system 1400. Examples of the client device can include a laptop computer, a desktop computer, a server, a wearable device (e.g., a smart watch), a mobile phone, a tablet, or an e-reader. Each forecast among the set of forecasts 1402 corresponds to a respective level of the hierarchy. At least one forecast in the set of forecasts 1402 can correspond to a higher level of the hierarchy than at least one other forecast of the set of forecasts 1402.

In block 2204, the system 1400 divides the set of forecasts 1402 by time point into a plurality of datasets 1410. Each dataset 1410 can correspond to a single time point. For example, each dataset 1410 may only include the data points corresponding to that single time point from the set of forecasts 1402. In other examples, the system 1400 may divide the forecasts 1402 into the datasets 1410 based on other factors, additionally or alternatively to time point.

In block 2206, the system 1400 distributes the plurality of datasets 1410 among a plurality of computing nodes 1406 of a distributed computing system 1400. Because the data points in the forecasts 1402 were grouped into the datasets 1410 by time point in block 2204, all of the data points corresponding to the same time point may be assigned to the same computing node. The plurality of computing nodes 1406 can be configured to collectively process the set of forecasts 1402 in parallel to implement an overall reconciliation process that involves adjusting the set of forecasts 1402 subject to one or more constraints, such as an aggregation constraint. Distributing the datasets 1410 among more nodes may result in a faster execution of the reconciliation process than distributing the datasets 1410 among fewer nodes.

FIG. 23 shows a flowchart of an example of a process for performing reconciliation on a computing node according to some aspects of the present disclosure. Other examples may include more operations, fewer operations, different operations, or a different sequence of operations than is shown. The operations of FIG. 23 are described below with reference to the components of FIG. 14 described above.

In block 2302, a computing node 1406a receives a dataset 1410a-1. The dataset 1410a-1 can include data points corresponding to a single time point in a set of forecasts 1402. The computing node 1406a may receive the dataset 1410a-1 from a reconciliation orchestrator 1404 or another source.

In block 2304, the computing node 1406a assigns the dataset 1410a-1 to a processing thread 1408a-1. In some

examples, the processing thread 1408a-1 may be a new processing thread generated by the computing node 1406a to handle the dataset 1410a-1.

In block 2306, the computing node 1406a constructs an S-matrix 1414a based on the dataset 1410a. For example, the computing node 1406a can generate an S-matrix 1414a that has a number of rows and columns that corresponds to the number of forecasts represented in the dataset 1410a.

In block 2308, the computing node 1406a validates the S-matrix 1414a. This step may be performed using the process described below with respect to FIG. 24.

In block 2310, the computing node 1406a constructs a G-matrix based on the S-matrix and a W-matrix. This step may be performed using any of the techniques described above.

In block 2312, the computing node 1406a executes the processing thread. When executed, the processing thread can implement the steps described below with respect to FIG. 25.

As noted earlier, in some examples the computing node 1406a can perform an S-matrix validation process prior to executing the reconciliation processes on the threads 1408a. FIG. 24 shows a flowchart of an example of such an S-matrix validation process according to some aspects of the present disclosure.

In block 2402, the computing node 1406a receives one or more datasets 1410a associated with a set of forecasts 1402. The computing node 1406a can receive the one or more datasets 1410a from a reconciliation orchestrator 1404, in some examples.

In block 2404, the computing node 1406a selects one of the datasets 1410a and generates an S-matrix 1414a based on the selected dataset 1410a-1.

In block 2406, the computing node 1406a receives one or more other S-matrices 1414b-n from one or more other computing nodes 1406b-n. The one or more other S-matrices 1414b-n may have been computed by the one or more other computing nodes 1406b-n based on the datasets 1410b-n assigned to those computing nodes 1406b-n.

In block 2408, the computing node 1406a determines whether its S-matrix 1414a matches the one or more other S-matrices 1414b-n. Two S-matrices can “match” if they are identical. If the S-matrix 1414a matches the one or more other S-matrices 1414b-n, then the process can proceed to block 2410 where computing node 1406a can proceed with the reconciliation process. Otherwise, the process can proceed to block 2412 where the computing node 1406a can output an error message 1420. For example, the computing node 1406a can transmit the error message 1420 to the reconciliation orchestrator 1404.

FIG. 25 shows a flowchart of an example of a process for performing reconciliation on processing thread of a computing node according to some aspects of the present disclosure. Other examples may include more operations, fewer operations, different operations, or a different sequence of operations than is shown. The operations of FIG. 25 are described below with reference to the components of FIG. 14 described above.

In block 2502, a thread 1408a-1 receives a dataset 1410a-1. The dataset 1410a-1 can include data points corresponding to a single time point in a set of forecasts 1402.

In block 2504, the thread 1408a-1 organizes the set of data points in the dataset 1410a-1 by forecast. For example, the thread 1408a-1 can sort the data points by forecast. This may help ensure that some or all of the datasets 1410 in the

system **1400** are organized the same way, which can prevent downstream problems and inaccuracies in the reconciliation process.

In block **2506**, the thread **1408a-1** compares the dataset **1410a-1** to the S-matrix **1414a** on the computing node **1406a** to perform a further validation. For example, the thread **1408a-1** can compare the dataset **1410a-1** to the S-matrix **1414a** previously computed by the computed node **1406a**, for example to make sure that all of forecasts (e.g., time series) used construct the S-matrix **1414a** exist in the dataset **1410a**, and vice versa. If not, the thread **1408a-1** can throw an error.

In block **2508**, the thread **1408a-1** determines if there are any missing values in the dataset **1410a-1**. For example, the thread **1408a-1** can identify any data points that have an empty value or a value of "NULL". If the thread **1408a-1** determines that the dataset **1410a-1** has a data point with a missing value, the process can proceed to block **2510**. Otherwise, the process can proceed to block **2514**.

In block **2510**, the thread **1408a-1** generates a modified S-matrix and a modified W-matrix that account for missing value. For example, the thread **1408a-1** can generate a new S-matrix that excludes a row and/or column of values associated with the forecast having the missing value. The thread **1408a-1** can also generate a new W-matrix that excludes a row and/or column of values associated with the forecast having the missing value.

In block **2512**, the thread **1408a-1** generates a modified G-matrix based on the modified S-matrix and the modified W-matrix. For example, the thread **1408a-1** can generate the modified G-matrix according to the following equation:

$$G_{modified} = (S_{modified} * W_{modified} * S_{modified}) / (S_{modified} * W_{modified})$$

Where $G_{modified}$ is the modified G-matrix, $S_{modified}$ is the modified S-matrix, and $W_{modified}$ is the modified weighting matrix.

In block **2514**, the thread **1408a-1** obtains an S-matrix **1414a**, a W-matrix, and a G-matrix **1416a**, some or all of which may have previously been computed. For example, the thread **1408a-1** can obtain an S-matrix **1414a** and a G-matrix **1416a** that the computing node **1406a** may have previously computed based on the same dataset **1410a-1** or a different dataset.

In block **2516**, the thread **1408a-1** executes a reconciliation process on the dataset **1410a-1** using the S-matrix, the W-matrix, and the G-matrix. The S-matrix can be the original or modified S-matrix, the W-matrix can be the original or modified W-matrix, and the G-matrix can be the original or modified G-matrix, depending on the result of block **2508**. The reconciliation process can yield one or more reconciled values **1412a-1**.

In block **2518**, the thread **1408a-1** outputs the one or more reconciled values **1412a-1**. For example, the thread **1408a-1** can transmit the one or more reconciled values **1412a-1** via one or more networks, such as a local area network or the Internet, to the reconciliation orchestrator **1404** or a client device.

In the previous description, for the purposes of explanation, specific details are set forth in order to provide a thorough understanding of examples of the technology. But various examples can be practiced without these specific details. The FIGURES and description are not intended to be restrictive.

The previous description provides examples that are not intended to limit the scope, applicability, or configuration of the disclosure. Rather, the previous description of the

examples provides those skilled in the art with an enabling description for implementing an example. Various changes may be made in the function and arrangement of elements without departing from the spirit and scope of the technology as set forth in the appended claims.

Specific details are given in the previous description to provide a thorough understanding of the examples. But the examples may be practiced without these specific details. For example, circuits, systems, networks, processes, and other components can be shown as components in block diagram form to prevent obscuring the examples in unnecessary detail. In other examples, well-known circuits, processes, algorithms, structures, and techniques may be shown without unnecessary detail in order to avoid obscuring the examples.

Also, individual examples may have been described as a process that is depicted as a flowchart, a flow diagram, a data flow diagram, a structure diagram, or a block diagram. Although a flowchart can describe the operations as a sequential process, many of the operations can be performed in parallel or concurrently. In addition, the order of the operations can be re-arranged. And a process can have more or fewer operations than are depicted in a figure. A process can correspond to a method, a function, a procedure, a subroutine, a subprogram, etc. When a process corresponds to a function, its termination can correspond to a return of the function to the calling function or the main function.

Systems depicted in some of the FIGURES can be provided in various configurations. In some examples, the systems can be configured as a distributed system where one or more components of the system are distributed across one or more networks in a cloud computing system.

The invention claimed is:

1. A system comprising:

one or more processors; and

one or more memories including program code that is executable by the one or more processors for causing the one or more processors to:

receive a plurality of forecasts that have a hierarchical relationship with respect to one another, wherein each forecast among the plurality of forecasts corresponds to a respective level of a hierarchy, and wherein at least one forecast in the plurality of forecasts corresponds to a higher level of the hierarchy than at least one other forecast of the plurality of forecasts; and

distribute the plurality of forecasts among a plurality of computing nodes of a distributed computing environment by time point, such that all data points corresponding to a same time point in the plurality of forecasts are assigned to a same computing node of the plurality of computing nodes, the plurality of computing nodes being configured to collectively process the plurality of forecasts in parallel to implement a reconciliation process that involves adjusting the plurality of forecasts subject to an aggregation constraint, the plurality of computing nodes being further configured to:

receive a plurality of datasets corresponding to a plurality of time points, each dataset of the plurality of datasets including a respective set of data points from the plurality of forecasts corresponding to a single time point;

organize the respective set of data points in each of the plurality of datasets by forecast to generate a plurality of ordered datasets;

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assign the plurality of ordered datasets to a plurality of processing threads on the plurality of computing nodes, the plurality of processing threads being executable in parallel to implement respective portions of the reconciliation process using the plurality of ordered datasets;

execute the plurality of processing threads to implement the reconciliation process on the plurality of forecasts, to thereby generate a plurality of reconciled values; and

output the plurality of reconciled values.

2. The system of claim 1, wherein the plurality of forecasts span a same time period and have a same time interval.

3. The system of claim 1, wherein a computing node in the plurality of computing nodes is configured to:

access a dataset of the plurality of datasets, wherein the dataset is assigned to the computing node and corresponds to a particular time point;

generate, based on the dataset, a summation matrix that encodes aggregation constraints;

determine at least one other summation matrix generated by at least one other computing node of the plurality of computing nodes; and

perform a comparison of the summation matrix against the at least one other summation matrix.

4. The system of claim 3, wherein the computing node is further configured to:

based on the comparison, determine that the summation matrix matches the at least one other summation matrix; and

in response to determining that the summation matrix matches the at least one other summation matrix, generate reconciled values associated with the particular time point based on the summation matrix and the dataset.

5. The system of claim 3, wherein the computing node is further configured to:

based on the comparison, determine that the summation matrix does not match the at least one other summation matrix; and

based on determining that the summation matrix does not match the at least one other summation matrix, output an error message.

6. The system of claim 3, wherein the computing node is further configured to:

generate a reconciliation matrix based on the summation matrix and a weighting matrix, wherein the weighting matrix is distinct from the summation matrix; and

generate reconciled values associated with the particular time point based on the reconciliation matrix, the summation matrix, and the dataset.

7. The system of claim 3, wherein a processing thread of the computing node is further configured to:

determine that the dataset includes a data point with a missing value, the data point being part of a forecast of the plurality of forecasts; and

based on determine that the dataset has the data point with the missing value:

adjust the summation matrix by removing a column and a row associated with the data point from the summation matrix, to thereby create an adjusted summation matrix;

adjust a weighting matrix by removing a column and a row associated with the data point from the weighting matrix, to thereby create an adjusted weighting matrix;

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generate a reconciliation matrix based on the adjusted summation matrix and the adjusted weighting matrix; and

generate reconciled values associated with the particular time point based on the reconciliation matrix and the dataset.

8. The system of claim 3, wherein the one or more memories further include program code that is executable by the one or more processors for causing the one or more processors to:

receive a plurality of data tables, each data table of the plurality of data tables corresponding to a respective level of the hierarchy and including all data points from all forecasts of the plurality of forecasts that correspond to that respective level of the hierarchy, wherein each row of each data table of the plurality of data tables corresponds to a single data point of a single forecast of the plurality of forecasts; and

generate a dataset, of the plurality of datasets, by extracting a set of datapoints corresponding to the same time point from the plurality of data tables and grouping them together as the dataset.

9. The system of claim 1, wherein the reconciliation process is configured to adjust the plurality of forecasts to minimize a weighted sum of variances of reconciled forecast errors associated with all forecasts in the hierarchy.

10. The system of claim 1, wherein the reconciliation process is configured to determine the plurality of reconciled values by:

multiplying a summation matrix by a reconciliation matrix to produce a product; and

multiplying the product by the plurality of forecasts.

11. The system of claim 1, wherein the plurality of computing nodes are configured to employ two levels of parallelism to expedite the reconciliation process, the two levels of parallelism including a first level of parallelism in which the plurality of forecasts are divided by timestamp into subsets for processing in parallel across the plurality of computing nodes, and a second level of parallelism in which multiple subsets assigned to each individual computing node of the plurality of computing nodes are processed in parallel by multiple processing threads on that individual computing node.

12. A method comprising:

receiving, by one or more processors, a plurality of forecasts that have a hierarchical relationship with respect to one another, wherein each forecast among the plurality of forecasts corresponds to a respective level of a hierarchy, and wherein at least one forecast in the plurality of forecasts corresponds to a higher level of the hierarchy than at least one other forecast of the plurality of forecasts; and

distributing, by the one or more processors, the plurality of forecasts among a plurality of computing nodes of a distributed computing environment by time point, such that all data points corresponding to a same time point in the plurality of forecasts are assigned to a same computing node of the plurality of computing nodes, the plurality of computing nodes being configured to collectively process the plurality of forecasts in parallel to implement a reconciliation process that involves adjusting the plurality of forecasts subject to an aggregation constraint, the plurality of computing nodes being further configured to:

receive a plurality of datasets corresponding to a plurality of time points, each dataset of the plurality of

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datasets including a respective set of data points from the plurality of forecasts corresponding to a single time point;
 organize the respective set of data points in each of the plurality of datasets by forecast to generate a plurality of ordered datasets;
 assign the plurality of ordered datasets to a plurality of processing threads on the plurality of computing nodes, the plurality of processing threads being executable in parallel to implement respective portions of the reconciliation process using the plurality of ordered datasets;
 execute the plurality of processing threads to implement the reconciliation process on the plurality of forecasts, to thereby generate a plurality of reconciled values; and
 output the plurality of reconciled values.

13. The method of claim 12, wherein the plurality of forecasts span a same time period.

14. The method of claim 12, wherein a computing node in the plurality of computing nodes is configured to:

access a dataset of the plurality of datasets, wherein the dataset is assigned to the computing node and corresponds to a particular time point;

generate, based on the dataset, a summation matrix that encodes aggregation constraints;

determine at least one other summation matrix generated by at least one other computing node of the plurality of computing nodes; and

perform a comparison of the summation matrix against the at least one other summation matrix.

15. The method of claim 14, wherein the computing node is further configured to:

based on the comparison, determine that the summation matrix matches the at least one other summation matrix; and

in response to determining that the summation matrix matches the at least one other summation matrix, generate reconciled values associated with the particular time point based on the summation matrix and the dataset.

16. The method of claim 14, wherein the computing node is further configured to:

based on the comparison, determine that the summation matrix does not match the at least one other summation matrix; and

based on determining that the summation matrix does not match the at least one other summation matrix, output an error message.

17. The method of claim 14, wherein the computing node is further configured to:

generate a reconciliation matrix based on the summation matrix and a weighting matrix, wherein the weighting matrix is distinct from the summation matrix; and
 generate reconciled values associated with the particular time point based on the reconciliation matrix, the summation matrix, and the dataset.

18. The method of claim 14, wherein a processing thread of the computing node is further configured to:

determine that the dataset includes a data point with a missing value, the data point being part of a forecast of the plurality of forecasts; and

based on determine that the dataset has the data point with the missing value:

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adjust the summation matrix by removing a column and a row associated with the data point from the summation matrix, to thereby create an adjusted summation matrix;

generate a reconciliation matrix based on the adjusted summation matrix and a weighting matrix; and
 generate reconciled values associated with the particular time point based on the reconciliation matrix and the dataset.

19. The method of claim 14, further comprising:

receiving a plurality of data tables, each data table of the plurality of data tables corresponding to a respective level of the hierarchy and including all data points from all forecasts of the plurality of forecasts that correspond to that respective level of the hierarchy, wherein each row of each data table of the plurality of data tables corresponds to a single data point of a single forecast of the plurality of forecasts; and

generating a dataset, of the plurality of datasets, by extracting a set of datapoints corresponding to the same time point from the plurality of data tables and grouping them together as the dataset.

20. The method of claim 14, wherein the reconciliation process is configured to adjust the plurality of forecasts to minimize a weighted sum of variances of reconciled forecast errors associated with all forecasts in the hierarchy.

21. The method of claim 14, wherein the reconciliation process is configured to determine the plurality of reconciled values by:

multiplying a summation matrix by a reconciliation matrix to produce a product; and

multiplying the product by the plurality of forecasts.

22. The method of claim 14, wherein the plurality of computing nodes are configured to employ two levels of parallelism to expedite the reconciliation process, the two levels of parallelism including a first level of parallelism in which the plurality of forecasts are divided by timestamp into subsets for processing in parallel across the plurality of computing nodes, and a second level of parallelism in which multiple subsets assigned to each individual computing node of the plurality of computing nodes are processed in parallel by multiple processing threads on that individual computing node.

23. A non-transitory computer-readable medium comprising program code that is executable by one or more processors for causing the one or more processors to:

receive a plurality of forecasts that have a hierarchical relationship with respect to one another, wherein each forecast among the plurality of forecasts corresponds to a respective level of a hierarchy, and wherein at least one forecast in the plurality of forecasts corresponds to a higher level of the hierarchy than at least one other forecast of the plurality of forecasts; and

distribute the plurality of forecasts among a plurality of computing nodes of a distributed computing environment by time point, such that all data points corresponding to a same time point in the plurality of forecasts are assigned to a same computing node of the plurality of computing nodes, the plurality of computing nodes being configured to collectively process the plurality of forecasts in parallel to implement a reconciliation process that involves adjusting the plurality of forecasts subject to an aggregation constraint, the plurality of computing nodes being further configured to: receive a plurality of datasets corresponding to a plurality of time points, each dataset of the plurality of

datasets including a respective set of data points from the plurality of forecasts corresponding to a single time point;
 organize the respective set of data points in each of the plurality of datasets by forecast to generate a plurality of ordered datasets;
 assign the plurality of ordered datasets to a plurality of processing threads on the plurality of computing nodes, the plurality of processing threads being executable in parallel to implement respective portions of the reconciliation process using the plurality of ordered datasets;
 execute the plurality of processing threads to implement the reconciliation process on the plurality of forecasts, to thereby generate a plurality of reconciled values; and
 output the plurality of reconciled values.

24. The non-transitory computer-readable medium of claim 23, wherein a computing node in the plurality of computing nodes is configured to:
 access a dataset of the plurality of datasets, wherein the dataset is assigned to the computing node and corresponds to a particular time point;
 generate, based on the dataset, a summation matrix that encodes aggregation constraints;
 determine at least one other summation matrix generated by at least one other computing node of the plurality of computing nodes; and
 perform a comparison of the summation matrix against the at least one other summation matrix.

25. The non-transitory computer-readable medium of claim 24, wherein the computing node is further configured to:
 based on the comparison, determine that the summation matrix matches the at least one other summation matrix; and
 in response to determining that the summation matrix matches the at least one other summation matrix, generate reconciled values associated with the particular time point based on the summation matrix and the dataset.

26. The non-transitory computer-readable medium of claim 24, wherein the computing node is further configured to:
 based on the comparison, determine that the summation matrix does not match the at least one other summation matrix; and
 based on determining that the summation matrix does not match the at least one other summation matrix, output an error message.

27. The non-transitory computer-readable medium of claim 24, wherein the computing node is further configured to:

generate a reconciliation matrix based on the summation matrix and a weighting matrix, wherein the weighting matrix is distinct from the summation matrix; and
 generate reconciled values associated with the particular time point based on the reconciliation matrix, the summation matrix, and the dataset.

28. The non-transitory computer-readable medium of claim 24, wherein a processing thread of the computing node is further configured to:

determine that the dataset includes a data point with a missing value, the data point being part of a forecast of the plurality of forecasts; and
 based on determine that the dataset has the data point with the missing value:

adjust the summation matrix by removing a column and a row associated with the data point from the summation matrix, to thereby create an adjusted summation matrix;
 generate a reconciliation matrix based on the adjusted summation matrix and a weighting matrix; and
 generate reconciled values associated with the particular time point based on the reconciliation matrix and the dataset.

29. The non-transitory computer-readable medium of claim 24, further comprising program code that is executable by the one or more processors for causing the one or more processors to:

receive a plurality of data tables, each data table of the plurality of data tables corresponding to a respective level of the hierarchy and including all data points from all forecasts of the plurality of forecasts that correspond to that respective level of the hierarchy, wherein each row of each data table of the plurality of data tables corresponds to a single data point of a single forecast of the plurality of forecasts; and

generate a dataset, of the plurality of datasets, by extracting a set of datapoints corresponding to the same time point from the plurality of data tables and grouping them together as the dataset.

30. The non-transitory computer-readable medium of claim 23, wherein the reconciliation process is configured to determine the plurality of reconciled values by:

multiplying a summation matrix by a reconciliation matrix to produce a product; and
 multiplying the product by the plurality of forecasts.

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