



(19) **United States**

(12) **Patent Application Publication**  
**WIGREN et al.**

(10) **Pub. No.: US 2016/0219396 A1**

(43) **Pub. Date: Jul. 28, 2016**

(54) **POSITIONING SYSTEMS AND METHODS FOR DETERMINING THE LOCATION OF A MOBILE COMMUNICATION DEVICE**

**Publication Classification**

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(51) **Int. Cl.**  
*H04W 4/02* (2006.01)  
*H04W 24/08* (2006.01)

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(52) **U.S. Cl.**  
CPC ..... *H04W 4/02* (2013.01); *H04W 24/08* (2013.01)

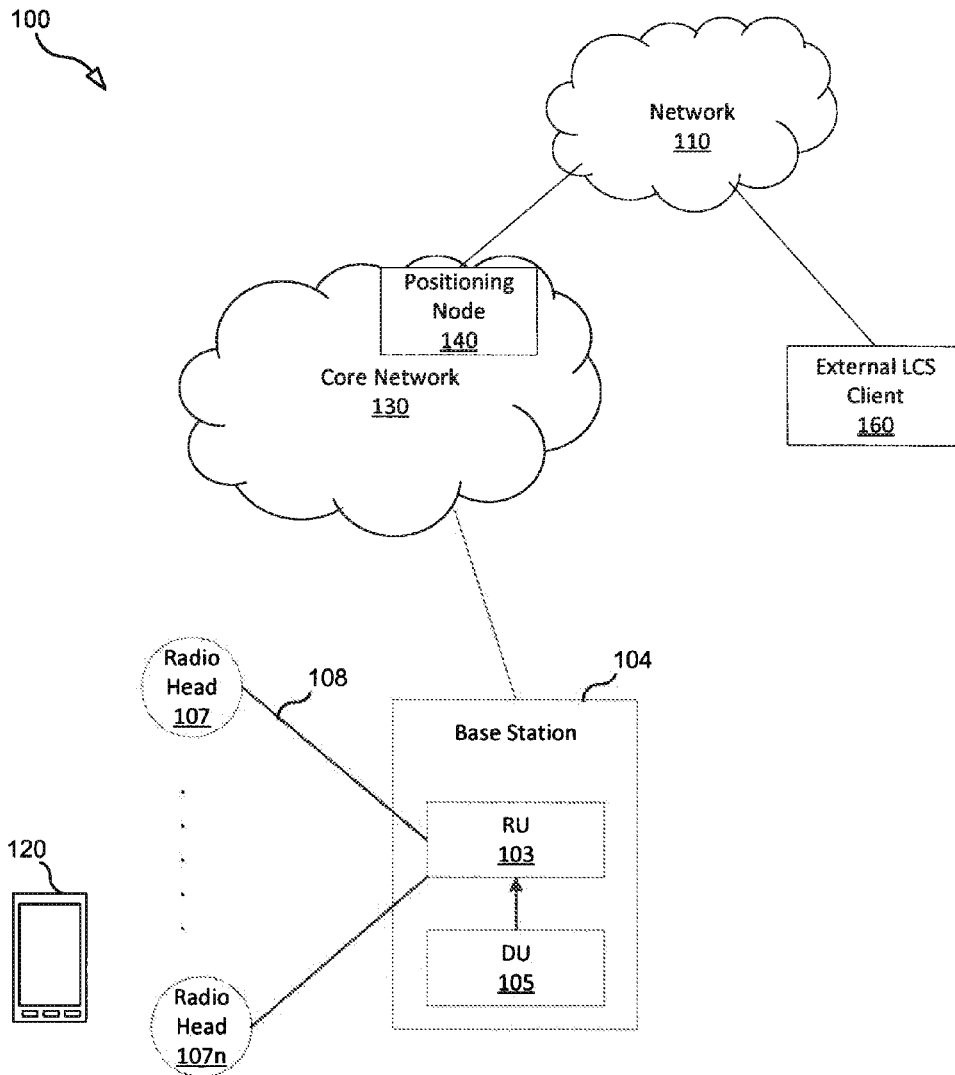
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(57) **ABSTRACT**

A localization approach based on cable length detection. In one aspect, a method performed by a positioning system for determining the location of a mobile communication device (MCD) is provided. In some embodiments, the method includes the positioning system determining a cable length value representative of the length of the cable connecting a base station to a radio head serving the MCD. The positioning system then determines a location of the MCD based on the determined cable length.

(21) Appl. No.: **14/606,287**

(22) Filed: **Jan. 27, 2015**



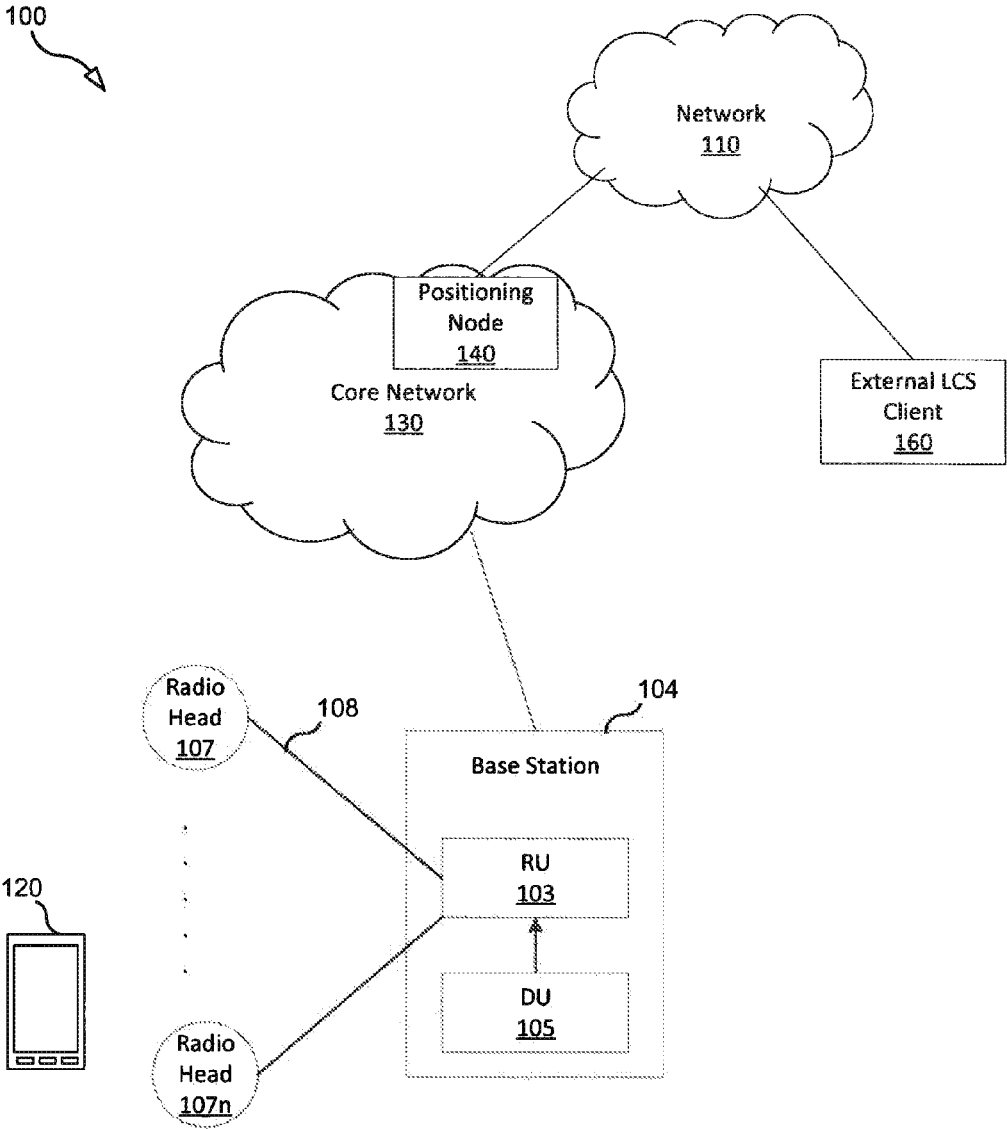


FIG. 1

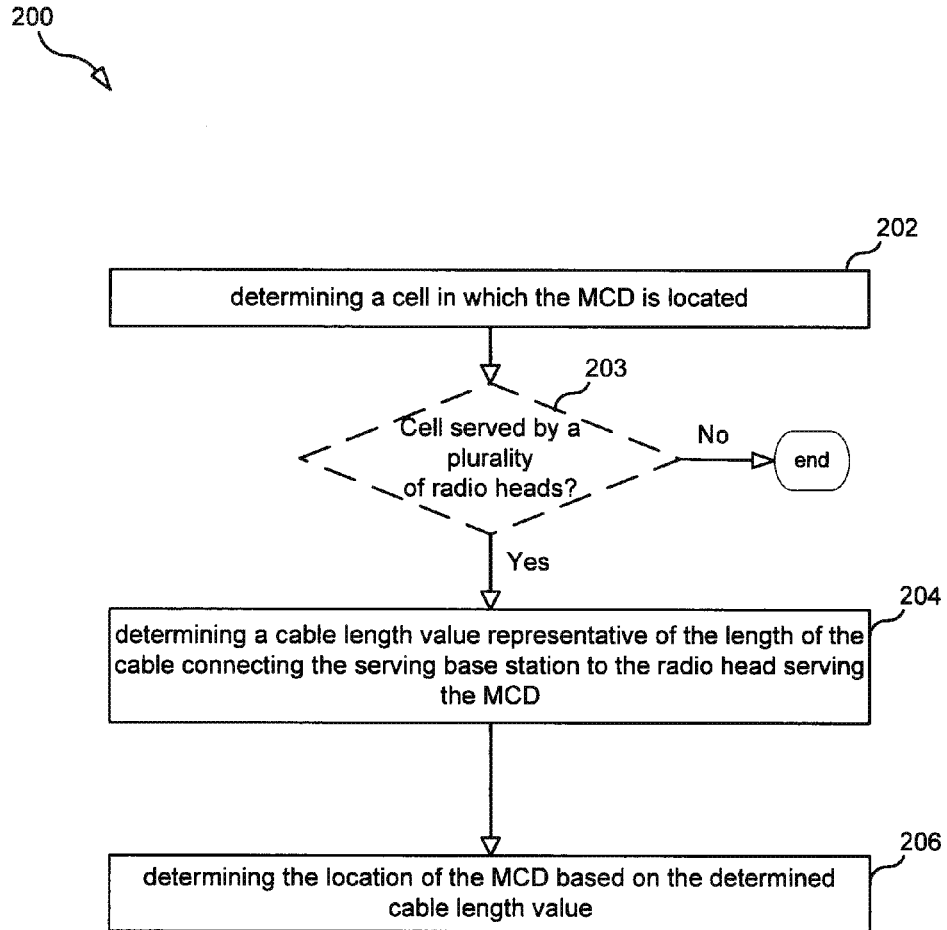


FIG. 2

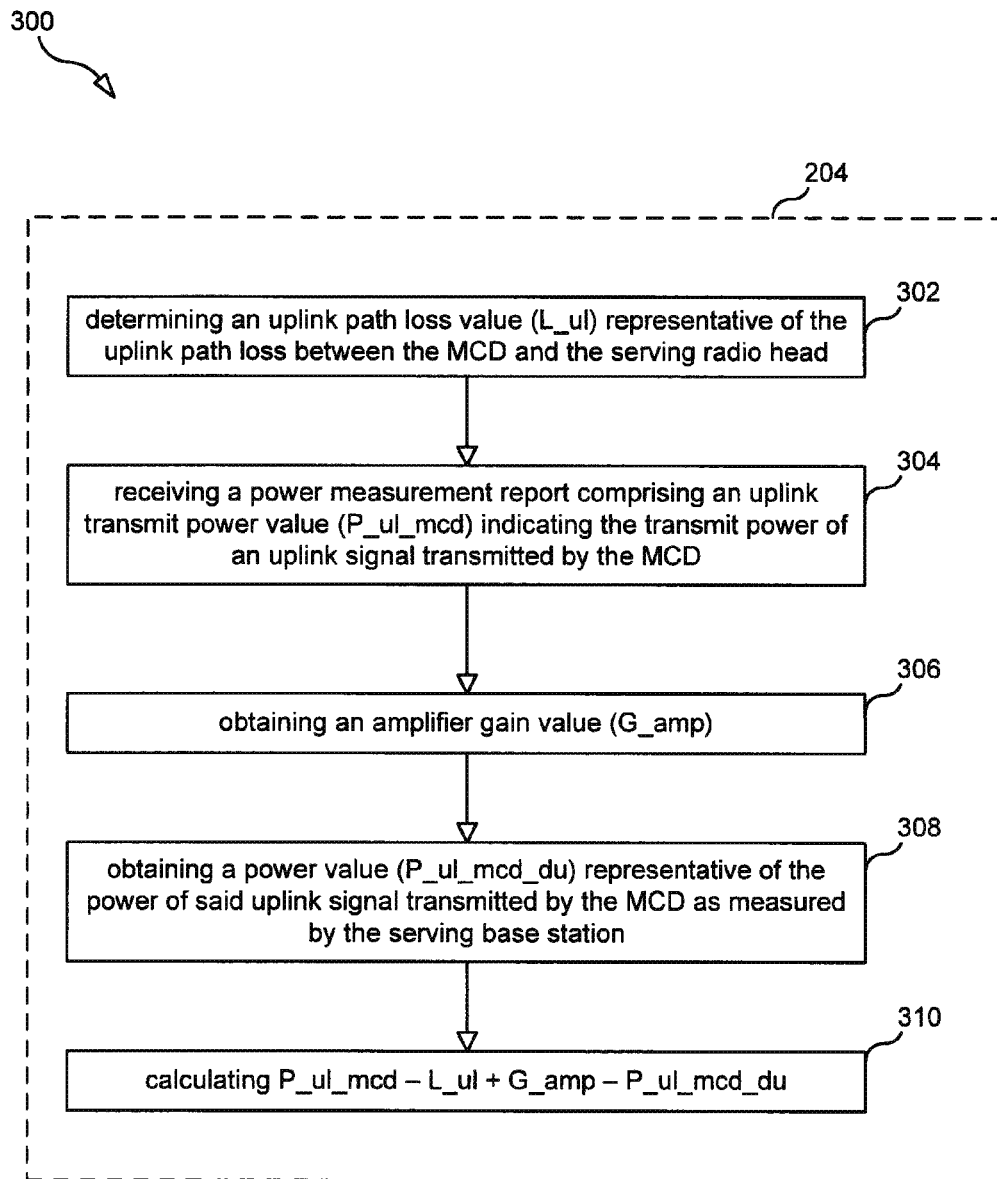


FIG. 3

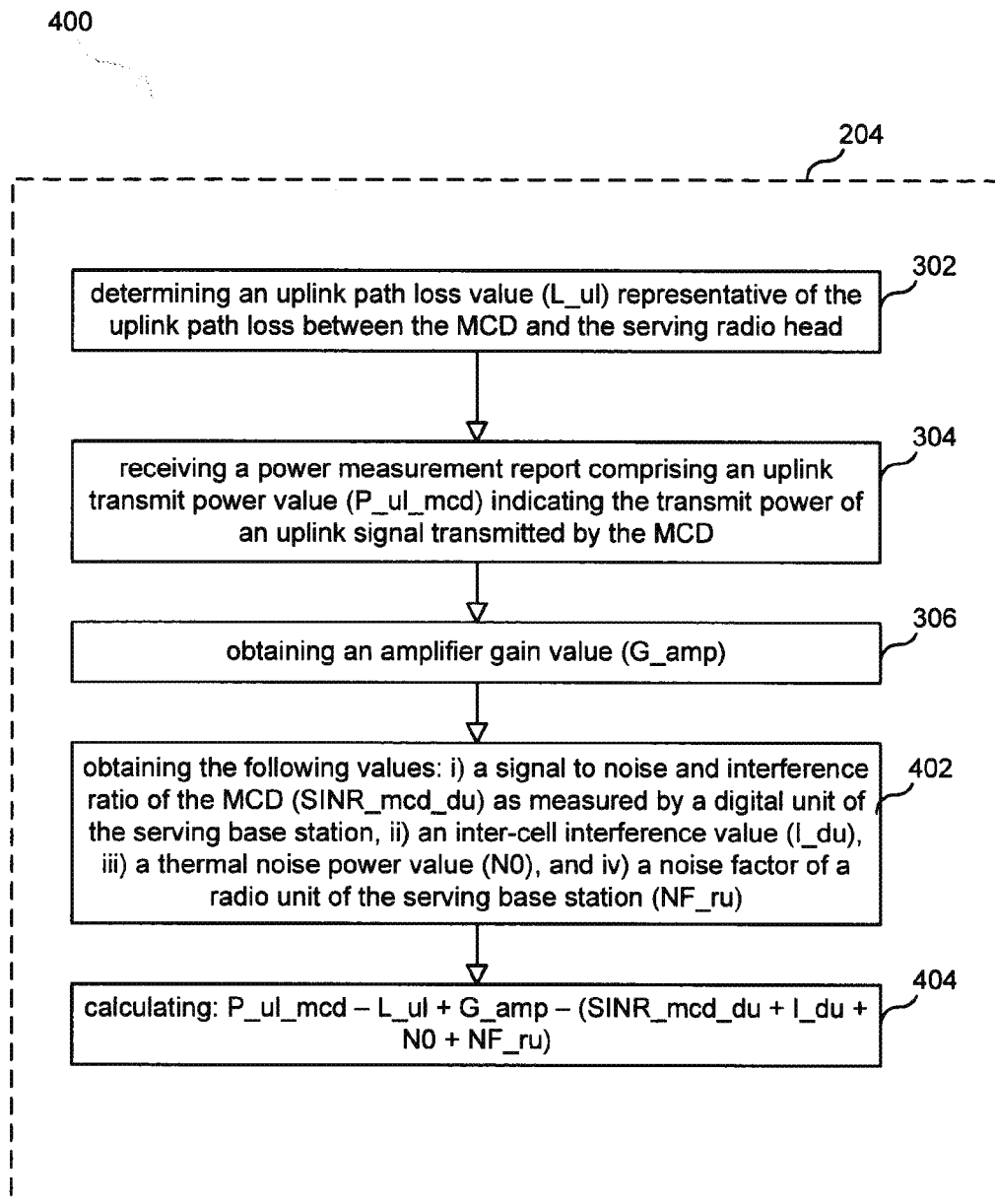


FIG. 4

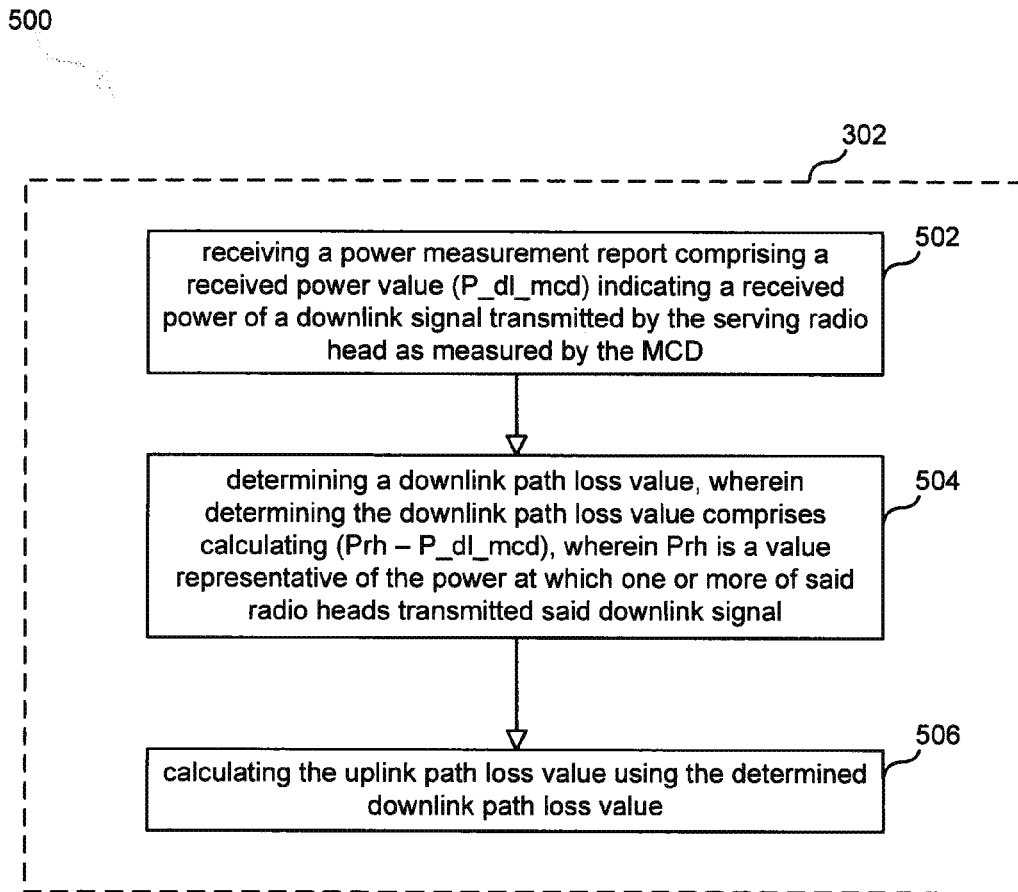


FIG. 5

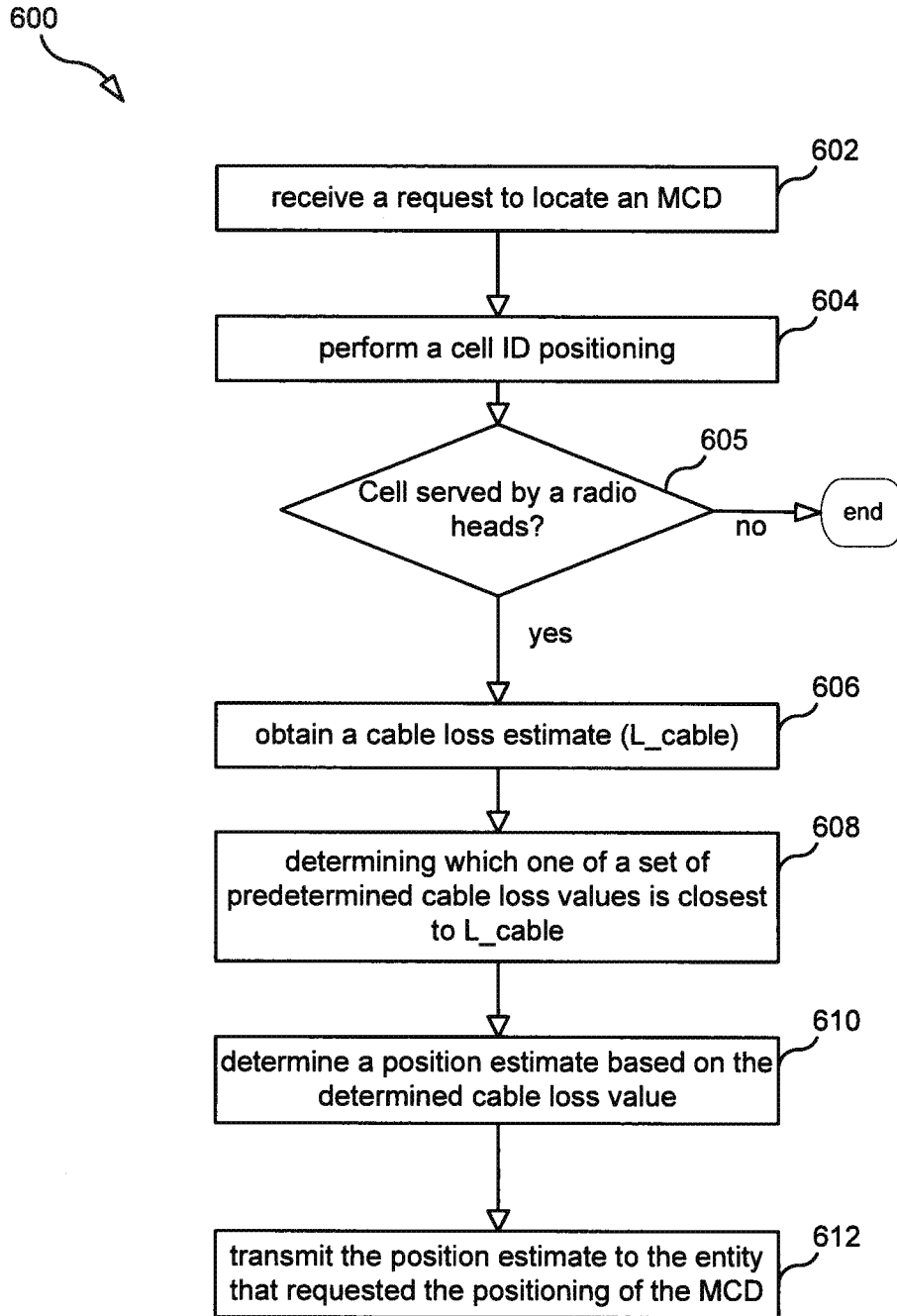


FIG. 6

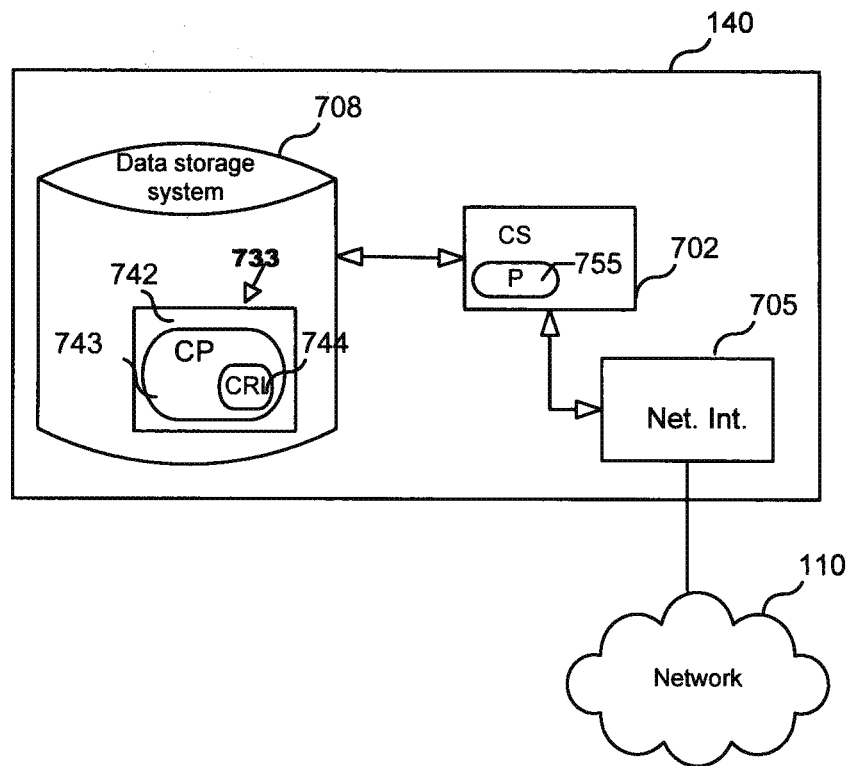


FIG. 7



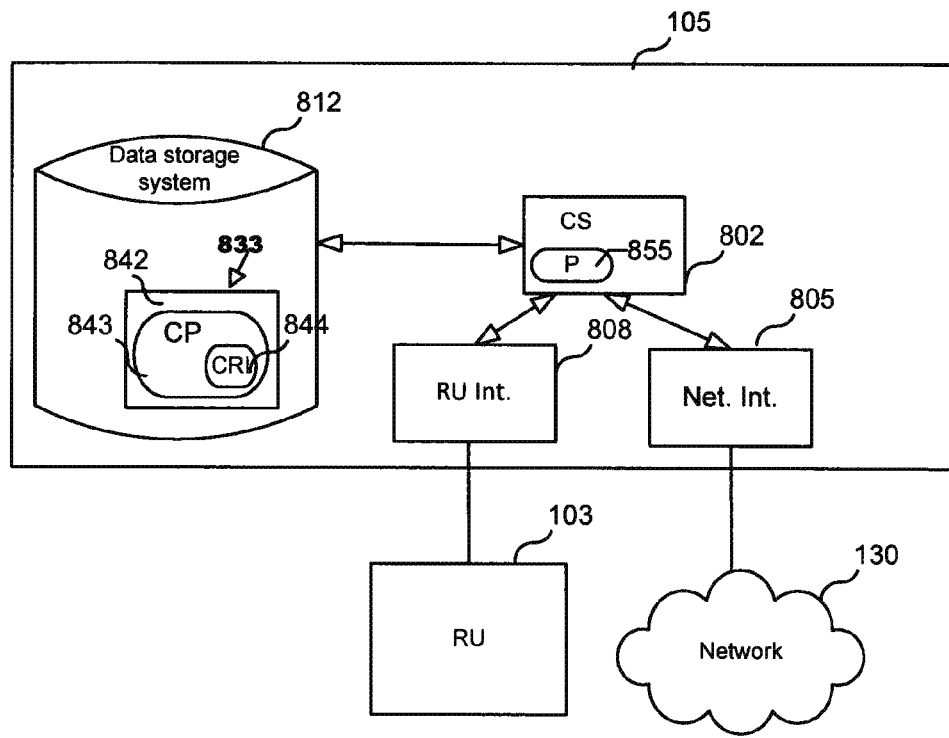


FIG. 8

**POSITIONING SYSTEMS AND METHODS  
FOR DETERMINING THE LOCATION OF A  
MOBILE COMMUNICATION DEVICE**

TECHNICAL FIELD

**[0001]** This disclosure relates to determining the location of a mobile communication device.

BACKGROUND

**[0002]** A cellular communication system is divided into cells, each of which is served by one specific base station. Each base station, however, may serve one or more cells. The base station functions to communicate with mobile communication devices (MCDs) (e.g., smartphones, tablets, phablets, etc.) to provide the MCD with access to a network (e.g., the Internet or other network). A base station typically includes one or more radio units (RU) and a digital unit (DU). An RU typically includes a receiver and a transmitter in order to transmit data to and receive data from an MCD.

**[0003]** The signal transmitted by a base station may be received by an MCD with poor quality when the MCD is in certain locations. For example, when an MCD is located indoors (e.g., in an office building) and the base station that is serving the MCD is located outdoors, the MCD may not receive a strong signal from the base station. Likewise, in such a situation, in order for the MCD to transmit a signal to the base station, the MCD may have to transmit the signal using more power than the MCD would have had to use had the MCD been located outdoors. Such a situation reduces the MCD's battery life.

**[0004]** A solution to this problem is to install small transmitter units (a.k.a., "radio heads") indoors and connect each of the radio heads to the RU of a base station using a cable (e.g., local area network (LAN) cable, such as an Ethernet cable). For example, in a large building with poor network coverage, a radio head connected via a cable to an RU may be placed on each floor of the building. Such a radio head receives via the cable a signal transmitted from the RU and then retransmits the signal wirelessly so that the signal will be received with good quality by an MCD located in the vicinity of the radio head. Likewise, when the MCD transmits a wireless signal, the signal is picked up by the radio head in the vicinity of the MCD and retransmitted by the radio head to the RU via the cable. In this way, a base station can provide good indoor coverage. Accordingly, radio heads include one or more antenna elements for broadcasting and receiving wireless signals, and radio heads may also include amplifiers so that a received signal (e.g., a signal from an RU or a wireless signal from an MCD) can be amplified before it is retransmitted.

**[0005]** One such commercial solution is the Ericsson "Radio Dot System" (RDS). In an RDS, multiple (e.g., one to eight) radio heads are each connected to an RU via an Ethernet cable. The radio heads receive power as well as the communication signals via the cable. In the downlink, each such radio head transmits with a maximum power of 100 mW. Power amplifiers are located in the radio head.

**[0006]** Emergency positioning needs (e.g., E-911) and other location services (LCS) require the position of an MCD to be determined within certain horizontal and vertical accuracies. For example, emergency position requirements may require horizontal inaccuracy to be below 50 meters. Additionally, the vertical inaccuracy requirement has recently

been tightened to 3 meters in North America in order to better distinguish between floors in buildings.

**[0007]** Accordingly, there is a need for an improved system for determining the location of an MCD.

SUMMARY

**[0008]** The fulfillment of emergency positioning requirements when an MCD is located indoors remains a challenging problem. For example, satellite positioning is not always available indoors. Additionally, cell ID positioning (i.e., determining the location of the MCD based on the cell ID of the cell in which the MCD is located) may not be accurate enough to meet the stringent emergency positioning needs. Thus, there exists a need to improve positioning of an MCD, particular when the MCD is located indoors.

**[0009]** This disclosure relates to systems and methods for determining the location of an MCD. In one aspect, a method is performed by a positioning system for determining the location of the MCD. The positioning system includes one or more of: a positioning node and a base station. The method includes the step of determining a cell in which the MCD is located (e.g., receiving a message including a cell identifier (cell ID) identifying the cell in which the MCD is located). The determined cell is served by a serving base station connected to a set of radio heads. Each one of the radio heads included in the set of radio heads is connected to the base station via a cable. One of the radio heads included in the set is serving the MCD. The method further includes determining a cable length value representative of the length of the cable connecting the base station to the radio head serving the MCD. The method further includes determining the location of the MCD based on the determined cable length value. For example, each radio head connected to the base station may be connected to the base station by a different length cable. Thus, determining a value that represents (e.g., corresponds to) the length of the cable that connects the serving radio head to the base station provides information as to which specific radio head is serving the MCD. Thus, each cable length value can be mapped to the coverage region of a specific radio head (e.g., a floor of a building). Accordingly, the location can be determined with improved accuracy compared to traditional cell id positioning.

**[0010]** In some embodiments, determining the cable length value includes calculating a cable loss value ( $L_{\text{cable}}$ ) representative of signal attenuation caused by the cable connecting the serving radio head to the serving base station.

**[0011]** In some embodiments, determining the cable loss value includes determining an uplink path loss value ( $L_{\text{ul}}$ ) representative of the uplink path loss between the MCD and the serving radio head. The method further includes the step of receiving a power measurement report including an uplink transmit power value ( $P_{\text{ul\_mcd}}$ ) indicating the transmit power of an uplink signal transmitted by the MCD. The method further includes the step of obtaining an amplifier gain value ( $G_{\text{amp}}$ ) representing the gain of an amplifier. The method further includes the step of calculating  $L_{\text{cable}}$  using  $P_{13\_ul\_mcd}$ ,  $L_{\text{ul}}$ , and  $G_{\text{amp}}$ .

**[0012]** In some embodiments, the step of determining the cable loss value further includes obtaining a power value ( $P_{\text{ul\_mcd\_du}}$ ) representative of the power of the uplink signal transmitted by the MCD as measured by the serving base station. In such embodiments, calculating  $L_{\text{cable}}$  consists of calculating  $P_{\text{ul\_mcd}} - L_{\text{ul}} + G_{\text{amp}} - P_{\text{ul\_mcd\_du}}$ .

**[0013]** In some embodiments, the step of determining the cable loss value further includes obtaining the following values: i) a signal to noise and interference ratio of the MCD ( $SINR_{mcd\_du}$ ) as measured by a digital unit of the serving base station, ii) an inter-cell interference value ( $I_{du}$ ), iii) a thermal noise power value ( $N0$ ), and iv) a noise factor of a radio unit of the serving base station ( $NF_{ru}$ ). The method further includes the step of calculating  $P_{ul\_mcd} - L_{ul} + G_{amp} - (SINR_{mcd\_du} + I_{du} + N0 + NF_{ru})$ . It is noted that all quantities are expressed in the logarithmic domain in this document, thereby allowing addition of powers and gains.

**[0014]** In some embodiments, the step of determining the uplink path loss value includes: receiving a power measurement report transmitted by the MCD, the power measurement report comprising a received power value ( $P_{dl\_mcd}$ ) indicating a received power of a downlink signal transmitted by the serving radio head as measured by the MCD; determining a downlink path loss value, wherein determining the downlink path loss value comprises calculating ( $Prh - P_{dl\_mcd}$ ), wherein  $Prh$  is a value representative of the power at which one or more of the radio heads transmitted the downlink signal; and obtaining the uplink path loss value based on the downlink path loss value.

**[0015]** In some embodiments, determining the location of the MCD based on the determined cable length value includes the steps of: determining which one of a set of predetermined cable length values is closest to the determined cable length value and estimating the location of the MCD using the predetermined cable length value that was determined to be closest to the determined cable length value.

**[0016]** In another aspect, a positioning system for determining the location of a mobile communication device (MCD) is provided. In some embodiments, the positioning system comprises one or more of: a positioning node; and a base station connected to a set of radio heads, wherein each one of the radio heads included in the set of radio heads is connected to the base station via a cable, and one of the radio heads included in the set is serving the MCD. The positioning system is configured to: determine a cell in which the MCD is located, the determined cell being served by the base station; determine a cable length value representative of the length of the cable connecting the base station to the radio head serving the MCD; and determine the location of the MCD based on the determined cable length value.

**[0017]** The above and other aspects and embodiments are described below.

#### BRIEF DESCRIPTION OF DRAWINGS

**[0018]** FIG. 1 is a block diagram of a positioning system, according to some embodiments.

**[0019]** FIG. 2 is a flow chart of a location method of an MCD, according to some embodiments.

**[0020]** FIG. 3 is a flow chart of a method for determining a cable length value, according to some embodiments.

**[0021]** FIG. 4 is a flow chart of a method for determining a cable length value, according to some embodiments.

**[0022]** FIG. 5 is a flow chart of a method for determining the uplink path loss between an MCD and the serving radio head, according to some embodiments.

**[0023]** FIG. 6 is a flow chart of a location method of an MCD, according to some embodiments.

**[0024]** FIG. 7 is a block diagram of a positioning node apparatus, according to some embodiments.

**[0025]** FIG. 8 is a block diagram of a digital unit apparatus, according to some embodiments.

#### DETAILED DESCRIPTION

**[0026]** Disclosed herein are systems and methods for determining the location of an MCD that is being served by a radio head by determining a value corresponding to the length of the cable connecting the serving radio head to a base station. A significant advantage of the disclosed systems and methods is that they may provide up to eight times reduced position inaccuracy as compared to cell ID positioning. Additionally, the disclosed techniques can be used to improve the accuracy of Radio Measurements Trace processing servers (TPSS). TPSSs play a major role in modern radio access network optimization by using geolocation measurements from MCDs to identify problems in the network. By using the positioning techniques disclosed herein, the position of specific events may be determined with higher accuracy, thereby improving TPS performance.

**[0027]** FIG. 1 is a block diagram of a positioning system 100, according to some embodiments. The positioning system 100 includes a base station 104, which comprises a radio unit (RU) 103 and a digital unit (DU) 105. The RU 103 and the DU 105 may be housed in the same housing or they be housed in separate housings that may or may not be co-located. In some embodiments, such as where the RU 103 and the DU 105 are not coupled in the same housing, DU 103 may be connected to the RU 103 via a cable (e.g., optical, electrical). A plurality of radio heads 107 is connected to base station 104 (more specifically, radio heads 107 are connected to RU 103 of base station 104). In some embodiments, each radio head 107 is connected via a cable 108, such as a local area network (LAN) cable (e.g., an Ethernet cable or other LAN cable), to the RU 103. Radio heads 107 includes one or more antenna elements for wirelessly transmitting signal to an MCD 120 and for wirelessly receiving signal transmitted by MCD 120. In some embodiments, radio heads 107 may further comprise a power amplifier. In some embodiments, RU 103 may comprise an indoor radio unit (IRU), and radio heads 107 may deliver mobile broadband access to the MCD 120 in a broad range of indoor locations.

**[0028]** Base station 104 may be connected to a core network 130 that includes a positioning node 140 for processing position requests as well as other core network nodes (e.g., a Mobility Management Entity (MME), a Serving Gateway (SGW), and Packet Data Network Gateway (PGW)). However, the embodiments disclosed herein are not limited to any specific type of core network. In embodiments where core network 130 is a core network of a Long Term Evolution (LTE) system, the positioning node 140 may comprise or consist of an Evolved Serving Mobile Location Center (E-SMLC) and the base station 104 may comprise or consist of an enhanced Node B (eNB). In embodiments where core network 130 is a WCDMA 3G cellular system, the positioning node 140 may comprise or consist of a stand-alone Serving Mobile Location Center (SAS) and the base station 104 may comprise or consist of a radio network controller (RNC).

**[0029]** In some embodiments, an LCS client 160 may transmit a positioning request to positioning node 140. In some embodiments, as shown in FIG. 1, LCS Client 160 may be a computer server connected to a network (e.g., the Internet), and thus is external to the core network 130.

**[0030]** In embodiments where core network 130 is an LTE network, a Gateway Mobile Location Center (GMLC) in

network **130** may receive from the external LCS client **160** a position request for a particular location services target, e.g., MCD **120**. The GMLC may then transmit the position request to an MME in core network **130**. The MME may in turn forward the request to the positioning node **140** (E-SMLC in this example). The positioning node **140** may then process the location services request to perform a positioning of the target MCD **120**. In some embodiments, the positioning node **140** may perform some or all of the processing for performing the calculations described in connection with FIGS. 2-6. In other embodiments, the base station **104** may perform some or all of the processing for performing the calculations described below in connection with FIGS. 2-6. The positioning node may then return the result of the position request back to the MME, which in turn will forward the position result back to requesting LCB client **160** (e.g., through the GMLC and network **110**).

**[0031]** As described below, in situations where MCD **120** is being served by a radio head **107**, positioning node **140** is configured to determine the location of the MCD **120** by determining a value representative of the length of the cable connecting the radio head **107** that is serving MCD **120** to base station **104**.

**[0032]** In the downlink direction, data from the DU **105** is sent to the RU **120** where it is transmitted in analogue form to the radio heads **107**. In the uplink direction, the signal received on each of the radio heads **107** from the MCD **120** is amplified and then sent to the base station **104**. In some embodiments, the gain of the amplifier can be set individually for each radio head **107**. In some embodiments, there may be significant losses (e.g., up to 30 dB) associated with each cable (up to 200 m) connecting the one or more radio heads **107** to the base station **104**. In some embodiments, such loss values may be configured in a database in base station **104**.

**[0033]** In some embodiments, an estimate of the cable loss ( $L_{\text{cable}}$ ) of the cable **108** connecting base station **104** with the radio head **107** serving the MCD **120** is calculated and then used to determine the location of MCD **102**. The estimated cable loss can be used to determine a position of the MCD because, in many networks, each cable **108** connecting one of the radio heads **107** to base station **104** has a unique cable loss (cable loss is directly proportional to cable length and in many networks each radio head connected to a particular RU of base station **104** is connected by cable having a length that is different than the lengths of the other cables used to connect the other radio heads to the RU). Thus, if the estimated cable loss value is accurate enough, it can be mapped to a specific location because the actual cable lengths (or cable losses) may be measured at installation of the radio heads. Thus, the location of the MCD can be determined more accurately as the cell coverage area may be split up into smaller areas corresponding to each radio head. Furthermore, in embodiments where each radio head is associated with one floor of a building, it may be further possible to resolve location information to a floor of that building.

**[0034]** FIG. 2 is a flow chart of a positioning method **200**, according to some embodiments, performed by a positioning system for determining the location of MCD **120**. In some embodiments, the positioning system comprises one or more of: positioning node **140** and base station **102**.

**[0035]** Referring to FIG. 2, step **202** includes determining a cell in which MCD **120** is located, the determined cell being served by a serving base station (base station **104**, in this example). As discussed above, cellular systems may be

divided into cells, and each cell may be served by one specific base station. In some embodiments, step **202** comprises or consists of the positioning system obtaining a cell identifier (Cell ID) identifying the cell in which the MCD is located (e.g., receiving a message comprising the Cell ID).

**[0036]** In some embodiments, after step **202**, the positioning system determines whether the determined cell is being served by a plurality of radio heads (step **203**). If this is the case, then the process proceeds to step **204**. For example, in step **203** the positioning system may use the Cell ID to obtain a database record from a database, which database record includes information identifying whether or not the determined cell is being served by a plurality of radio heads.

**[0037]** Step **204** includes determining a cable length value ( $C_{\text{length}}$ ) representative of the length of the cable connecting the serving base station to the radio head serving the MCD. In some embodiments, determining the cable length value consists of determining a cable loss value denoted  $L_{\text{cable}}$ . In some embodiments, the positioning node **140** may instruct the base station **104** to perform step **204**.

**[0038]** In step **206**, a location of the MCD is determined based on the determined cable length value. For example, in step **206** an area in which the MCD is likely to be found is determined based on the determined cable length value.

**[0039]** In some embodiments, determining the location of the MCD based on the determined cable length value comprises: obtaining a set of predetermined cable length values; determining which one of a set of predetermined cable length values is closest to the determined cable length value; and estimating the location of the MCD using the predetermined cable length value that was determined to be closest to the determined cable length value.

**[0040]** In some embodiments, estimating the location of the MCD using the predetermined cable length value that was determined to be closest to the determined cable length value comprises using the predetermined cable length value to retrieve location information from a database (e.g., from a table). That is, each of the predetermined cable length values may be stored in a table that maps the predetermined cable length value to a position (e.g., to a floor of a building or a set of coordinates). Thus, determining an estimate of the cable length value allows one to map that information to a specific area (i.e., the entire area served by the serving radio head). In some embodiments, estimating the location of the MCD further comprises obtaining a path loss value representative of a path loss between the MCD and the serving radio head and using the path loss value to estimate the distance between the MCD and the serving radio head. This enables path loss feature enables the positioning system to further narrow the area in which the MCD is likely to be found. Additionally, in some embodiments, an Adaptive Enhanced Cell Identity (AECID) fingerprinting method known in the art could be augmented to take into account location information determined in step **206**.

**[0041]** In some other embodiments, determining the location of the MCD based on the determined cable length value ( $C_{\text{length}}$ ) comprises: obtaining a set of predetermined cable length values ( $C_{\text{length\_pre\_i}}$ ,  $i=1, 2, \dots, N$ ); determining a subset of the set of predetermined cable length values that are within a certain threshold distance ( $T$ ) of the determined cable length value; and estimating the location of the MCD using the determined subset of predetermined cable length values. That is, if  $|C_{\text{length\_pre\_i}} - C_{\text{length}}| < T$ , then  $C_{\text{length\_pre\_i}}$  is included in the subset of predetermined

cable length values that are used to determine the location of the MCD. In some embodiments, when the subset includes two or more predetermined cable length values, the location of the MCD may be determined to be the union of the coverage areas of the radio heads corresponding to the subset of predetermined cable length values.

**[0042]** In some embodiments, step 204 includes calculating a plurality of cable length values ( $C\_length\_i, i=1, 2, \dots, M$ ) (e.g., one cable length value is calculated for each radio head included in the set of radio heads). This could be needed since different radio heads may have different gain settings depending on the cable length. In this embodiment, each of the plurality of predetermined cable length values (i.e.,  $C\_length\_pre\_i$ ) is compared against at least one of the calculated cable length values ( $C\_length\_i$ ) in order to determine the predetermined cable length value that is closest to a calculated cable length value. For the case where  $M=N$ , one computes:

**[0043]**  $\text{Argmin} [|C\_length\_i - C\_length\_pre\_i|, i]$  to determine the predetermined cable length value that is closest to a calculated cable length value. Alternatively, each of the plurality of predetermined cable length values is compared against at least one of the calculated cable length values in order to determine the subset of zero or more predetermined cable length values that are within a threshold distance of a calculated cable length value. As discussed above, this determined subset of predetermined cable length values is used to determine the position of the MCD.

**[0044]** In some embodiments, the set of predetermined cable length values may be obtained by retrieving the set of values from a database using the cell ID of the cell in which the MCD is located. That is, in some embodiments, the database links each cell ID included in a certain set of cell IDs with a set of cable length values. For example, suppose a given cell ID (e.g., cell-id-123) identifies a cell served by an RU of a base station that is connected to a set of radio heads. The database may link the given cell ID with a set of cable length values, where each one of the cable length values represents the length of the cable connecting one of the radio heads to the RU. The database may be hosted by DU 105, positioning node 140, or another entity.

**[0045]** In some embodiments, a 90% confidence radius (or other pre-configured confidence limit) may be calculated for every radio head position by calculating the standard deviation of  $C\_length\_pre\_i$  around determined  $C\_length$ . The confidence radius around the radio head will be given as function of Standard deviation of  $C\_length\_pre\_i$  shown below in the equation below:

$$RH\_Conf\_Radius = f(\text{Standard\_deviation}(C\_length\_pre\_i)).$$

**[0046]** The calculated confidence interval could then be forwarded to a location based service or TPS system in a similar manner as Cell ID, TA, and other methods.

**[0047]** FIG. 3 is a flow chart of a method 300, according to some embodiments, performed by the positioning system for determining a cable length value. As noted above, the positioning system includes one or more of: positioning node 140 and base station 104.

**[0048]** In step 302, an uplink path loss value ( $L\_ul$ ) representative of the uplink path loss between the MCD and the serving radio head is determined. In some embodiments,  $L\_ul$  may be determined from a calculated downlink path loss ( $L\_dl$ ) value. Thus, in some embodiments, in order to determine  $L\_ul$ , the positioning node 140 may first order the base

station 104 to determine the downlink path loss ( $L\_dl$ ). Determination of the  $L\_ul$  value from the  $L\_dl$  value is described in further detail below in connection with FIG. 5.

**[0049]** In step 304, a power measurement report comprising an uplink transmit power value ( $P\_ul\_mcd$ ) indicating the transmit power of an uplink signal transmitted by the MCD is received. In some embodiments, the MCD 120 may report its uplink transmit power  $P\_ul\_mcd$ . In some embodiments, measurement orders may be transmitted to the MCD 120 from the serving base station 104 for the MCD to report the  $P\_ul\_mcd$  value. In the case of a Trace Processing Server (TPS) geolocation scenario, TPS may utilize 3G/4G Radio Enhanced Statistics (RES) features which turn on measurements on all MCDs to report  $P\_ul\_mcd$ , the uplink transmit power, in measurement reports. These measurements are called UeTxPower measurement, and are reported periodically (e.g., as frequently as every 2 seconds). Thus, the base station 104 may receive the  $P\_ul\_mcd$  value from the base station and perform further processing using that value. In other embodiments, the base station 104 may forward the  $P\_us\_mcd$  value to the positioning node 140 for further processing.

**[0050]** In step 306, an amplifier gain value is obtained. The amplifier gain value ( $G\_amp$ ) may be set individually for each radio head 107 or each radio head may use the same amplifier gain value. In the latter case, only a single cable length value needs to be calculated, otherwise, in the former case the set of cable length values ( $C\_length\_i$ ) is calculated, as described above. In some embodiments, the positioning node 140 and/or base station 104 may obtain  $G\_amp$  from preconfigured information stored in a database.

**[0051]** In step 308, the power value representative of the power of the uplink signal transmitted by the MCD as measured by the serving base station ( $P\_ul\_mcd\_du$ ) is obtained. In some embodiments, the  $P\_ul\_mcd\_du$  value can be determined from power headroom reports and the configured maximum value of the MCD 120 power. In some embodiments, the received MCD power ( $P\_ul\_mcd\_du$ ) is measured directly in the DU 105 of base station 104, e.g., after despreading in a WCDMA network. In some embodiments, the base station 104 sends the  $P\_ul\_mcd\_du$  value to the positioning node 140, for further processing.

**[0052]** In step 310,  $P\_ul\_mcd - L\_ul + G\_amp - P\_ul\_mcd\_du$  is calculated. In some embodiments, the positioning node 140 performs the calculation in step 310. In other embodiments, the base station 104 performs the calculation in step 310. In some embodiments, the cable loss value for the radio head ( $L\_cable\_i$ ) connected to the MCD 120 is calculated according to the equation below:

$$L\_cable\_i = P\_ul\_mcd - G\_amp - P\_ul\_mcd\_du$$

**[0053]** As described above, the cable loss value  $L\_cable\_i$  is representative of the length of the cable connecting the serving base station 104 to the radio head 107 serving the MCD 120.

**[0054]** FIG. 4 is a flow chart of a method 400 for determining a cable length value, according to other embodiments. In some embodiments, the steps of cable length value determination method 400 may be performed by a positioning node 140. In other embodiments, the steps of cable length value determination method 400 may be performed by both a positioning node 140 and a base station 104. Like, method 300, method 400 includes steps 302-306 (see FIG. 3).

[0055] In step 402, the following values are obtained: i) a signal to noise and interference ratio of the MCD as measured by a DU of the base station serving the MCD (SINR\_mcd\_du), ii) an inter-cell interference value (I\_du), iii) a thermal noise power value (NO), and iv) a noise factor of a radio unit of the serving base station (NF\_ru).

[0056] The SINR\_mcd\_du value is measured by the DU 105 of the serving base station 104. Thus, in some embodiments, the base station 104 may obtain the SINR\_mcd\_du value and perform further processing using that value. In some embodiments, the DU 105 of base station 104 may simply transmit the SINR\_mcd\_du value to the positioning node 140 for further processing.

[0057] The NO+NF\_ru value may be estimated in the RU 103 of base station 104. Alternatively, in some embodiments, instead of estimating values of NO+NF\_ru, pre-configured values may be used. In other embodiments, different algorithms may be used to estimate the NO+NF\_ru value.

[0058] One algorithm for estimating the NO+NF\_ru value is the sliding window noise floor estimation. Since it may not be possible to obtain exact estimates of this value due to neighbor cell interference, the estimation algorithm applies an approximation using the soft minimum computed over a long window of time. Thus, this estimation relies on the fact that the noise floor may be constant over very long periods of time, disregarding the small temperature drift. However, the sliding window algorithm has a disadvantage of requiring a large amount of storage memory. The amount of storage memory may be particularly troublesome in cases where a large number of instances of the algorithm are needed, which may be the case when interference cancellation is introduced in the uplink.

[0059] Another algorithm for estimating the NO+NF\_ru value is the recursive noise floor estimation. For example, to reduce the memory consumption of the sliding window algorithm described above, one such recursive algorithm is disclosed in T. Wigren, "Recursive noise floor estimation in WCDMA," IEEE Trans. Vehicular Tech., vol. 69, no. 5, pp. 2615-2620, 2010. The recursive algorithm may reduce the memory requirements of the sliding window algorithm described above by at least a factor of 100.

[0060] Thus, the NO+NF\_ru value may be estimated by the base station 104 and be used for further processing. In some embodiments, the base station 104 may forward the NO+NF\_ru value to the positioning node 140 for further processing.

[0061] Once the NO+NF\_ru value is obtained, the neighbor cell interference value (I\_du) may be determined using the equation shown below.

$$I_{du} = P_{mcd\_total} - P_{ul\_mcd\_du} - NO_{NF\_ru}$$

[0062] A more detailed explanation of the calculation of I\_du is disclosed in T. Wigren, "Soft uplink load estimation in WCDMA," IEEE Trans. Vehicular Tech., vol. 58, no. 2, pp. 760-772, February 2009, which is incorporated herein by reference.

[0063] In step 404, the following value is calculated, which is representative of the cable loss value of the cable (L\_cable\_i) connecting the serving base station 104 to the radio head 107 serving the MCD 120:

$$L_{cable\_i} = P_{ul\_mcd} - L_{ul} + G_{amp} - (SINR_{mcd\_du} + I_{du} + NO + NF_{ru})$$

[0064] Thus, in alternative embodiments, a value representative of (SINR\_mcd\_du+I\_du+NO+NF\_ru) may be used in

lieu of the P\_ul\_mcd\_du value described above in connection with step 308 of FIG. 3. The relationship between these two values is shown below:

$$P_{ul\_mcd\_du} = SINR_{mcd\_du} + I_{du} + NO + NF_{ru}$$

[0065] FIG. 5 is a flow chart of a method 500, according to some embodiments, for determining an uplink path loss value (L\_ul) representative of the uplink path loss between the MCD and the serving radio head.

[0066] In step 502, a power measurement report comprising a received power value (P\_dl\_mcd) indicating a received power of a downlink signal transmitted by the serving radio head as measured by the MCD is received. In some embodiments, the MCD 120 may measure the received power (P\_dl\_mcd) for the radio head 107 to which it is connected. In some embodiments, measurement orders may be transmitted to the MCD 120 from the serving base station 104 for MCD to measure the P\_dl\_mcd value. In the case of a TPS geolocation scenario, TPS may utilize 3G/4G RES features which turn on measurements on all MCDs to report P\_dl\_mcd, the downlink transmit power, in measurement reports. These measurements are called UeRxPower measurement and are reported periodically (e.g., as frequently as every 2 seconds). Thus, the MCD 120 may transmit the measured P\_dl\_mcd value in a measurement report as the UeRxPower to the base station 104. In some embodiments, base station 104 may send the P\_dl\_mcd value to the positioning node 140 for determination of L\_ul, and in other embodiments, determination of L\_ul may be performed by the base station 104.

[0067] In step 504, a downlink path loss value (L\_dl) is determined, wherein the determination comprises calculating (P\_dl\_mcd-Prh), wherein Prh is a value representative of the power at which the radio head transmitted the downlink signal. In some embodiments, the configured downlink transmit power Prh may be known for each radio head 107. Thus, a downlink path loss value (L\_dl) may be determined according to the equation below:

$$L_{dl} = P_{rh} - P_{dl\_mcd}$$

[0068] In embodiments where all radio heads have a different power (Prh\_i) in the downlink signal, the L\_dl\_i value may be determined according to the equation below:

$$L_{dl\_i} = Prh_i - P_{dl\_mcd}$$

[0069] Alternatively, in some embodiments, a dedicated measurement may be used for L\_dl.

[0070] In step 506, the uplink path loss value is calculated using the determined downlink path loss value. Thus, in some embodiments the uplink path loss value (L\_ul) may be determined from the downlink path loss (L\_dl) value determined in step 504. In some embodiments, once the L\_dl value is determined, the positioning node 140 may then order the base station 104 to perform a measurement of the uplink path loss (L\_ul). Alternatively, the positioning node 140 may perform a measurement of the uplink path loss. In some embodiments, it may be assumed (for simplicity) that the propagation conditions of the uplink are similar to those of the downlink, and thus L\_ul = L\_dl. For example, in the case of time division duplex, the reciprocity of the propagation can be used to motivate why L\_ul = L\_dl.

[0071] Alternatively, in the case of frequency division duplex, a calculation that is correct on average may be made to conclude a functional dependence between L\_ul and L\_dl. In such scenarios, a compensation value depending on the

carrier frequency ( $f_{carrier}$ ) is typically needed. Thus, the following general relation shown in the equation below may be assumed to hold:

$$L_{ul} = F(L_{dl}, f_{carrier})$$

[0072] The above relation may have errors; however, these errors may be assumed to be small as compared to the cable loss variation that may approach 30 dB for the Ethernet cable technology used with certain small cell systems, such as DTS.

[0073] FIG. 6 is a flow chart of a location method 600, according to some embodiments. Method 600 may be performed by the positioning node 140 and/or the base station 104.

[0074] In step 602, a request is received to locate an MCD. For example, in some embodiments, the location request may be submitted by a LCS client 160 to the positioning node 140, potentially through one or more intermediaries as described above. In some embodiments, once the positioning node 140 receives the location request.

[0075] In step 604, a cell ID positioning is performed. For example, the positioning system obtains a cell ID identifying the cell in which the MCD is located.

[0076] In step 605, based on the obtained cell ID, a determination is made as to whether the cell identified by the cell ID is served by a plurality of radio heads connected to a base station. If yes, the process continues to step 606, otherwise the process ends.

[0077] In step 606, a cable loss estimate ( $L_{cable}$ ) is obtained. The cable loss estimate  $L_{cable}$  value may be obtained by the positioning node 140 and/or the base station 104 as described above in connection with FIGS. 3-4.

[0078] In step 608, a determination is made as to which one of a set of predetermined cable loss values is closest to  $L_{cable}$ . The determination made be made by the base station 104 and/or the positioning node 140.

[0079] In step 610, a position estimate is determined based on the determined cable loss value ( $L_{cable}$ ). The position estimate is determined by the base station 104 and/or the positioning node 140 as described above in connection with step 206 of FIG. 2.

[0080] In step 612, the position estimate is transmitted to the entity that requested the positioning of the MCD. For example, in some embodiments, the base station 104 and/or the positioning node 140 may transmit the positioning of the MCD 120 to the original LCS client 160 that submitted the location request.

[0081] FIG. 7 is a block diagram of a positioning node apparatus, such as positioning node 140. As shown in FIG. 7, positioning node apparatus 140 may include or consist of: a computer system (CS) 702, which may include one or more processors 755 (e.g., a microprocessor) and/or one or more circuits, such as an application specific integrated circuit (ASIC), field-programmable gate arrays (FPGAs), a logic circuit, and the like; a network interface 705 for connecting apparatus 104 to a network 110; and a data storage system 708, which may include one or more non-volatile storage devices and/or one or more volatile storage devices (e.g., random access memory (RAM)).

[0082] In embodiments where apparatus 140 includes a processor 755, a computer program product (CPP) 733 may be provided. CPP 733 includes or is a computer readable medium (CRM) 742 storing a computer program (CP) 743 comprising computer readable instructions (CRI) 744 for performing steps described herein (e.g., one or more of the

steps shown in FIGS. 2-6). CP 743 may include an operating system (OS) and/or application programs. CRM 742 may include a non-transitory computer readable medium, such as, but not limited to, magnetic media (e.g., a hard disk), optical media (e.g., a DVD), solid state devices (e.g., random access memory (RAM), flash memory), and the like.

[0083] In some embodiments, the CRI 744 of computer program 743 is configured such that when executed by computer system 702, the CRI causes the apparatus 740 to perform steps described above (e.g., steps described above and below with reference to the flow charts shown in the drawings). In other embodiments, positioning node apparatus 140 may be configured to perform steps described herein without the need for a computer program. That is, for example, computer system 702 may consist merely of one or more ASICs. Hence, the features of the embodiments described herein may be implemented in hardware and/or software.

[0084] FIG. 8 is a block diagram of DU 105, according to some embodiments. As shown in FIG. 4, DU apparatus 105 may include or consist of: a computer system (CS) 802, which may include one or more processors 855 (e.g., a microprocessor) and/or one or more circuits, such as an application specific integrated circuit (ASIC), field-programmable gate arrays (FPGAs), a logic circuit, and the like; a network interface 805 for connecting DU 105 to network 130; one or more RU interfaces 808 for connecting DU 105 to one more RUs; and a data storage system 812, which may include one or more non-volatile storage devices and/or one or more volatile storage devices (e.g., random access memory (RAM)). In some embodiments, network interface 805 and RU interface 808 include a transceiver for transmitting data and receiving data.

[0085] In embodiments where DU apparatus 105 includes a processor 855, a computer program product (CPP) 833 may be provided. CPP 833 includes or is a computer readable medium (CRM) 842 storing a computer program (CP) 843 comprising computer readable instructions (CRI) 844 for performing steps described herein (e.g., one or more of the steps shown in FIGS. 2-6). CP 843 may include an operating system (OS) and/or application programs. CRM 842 may include a non-transitory computer readable medium, such as, but not limited to, magnetic media (e.g., a hard disk), optical media (e.g., a DVD), solid state devices (e.g., random access memory (RAM), flash memory), and the like.

[0086] In some embodiments, the CRI 844 of computer program 843 is configured such that when executed by computer system 802, the CRI causes the apparatus 105 to perform steps described above (e.g., steps described above and below with reference to the flow charts shown in the drawings). In other embodiments, apparatus 105 may be configured to perform steps described herein without the need for a computer program. That is, for example, computer system 802 may consist merely of one or more ASICs. Hence, the features of the embodiments described herein may be implemented in hardware and/or software.

[0087] While various embodiments have been described above, it should be understood that they have been presented by way of example only, and not limitation. Thus, the breadth and scope of the present invention should not be limited by any of the above-described exemplary embodiments. Moreover, any combination of the above-described elements in all possible variations thereof is encompassed by the invention unless otherwise indicated herein or otherwise clearly contradicted by context.

**[0088]** Additionally, while the processes described above and illustrated in the drawings are shown as a sequence of steps, this was done solely for the sake of illustration. Accordingly, it is contemplated that some steps may be added, some steps may be omitted, the order of the steps may be rearranged, and some steps may be performed in parallel.

**[0089]** Abbreviations

**[0090]**  $RH_i$ =Radio head  $i$  of a maximum of  $n$ .

**[0091]**  $P_{ul\_mcd}$ =The uplink transmit power as measured by the MCD [dBw].

**[0092]**  $P_{dl\_mcd}$ =The measured received power in the downlink as measured by the MCD [dBw]

**[0093]**  $L_{ul}$ =The uplink path loss between the MCD and the serving radio head [dB].

**[0094]**  $L_{dl}$ =The downlink path loss between the serving radio head and the MCD [dB].

**[0095]**  $Prh$ =The transmit power of the radio head [dBw].

**[0096]**  $G_{amp}$ =The gain of the uplink amplifier of the radio head [dB].

**[0097]**  $L_{cable}$ =The determined cable loss [dB].

**[0098]**  $NF_{ru}$ =The noise factor of the RU [dB].

**[0099]**  $SINR_{mcd\_du}$ =The signal to noise and interference ratio of the MCD, as measured in the DU [dB]

**[0100]**  $P_{ul\_mcd\_du}$ =The MCD power, as measured in the DU [dBw].

**[0101]**  $P_{mcd\_total}$ =the total power of the MCD

**[0102]**  $N_0$ =Thermal noise power [dBw].

**[0103]**  $I_{du}$ =Inter-cell interference [dBw].

**[0104]**  $C_{length}$ =a cable length value

1. A method performed by a positioning system for determining a location of a mobile communication device (MCD), the method comprising:

determining a cell in which the MCD is located, said determined cell being served by a base station connected to a set of radio heads, wherein each one of the radio heads included in said set of radio heads is connected to the base station via a cable, and one of said radio heads included in said set is serving the MCD;

determining a cable length value representative of the length of the cable connecting the base station to said radio head serving the MCD, wherein determining the cable length value comprises calculating a cable loss value ( $L_{cable}$ ) representative of signal attenuation caused by the cable connecting the serving radio head to the base station by

determining an uplink path loss value ( $L_{ul}$ ) representative of the uplink path loss between the MCD and the serving radio head,

receiving a power measurement report comprising an uplink transmit power value ( $P_{ul\_mcd}$ ) indicating the transmit power of an uplink signal transmitted by the MCD,

obtaining an amplifier gain value ( $G_{amp}$ ) representing the gain of an amplifier, and

calculating the  $L_{cable}$  using  $P_{ul\_mcd}$ ,  $L_{ul}$ , and  $G_{amp}$ ; and

determining the location of the MCD based on the determined cable length value.

2. (canceled)

3. (canceled)

4. The method of claim 1, wherein

determining the cable loss value further comprises obtaining a power value ( $P_{ul\_mcd\_du}$ ) representative of the

power of said uplink signal transmitted by the MCD as measured by the base station, and

calculating  $L_{cable}$  comprises calculating  $P_{ul\_mcd}-L_{ul}+G_{amp}-P_{ul\_mcd\_du}$ .

5. The method of claim 1, wherein

determining the cable loss value further comprises obtaining the following values: i) a signal to noise and interference ratio of the MCD ( $SINR_{mcd\_du}$ ) as measured by a digital unit of the base station, ii) an inter-cell interference value ( $I_{du}$ ), iii) a thermal noise power value ( $N_0$ ), and iv) a noise factor of a radio unit of the base station ( $NF_{ru}$ ), and

calculating  $L_{cable}$  comprises calculating:  $P_{ul\_mcd}-L_{ul}+G_{amp}-(SINR_{mcd\_du}+I_{du}+N_0+NF_{ru})$ .

6. The method of claim 1, wherein the step of determining the uplink path loss value comprises:

receiving a power measurement report transmitted by the MCD, the power measurement report comprising a received power value ( $P_{dl\_mcd}$ ) indicating a received power of a downlink signal transmitted by the serving radio head as measured by the MCD;

determining a downlink path loss value, wherein determining the downlink path loss value comprises calculating ( $Prh-P_{dl\_mcd}$ ), wherein  $Prh$  is a value representative of the power at which one or more of said radio heads transmitted said downlink signal; and

obtaining the uplink path loss value based on the downlink path loss value.

7. The method of claim 1, wherein determining the cell in which the MCD is located comprises receiving a message comprising a cell identifier (cell ID) identifying the cell in which the MCD is located.

8. The method of claim 1, wherein the positioning system comprises one or more of: the base station and a positioning node.

9. The method of claim 1, wherein determining the location of the MCD based on the determined cable length value comprises:

determining which one of a set of predetermined cable length values is closest to the determined cable length value; and

estimating the location of the MCD using the predetermined cable length value that was determined to be closest to the determined cable length value.

10. The method of claim 1, wherein

determining the cell in which the MCD is located comprises obtaining an cell identifier (Cell ID) identifying the cell in which the MCD is located, and

the method further comprises using the Cell ID to determine whether the cell identified by the Cell ID is being served by a plurality of radio heads.

11. A positioning system for determining a location of a mobile communication device (MCD), said positioning system comprising one or more of:

a positioning node; and

a base station connected to a set of radio heads, wherein each one of the radio heads included in said set of radio heads is connected to the base station via a cable, and one of said radio heads included in said set is serving the MCD

the positioning system is configured to:

determine a cell in which the MCD is located, said determined cell being served by the base station;



determine a cable length value representative of the length of the cable connecting the base station to said radio head serving the MCD, wherein the determine the cable length value comprises calculating a cable loss value ( $L_{\text{cable}}$ ) representative of signal attenuation caused by the cable connecting the serving radio head to the base station by:

determining an uplink path loss value ( $L_{\text{ul}}$ ) representative of the uplink path loss between the MCD and the serving radio head;

obtaining an uplink transmit power value ( $P_{\text{ul\_mcd}}$ ) indicating the transmit power of an uplink signal transmitted by the MCD;

obtaining an amplifier gain value ( $G_{\text{amp}}$ ) representing the gain of an amplifier; and

calculating the  $L_{\text{cable}}$  using  $P_{\text{ul\_mcd}}$ ,  $L_{\text{ul}}$ , and  $G_{\text{amp}}$ ; and

determine the location of the MCD based on the determined cable length value.

12. (canceled)

13. (canceled)

14. The positioning system of claim 11, wherein the positioning system is further configured to:

obtain a power value ( $P_{\text{ul\_mcd\_du}}$ ) representative of the power of said uplink signal transmitted by the MCD as measured by the base station, and

calculate  $L_{\text{cable}}$  by calculating  $P_{\text{ul\_mcd}} - L_{\text{ul}} + G_{\text{amp}} - P_{\text{ul\_mcd\_du}}$ .

15. The positioning system of claim 11, wherein the positioning system is further configured to:

obtain the following values: i) a signal to noise and interference ratio of the MCD ( $\text{SINR}_{\text{mcd\_du}}$ ) as measured by a digital unit of the base station, ii) an inter-cell interference value ( $I_{\text{du}}$ ), iii) a thermal noise power value ( $N_0$ ), and iv) a noise factor of a radio unit of the base station ( $\text{NF}_{\text{ru}}$ ), and

calculate  $L_{\text{cable}}$  by calculating  $P_{\text{ul\_mcd}} - L_{\text{ul}} + G_{\text{amp}} - (\text{SINR}_{\text{mcd\_du}} + I_{\text{du}} + N_0 + \text{NF}_{\text{ru}})$ .

16. The positioning system of claim 11, wherein the positioning system is further configured to:

obtain a received power value ( $P_{\text{dl\_mcd}}$ ) indicating a received power of a downlink signal transmitted by the serving radio head as measured by the MCD;

determine a downlink path loss value, wherein determining the downlink path loss value comprises calculating ( $\text{Prh} - P_{\text{dl\_mcd}}$ ), wherein  $\text{Prh}$  is a value representative of the power at which one or more of said radio heads transmitted said downlink signal; and

obtain the uplink path loss value based on the downlink path loss value.

17. The positioning system of claim 11, wherein the positioning system is configured to determine the cell in which the MCD is located by obtaining a cell identifier (cell ID) identifying the cell in which the MCD is located.

18. The positioning system of claim 11, wherein the positioning system is further configured to:

determine which one of a set of predetermined cable length values is closest to the determined cable length value; and

estimate the location of the MCD using the predetermined cable length value that was determined to be closest to the determined cable length value.

19. The positioning system of claim 11, wherein the positioning system is configured to determine the cell in which the MCD is located comprising by obtaining an cell identifier (Cell ID) identifying the cell in which the MCD is located, and

the positioning system is further configured to use the Cell ID to determine whether the cell identified by the Cell ID is being served by a plurality of radio heads.

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