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**Sherrill**

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(54) **CLASPING STABILITY DEVICE AND CLASPING STABILIZED HAND TRUCK**

(52) **U.S. Cl.**  
CPC ..... **B62B 1/142** (2013.01); **B62B 5/00** (2013.01); **B65G 7/04** (2013.01)

(71) Applicant: **Robert L. Sherrill**, Magnolia, TX (US)

(57) **ABSTRACT**

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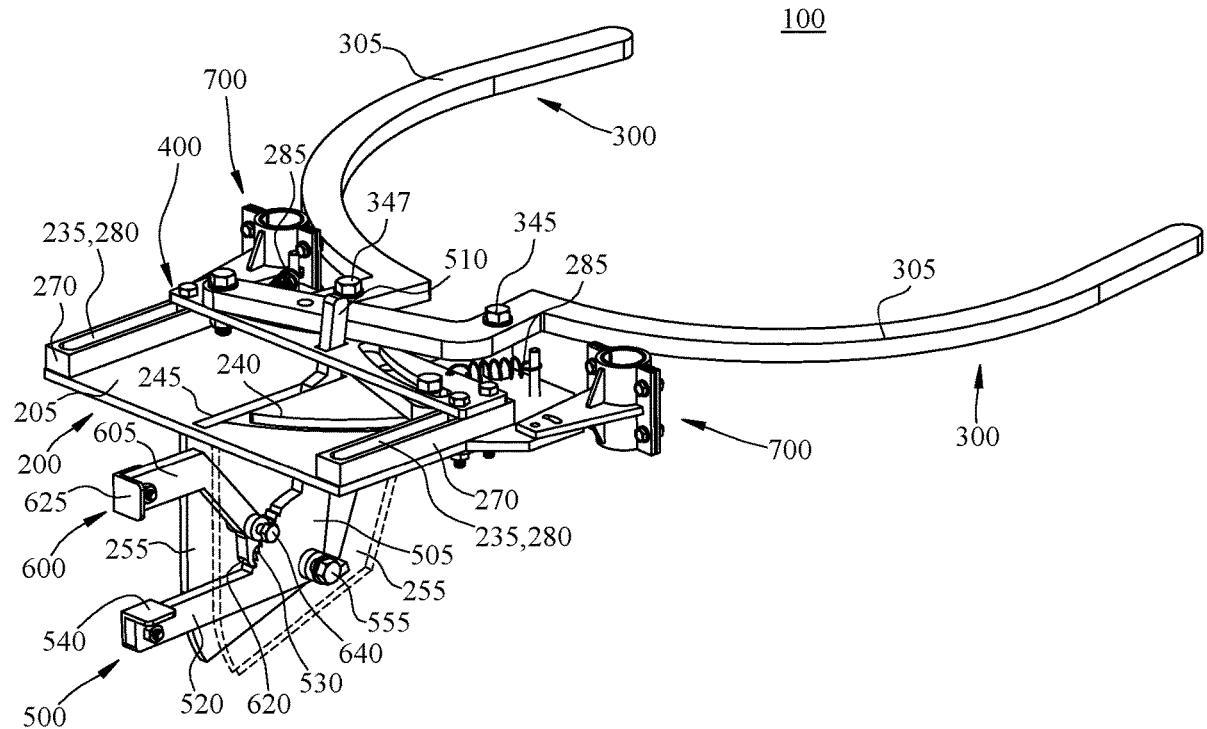
A clasp stability device and clasp stabilized hand truck provide a stable material handling platform safely operable by a single human operator from the rear of the hand truck, without having to use straps or ties. The clasp stability device may assist in loading material onto the hand truck at the source location, stabilize the material during transport, and assist in unloading the material from the hand truck at the destination location. The clasp mechanism may automatically lock into place once the clasp arms are closed to a sufficient degree to secure the material. The locking mechanism may remain locked, stabilizing the material during transport, until the locking mechanism is released. The clasp stability device provides a single stroke clasp and release mechanism that is engaged entirely from the rear of the hand truck.

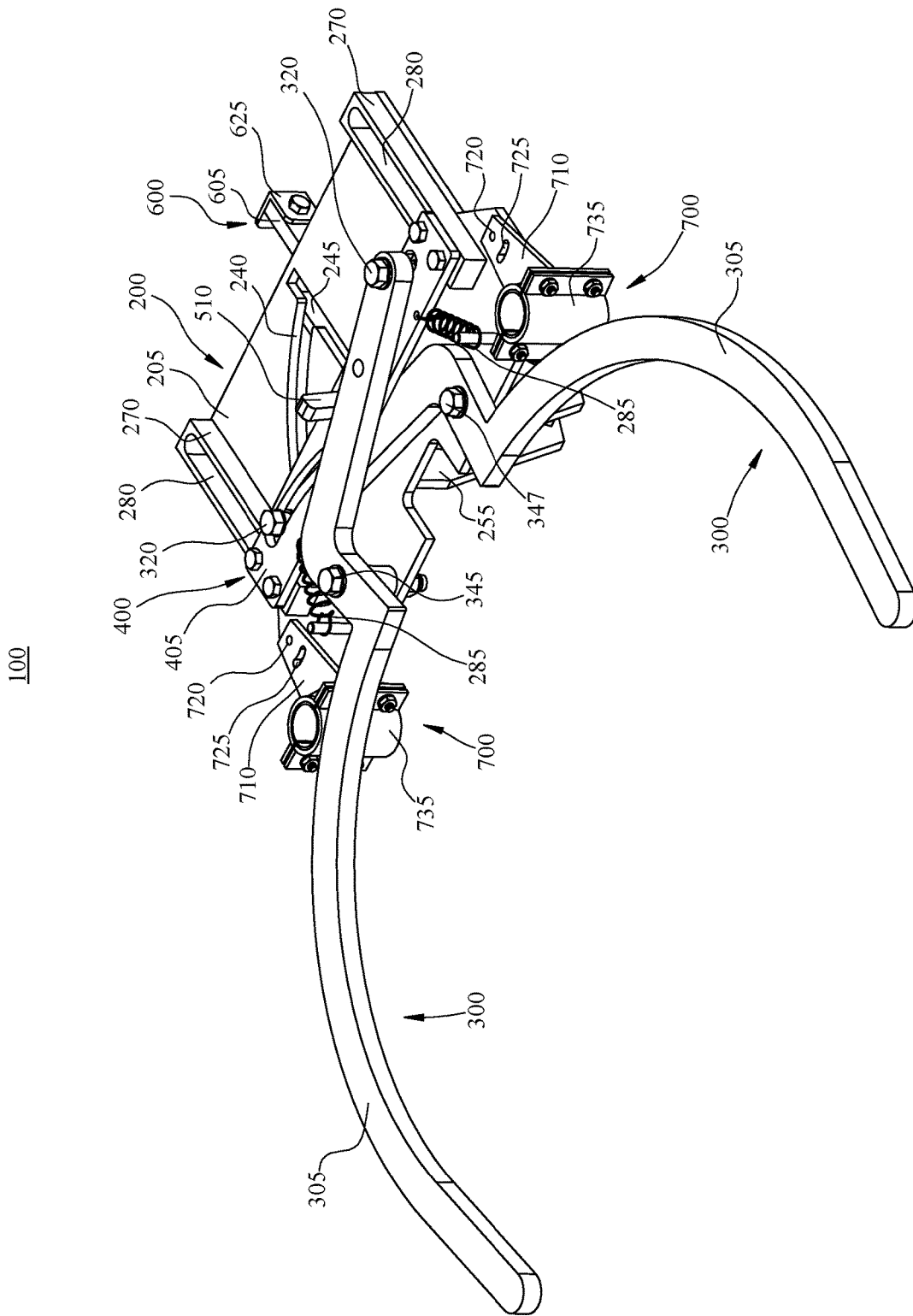
(21) Appl. No.: **17/841,060**

(22) Filed: **Jun. 15, 2022**

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**B62B 1/14** (2006.01)  
**B62B 5/00** (2006.01)  
**B65G 7/04** (2006.01)





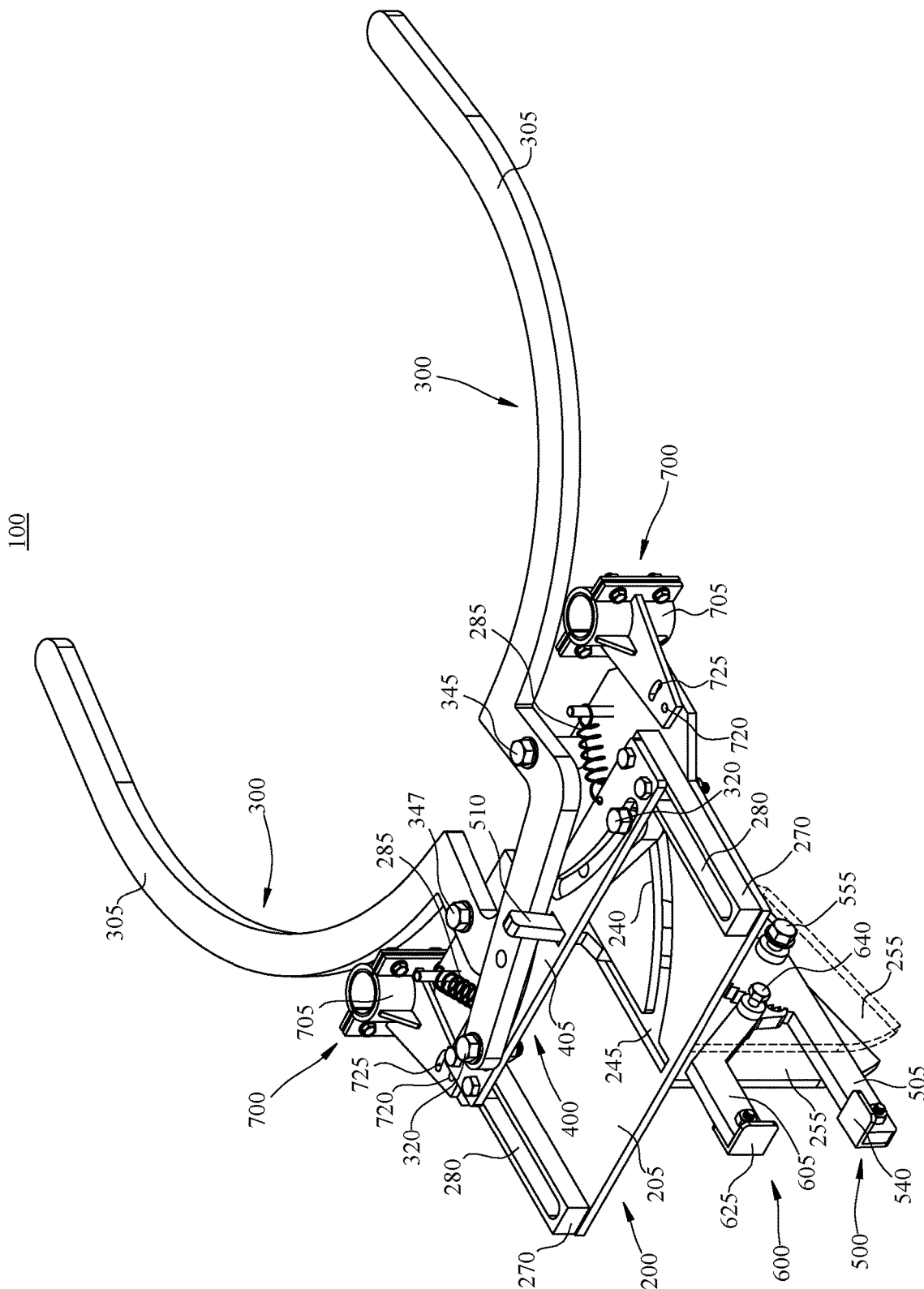
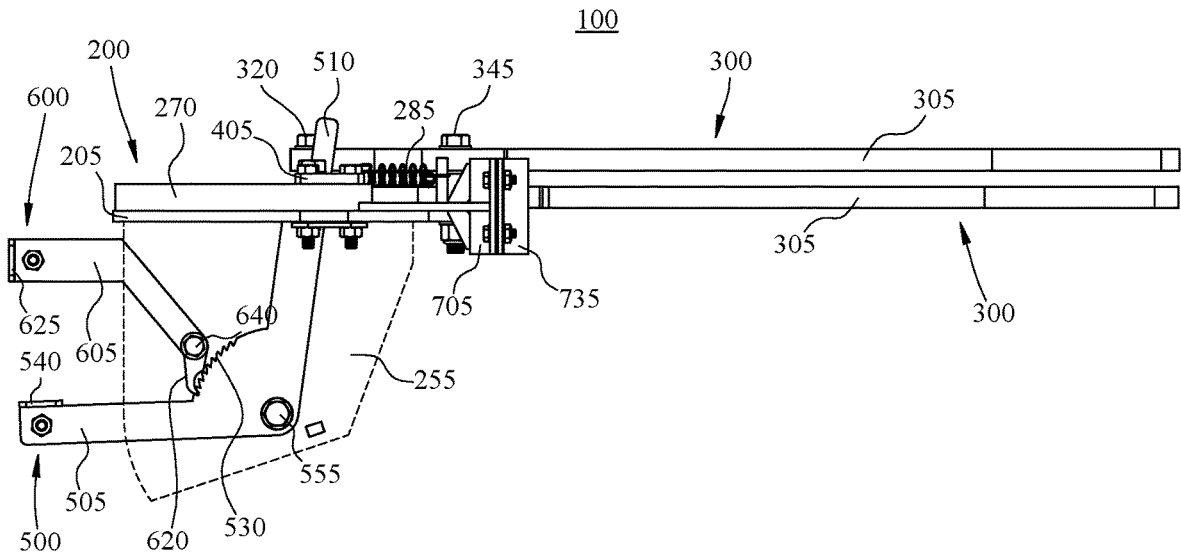
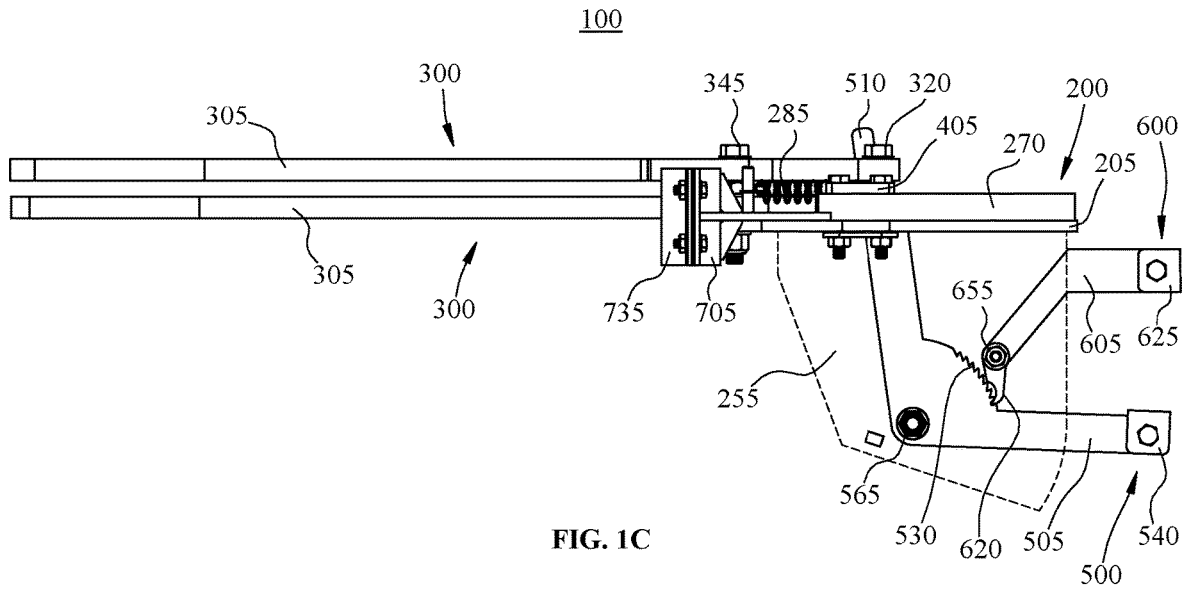


FIG. 1B



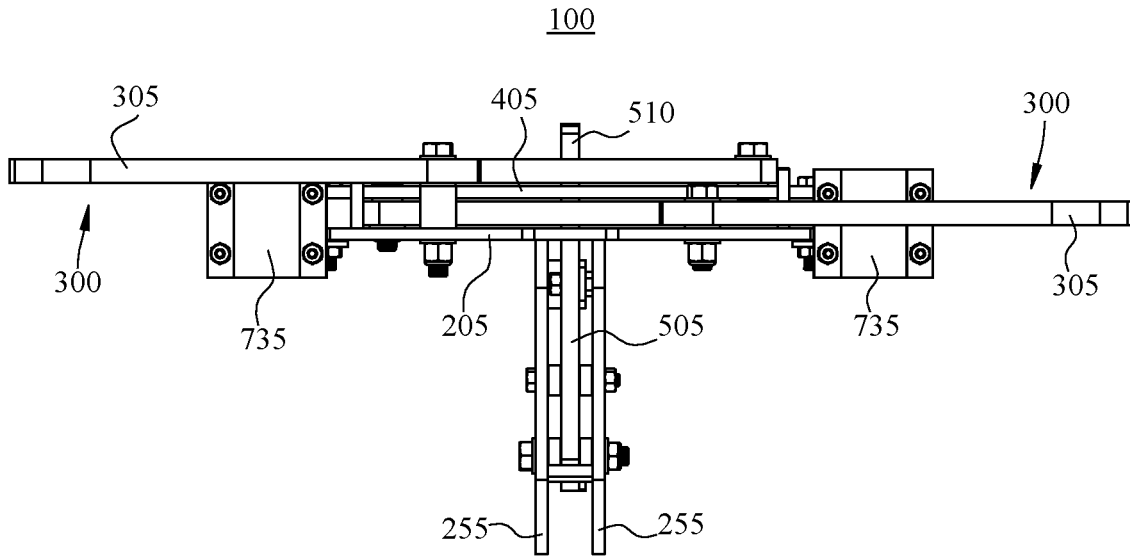


FIG. 1E

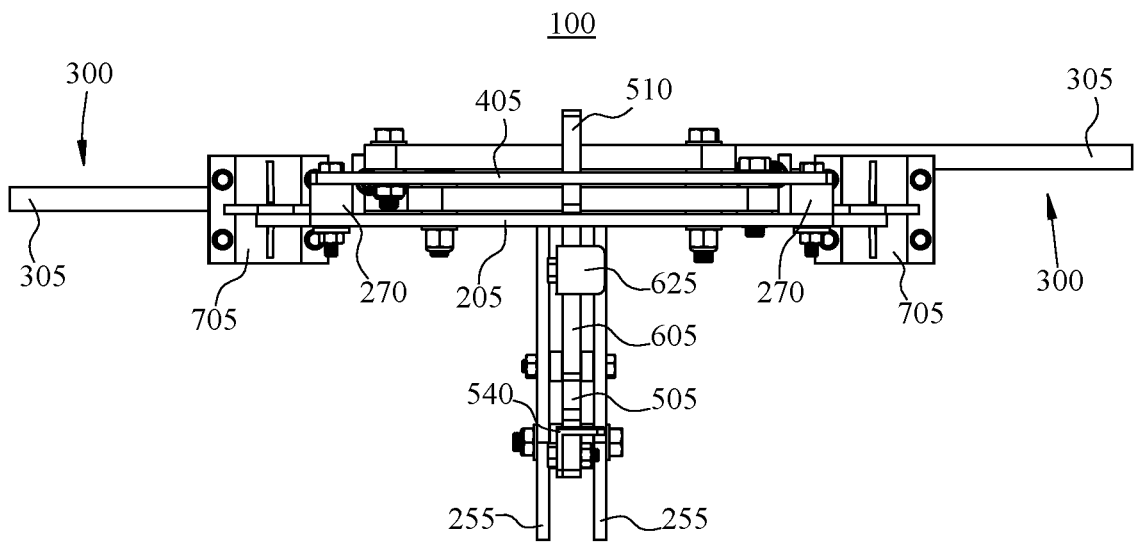
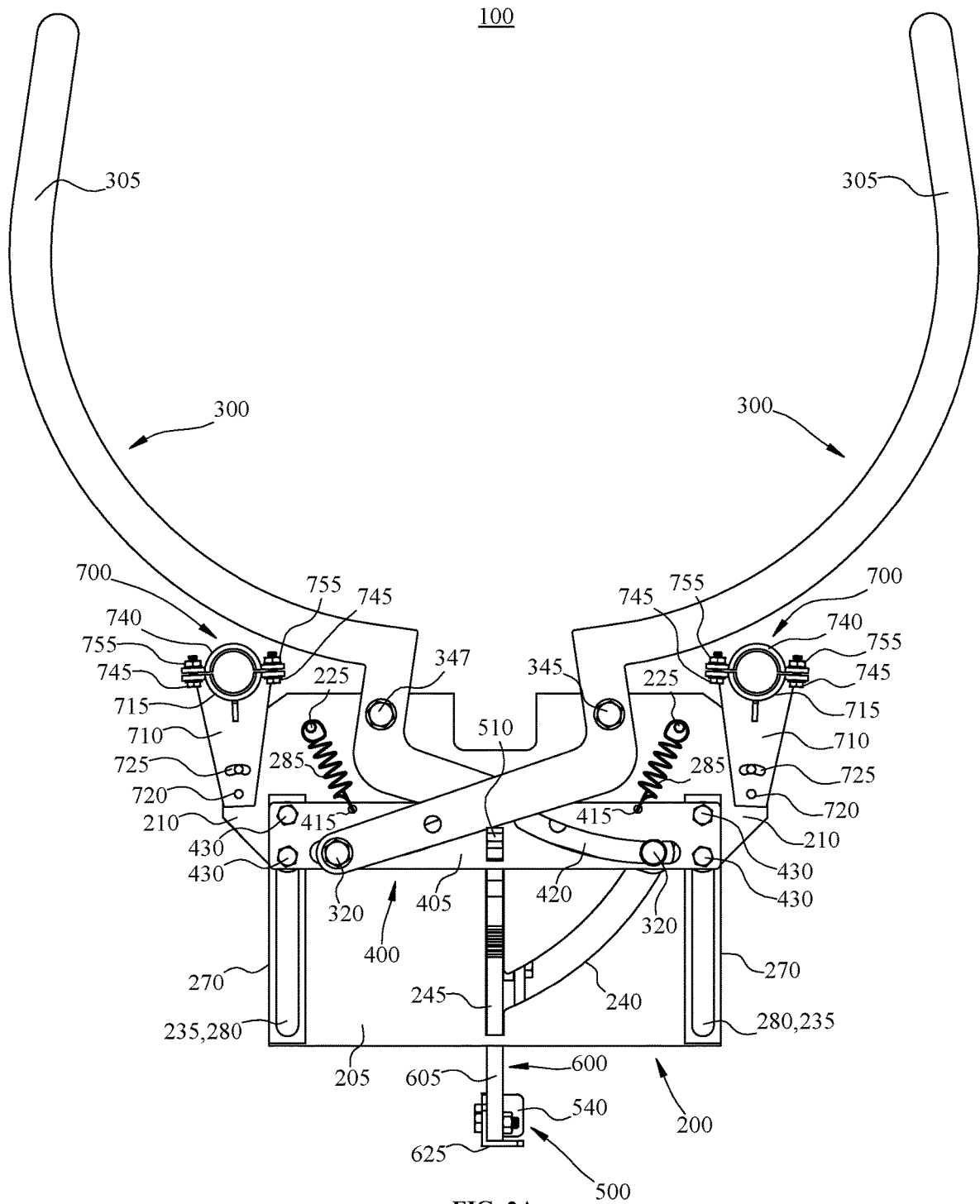


FIG. 1F





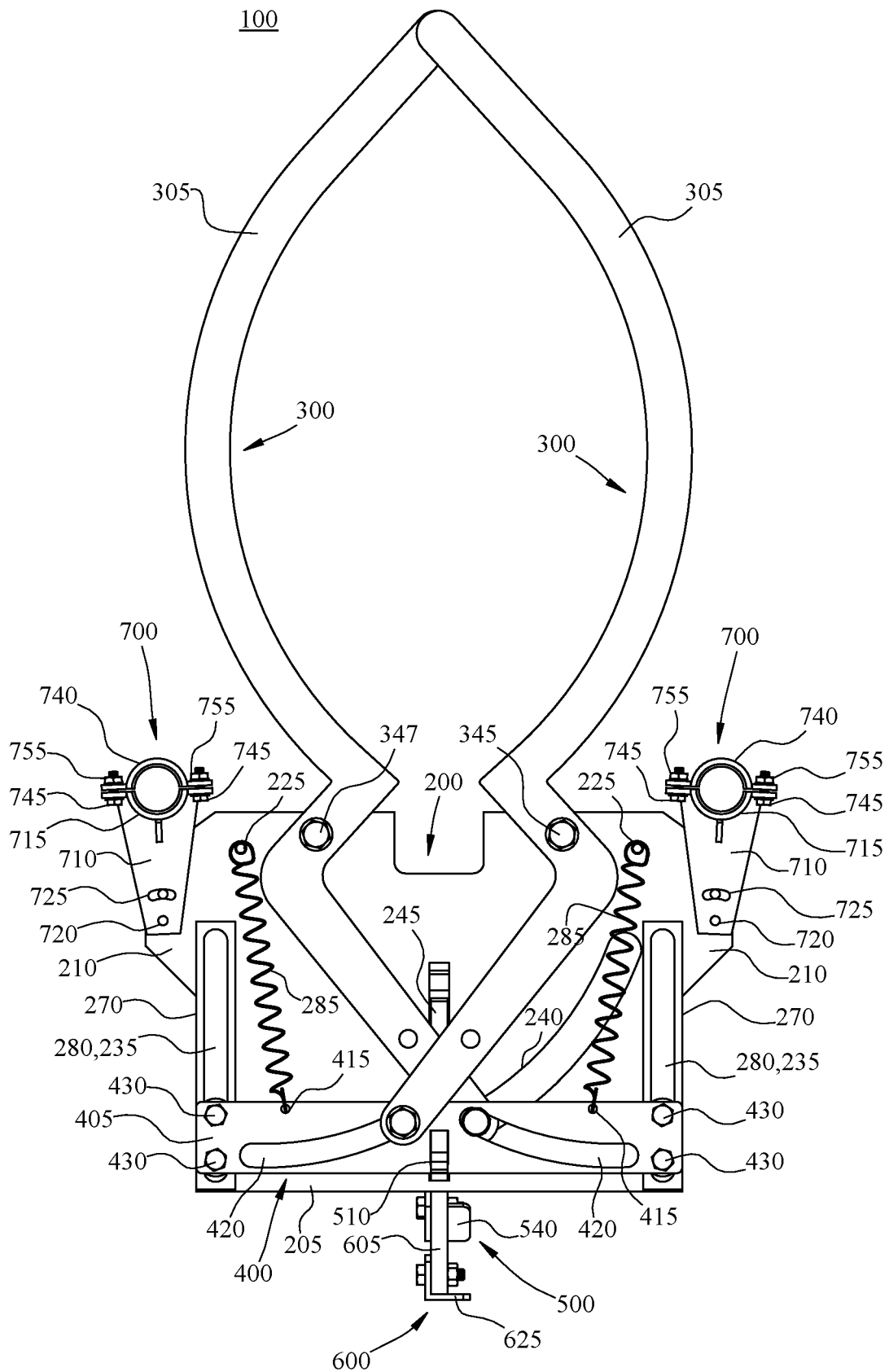


FIG. 2C



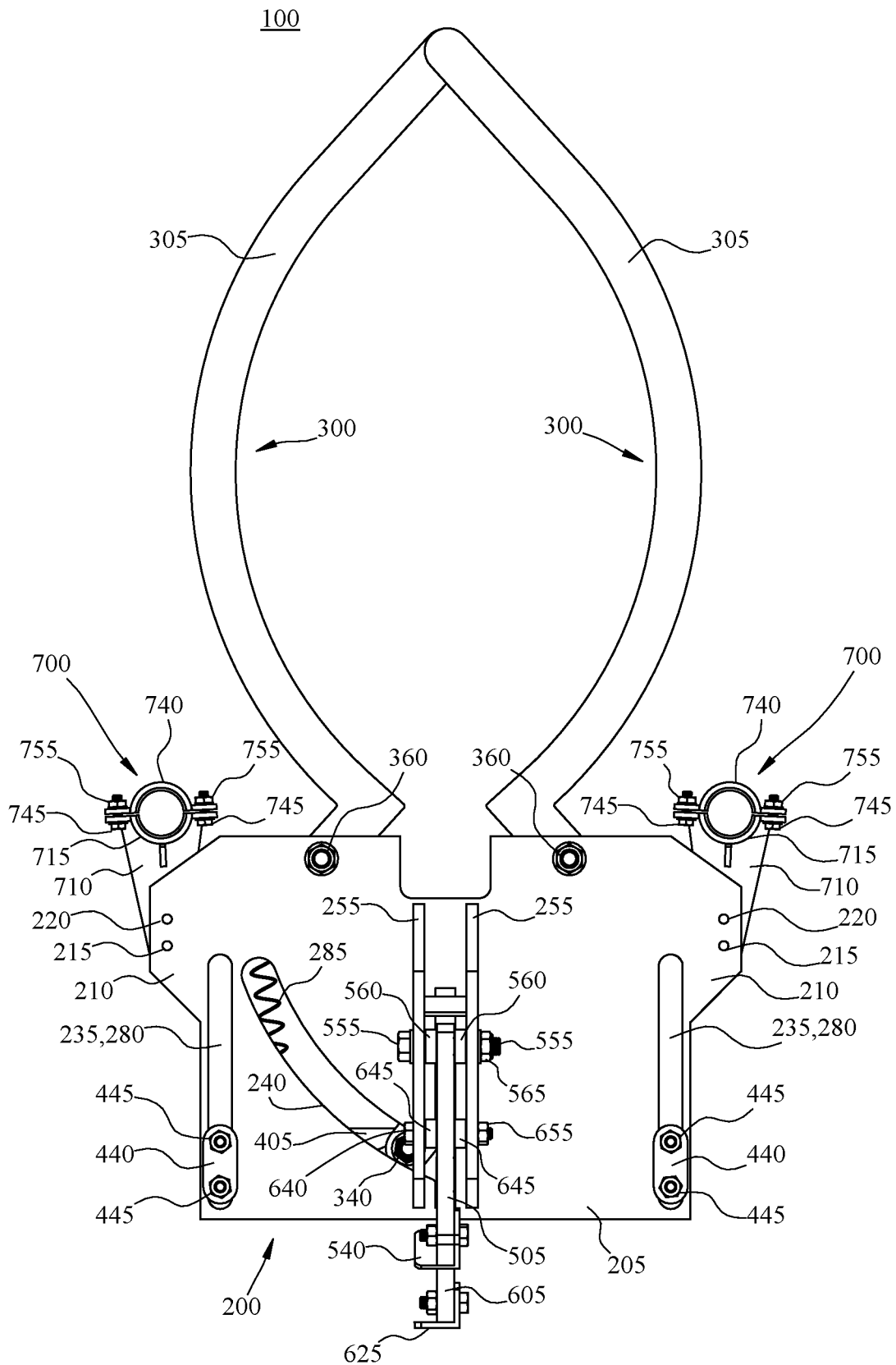


FIG. 2D

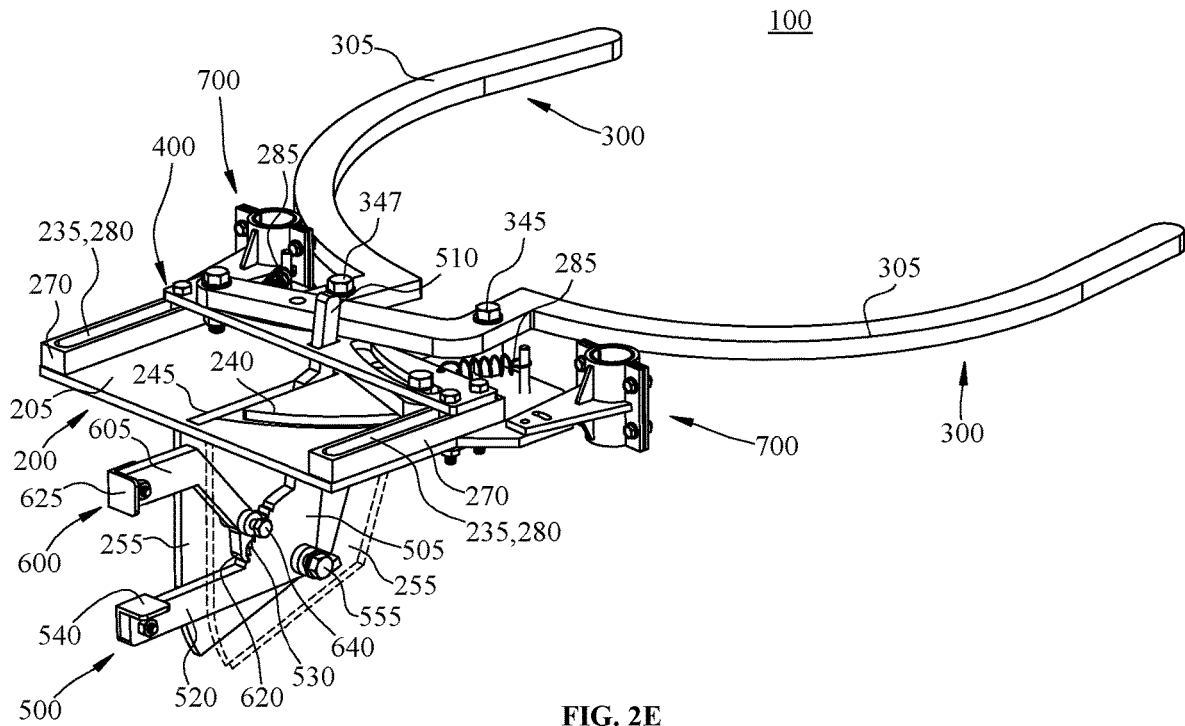


FIG. 2E

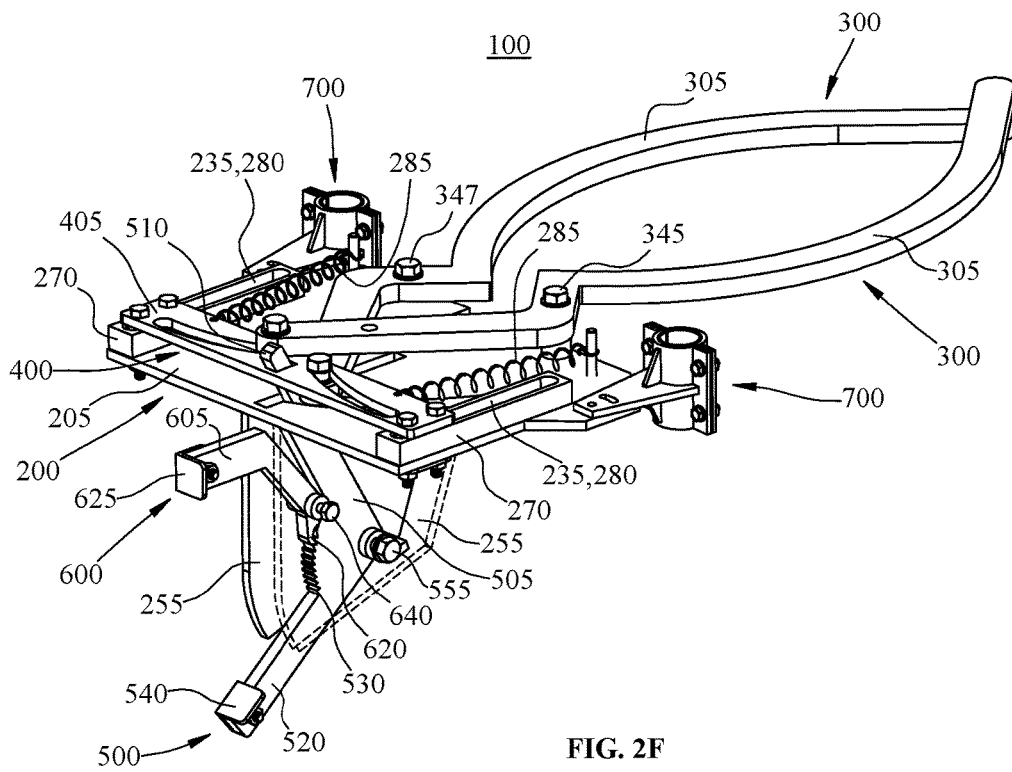


FIG. 2F

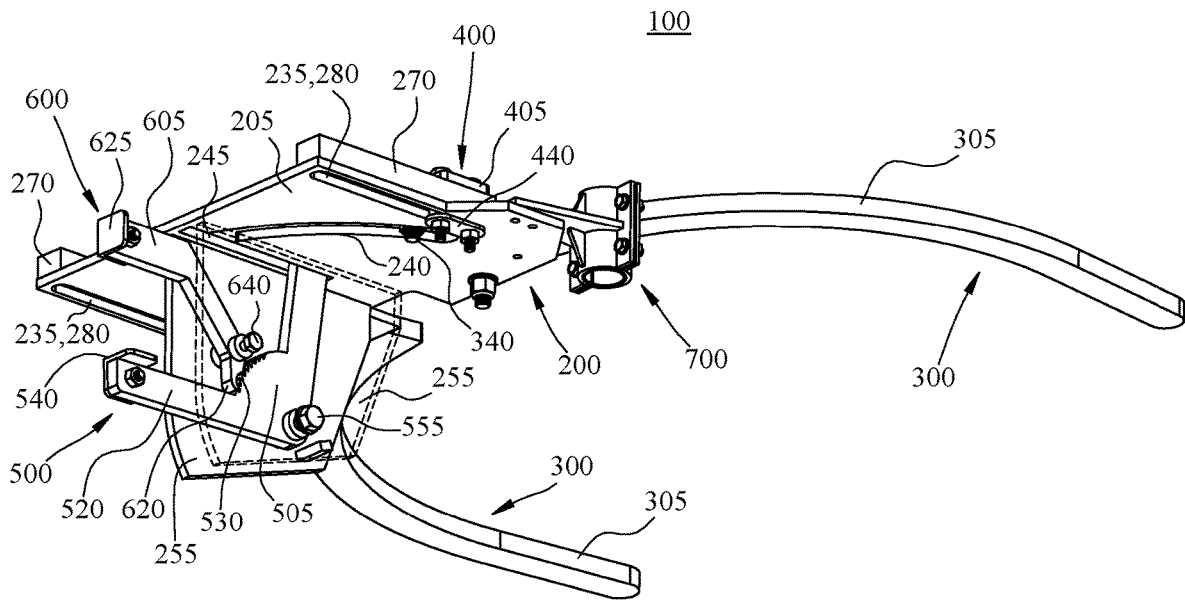


FIG. 2G

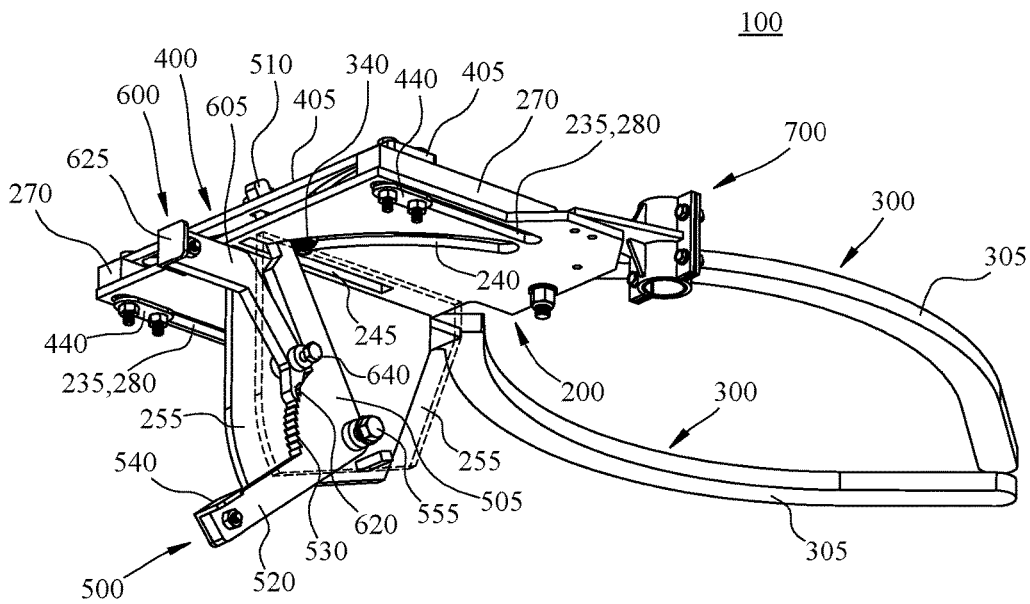


FIG. 2H

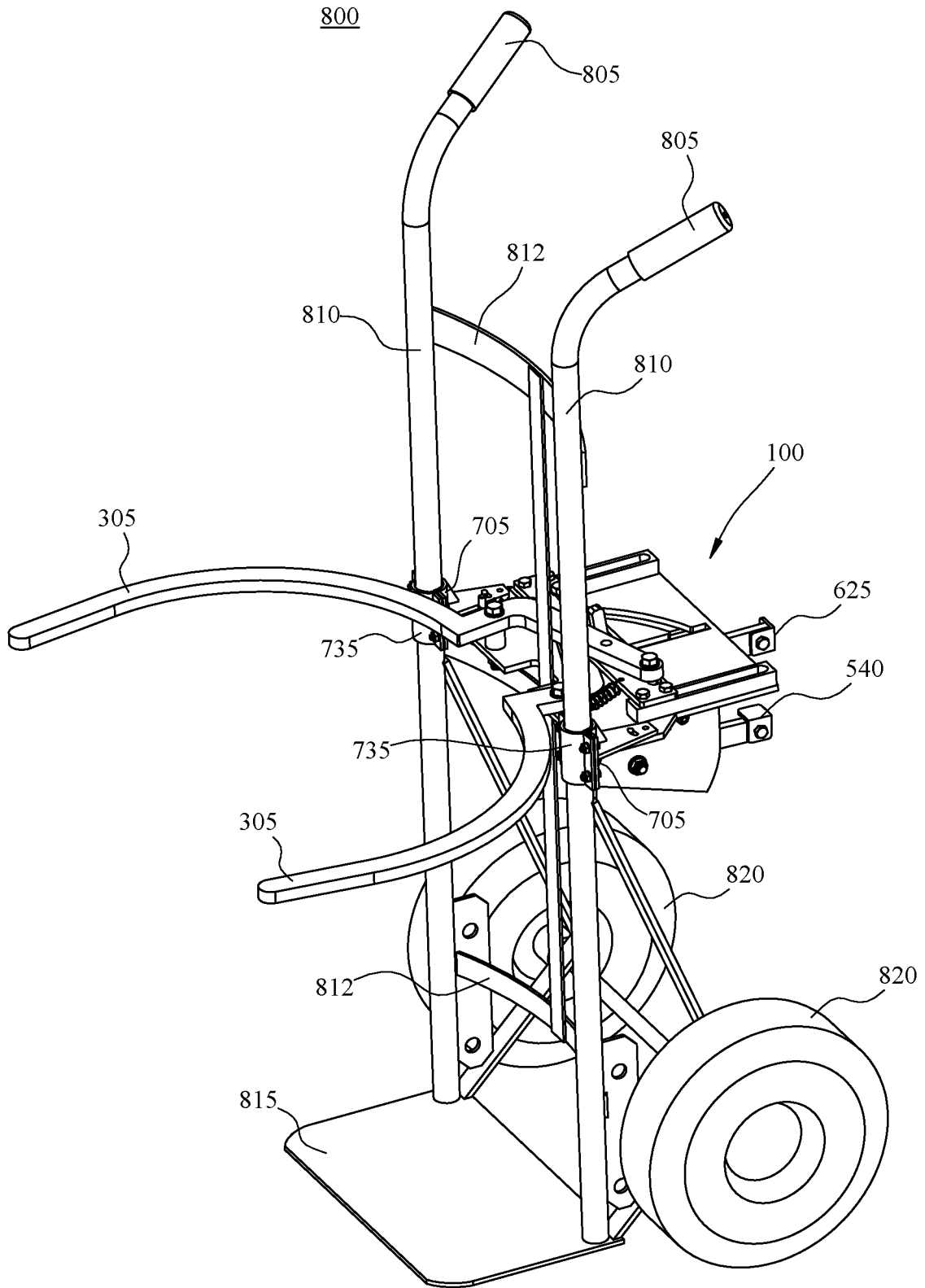


FIG. 3A

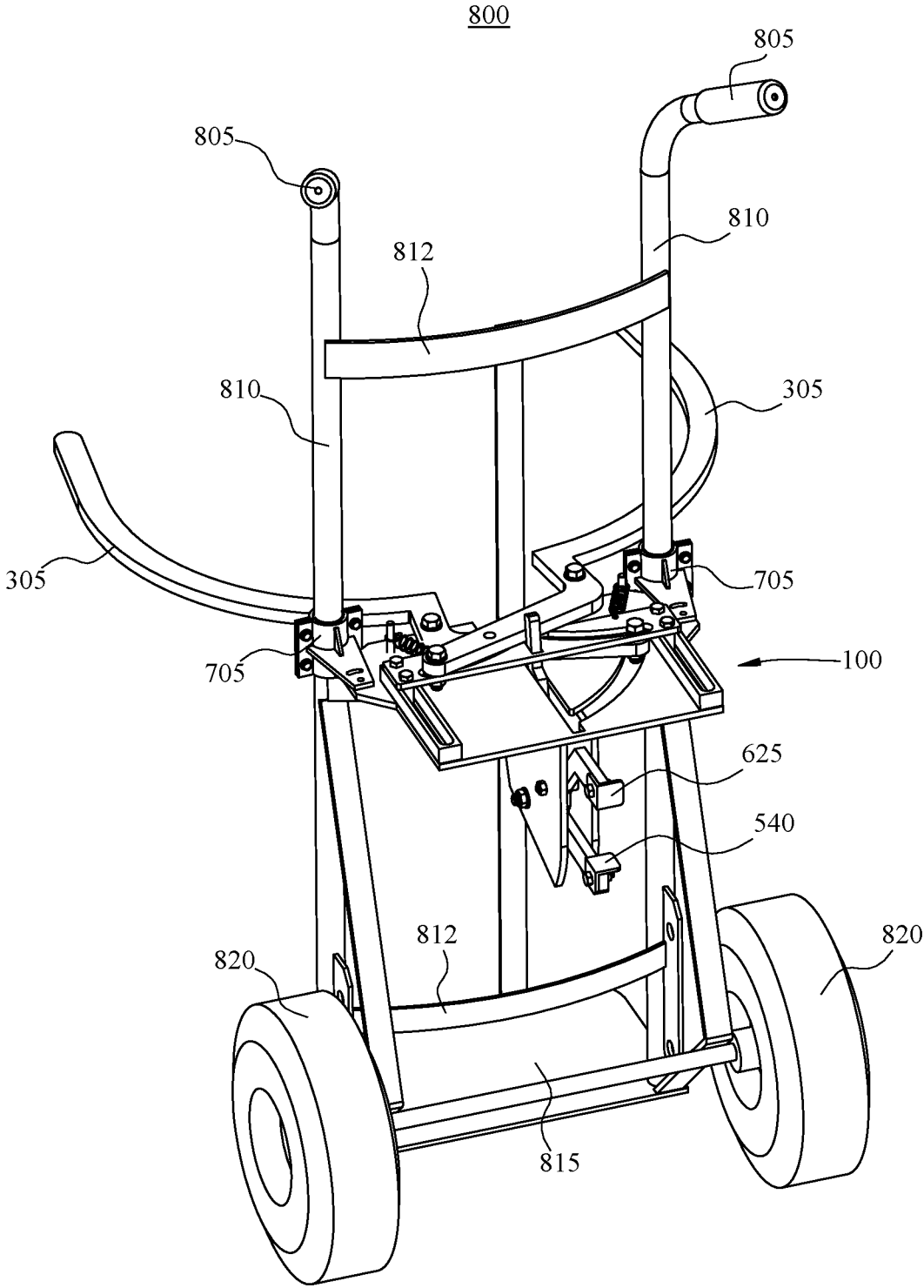


FIG. 3B

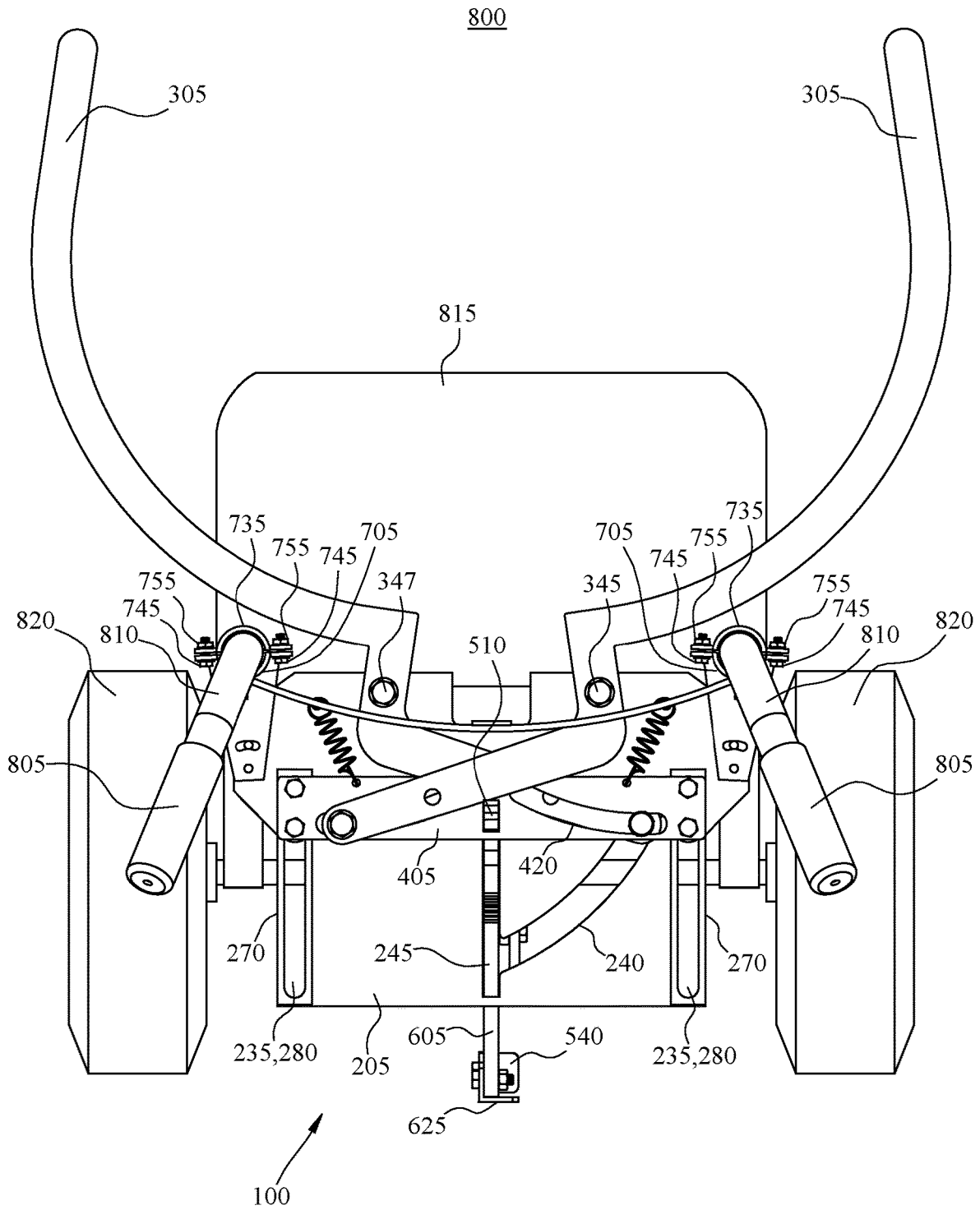


FIG. 3C

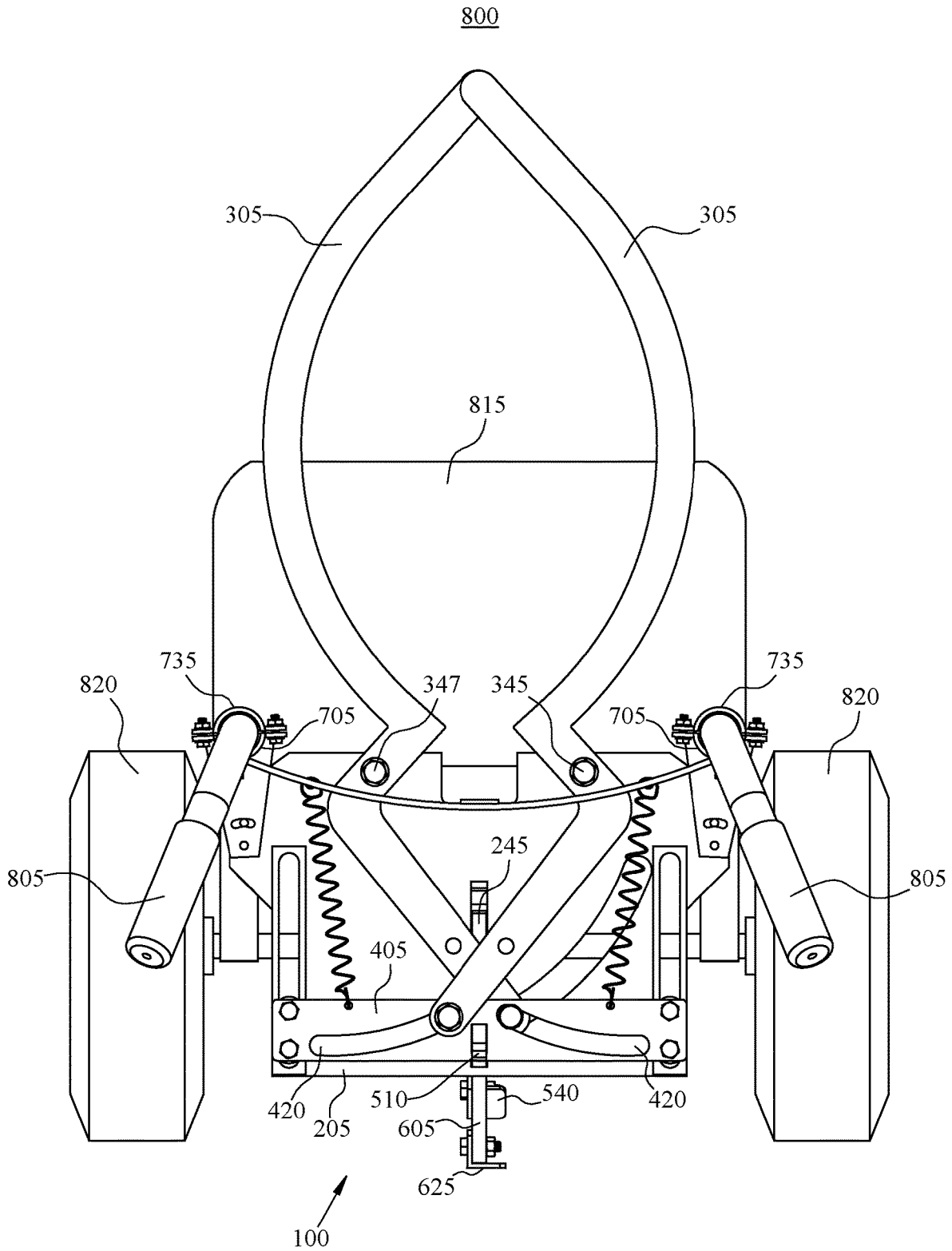


FIG. 3D

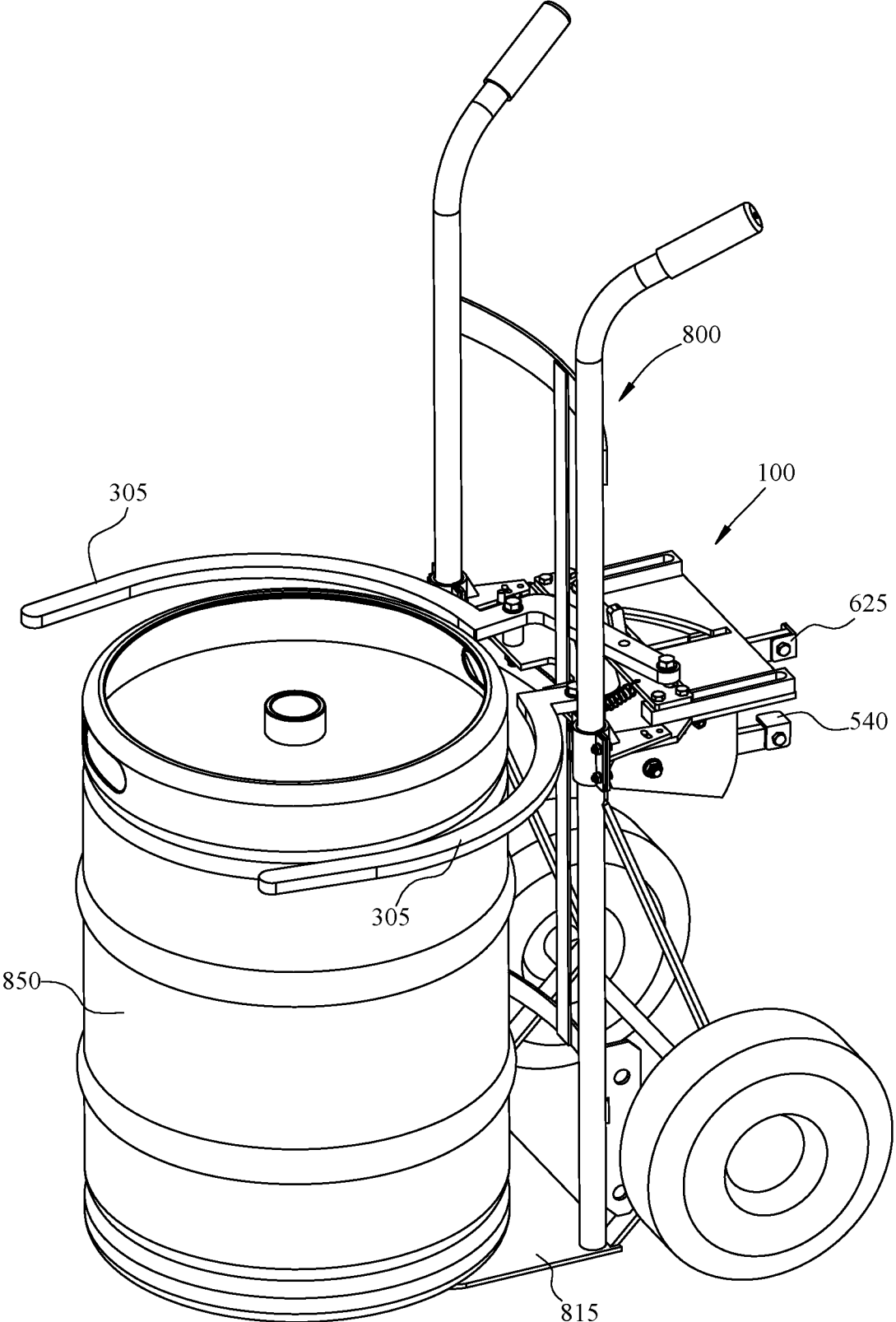


FIG. 4A



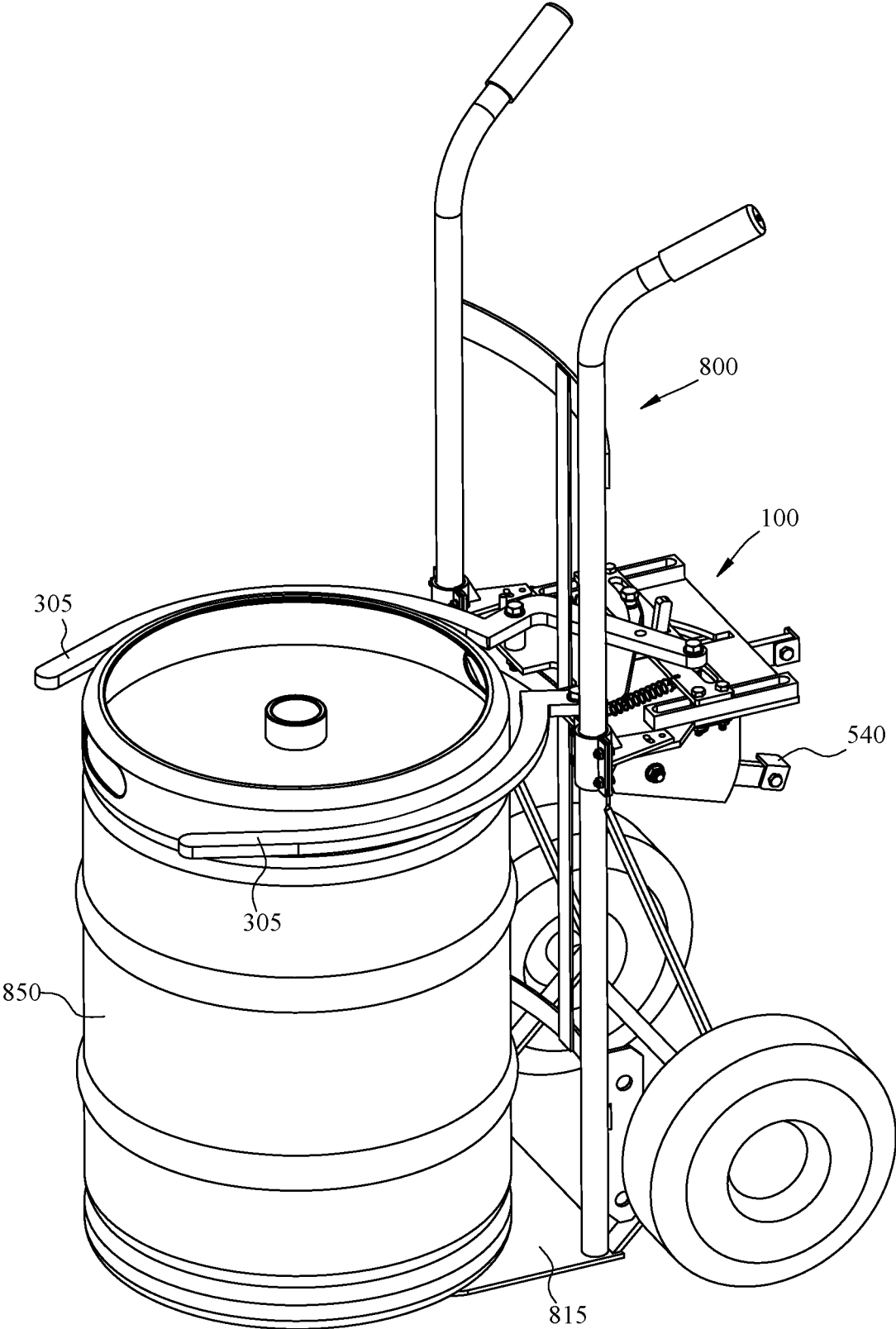


FIG. 4B

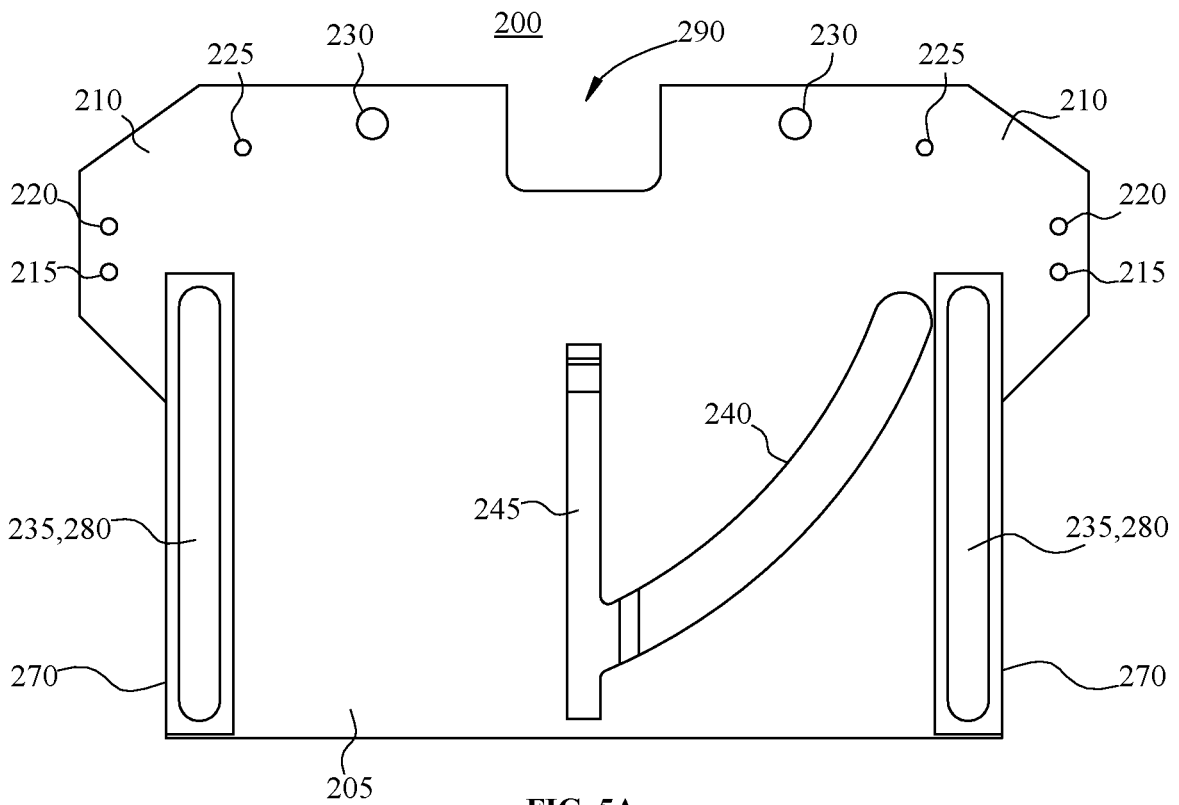


FIG. 5A

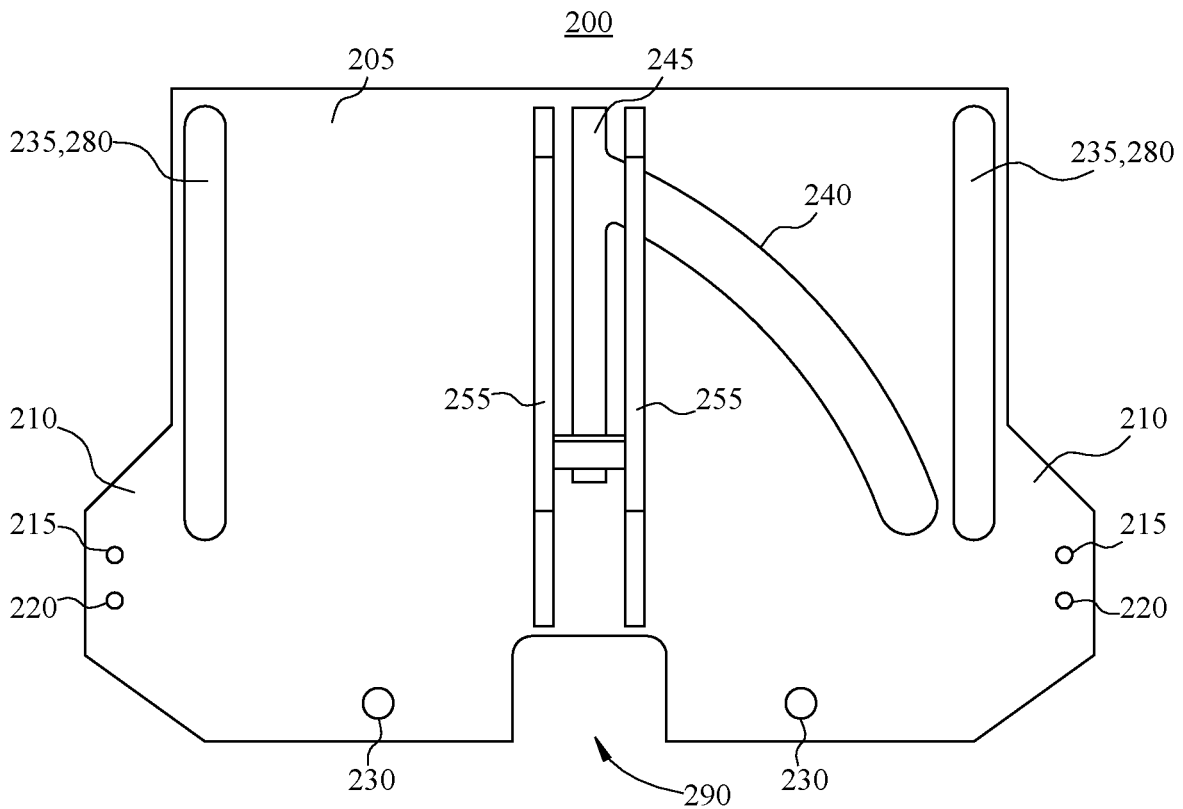


FIG. 5B

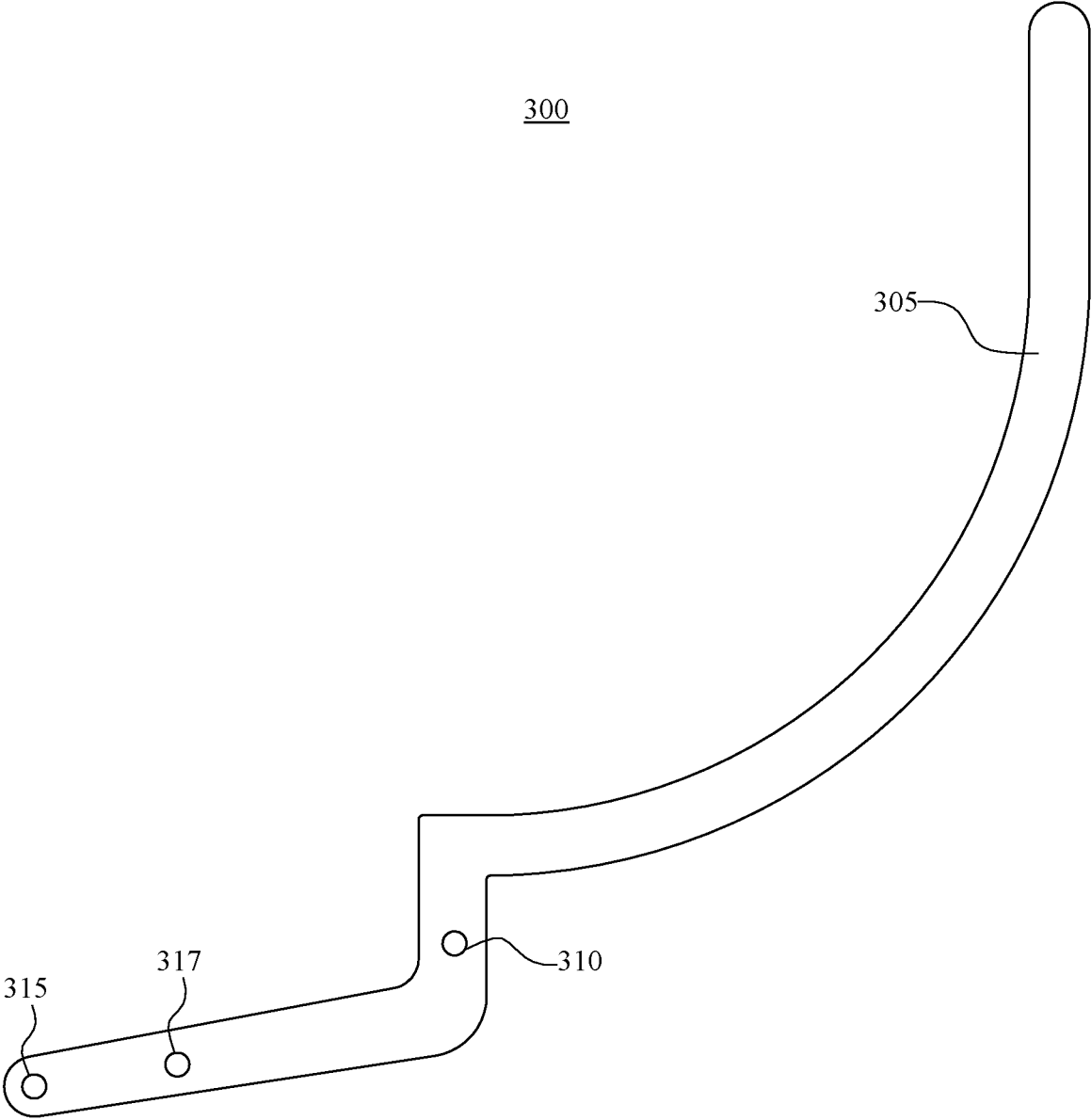


FIG. 5C

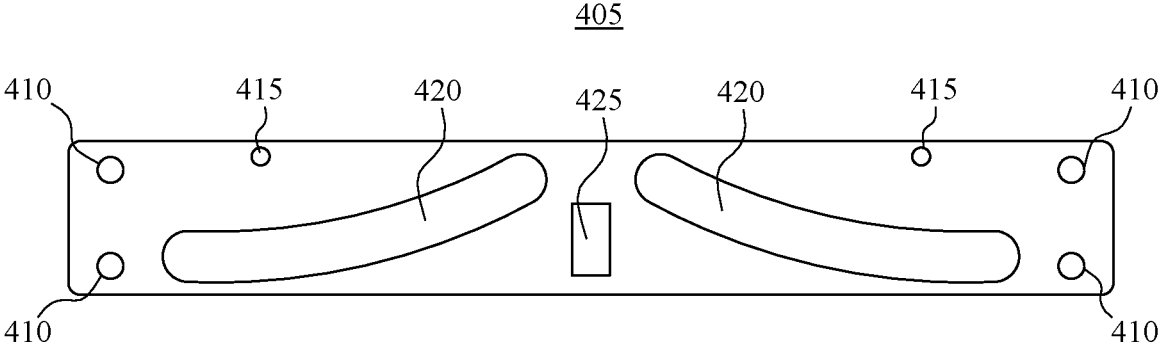


FIG. 5D

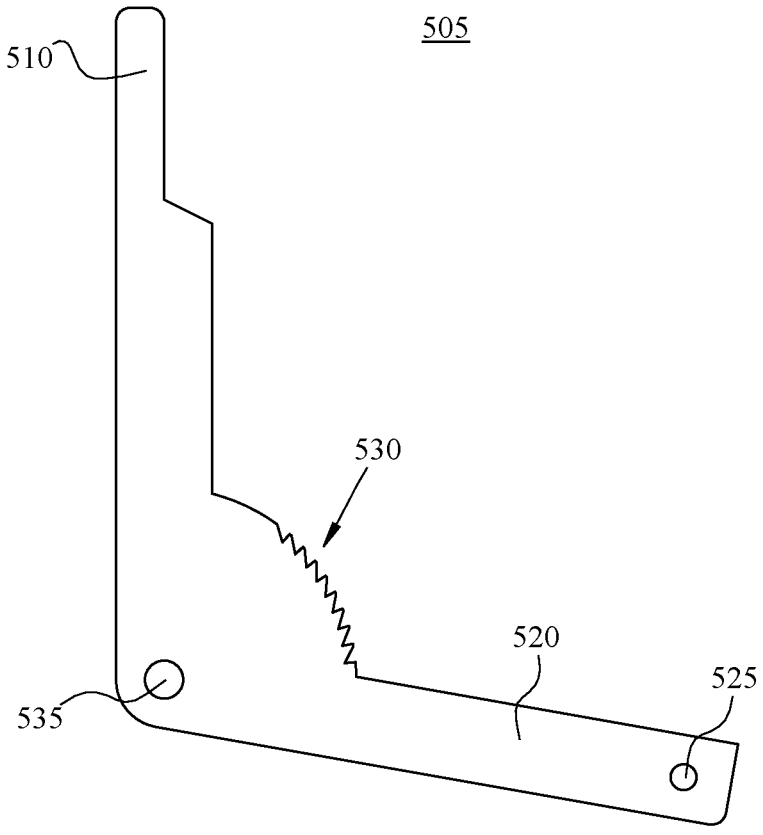


FIG. 5E

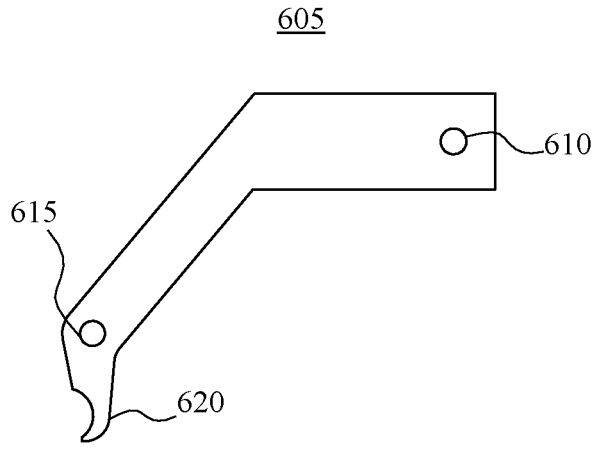


FIG. 5F

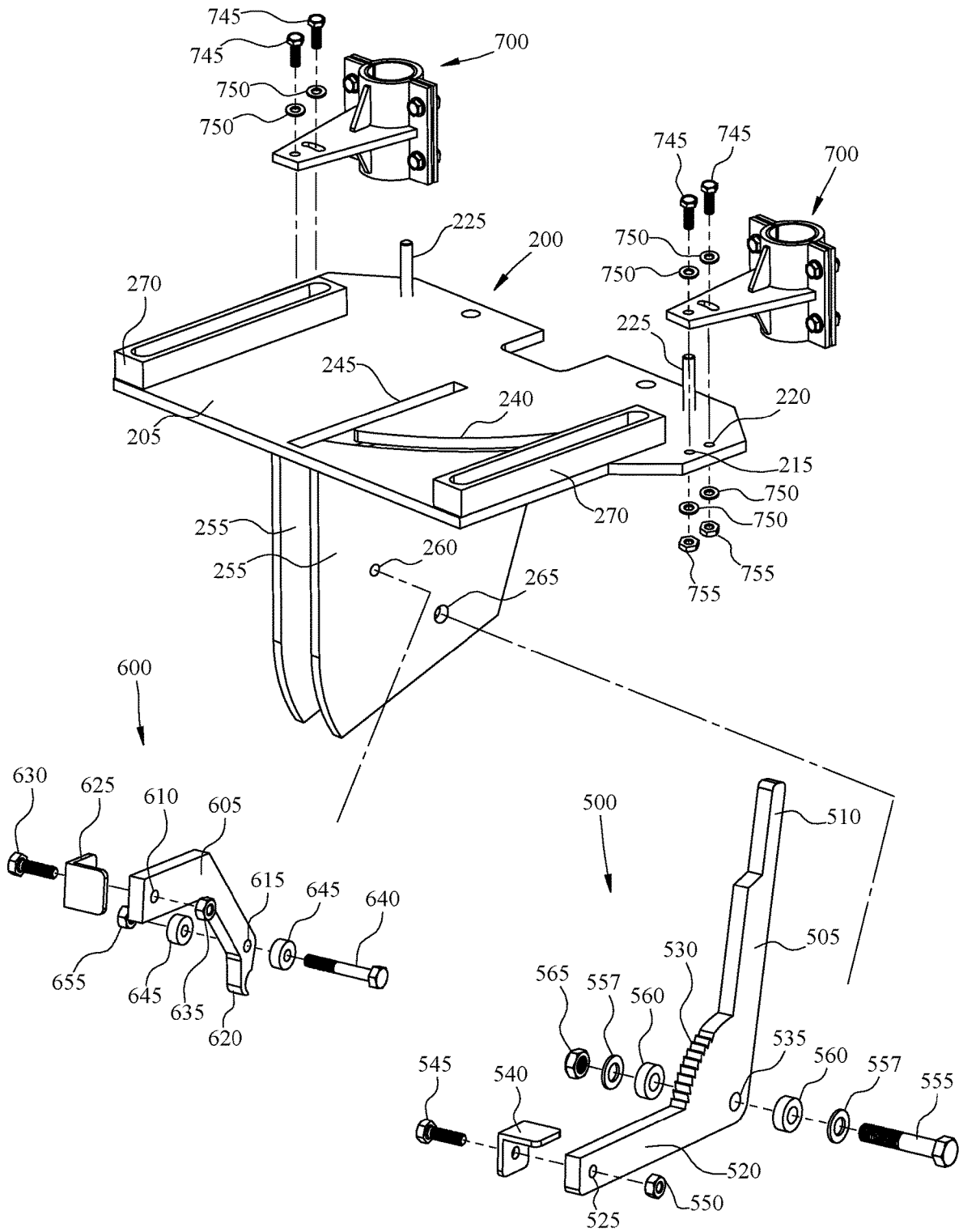


FIG. 6A

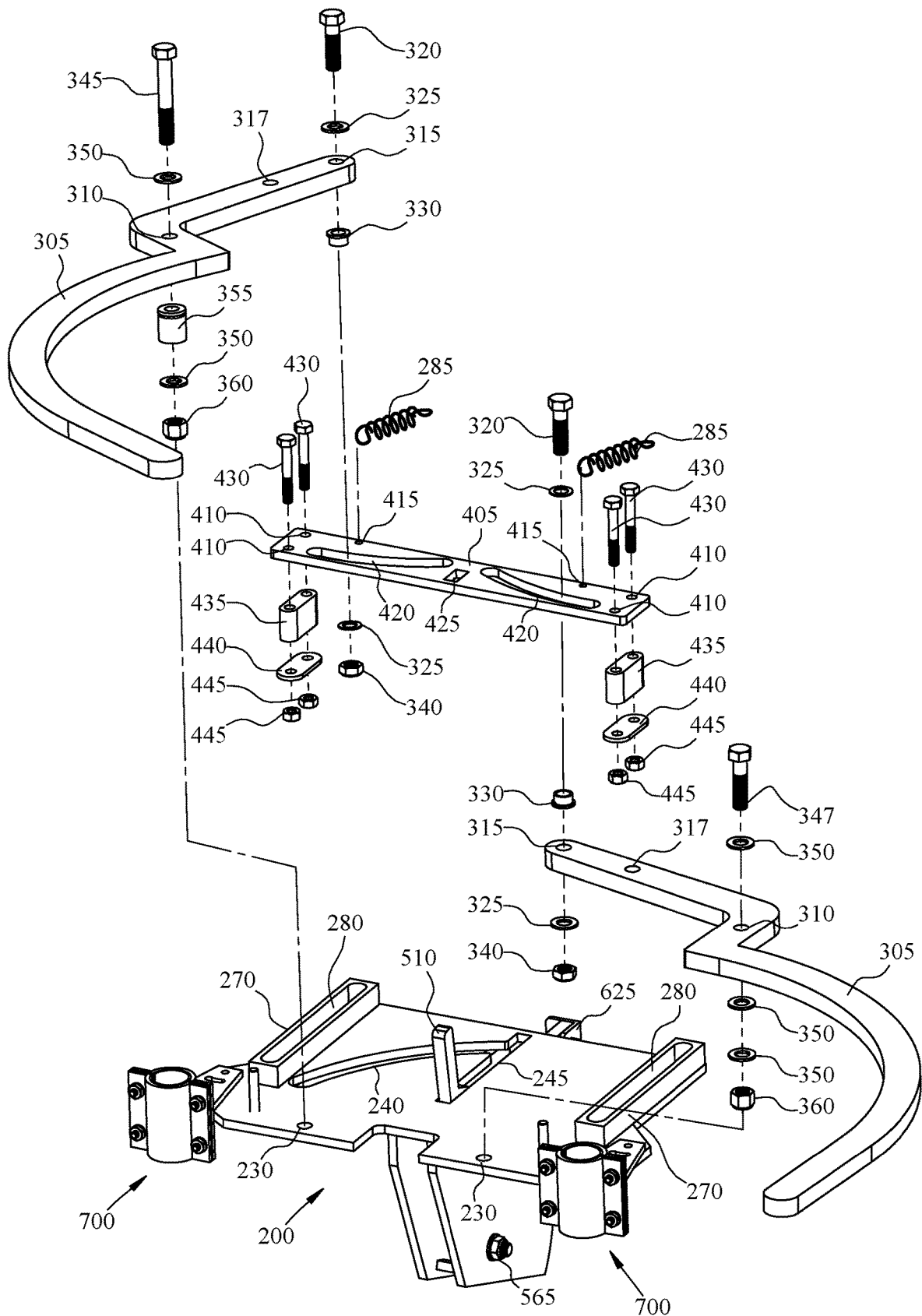


FIG. 6B

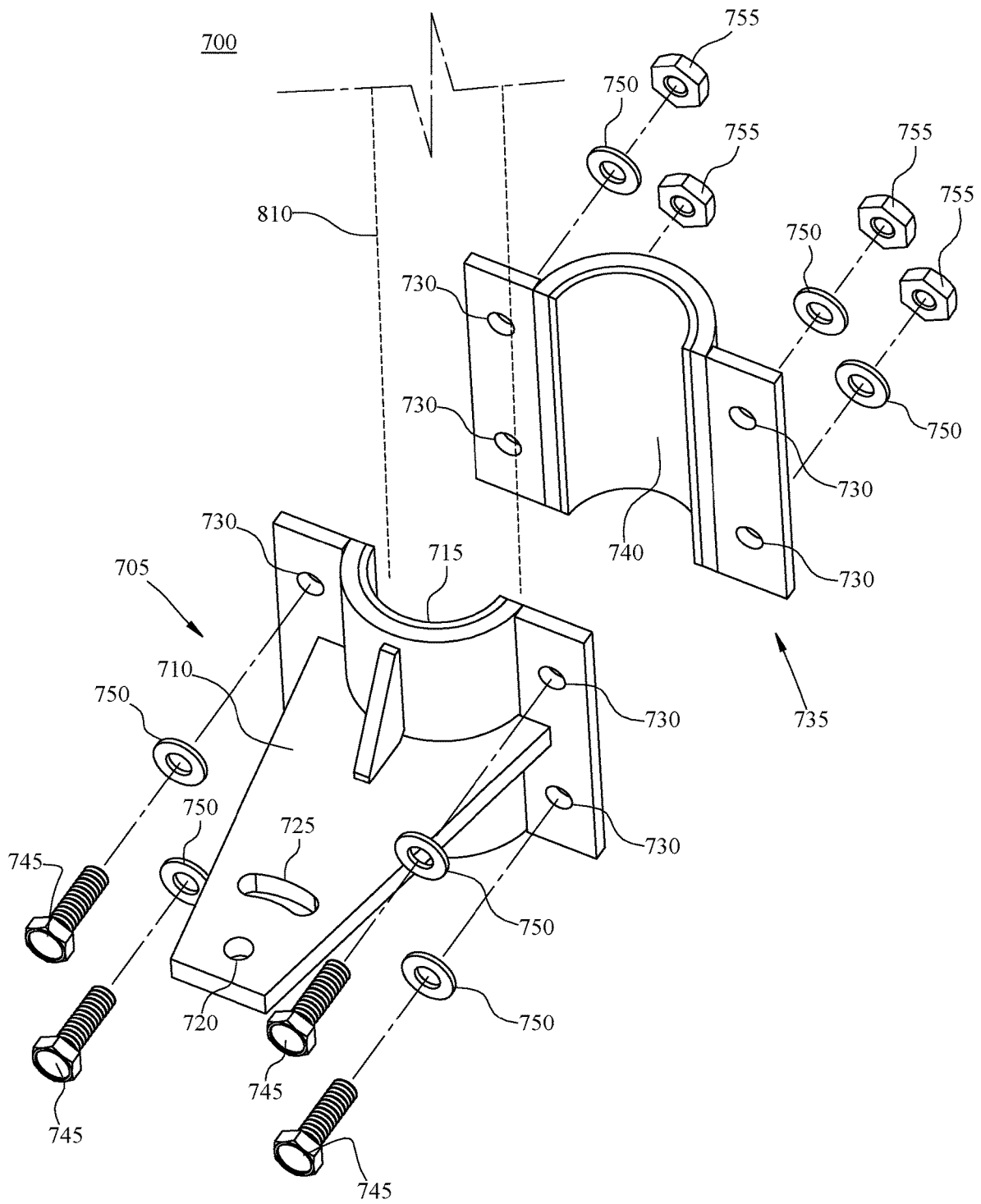


FIG. 6C

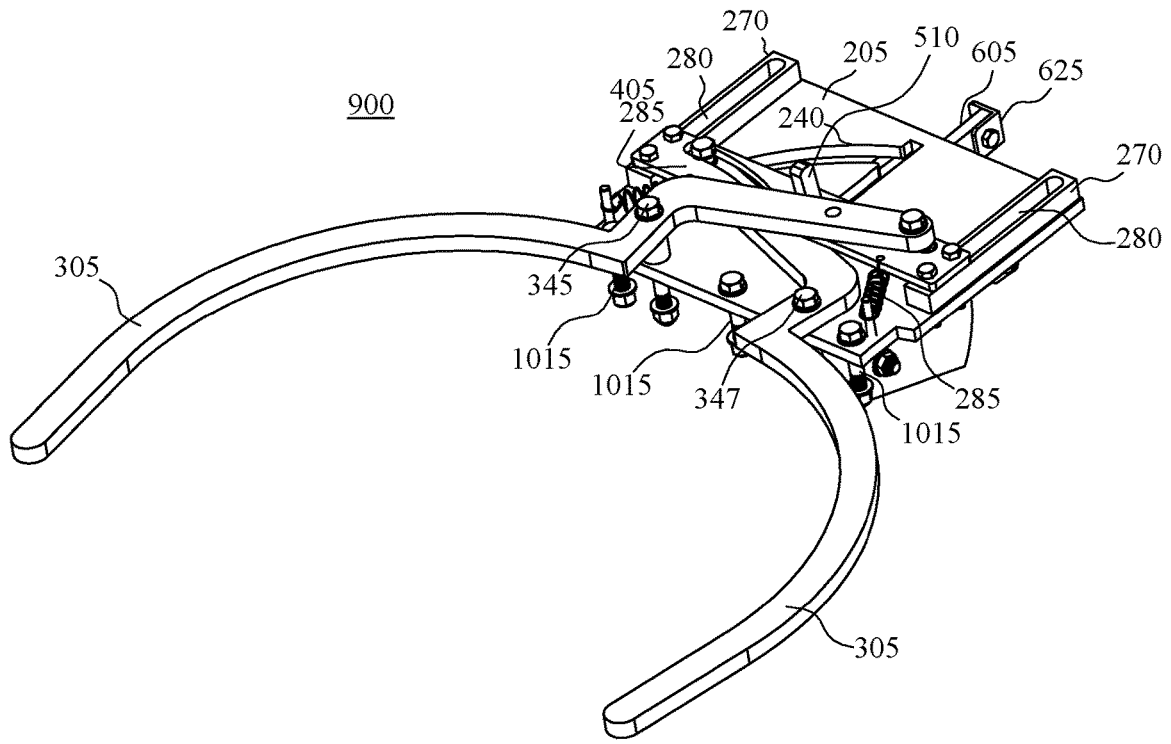


FIG. 7A

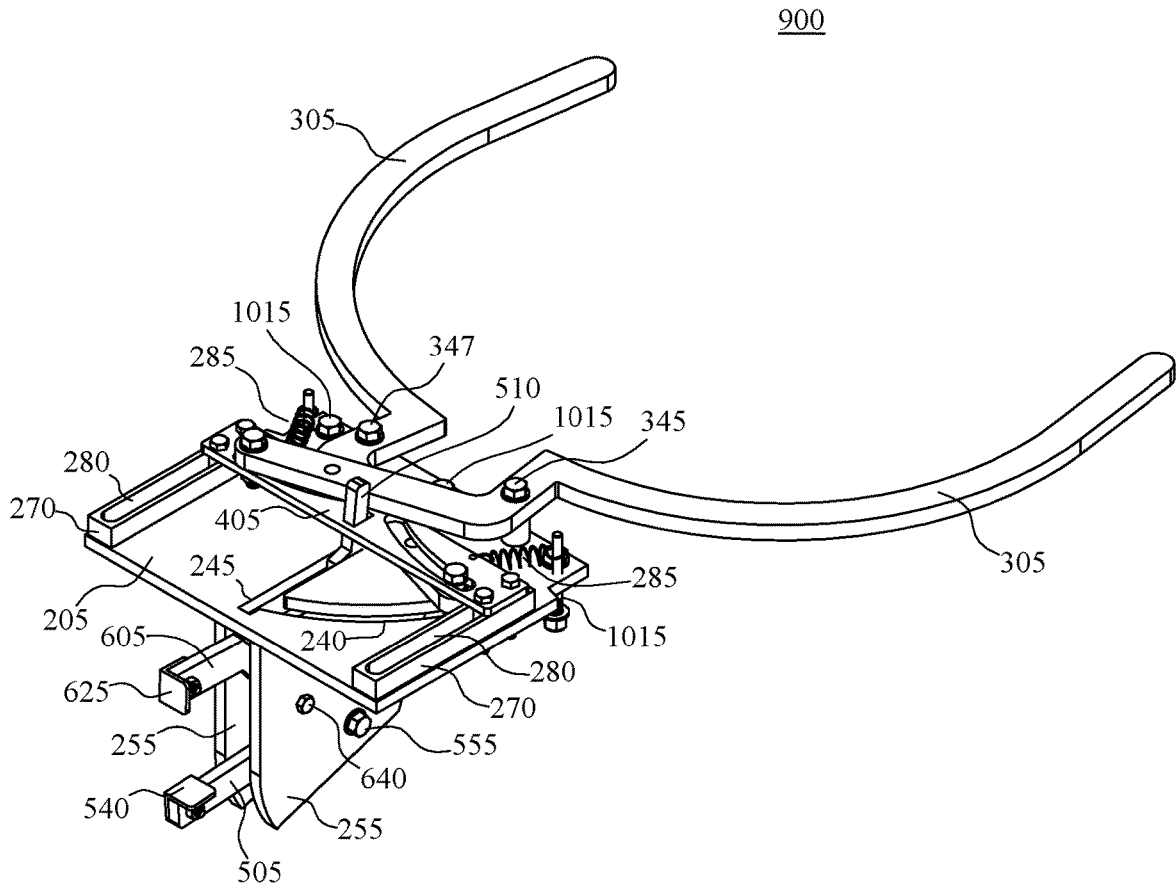


FIG. 7B



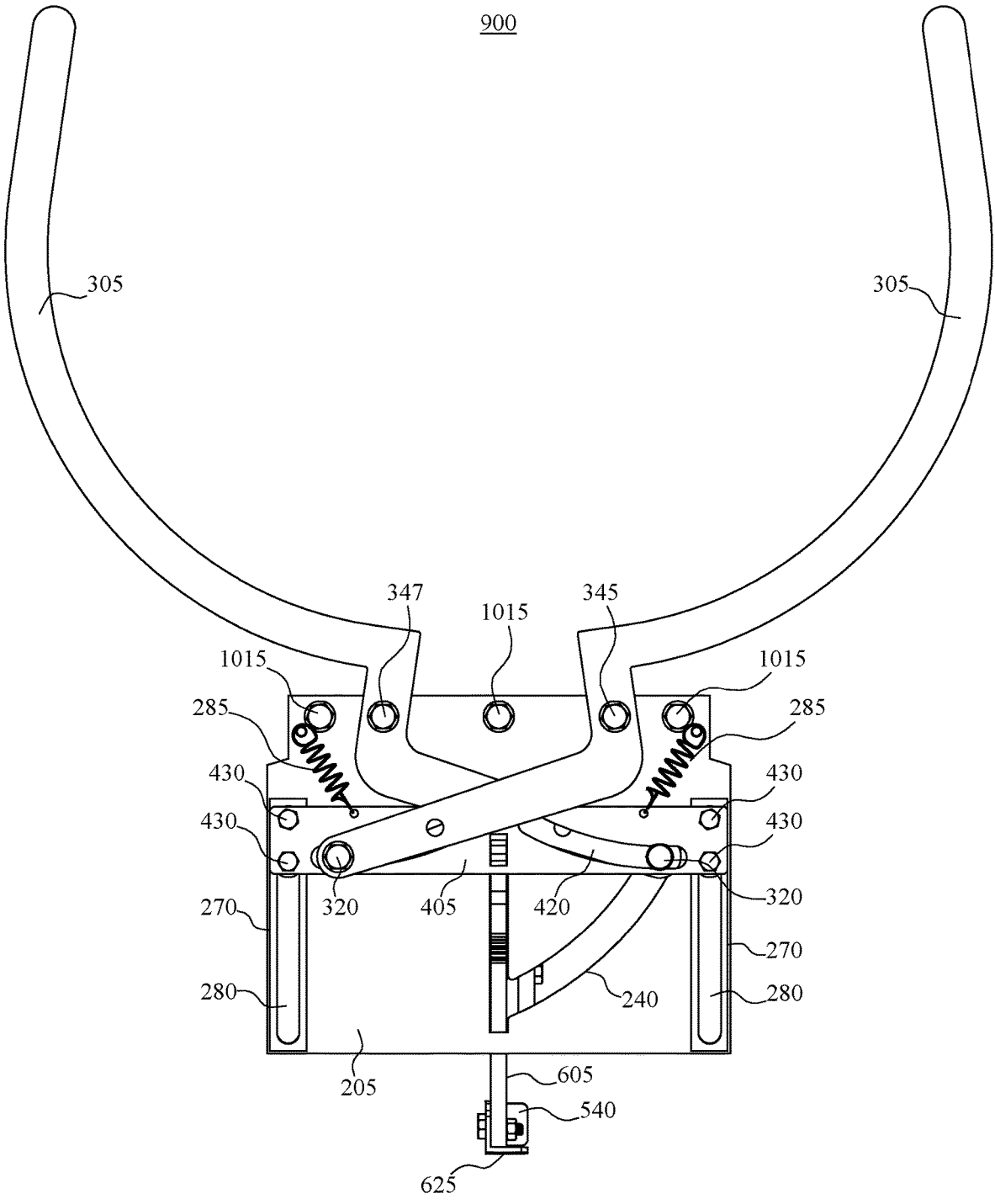


FIG. 7C

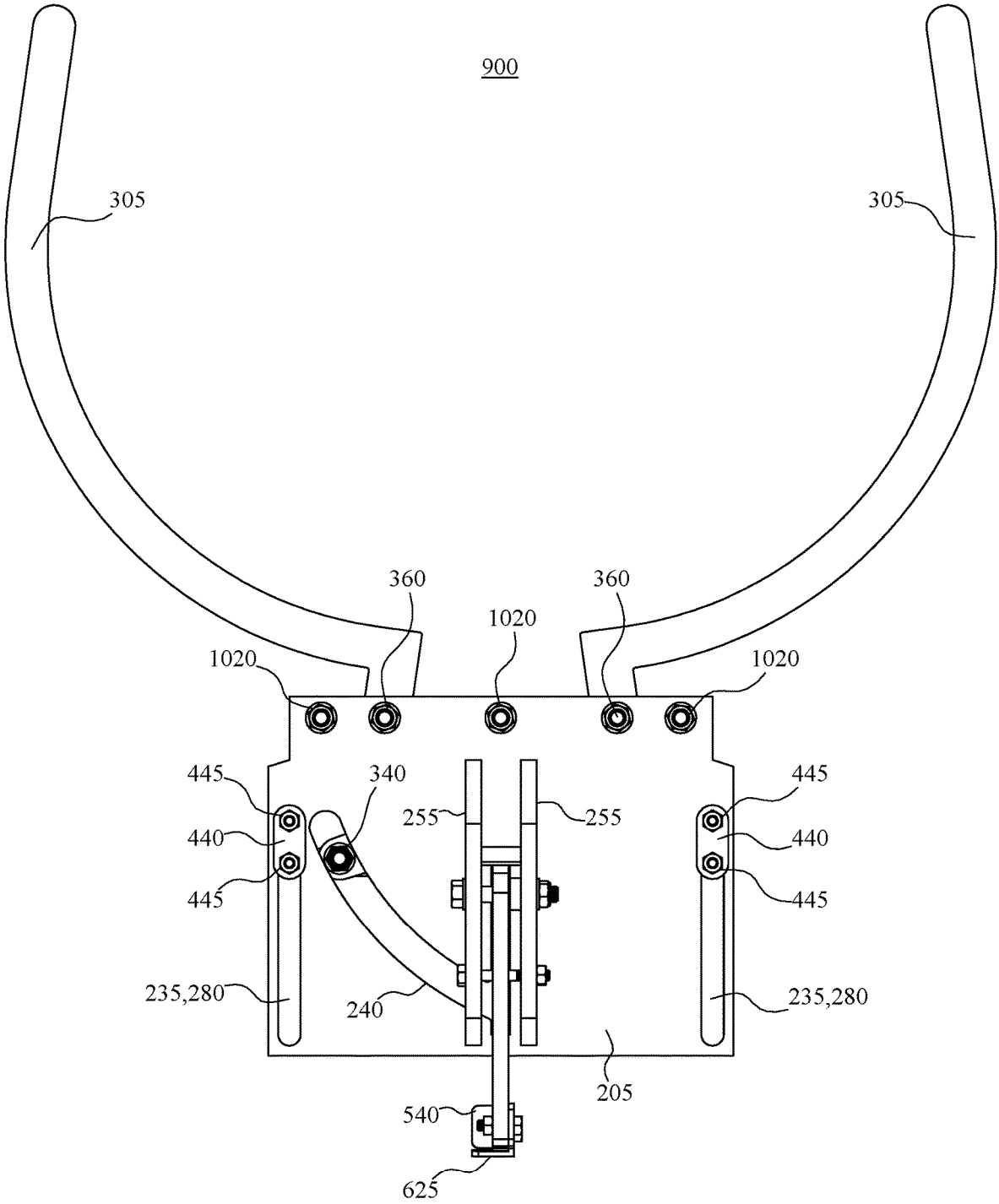


FIG. 7D

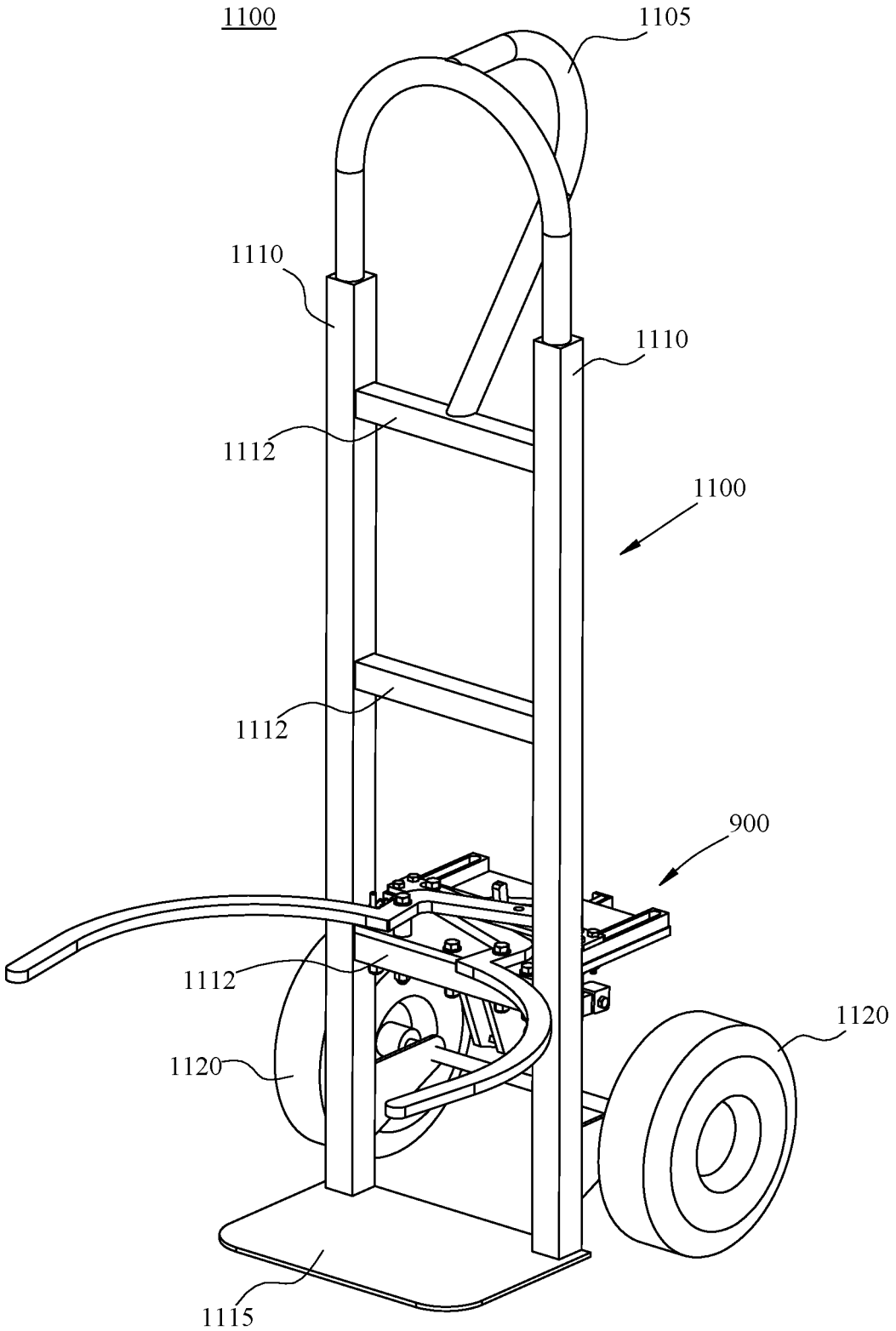


FIG. 8A

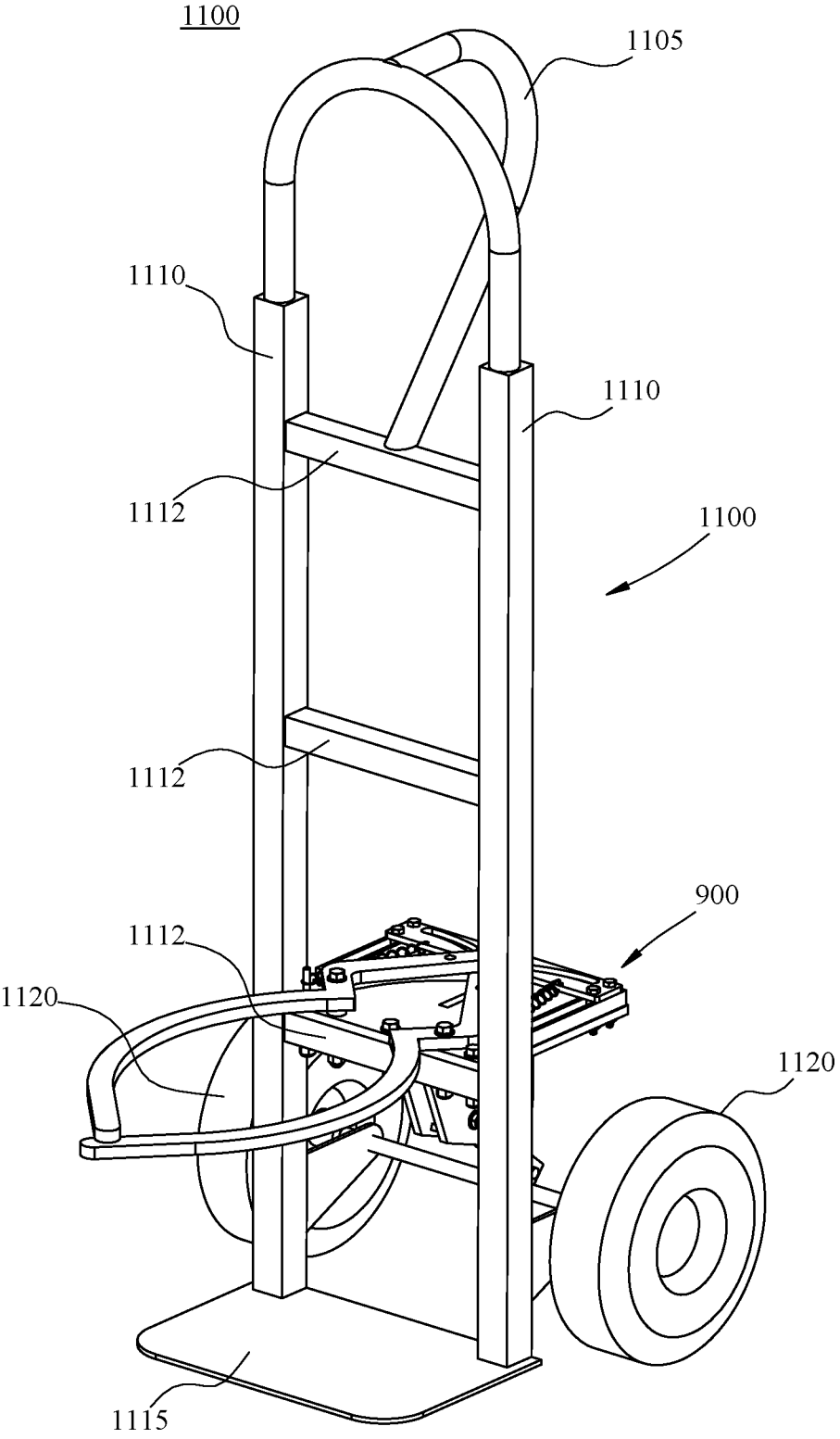


FIG. 8B

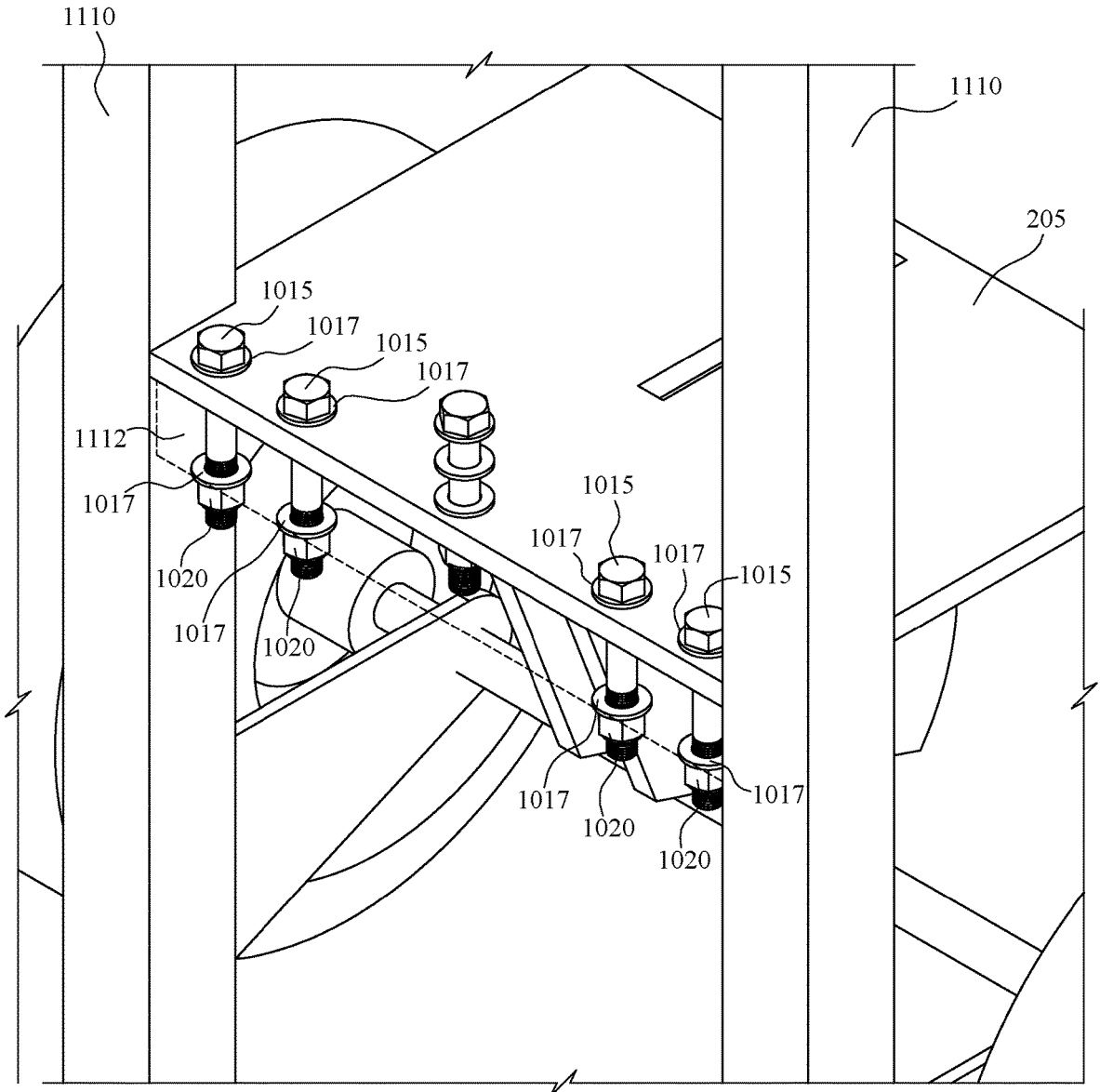


FIG. 8C

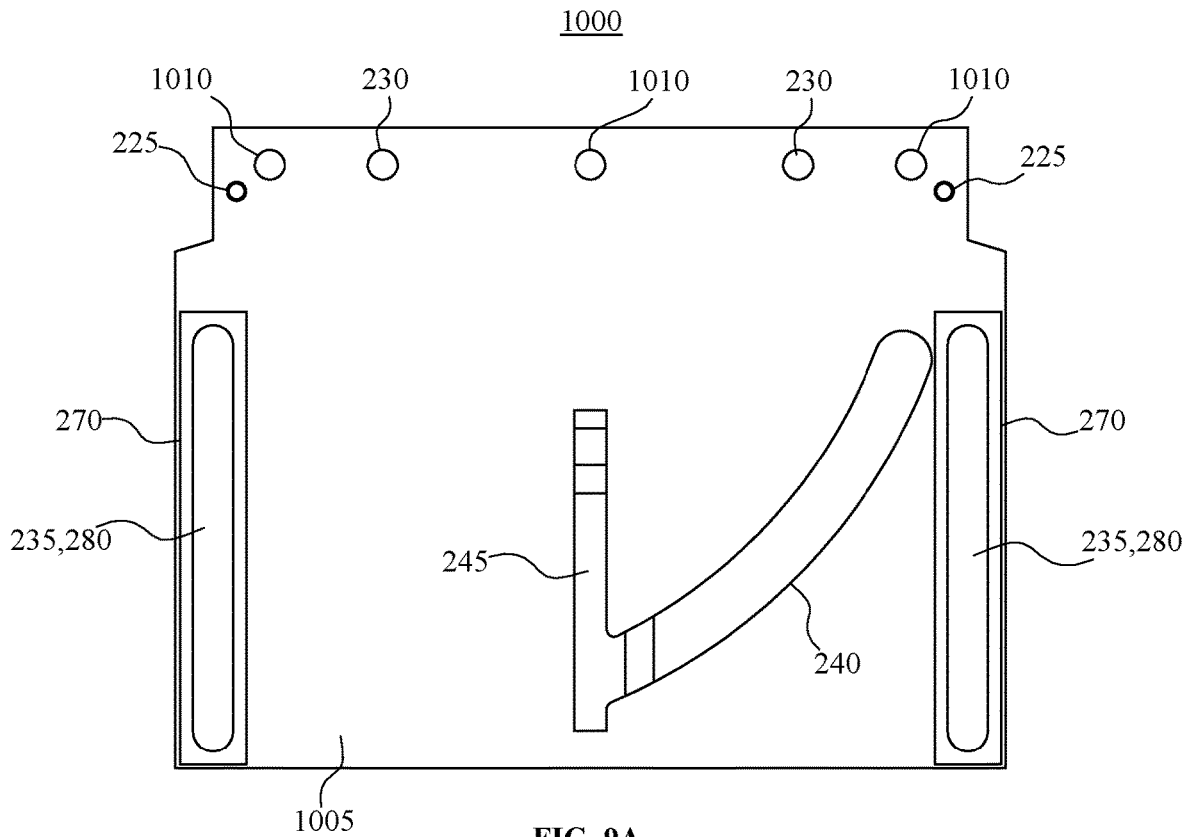


FIG. 9A

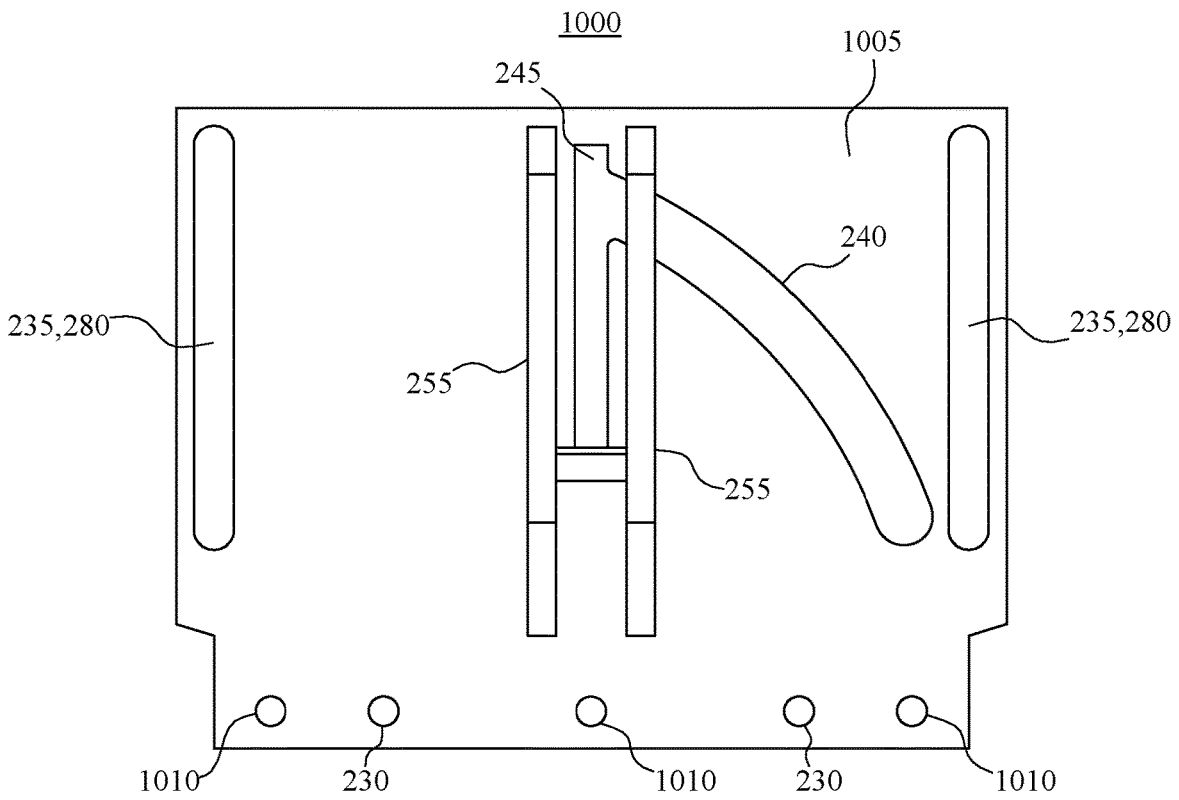


FIG. 9B

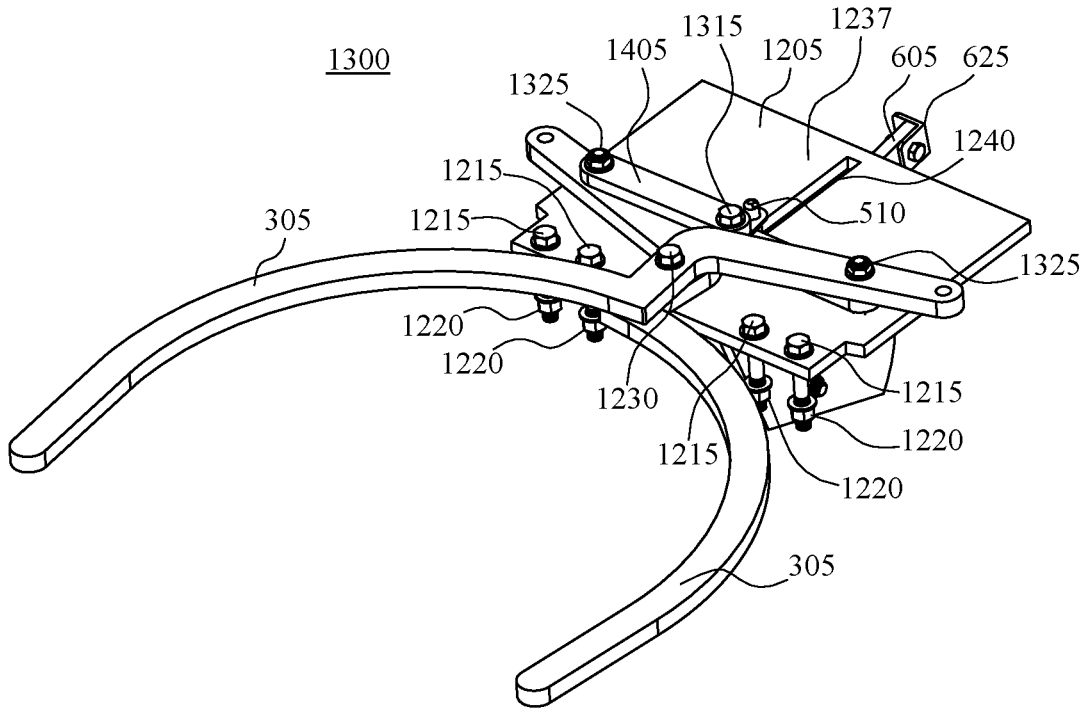


FIG. 10A

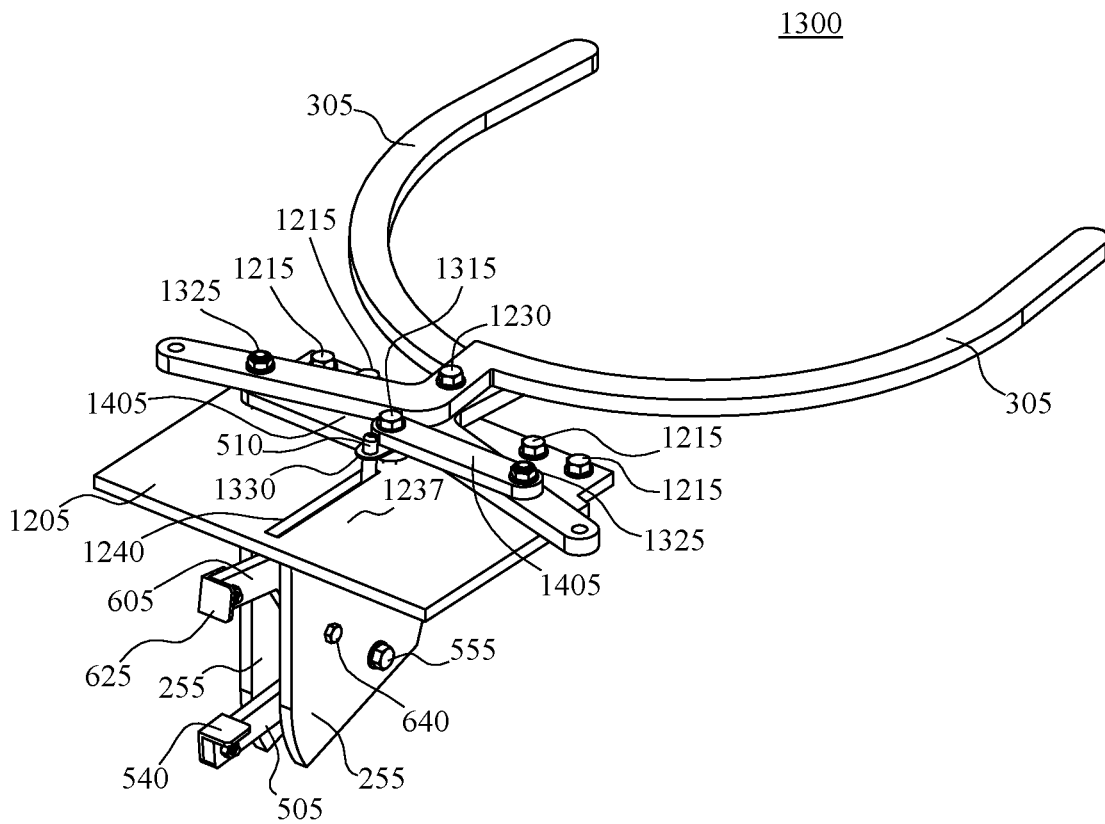


FIG. 10B

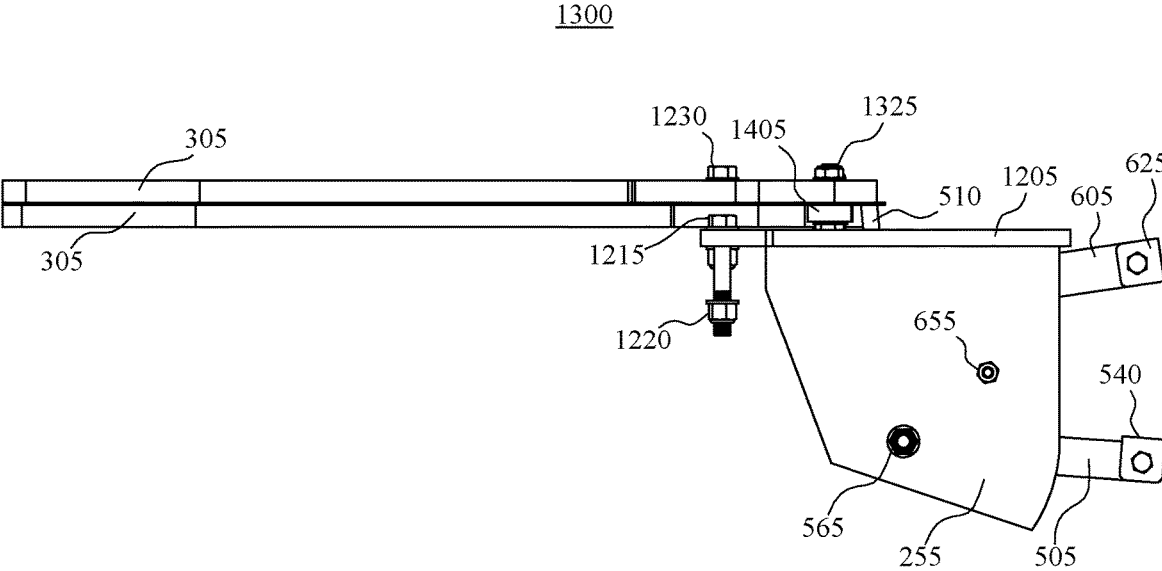


FIG. 10C

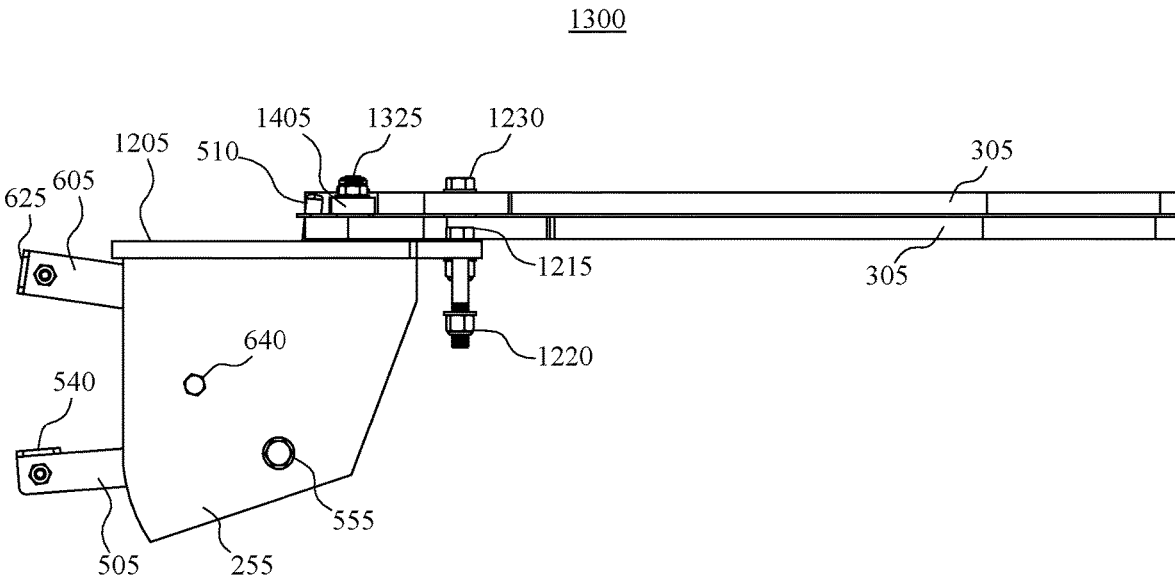


FIG. 10D



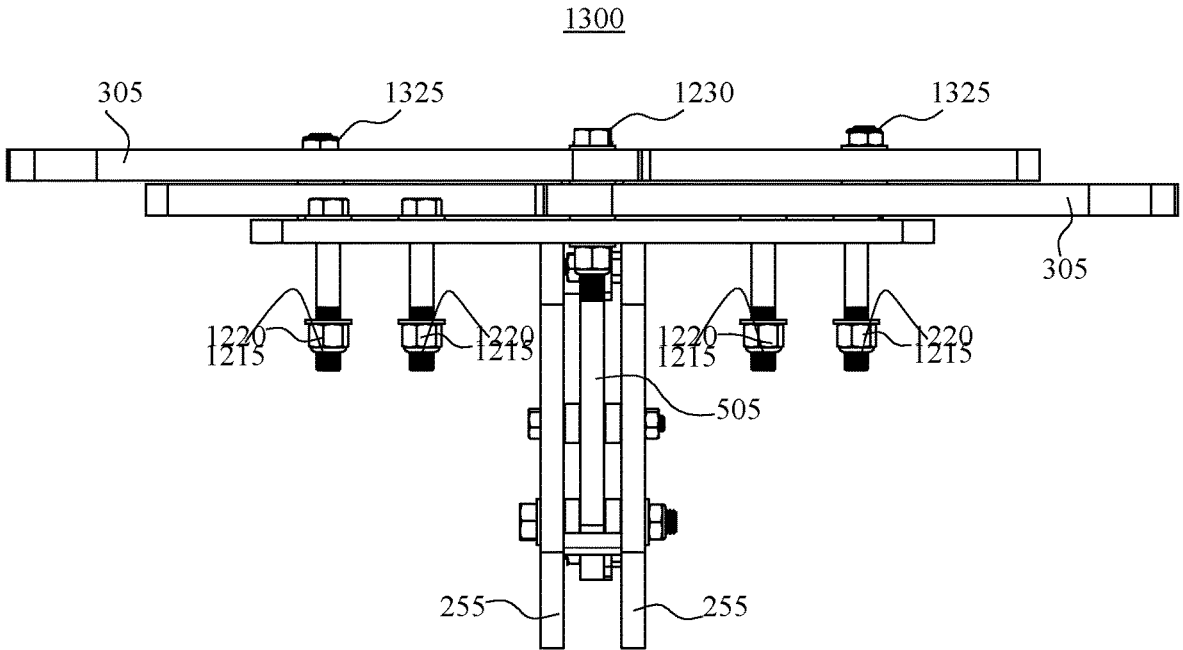


FIG. 10E

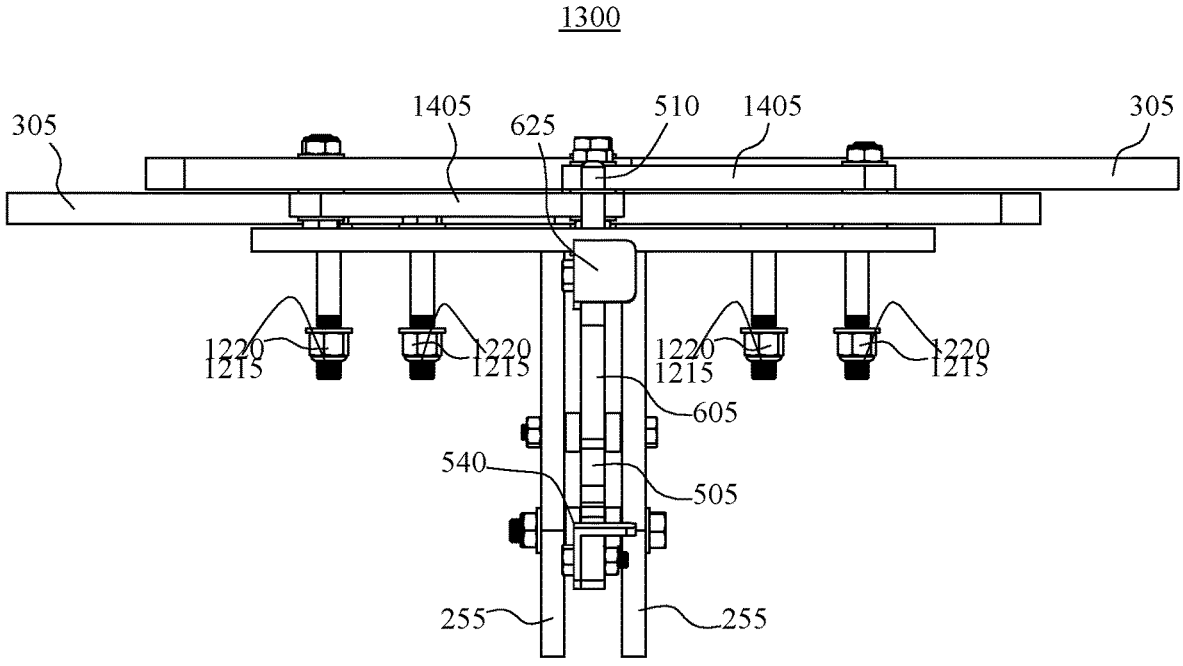


FIG. 10F

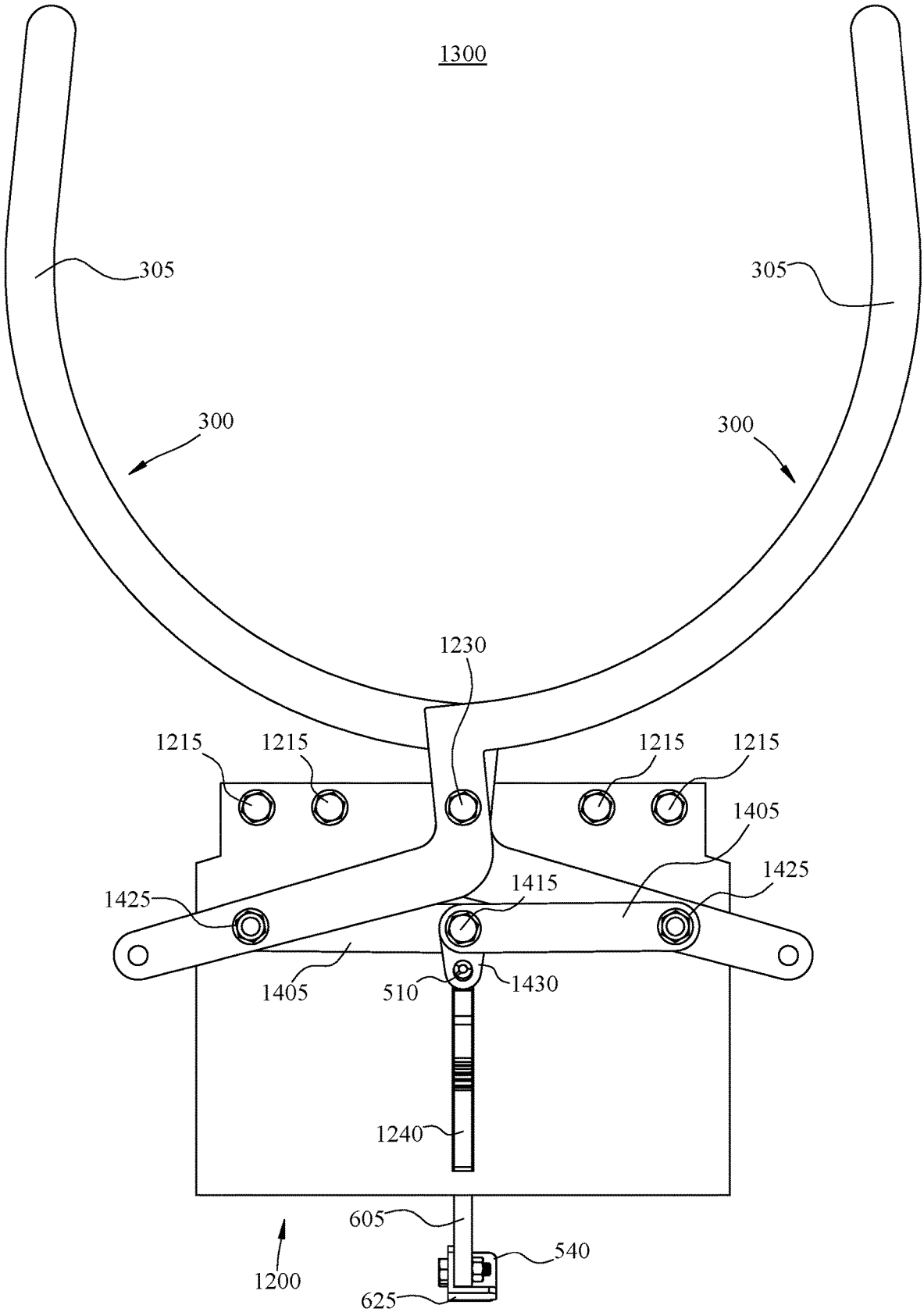


FIG. 11A

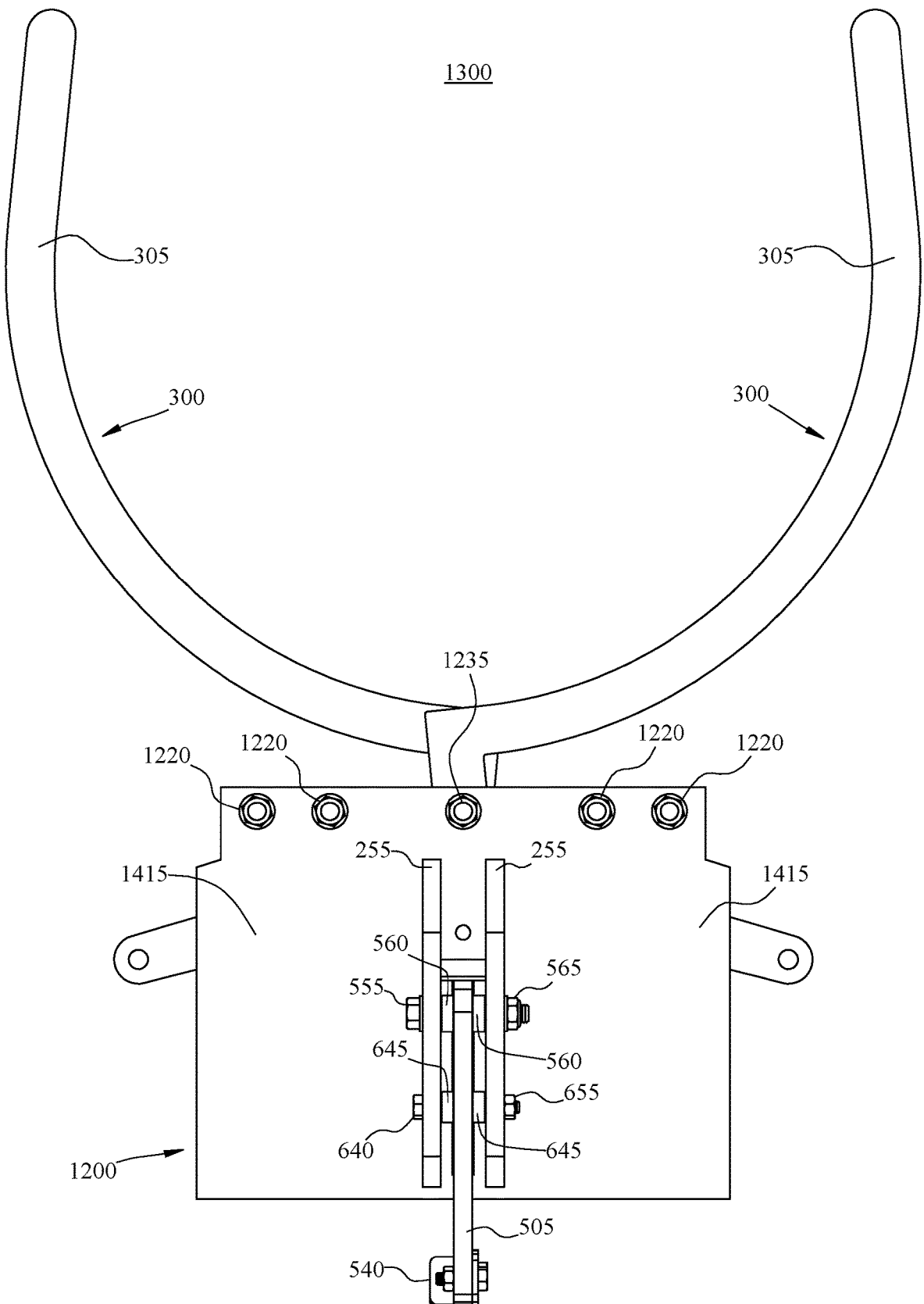


FIG. 11B

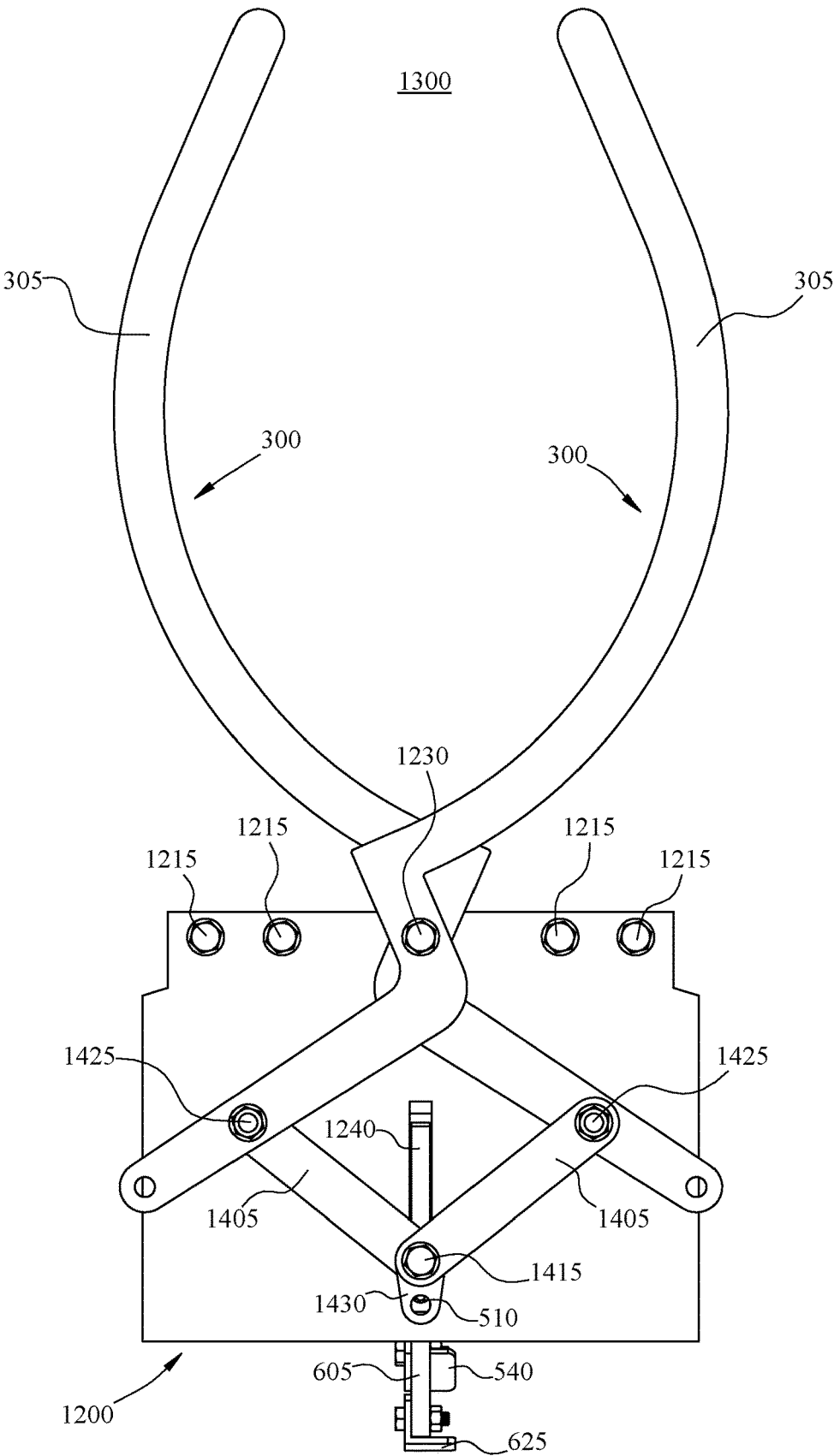


FIG. 11C

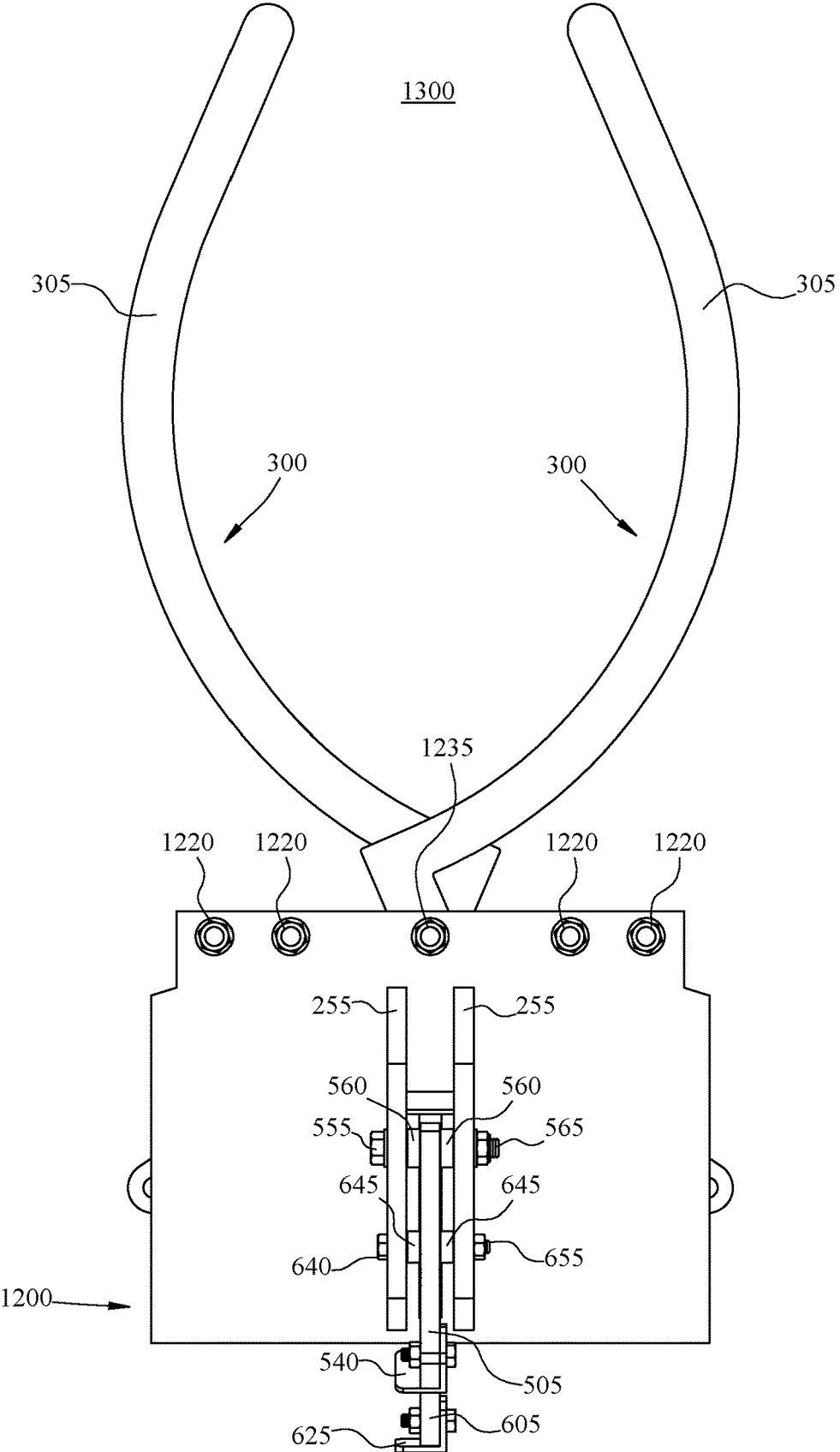


FIG. 11D

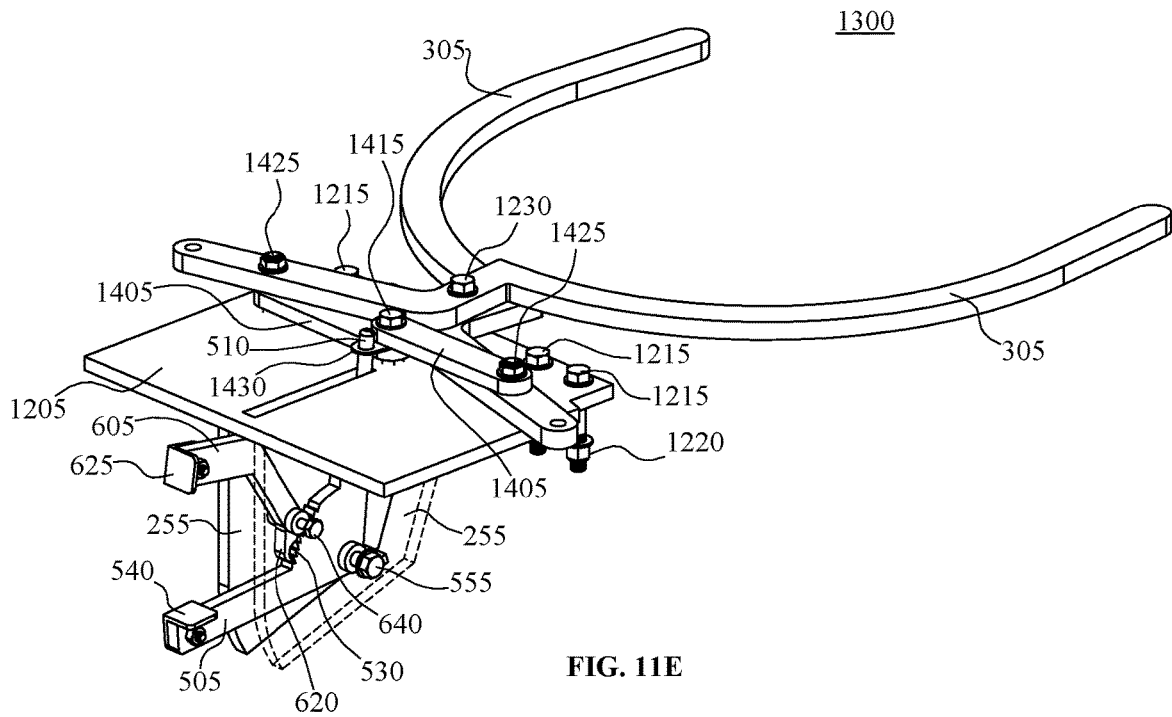


FIG. 11E

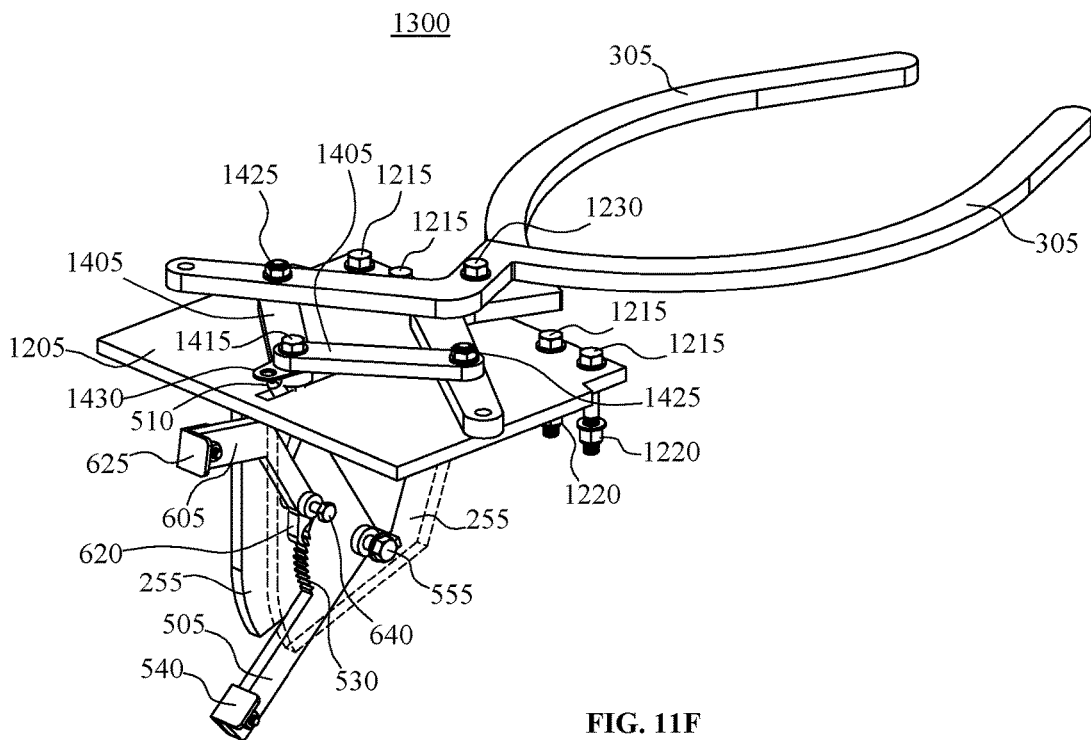


FIG. 11F

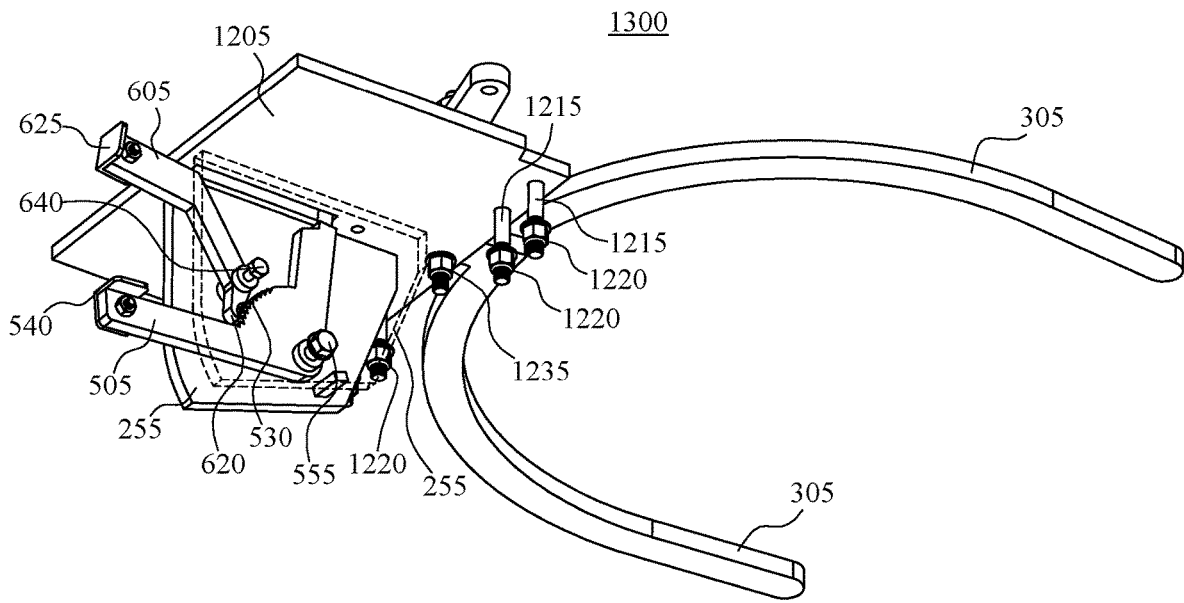


FIG. 11G

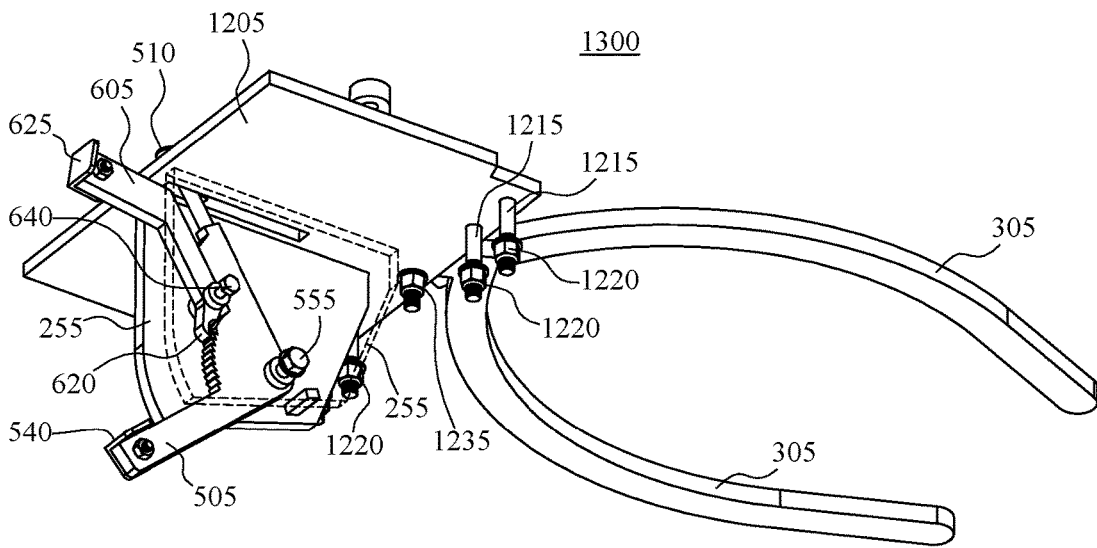


FIG. 11H

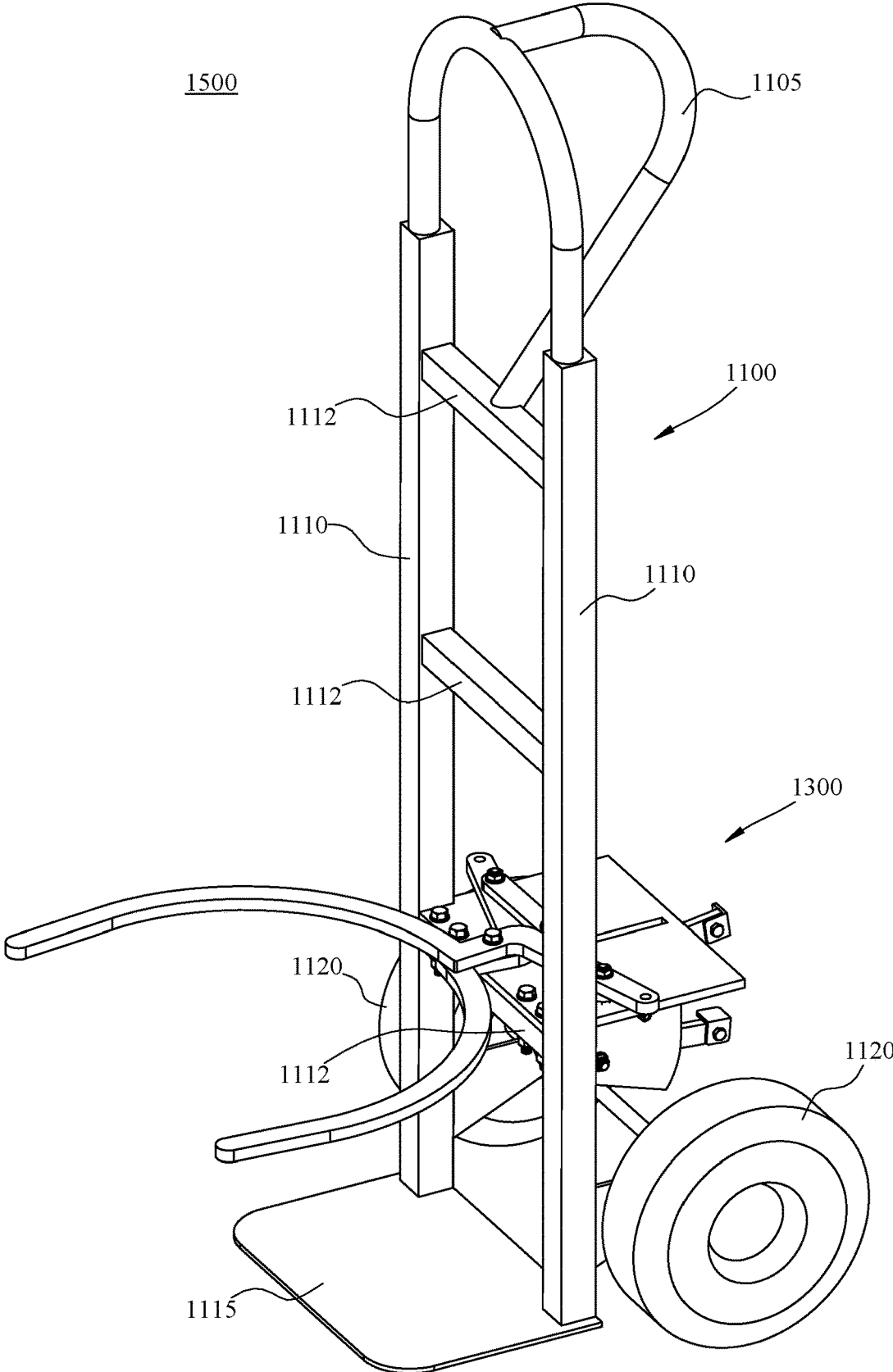


FIG. 12A



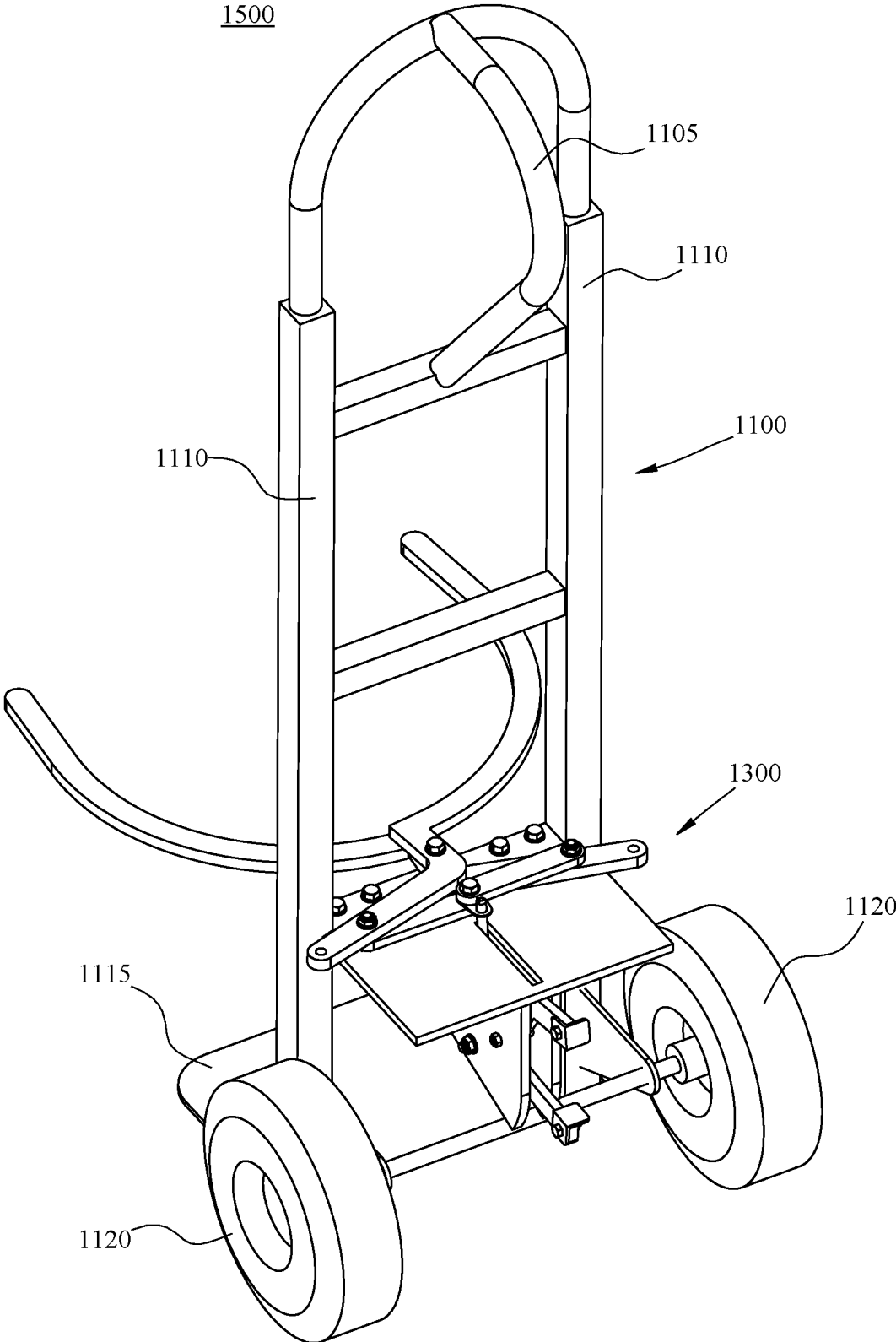


FIG. 12B

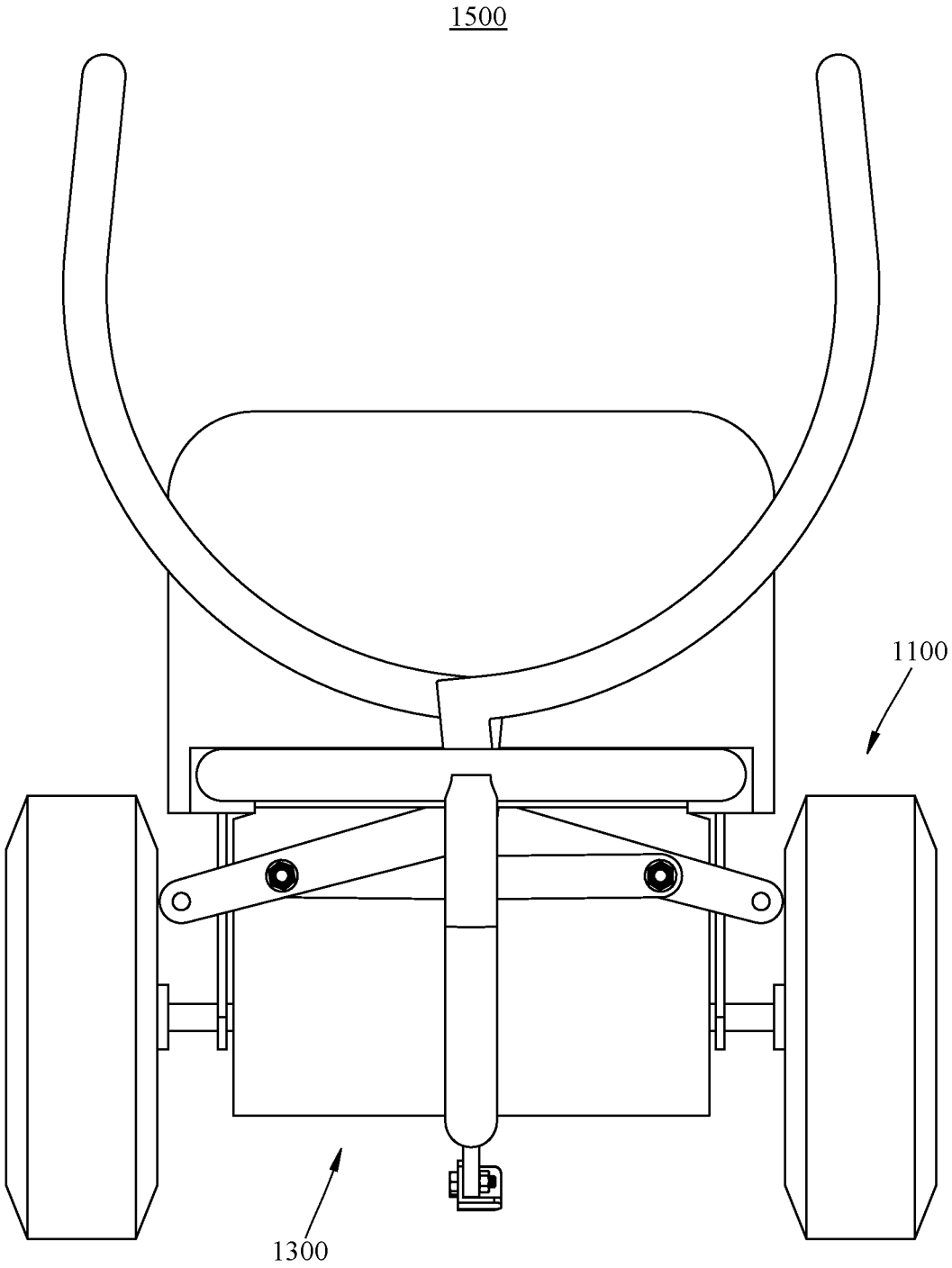


FIG. 12C

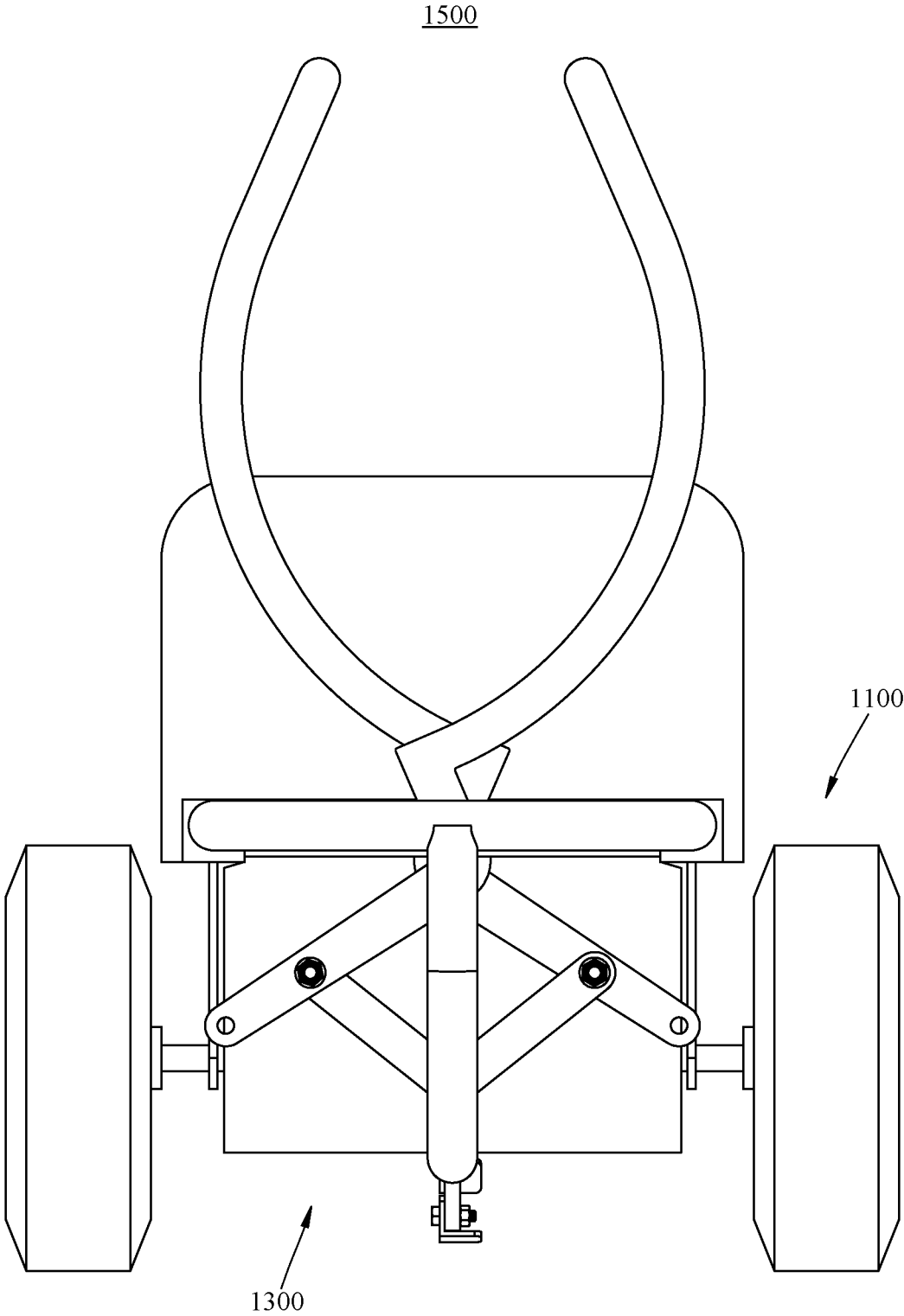


FIG. 12D

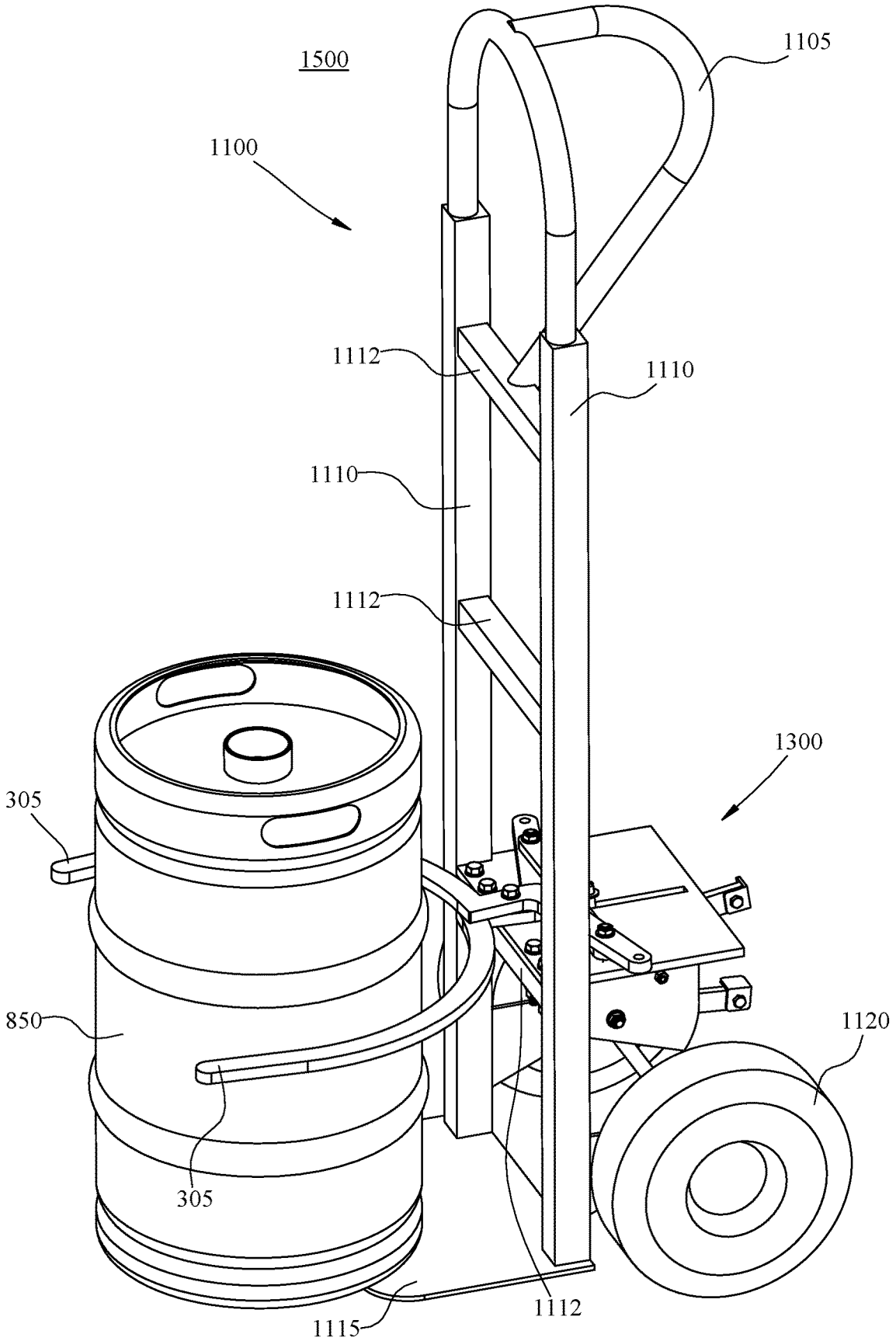


FIG. 13A

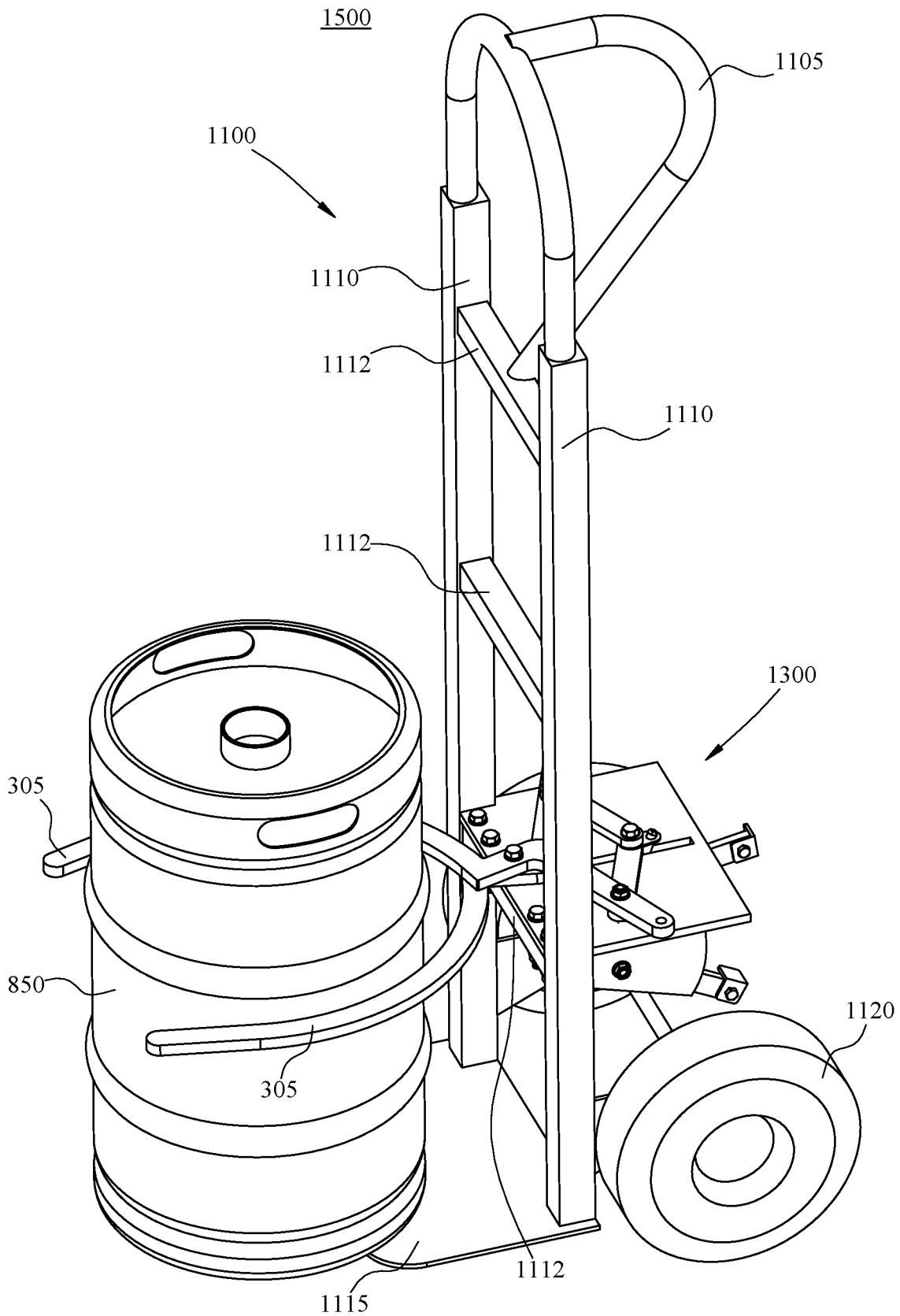


FIG. 13B

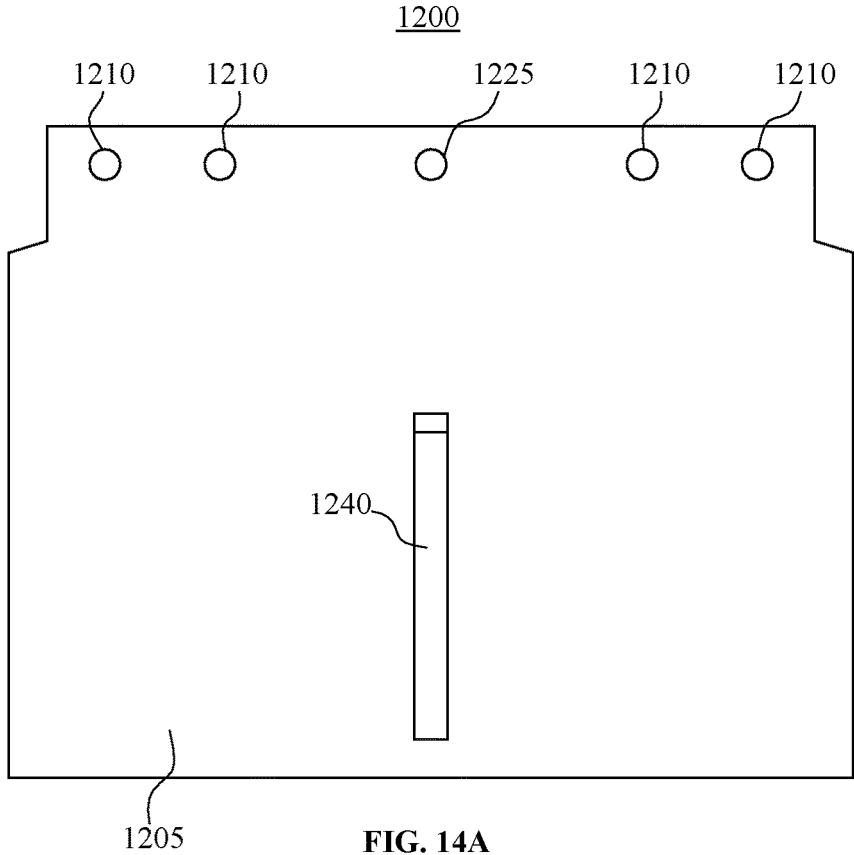


FIG. 14A

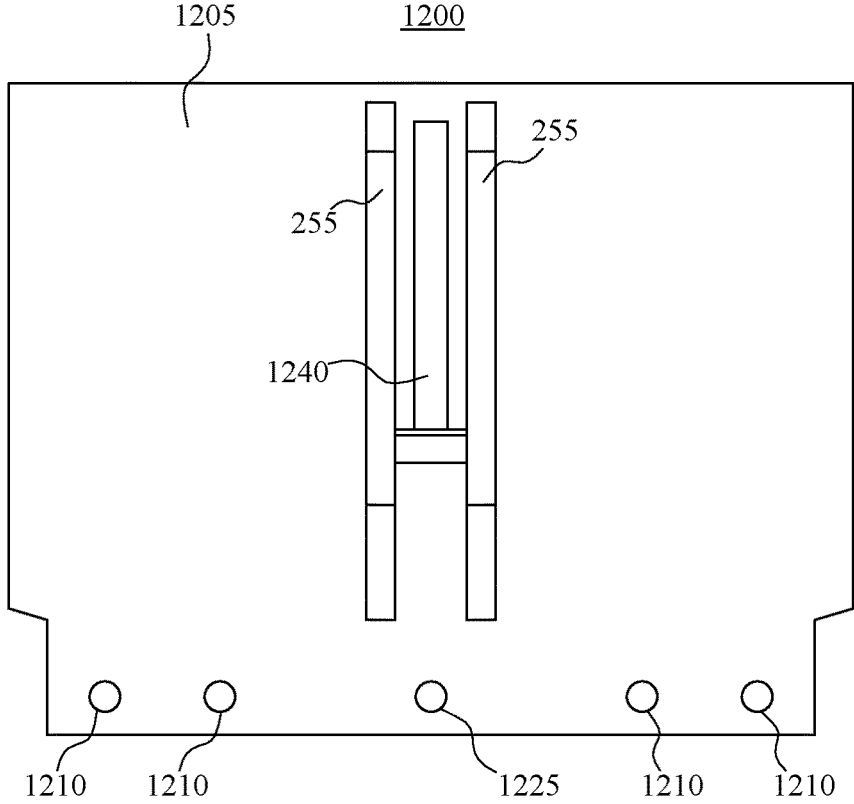
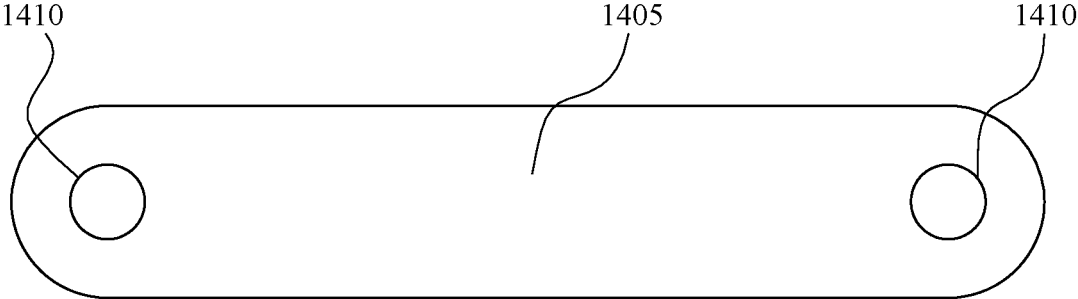


FIG. 14B

1400



**FIG. 14C**

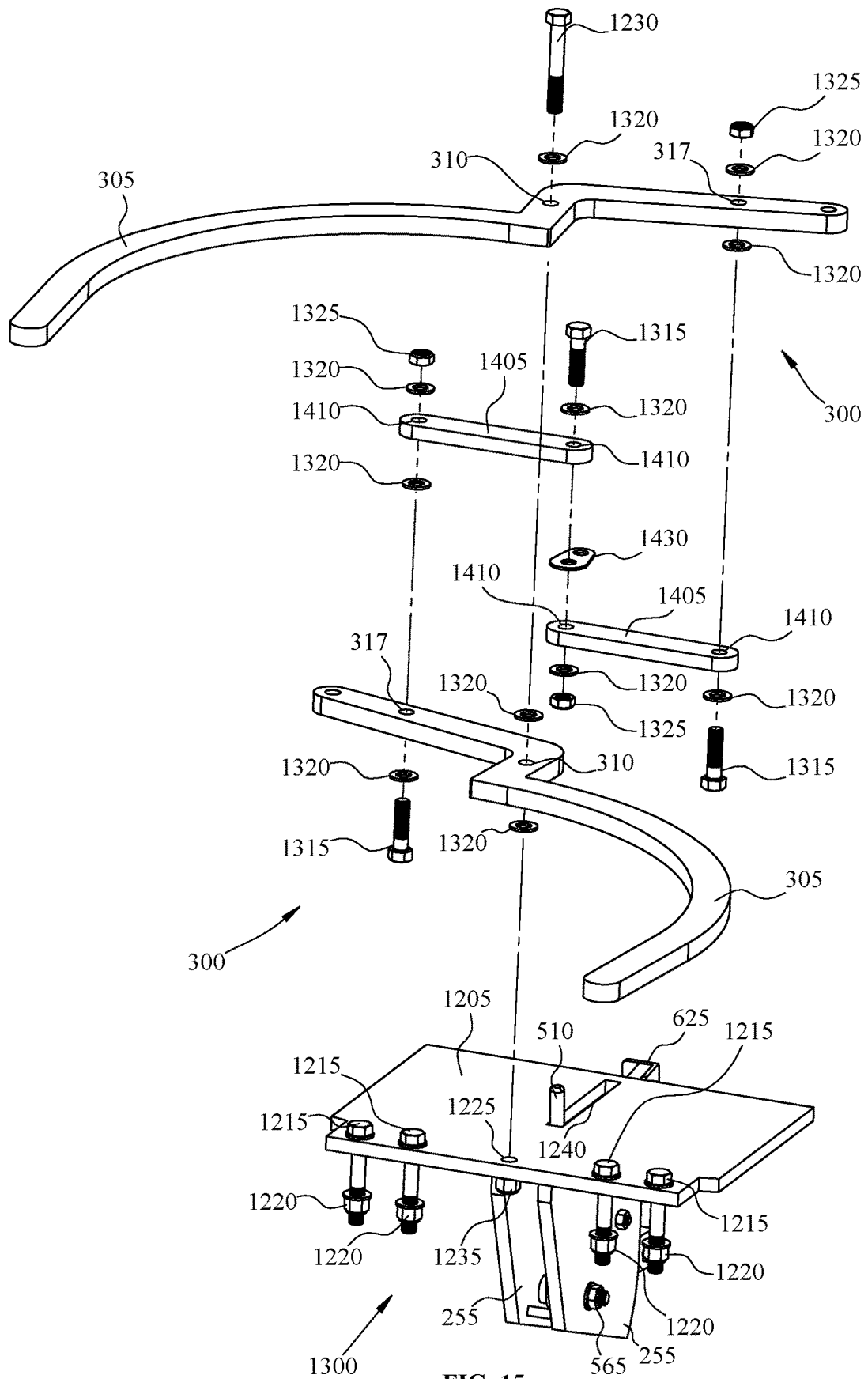


FIG. 15



## CLASPING STABILITY DEVICE AND CLASPING STABILIZED HAND TRUCK

### BACKGROUND OF THE INVENTION

[0001] A hand truck is used to assist a human operator in moving material from one location to another. Hand trucks are particularly useful when the size, shape, or weight of the material make it difficult for the human operator to move it by hand. There are several different types of hand trucks in common use, including, for example, commercial hand trucks, bread tray hand trucks, pail hand trucks, pallet hand trucks, and pry lever hand trucks. Conventional hand trucks typically include one or more handles, a wheeled frame, and a front-facing nose plate that is used to support material placed thereon. The nose plate is typically angled slightly down to assist in loading the material onto the nose plate. The human operator will typically position the edge of the nose plate near the edge of the object, use a foot to push the bottom portion of the hand truck forward to wedge the nose plate under the material while simultaneously using a hand to pull the material backward onto the nose plate. Once the nose plate is positioned under the material, the human operator typically places one hand on the handle of the hand truck and the other hand on the material to stabilize it while the human operator uses a foot to break the hand truck backwards toward the human operator. In doing so, the nose plate is angled up such that the material is supported at least partially on one side by the wheeled frame and at least partially by the nose plate. The human operator then uses the one or more handles to wheel the hand truck and material to the destination location.

### BRIEF SUMMARY OF THE INVENTION

[0002] According to one aspect of one or more embodiments of the present invention, a clasp stability device includes a pair of clasp arms each having a clasp portion, a pivoting attachment portion, and a rotating attachment portion, a base plate assembly having a base plate, a plurality of actuator travel positioner receivers disposed on top side of the base plate, and a plurality of pedal mounting plates disposed on a bottom side of the base plate, an actuator assembly having an actuator plate and a plurality of actuator travel positioners attached to a bottom side of the actuator plate, a pedal arm disposed in between the pedal mounting plates having an engagement portion, a pivot attachment portion, an index latch track, and an actuating portion, and a pedal latch disposed in between the pedal mounting plates having a release portion, a pivot attachment portion, and an index latch. The clasp arms are controllably closed by pushing the engagement portion of the pedal arm causing the pedal arm to travel such that the actuating portion of the pedal arm disposed within a cutout of the actuator plate causes the actuator plate assembly to travel in the actuator travel positioner receivers toward a rear of the base plate. The travel of the actuator plate assembly causes the rotating attachment portion of the clasp arms to travel within arcuate travel cutouts in the actuator plate while the pivot attachment portion of the clasp arms pivot causing the clasp arms to close. Upon release of the engagement portion the index latch engages the index latch track to stably retain a degree of closure of the clasp arms.

[0003] According to one aspect of one or more embodiments of the present invention, a clasp stabilized hand

truck includes a hand truck having a plurality of longitudinal support members, and a clasp stability device removably attached to the hand truck by a plurality of clasp assemblies. Each clasp assembly includes a front member having a radiused portion and a rear member having a radiused portion. The front member is removably attached to the rear member such that the radiused portions secure the clasp stability device to the longitudinal support members of the hand truck. The clasp stability device includes a pair of clasp arms each having a clasp portion, a pivoting attachment portion, and a rotating attachment portion, a base plate assembly having a base plate, a plurality of actuator travel positioner receivers disposed on top side of the base plate, and a plurality of pedal mounting plates disposed on a bottom side of the base plate, an actuator assembly having an actuator plate and a plurality of actuator travel positioners attached to a bottom side of the actuator plate, a pedal arm disposed in between the pedal mounting plates having an engagement portion, a pivot attachment portion, an index latch track, and an actuating portion, and a pedal latch disposed in between the pedal mounting plates having a release portion, a pivot attachment portion, and an index latch. The clasp arms are controllably closed by pushing the engagement portion of the pedal arm causing the pedal arm to travel such that the actuating portion of the pedal arm disposed within a cutout of the actuator plate causes the actuator plate assembly to travel in the actuator travel positioner receivers toward a rear of the base plate. The travel of the actuator plate assembly causes the rotating attachment portion of the clasp arms to travel within arcuate travel cutouts in the actuator plate while the pivot attachment portion of the clasp arms pivot causing the clasp arms to close. Upon release of the engagement portion the index latch engages the index latch track to stably retain a degree of closure of the clasp arms.

[0004] According to one aspect of one or more embodiments of the present invention, a clasp stabilized hand truck includes a hand truck having a plurality of transverse support members, and a clasp stability device removably attached to the hand truck by a plurality of mounting bolts that secure the clasp stability device to the transverse support member of the hand truck. The clasp stability device includes a pair of clasp arms each having a clasp portion, a pivoting attachment portion, and a rotating attachment portion, a base plate assembly having a base plate, a plurality of actuator travel positioner receivers disposed on top side of the base plate, and a plurality of pedal mounting plates disposed on a bottom side of the base plate, an actuator assembly having an actuator plate and a plurality of actuator travel positioners attached to a bottom side of the actuator plate, a pedal arm disposed in between the pedal mounting plates having an engagement portion, a pivot attachment portion, an index latch track, and an actuating portion, and a pedal latch disposed in between the pedal mounting plates having a release portion, a pivot attachment portion, and an index latch. The clasp arms are controllably closed by pushing the engagement portion of the pedal arm causing the pedal arm to travel such that the actuating portion of the pedal arm disposed within a cutout of the actuator plate causes the actuator plate assembly to travel in the actuator travel positioner receivers toward a rear of the base plate. The travel of the actuator plate assembly causes the rotating attachment portion of the clasp arms to travel within arcuate travel cutouts in the actuator plate

while the pivot attachment portion of the claspings arms pivot causing the claspings arms to close. Upon release of the engagement portion the index latch engages the index latch track to stably retain a degree of closure of the claspings arms.

[0005] Other aspects of the present invention will be apparent from the following description and claims.

#### BRIEF DESCRIPTION OF THE DRAWINGS

[0006] FIG. 1A shows a front facing top-side perspective view of a claspings stability device in accordance with one or more embodiments of the present invention.

[0007] FIG. 1B shows a rear facing top-side perspective view of the claspings stability device in accordance with one or more embodiments of the present invention.

[0008] FIG. 1C shows a left-side elevation view of the claspings stability device in accordance with one or more embodiments of the present invention.

[0009] FIG. 1D shows a right-side elevation view of the claspings stability device in accordance with one or more embodiments of the present invention.

[0010] FIG. 1E shows a front elevation view of the claspings stability device in accordance with one or more embodiments of the present invention.

[0011] FIG. 1F shows a rear elevation view of the claspings stability device in accordance with one or more embodiments of the present invention.

[0012] FIG. 2A shows a top plan view of a claspings stability device in an opened state in accordance with one or more embodiments of the present invention.

[0013] FIG. 2B shows a bottom plan view of the claspings stability device in the opened state in accordance with one or more embodiments of the present invention.

[0014] FIG. 2C shows a top plan view of the claspings stability device in a closed state in accordance with one or more embodiments of the present invention.

[0015] FIG. 2D shows a bottom plan view of the claspings stability device in the closed state in accordance with one or more embodiments of the present invention.

[0016] FIG. 2E shows a rear facing top-side perspective view of the claspings stability device in the opened state in accordance with one or more embodiments of the present invention.

[0017] FIG. 2F shows a rear facing top-side perspective view of the claspings stability device in the closed state in accordance with one or more embodiments of the present invention.

[0018] FIG. 2G shows a rear facing bottom-side perspective view of the claspings stability device in the opened state in accordance with one or more embodiments of the present invention.

[0019] FIG. 2H shows a rear facing bottom-side perspective view of the claspings stability device in the closed state in accordance with one or more embodiments of the present invention.

[0020] FIG. 3A shows a front facing top-side perspective view of a claspings stabilized hand truck in accordance with one or more embodiments of the present invention.

[0021] FIG. 3B shows a rear facing top-side perspective view of the claspings stabilized hand truck in accordance with one or more embodiments of the present invention.

[0022] FIG. 3C shows a top plan view of the claspings stabilized hand truck in an opened state in accordance with one or more embodiments of the present invention.

[0023] FIG. 3D shows a top plan view of the claspings stabilized hand truck in a closed state in accordance with one or more embodiments of the present invention.

[0024] FIG. 4A shows a front facing top-side perspective view of a claspings stabilized hand truck in an opened state showing an environment of use in accordance with one or more embodiments of the present invention.

[0025] FIG. 4B shows a front facing top-side perspective view of the claspings stabilized hand truck in a closed state showing an environment of use in accordance with one or more embodiments of the present invention.

[0026] FIG. 5A shows a top plan view of a base plate assembly of a claspings stability device in accordance with one or more embodiments of the present invention.

[0027] FIG. 5B shows a bottom plan view of the base plate assembly of the claspings stability device in accordance with one or more embodiments of the present invention.

[0028] FIG. 5C shows a top plan view of a claspings arm of the claspings stability device in accordance with one or more embodiments of the present invention.

[0029] FIG. 5D shows a top plan view of an actuator plate of the claspings stability device in accordance with one or more embodiments of the present invention.

[0030] FIG. 5E shows a right-side elevation view of a pedal arm of the claspings stability device in accordance with one or more embodiments of the present invention.

[0031] FIG. 5F shows a right-side elevation view of a pedal latch of the claspings stability device in accordance with one or more embodiments of the present invention.

[0032] FIG. 6A shows assembly of a portion of a claspings stability device in accordance with one or more embodiments of the present invention.

[0033] FIG. 6B shows assembly of a portion of the claspings stability device in accordance with one or more embodiments of the present invention.

[0034] FIG. 6C shows assembly of a portion of the claspings stability device in accordance with one or more embodiments of the present invention.

[0035] FIG. 7A shows a front facing top-side perspective view of a claspings stability device in accordance with one or more embodiments of the present invention.

[0036] FIG. 7B shows a rear facing top-side perspective view of the claspings stability device in accordance with one or more embodiments of the present invention.

[0037] FIG. 7C shows a top plan view of a claspings stability device in an opened state in accordance with one or more embodiments of the present invention.

[0038] FIG. 7D shows a bottom plan view of the claspings stability device in the opened state in accordance with one or more embodiments of the present invention.

[0039] FIG. 8A shows a front facing top-side perspective view of a claspings stabilized hand truck in an opened state in accordance with one or more embodiments of the present invention.

[0040] FIG. 8B shows a front facing top-side perspective view of the claspings stabilized hand truck in a closed state in accordance with one or more embodiments of the present invention.

[0041] FIG. 8C shows a detail view of the attachment of the claspings stability device to the hand truck in accordance with one or more embodiments of the present invention.

[0042] FIG. 9A shows a top plan view of a base plate of a claspings stability device in accordance with one or more embodiments of the present invention.

[0043] FIG. 9B shows a bottom plan view of the base plate of the clasp stability device in accordance with one or more embodiments of the present invention.

[0044] FIG. 10A shows a front facing top-side perspective view of a clasp stability device in accordance with one or more embodiments of the present invention.

[0045] FIG. 10B shows a rear facing top-side perspective view of the clasp stability device in accordance with one or more embodiments of the present invention.

[0046] FIG. 10C shows a left-side elevation view of the clasp stability device in accordance with one or more embodiments of the present invention.

[0047] FIG. 10D shows a right-side elevation view of the clasp stability device in accordance with one or more embodiments of the present invention.

[0048] FIG. 10E shows a front elevation view of the clasp stability device in accordance with one or more embodiments of the present invention.

[0049] FIG. 10F shows a rear elevation view of the clasp stability device in accordance with one or more embodiments of the present invention.

[0050] FIG. 11A shows a top plan view of a clasp stability device in an opened state in accordance with one or more embodiments of the present invention.

[0051] FIG. 11B shows a bottom plan view of the clasp stability device in the opened state in accordance with one or more embodiments of the present invention.

[0052] FIG. 11C shows a top plan view of the clasp stability device in a closed state in accordance with one or more embodiments of the present invention.

[0053] FIG. 11D shows a bottom plan view of the clasp stability device in the closed state in accordance with one or more embodiments of the present invention.

[0054] FIG. 11E shows a rear facing top-side perspective view of the clasp stability device in the opened state in accordance with one or more embodiments of the present invention.

[0055] FIG. 11F shows a rear facing top-side perspective view of the clasp stability device in the closed state in accordance with one or more embodiments of the present invention.

[0056] FIG. 11G shows a rear facing bottom-side perspective view of the clasp stability device in the opened state in accordance with one or more embodiments of the present invention.

[0057] FIG. 11H shows a rear facing bottom-side perspective view of the clasp stability device in the closed state in accordance with one or more embodiments of the present invention.

[0058] FIG. 12A shows a front facing top-side perspective view of a clasp stabilized hand truck in accordance with one or more embodiments of the present invention.

[0059] FIG. 12B shows a rear facing top-side perspective view of the clasp stabilized hand truck in accordance with one or more embodiments of the present invention.

[0060] FIG. 12C shows a top plan view of the clasp stabilized hand truck in an opened state in accordance with one or more embodiments of the present invention.

[0061] FIG. 12D shows a top plan view of the clasp stabilized hand truck in a closed state in accordance with one or more embodiments of the present invention.

[0062] FIG. 13A shows a front facing top-side perspective view of a clasp stabilized hand truck in an opened state

showing an environment of use in accordance with one or more embodiments of the present invention.

[0063] FIG. 13B shows a front facing top-side perspective view of the clasp stabilized hand truck in a closed state showing an environment of use in accordance with one or more embodiments of the present invention.

[0064] FIG. 14A shows a top plan view of a base plate of a clasp stability device in accordance with one or more embodiments of the present invention.

[0065] FIG. 14B shows a bottom plan view of the base plate of the clasp stability device in accordance with one or more embodiments of the present invention.

[0066] FIG. 14C shows a top plan view of an actuator plate of the clasp stability device in accordance with one or more embodiments of the present invention.

[0067] FIG. 15 shows assembly of a portion of a clasp stability device in accordance with one or more embodiments of the present invention.

#### DETAILED DESCRIPTION OF THE INVENTION

[0068] One or more embodiments of the present invention are described in detail with reference to the accompanying figures. For consistency, like elements in the various figures are denoted by like reference numerals. In the following detailed description of the present invention, specific details are described to provide a thorough understanding of the present invention. In other instances, aspects that are well-known to those of ordinary skill in the art are not described to avoid obscuring the description of the present invention.

[0069] An inherent problem with conventional hand trucks is that they lack stability with respect to the material they transport. Depending on its size, shape, and weight, the material may become unstable and move or even fall off the hand truck. The problem may be exacerbated by ground that is not level, obstructions in the path of travel, and shifting weight caused by movement of the hand truck during transport. This presents a risk to the operator and may give rise to more serious safety and environmental concerns when the material includes chemical, flammable, or hazardous materials.

[0070] The nose plate of a conventional hand truck is typically smaller in at least one dimension than the material it is used to transport. As such, the nose plate is only capable of supporting a portion of the material. The practical consequence of this is that the human operator must load the material and tilt the hand truck backwards to use the wheeled frame to provide additional support to the material during transport. Specifically, the human operator must position the edge of the nose plate of the hand truck near the edge of the material, push the hand truck forward with their foot to wedge the nose plate under the material, while simultaneously pulling the material towards the rear of the nose plate with their hand. Once the nose plate is properly positioned under the material, the human operator must then tilt the hand truck backwards using one hand and one foot while simultaneously supporting the material with the other hand until it is at least partially supported on one side by the wheeled frame of the hand truck in the tilted-back position. Because the configuration and shape of the wheeled frame varies from hand truck to hand truck, the degree of support that the wheeled frame provides varies from design to design and also varies with the size, shape, and weight of the material. Once the hand truck is in the titled-back position,

the material is at least partially supported by the wheeled frame and the nose plate. The human operator may then attempt to transport the material to the desired location. However, there is little to no support for the material on at least four sides, and the material is prone to fall off the hand truck in any of the unsupported directions during transport.

**[0071]** In an effort to stabilize the material, various straps or ties may be used to secure the material to the hand truck. However, the use of straps or ties require the human operator to load the material as described above, then set the hand truck down on the nose plate, walk around to the front of the hand truck, and manually strap or tie down the material to the hand truck. The fact that the human operator cannot strap or tie down the material from the rear of the hand truck is problematic because some materials become unstable merely from setting the hand truck down, where the nose plate is typically angled slightly down. As such, straps and ties are not effective for materials that have a size, shape, or weight, such as, for example, large and heavy cylindrical-shaped materials, that make it difficult to secure to the hand truck from the front of the hand truck. Notwithstanding, the use of straps or ties slows down the transport operation considerably and increases costs.

**[0072]** Accordingly, in one or more embodiments of the present invention, a clasp stability device and clasp stabilized hand truck provide a stable material handling platform safely operable by a single human operator. The operator may safely and securely load, transport, and unload material entirely from the rear of the hand truck, without having to use straps or ties. The clasp stability device may assist in loading material onto the hand truck at the source location, stabilize the material during transport, and assist in unloading the material from the hand truck at the destination location. The clasp stability device includes a clasp mechanism that may assist in pulling material toward the rear of the nose plate of the hand truck, and onto the nose plate, while the clasp mechanism is closing. The clasp mechanism may lock into place once the clasp arms are closed to a sufficient degree to secure the material. The locking mechanism may be automatically engaged upon release of the engagement portion of the pedal arm of the clasp stability device. The locking mechanism may remain locked, stabilizing the material on the hand truck, during transport until the release portion of the pedal latch of the clasp stability device is engaged. The clasp mechanism may assist in releasing material toward the front of the nose plate while the clasp mechanism is opening. Advantageously, the clasp stability device provides a single stroke clasp mechanism that is engaged entirely from the rear of the hand truck and that automatically locks into place to secure the material to the hand truck. In addition, the clasp stability device provides a single stroke release mechanism that is also engaged entirely from the rear of the hand truck. The ability of a single human operator to safely load, transport, and unload material is substantially enhanced, and the time required is minimized. Moreover, the clasp stability device and clasp stabilized hand truck improve the safety of transporting chemical, flammable, and hazardous materials and well as materials that have a size, shape, or weight that is problematic for conventional hand trucks.

**[0073]** FIG. 1A shows a front facing top-side perspective view of a clasp stability device 100 in accordance with one or more embodiments of the present invention. Clasp

stability device 100 may include a secure clasp mechanism that may be used to stabilize material on a hand truck (not shown). Clasp stability device 100 may include a base plate assembly 200 and a pair of clasp arm assemblies 300 removably attached to base plate assembly 200. Continuing, FIG. 1B shows a rear facing top-side perspective view of clasp stability device 100 in accordance with one or more embodiments of the present invention. Clasp stability device 100 may also include an actuator assembly 400 that facilitates the clasp and release mechanisms of clasp arm assemblies 300, a pedal arm assembly 500 that may controllably engage the clasp mechanism of clasp arms 300, and a pedal latch assembly 600 that may engage the locking mechanism or release mechanism of clasp arm assemblies 300. In the embodiment depicted, clasp stability device 100 may include a plurality of clasp assemblies 700 removably attached to base plate assembly 200. Clasp assemblies 700 may be used to removably attach clasp stability device 100 to a hand truck (not shown). Base plate assembly 200 may include a base plate 205, a plurality of actuator travel positioner receivers 270 disposed on a top side of base plate 205, and a plurality of pedal mounting plates 255 disposed on a bottom side of base plate 205.

**[0074]** Continuing, FIG. 1C shows a left-side elevation view of clasp stability device 100 in accordance with one or more embodiments of the present invention. As shown in this view, pedal arm assembly 500 may be disposed below pedal latch assembly 600, to enable the use of the human operator's foot to engage pedal arm 505 from the rear of a hand truck (not shown). Continuing, FIG. 1D shows a right-side elevation view of the clasp stability device 100 in accordance with one or more embodiments of the present invention. Pedal arm 505 may include an actuating portion 510 that extends through a travel cutout (not shown) of base plate 205 and a cutout (not shown) of actuator plate 405, as described in more detail herein. When pedal arm 505 is engaged by pushing down on foot pedal 540, actuating portion 510 moves toward the rear of base plate 205, causing actuator assembly 400 to travel (not shown) towards the rear of base plate 205, and thereby causing clasp portions 305 of clasp arms 300 to close, as described in more detail herein. Upon release of foot pedal 540 of pedal arm 505, pedal arm 505 will be stably locked into place by pedal latch 605, securing the corresponding degree of closure of clasp arms 300. As shown in this view, an upper clasp arm 300 may be disposed above actuator plate 405 and a lower clasp arm 300 may be disposed below actuator plate 405, but above base plate 205. Continuing, FIG. 1E shows a front elevation view of clasp stability device 100 and FIG. 1F shows a rear elevation view of clasp stability device 100 in accordance with one or more embodiments of the present invention.

**[0075]** FIG. 2A shows a top plan view of a clasp stability device 100 in an opened state in accordance with one or more embodiments of the present invention. Base plate assembly 200 may include base plate 205 and a plurality of actuator travel positioner receivers 270 disposed on a top side of base plate 205. Each actuator travel positioner receiver 270 may include a travel cutout 280 aligned with a corresponding travel cutout 235 formed in base plate 205. Base plate 205 may include a travel cutout 245 for travel of actuating portion 510 of pedal arm 505 and

an arcuate travel cutout **240** for travel of lower clasp arm **300** (more specifically bolt **320** and nut **340** thereof).

[0076] Actuator assembly **400** may include actuator plate **405** and a plurality of actuator travel positioners (**435**, not shown in this view) attached to a bottom side of actuator plate **405** (via the bottom side of base plate **205**). Each actuator travel positioner (**435**, not shown in this view) may be attached to actuator plate **405** by one or more bolts **430** that extend through a top side of actuator plate **405** and the actuator travel positioner (**435**, not shown in this view) itself, that is secured on a bottom side of base plate **205** by a washer (**440**, not shown in this view) and one or more nuts (**445**, not shown in this view) that prevent each actuator travel positioner (**435**, not shown in this view) from coming out of its actuator travel positioner receiver **270**. The actuator travel positioners (**435**, not shown in this view) of actuator assembly **400** are capable of travel within actuator travel positioner receivers **270** of base plate assembly **200**, as described in more detail herein. Actuator plate **405** may also include a cutout (**425**, not shown in this view) to receive actuating portion **510** of the pedal arm (**505**, not shown in this view).

[0077] Each clasp arm assembly **300** may include a clasp portion **305**, a pivoting attachment portion (**310**, not shown in this view, corresponding to location of bolt **345** or **347**), a rotating attachment portion (**315**, not shown in this view, corresponding to location of bolt **320**), and various bolts and nuts. Pivoting attachment portion (**310**, not shown in this view) of upper clasp arm **300** may be removably attached to a front portion of base plate **205** by bolt **345**, but remain capable of pivoting. Similarly, pivoting attachment portion (**310**, not shown in this view) of lower clasp arm **300** may be removably attached to a front portion of base plate **205** by bolt **347**, but remain capable of pivoting. Rotating attachment portion (**315**, not shown in this view) of upper clasp arm **300** may be removably attached to a top side of actuator plate **405** by bolt **320** through an arcuate travel cutout (**420**, not shown in this view) formed in actuator plate **405**. The rotating attachment portion (**315**, not shown in this view) of lower clasp arm **300** may be removably attached to a bottom side of actuator plate **405** by bolt **320** that extends through the arcuate travel cutout **420** of actuator plate **405** and through the arcuate travel cutout **240** of base plate **205**. In the opened state depicted, a plurality of springs **285** may be used to bias actuator plate **405** toward the front of base plate **205** and, when locked into place, clasp arms **300** may remain in the open position, ready for engagement with material.

[0078] Arcuate travel cutout **240** of base plate **205** permits the compaction of base plate assembly **200**, clasp arms assembly **300**, and actuator assembly **400**, to reduce torsional forces and friction between moving parts. However, in certain embodiments, specifically those with lighter loads, actuator assembly **400** could be raised off base plate assembly **205** such that no cutout **240** would be required in base plate **205**.

[0079] Continuing, FIG. 2B shows a bottom plan view of clasp stability device **100** in the opened state in accordance with one or more embodiments of the present invention. As shown in this view, a plurality of washers **440** and nuts **445** may be used to secure actuator travel positioners (**435**, not shown in this view) to a bottom side of the actuator plate (**405**, not shown in this view), from a bottom side of travel cutout **235** formed in base plate **205**, maintaining the

actuator travel positioners (**435**, not shown in this view) of actuator assembly **400** within the actuator travel positioner receivers (**270**, not shown in this view) of base plate **205**, while the actuator travel positioners (**435**, not shown in this view) remain capable of travel between the front and rear of base plate **205**. In the view depicted, nut **340** secures bolt **320** of lower clasp arm **300** to actuator plate **405**, positioned such that it may travel in both the arcuate travel cutout (**420**, not shown in this view) of actuator plate **405** and the arcuate travel cutout **240** formed in base plate **205**. In this way, arcuate travel cutout **240** of base plate **205** permits travel of bolt **320** and nut **340** of lower clasp arm **300** while the clasp mechanism or release mechanism is engaged. Also shown in this view, the plurality of pedal mounting plates **255** attached to the bottom side of base plate **205**.

[0080] Continuing, FIG. 2C shows a top plan view of clasp stability device **100** in a closed state in accordance with one or more embodiments of the present invention. When a human operator wishes to engage the clasp mechanism to close on material (not shown), the operator may depress foot pad **540** of the pedal arm (**505**, not shown in this view), where the extent to which it is depressed corresponds to the extent to which the clasp arms **300** close. The depression of foot pad **540** causes the pedal arm (**505**, not shown in this view) to pivot, such that actuating portion **510** of the pedal arm (**505**, not shown in this view) travels toward the rear of base plate **205**. The travel of actuating portion **510**, disposed within the cutout (**425**, not shown in this view) of actuator plate **405**, causes actuator assembly **400** to move toward the rear of base plate **205**. As actuator assembly **400** travels toward the rear, the rotating portions of clasp arms **300** rotate in their respective arcuate travel cutout **420** formed in actuator plate **405**. As the rotating attachment portions of clasp arms **300** rotate, the pivoting attachment portions of clasp arms **300** pivot, such that clasp portions **305** of clasp arms **300** begin to close. While not shown in this view, when the human operator releases foot pedal **540**, pedal latch **605** automatically latches onto pedal arm **505**, locking clasp arms **300** in their present degree of closure. In this way, clasp stability device **100** may provide stable clasp with any desired amount of closure from fully open to fully closed, thereby accommodating a large variety of materials.

[0081] In certain embodiments, clasp stability device **100** may be removably attached to existing hand trucks (not shown). A plurality of clamping assemblies **700** may be used to removably attach clasp stability device **100** to longitudinal support members (not shown) of the hand truck (not shown) that are typically tubular in shape. To accommodate variation in the space between longitudinal support members (not shown) of hand trucks (not shown), each clamping assembly **700** may include a rear mounting hole **720** to securely attach clamping assembly **700** to base plate **205** and an arcuate adjustment mounting hole **725** that permits the positioning of each clamping assembly **700** to fit a particular hand truck (not shown). In other embodiments, clasp stability device **100** may be attached to a hand truck (not shown) during the original equipment manufacturer (“OEM”) build of the hand truck (not shown).

[0082] Continuing, FIG. 2D shows a bottom plan view of clasp stability device **100** in the closed state in accordance with one or more embodiments of the present invention. The travel of actuator assembly **400** toward the rear of

base plate 205, is shown by the travel of washers 440 and nuts 445 of the actuator travel positioners (435, not shown in this view) that have now moved toward the rear of base plate 205 in travel cutout 280 of actuator plate 405 and corresponding travel cutout 235 of base plate 205. In addition, the travel of nut 340 of lower clasp arm 300 within the arcuate travel cutout 240 of base plate 205 is shown.

[0083] Continuing, FIG. 2E shows a rear facing top-side perspective view of clasp stability device 100 in the opened state in accordance with one or more embodiments of the present invention. A portion of pedal arm assembly 500 and pedal latch assembly 600 may be disposed in between a pair of pedal mounting plates 255 disposed on a bottom side of base plate 205. For purposes of illustration only, the right-side pedal mounting plate 255 is drawn transparent to more clearly show the interaction of pedal arm assembly 500 and pedal latch assembly 600. Pedal arm assembly 500 may include a pedal arm 505 having an engagement portion 520, a pivoting attachment portion (535, not shown in this view, corresponding to location of bolt 555), an index latch track 530, actuating portion 510, and various nuts and bolts. Pedal latch assembly 600 may include a pedal latch 605 having a release portion (610, not shown in this view), a pivoting attachment portion (615, not shown in this view, corresponding to location of bolt 640), an index latch 620, and various nuts and bolts. In the opened state, actuating portion 510 of pedal arm 505 as well as actuator assembly 400 are positioned towards the front of base plate 205, nearest clasp portions 305. Index latch track 530 of pedal arm 505 may include an arcuate track of stairs disposed about the pivot point of pedal arm 505. Index latch 620 of pedal latch 605 may have a complimentary shape to that of index latch track 530, such that index latch 620 may engage each stair of index latch track 530 and securely maintain the position of pedal arm 505.

[0084] Continuing, FIG. 2F shows a rear facing top-side perspective view of clasp stability device 100 in the closed state in accordance with one or more embodiments of the present invention. When a human operator wishes to engage the clasp mechanism of clasp stability device 100, the operator may depress foot pedal 540 of pedal arm 505, causing pedal arm 505 to pivot about its pivoting attachment point (535, not shown in this view, corresponding to location of bolt 555) such that actuating portion 510 of pedal arm 505 and actuator assembly 400 that it is disposed through, to travel toward the rear of base plate 205, thereby causing clasp arms 300 to close in a corresponding amount. As foot pedal 540 is being depressed, index latch 620 travels through successive stairs of index latch track 530, until such time as the operator disengages foot pedal 540. At that point, index latch 620 securely maintains its position in index latch track 530, maintaining the degree of closure of clasp arms 300. Index latch 620 may have a complimentary shape to that of index latch track 530, such that when index latch 620 engages index latch track 530, index latch 620 is capable of maintaining the current position of clasp arms 300. Showing a different angle, FIG. 2G shows a rear facing bottom-side perspective view of clasp stability device 100 in the opened state and FIG. 2H shows a rear facing bottom-side perspective view of clasp stability device 100 in the closed state in accordance with one or more embodiments of the present invention.

[0085] FIG. 3A shows a front facing top-side perspective view of a clasp stabilized hand truck 800 in accordance with one or more embodiments of the present invention. Clasp stabilized hand truck 800 may include one or more handles 805, a plurality of longitudinal support members 810, that are typically tubular in shape, a plurality of transverse support members 812, a nose plate 815, and a plurality of wheels 820. The plurality of longitudinal support members 810 and transverse support members 812 form the wheeled frame of hand truck 800. A pair of clamping assemblies 700 may be used to secure clasp stability device 100 to a pair of longitudinal support members 810 of hand truck 800, at a desired height along the length of longitudinal support members 810. In this way, clasp stability device 100 may be disposed at a suitable height to accommodate the size or shape of the material (not shown) intended to be transported. Continuing, FIG. 3B shows a rear facing top-side perspective view of clasp stabilized hand truck 800 in accordance with one or more embodiments of the present invention. Because clasp stability device 100 includes controls disposed exclusively at the rear of device 100, a human operator (not shown) may fully operate hand truck 800 from the rear, without having to walk around to the front, or use straps (not shown), or ties (not shown). Continuing, FIG. 3C shows a top plan view of clasp stabilized hand truck 800 in an opened state and FIG. 3D shows a top plan view of clasp stabilized hand truck 800 in a closed state in accordance with one or more embodiments of the present invention.

[0086] FIG. 4A shows a front facing top-side perspective view of a clasp stabilized hand truck 800 in an opened state showing an environment of use in accordance with one or more embodiments of the present invention. Hand trucks are commonly used to transport tanks and containers that have a substantially cylindrical shape. These tanks and containers may vary in size, shape, and weight, and often present stability and safety problems for transport. In one or more embodiments of the present invention, a clasp stabilized hand truck 800 may safely transport tanks and containers in a safe and secure manner that protects the safety of the operator as well as the environment. In operative use, the operator may wheel hand truck 800 into position (not shown) in front of a large container 850, with one or more hands on the one or more handles 805. Hand truck 800 may be positioned in front of container 850 and then, using a foot, the operator may wedge the nose plate 815 under container 850, while pushing hand truck 800 forward. Continuing, FIG. 4B shows a front facing top-side perspective view of clasp stabilized hand truck 800 in a closed state showing an environment of use in accordance with one or more embodiments of the present invention. Once container 850 is well positioned with respect to nose plate 815, the operator may use a foot to engage foot pedal 540 to close the clasp portion 305 of clasp arms 300 around container 850. Once sufficient closure is achieved, the operator may remove the foot from foot pedal 540, and pedal latch 605 may automatically latch pedal arm 505 into place, securing the degree of closure of clasp arms 300 and providing stable support for container 850. Container 350 is now substantially supported such that it may be stably and securely transported from source to destination. Advantageously, the operator may perform all of these operations

from the rear of hand truck **800**, without having to walk to the front of hand truck **800**, and without the use of straps (not shown) or ties (not shown).

[0087] FIG. 5A shows a top plan view of a base plate assembly **200** of a clasp stability device **100** in accordance with one or more embodiments of the present invention. Base plate assembly **200** includes base plate **205**, a plurality of actuator travel positioner receivers **270** disposed on a top side of base plate **205**, and a plurality of pedal mounting plates (**255**, not shown in this view) disposed on a bottom side of base plate **205**. Base plate **205** may also include a flared portion **210** to support clamping assemblies (**700**, not shown in this view). Base plate **205** may include, for each clamping assembly (e.g., **700**) a rear mounting hole **215** and an adjustment mounting hole **220**. Base plate **205** may also include a plurality of spring mounting posts **225**, and a plurality of pivoting attachment holes **230** for attachment of the clasp arms (e.g., **300**). The plurality of actuator travel positioner receivers **270** may include a travel cutout **280** that extends through to a corresponding travel cutout **235** formed in base plate **205**. Base plate **205** may include an arcuate travel cutout **240** for a lower clasp arm (e.g., **300**) and a travel cutout for the actuating portion (e.g., **510**) of the pedal arm (e.g., **500**). Continuing, FIG. 5B shows a bottom plan view of the base plate assembly **200** of the clasp stability device **100** in accordance with one or more embodiments of the present invention. Base plate **205** includes a plurality of pedal mounting plates **255** disposed on the bottom-side of base plate **205**. In certain embodiments, base plate **205** may be composed of stainless steel. In other embodiments, base plate **205** may be composed of carbon steel. In still other embodiments, base plate **205** may be composed of aluminum. In still other embodiments, base plate **205** may be composed of any other metal or alloy. In still other embodiments, base plate **205** may be composed of plastic, composites, or any other lightweight material. One of ordinary skill in the art will recognize that the composition of material used to form base plate **205** may vary in accordance with one or more embodiments of the present invention.

[0088] FIG. 5C shows a top plan view of a clasp arm **300** of a clasp stability device **100** in accordance with one or more embodiments of the present invention. Clasp arm assembly **300** includes a clasp portion **305**, a pivoting attachment portion **310**, a rotating attachment portion **315**, an optional rotating attachment portion **317**. Each of pivoting attachment portion **310**, rotating attachment portion **315**, and optional rotating attachment portion **317** may comprise a corresponding mounting hole for assembly. Clasp arm assembly **300** may also include bolts, washers, and nuts required for assembly that are not shown in this view. In certain embodiments, clasp arm **300** may be composed of stainless steel. In other embodiments, clasp arm **300** may be composed of carbon steel. In still other embodiments, clasp arm **300** may be composed of aluminum. In still other embodiments, clasp arm **300** may be composed of any other metal or alloy. In still other embodiments, clasp arm **300** may be composed of plastic, composites, or any other lightweight material. One of ordinary skill in the art will recognize that the composition of material used to form clasp arm **300** may vary in accordance with one or more embodiments of the present invention.

[0089] FIG. 5D shows a top plan view of an actuator plate **405** of the clasp stability device **100** in accordance with

one or more embodiments of the present invention. Actuator plate **405** may include a plurality of mounting holes **410** for one or more actuator travel positioners (**435**, not shown), a plurality of mounting holes **415** for attachment of a bias spring (**285**, not shown), a plurality of arcuate travel cutouts **420** for travel of the clasp arms (**300**, not shown), and a cutout **425** for the actuating portion (**510**, not shown) of the pedal arm (**500**, not shown). In certain embodiments, actuator plate **405** may be composed of stainless steel. In other embodiments, actuator plate **405** may be composed of carbon steel. In still other embodiments, actuator plate **405** may be composed of aluminum. In still other embodiments, actuator plate **405** may be composed of any other metal or alloy. In still other embodiments, actuator plate **405** may be composed of plastic, composites, or any other lightweight material. One of ordinary skill in the art will recognize that the composition of material used to form actuator plate **405** may vary in accordance with one or more embodiments of the present invention.

[0090] Continuing, FIG. 5E shows a right-side elevation view of a pedal arm **505** of the clasp stability device **100** in accordance with one or more embodiments of the present invention. Pedal arm **505** may include an engagement portion **520**, a pivot attachment portion **535** corresponding to a mounting hole, an index latch track **530**, and an actuating portion **510**. Index latch track **530** may include a plurality of stairs disposed in an arcuate pattern about the pivot point of pivoting attachment portion **535**. A foot pedal (**540**, not shown) may be removably attached to mounting hole **525** of pedal arm **505**, for operator use. In certain embodiments, pedal arm **505** may be composed of stainless steel. In other embodiments, pedal arm **505** may be composed of carbon steel. In still other embodiments, pedal arm **505** may be composed of aluminum. In still other embodiments, pedal arm **505** may be composed of any other metal or alloy. In still other embodiments, pedal arm **505** may be composed of plastic, composites, or any other lightweight material. One of ordinary skill in the art will recognize that the composition of material used to form a pedal arm **505** may vary in accordance with one or more embodiments of the present invention.

[0091] FIG. 5F shows a right-side elevation view of a pedal latch **605** of the clasp stability device **100** in accordance with one or more embodiments of the present invention. Pedal latch **605** may include a release portion **610**, a pivot attachment portion **615** corresponding to a mounting hole, and an index latch **620**. Index latch **620** may have a complimentary shape to that of the index latch track (**530**, not shown) of the pedal arm (**505**, not shown). In certain embodiments, pedal latch **605** may be composed of stainless steel. In other embodiments, pedal latch **605** may be composed of carbon steel. In still other embodiments, pedal latch **605** may be composed of aluminum. In still other embodiments, pedal latch **605** may be composed of any other metal or alloy. In still other embodiments, pedal latch **605** may be composed of plastic, composites, or any other lightweight material. One of ordinary skill in the art will recognize that the composition of material used to form a pedal latch **605** may vary in accordance with one or more embodiments of the present invention.

[0092] One of ordinary skill in the art will recognize that one or more of the components of clasp stability device **100** may be scaled to create a clasp stability device suitable for any specific application in accordance with one

or more embodiments of the present invention. In addition, one of ordinary skill in the art will recognize that one or more components of clasp stability device 100 may be composed of alternative materials to achieve one or more goals of a specific application in accordance with one or more embodiments of the present invention. For example, certain components that come into contact with material may be composed of aluminum so as to minimize the risk of sparking when handling chemical, flammable, or hazardous materials.

[0093] FIG. 6A shows assembly of a portion of a clasp stability device 100 in accordance with one or more embodiments of the present invention. A foot pedal 625 may be attached to release portion 610 of pedal latch 605 by a bolt 630 that extends through a mounting hole of foot pedal 625 and mounting hole 610 of pedal latch 605 and secured in place by nut 635. Pedal latch 605 may be disposed in between pedal mounting plates 255 of base plate 205. Pivoting attachment portion 615 may be aligned with mounting holes 260 of pedal mounting plates 255. A plurality of spacers 640 may be disposed on both sides of pivoting attachment portion 615 of pedal latch 605, within pedal mounting plates 255. A bolt 640 may be disposed through mounting hole 260 of pedal mounting plate 255, spacer 645, pivoting attachment portion 615 of pedal latch 605, spacer 645, mounting hole 260 of pedal mounting plate 255, and secured in place by nut 655. Similarly, a foot pedal 540 may be attached to engagement portion 520 of pedal arm 505 by a bolt 545 that extends through a mounting hole of pedal 540 and mounting hole 525 of pedal arm 505 and secured in place by nut 550. Pedal arm 505 may be disposed in between pedal mounting plates 255 of base plate 205, under pedal latch 605. Actuating portion 510 may be disposed through cutout 245 of base plate 205 and pivoting attachment portion 535 may be aligned with mounting holes 265 of pedal mounting plates 255. A plurality of spacers 560 may be disposed on both sides of pivoting attachment portion 535 of pedal arm 505. A bolt 555 may be disposed through washer 557, mounting hole 265 of mounting plate 255, spacer 560, pivoting attachment portion 535 of pedal arm 505, spacer 560, mounting hole 265 of mounting plate 255, washer 557, and secured in place by nut 565.

[0094] Continuing, FIG. 6B shows assembly of a portion of the clasp stability device 100 in accordance with one or more embodiments of the present invention. Rotating attachment portion 315 of upper clasp arm 305 may be attached to a top side of actuator plate 405. Bolt 320 may be disposed through washer 325, rotating attachment portion 315 of clasp arm 305, arcuate travel cutout 420 of actuator plate 405, spacer 330, washer 325, and secured by nut 340. Pivoting attachment portion 310 of upper clasp arm 305 may be attached to a top side of base plate 205. Bolt 345 may be disposed through washer 350, pivoting attachment portion 310, spacer 355, mounting hole 230 of base plate 205, washer 350, and secured in place by nut 360. Similarly, rotating attachment portion 315 of lower clasp arm 305 may be attached to a bottom side of actuator plate 405. Bolt 320 may be disposed through washer 325, arcuate travel cutout 420 of actuator plate 405, spacer 330, rotating attachment portion 315 of clasp arm 305, arcuate travel cutout 240 of base plate 205, washer 325 and secured in place by nut 340. Pivoting attachment portion 310 of lower clasp arm 305 may be attached to a top side of base plate 205. Bolt 347 may be disposed through washer 350, pivoting

attachment portion 310 of clasp arm 300, washer 350, mounting hole 230 of base plate 205, washer 350, and secured in place by nut 360. For each actuator travel positioner 435, a plurality of bolts 430 may be disposed through mounting holes 410 of actuator plate 405 and through actuator travel positioner 435 itself. Actuator travel positioner 435 may be placed within travel cutout 280 of actuator travel positioner receiver 270 of base plate 205, and a washer 440 may be disposed under the corresponding travel cutout 235 of base plate 205, and bolts 430 may be secured in place with nuts 445. Washer 440 may have a size that prevents it from fitting into travel cutouts 235 of base plate 205 or travel cutout 280 of actuator travel positioner receiver 270. A first end of a bias spring 285 may be removably attached to spring mounting hole 415 of actuator plate 405 and a second end of bias spring 285 may be removably attached to spring mounting post 225 of base plate 205.

[0095] Continuing, FIG. 6C shows assembly of a portion of the clasp stability device 100 in accordance with one or more embodiments of the present invention. A plurality of clamping assemblies 700 may be used to secure a clasp stability device 100 to a hand truck (not shown). Each clamping assembly 700 may include a rear portion 705 that is removably attached to a front portion 735 around a tubular such as a longitudinal support member 810 of a hand truck (not shown). A plurality of bolts 745 may be disposed through washer 750, mounting hole 730 of rear portion 705, mounting hole 730 of front portion 735, washer 750, and secured in place by a plurality of nuts 755. Each clamping assembly 700 may be removably attached to the base plate (205, not shown) by a bolt, washer, and nut (not shown) through rear mounting hole 720. Adjustment mounting hole 725 may be used to adjust the positioning of clamping assembly 700 to fit a particular hand truck (not shown). The arcuate shape of adjustment mounting hole 725 allows the clamping assembly 700 to pivot on the rear mounting hole 720 and adjust the spacing between clamping assemblies 700.

[0096] In one or more embodiments of the present invention, a clasp stability device may be directly mounted onto a transverse supporting member of a hand truck. In such embodiments, the base plate of the clasp stability device is directly mounted to the transverse supporting member and there is no need for clamping assemblies.

[0097] FIG. 7A shows a front facing top-side perspective view of a clasp stability device 900 in accordance with one or more embodiments of the present invention. Clasp stability device 900 includes a plurality of direct mounting holes (1010, not shown) disposed on a front portion of base plate 205 for directly mounting clasp stability device 900 to a transverse support member (not shown) of a hand truck (not shown). Clasp stability device 900 may be substantially the same as clasp stability device 100 previously disclosed, with the only substantive difference being the use of direct mounting through the base plate 205 rather than using clamping assemblies (e.g., 700 of clasp stability device 100). Continuing, FIG. 7B shows a rear facing top-side perspective view of clasp stability device 900 and in accordance with one or more embodiments of the present invention. Continuing, FIG. 7C shows a top plan view of clasp stability device 900 in an opened state in accordance with one or more embodiments of the present invention. In this view, a plurality of mounting bolts 1015



that may be used to directly mount claspings stability device 900 to a transverse support member (not shown) of a hand truck (not shown) are shown instead of clamping assemblies (e.g., 700 of claspings stability device 100). Continuing, FIG. 7D shows a bottom plan view of claspings stability device 900 in the disengaged state in accordance with one or more embodiments of the present invention. In this view, a plurality of nuts 1020 for mounting bolts 1015, typically disposed under a transverse support member (not shown) of a hand truck (not shown) are shown for purposes of illustration only.

[0098] FIG. 8A shows a front facing top-side perspective view of a claspings stabilized hand truck 1100 in an opened state in accordance with one or more embodiments of the present invention. Claspings stabilized hand truck 1100 may include a handle 1105, a plurality of longitudinal support members 1110, a plurality of transverse support members 1112, a nose plate 1115, and a plurality of wheels 1120. A claspings stability device 900 may be removably attached to hand truck 1100 by a plurality of bolts that directly attach claspings stability device 900 to a transverse support member 1112. Continuing, FIG. 8B shows a front facing top-side perspective view of claspings stabilized hand truck 1100 in a closed state in accordance with one or more embodiments of the present invention. Continuing, FIG. 8C shows a detail view of the direct attachment of claspings stability device 900 to hand truck 1100 in accordance with one or more embodiments of the present invention. A bolt 1015 may be disposed through a washer 1017, a mounting hole 1010 of base plate 205, a mounting hole (not shown) drilled in transverse support member 1112, a washer 1017, and secured in place with nut 1020.

[0099] FIG. 9A shows a top plan view of a base plate assembly 1000 of a claspings stability device 900 in accordance with one or more embodiments of the present invention. Base plate 1105 of claspings stability device 900 is substantially the same as base plate 205 of claspings stability device 100 with the only substantive difference being the removal of the clamping assemblies (700 of claspings stability device 100) and the addition of direct mounting holes 1010 that are used to removably attach claspings stability device 900 to a transverse support member (not shown) of a hand truck (not shown). Continuing, FIG. 9B shows a bottom plan view of the base plate 1000 of claspings stability device 900 in accordance with one or more embodiments of the present invention.

[0100] In one or more embodiments of the present invention, a claspings stability device may use alternative claspings or release mechanisms that may be suitable for different applications or designs.

[0101] FIG. 10A shows a front facing top-side perspective view of a claspings stability device 1300 in accordance with one or more embodiments of the present invention. Claspings stability device 1300 may include a secure claspings mechanism that may be used to stabilize material on a hand truck (not shown). Claspings stability device 1300 may include a base plate assembly 1200 and a pair of claspings arm assemblies 300 removably attached to base plate assembly 1200. Continuing, FIG. 10B shows a rear facing top-side perspective view of claspings stability device 1300 in accordance with one or more embodiments of the present invention. Claspings stability device 1300 may also include a plurality of actuator plates 1405 that facilitates the claspings and release mechanism of claspings arm assemblies 300, a pedal

arm assembly 500 that may controllably engage the claspings mechanism of claspings arms 300, and a pedal latch assembly 600 that may lock or release the claspings mechanism of claspings arm assemblies 300. In the embodiment depicted, claspings stability device 1300 may be directly mounted via a plurality of mounting holes 1210 in base plate 1205 to a hand truck (not shown). Base plate assembly 1200 may include a base plate 1205 and a plurality of pedal mounting plates 255 disposed on a bottom side of base plate 1205.

[0102] Continuing, FIG. 10C shows a left-side elevation view of claspings stability device 1300 in accordance with one or more embodiments of the present invention. As shown in this view, pedal arm assembly 500 may be disposed below pedal latch assembly 600, to enable the use of the human operator's foot to engage pedal arm 505 from the rear of a hand truck (not shown). Continuing, FIG. 10D shows a right-side elevation view of claspings stability device 1300 in accordance with one or more embodiments of the present invention. Pedal arm 505 may include an actuating portion 510 that extends through base plate 205 and actuator plates 1405, as discussed in more detail herein. When pedal arm 505 is engaged by pushing down on foot pedal 540, actuating portion 510 moves toward the rear of base plate 1205, causing the attached ends of actuator plates 1405 to travel towards the rear of base plate 1205, and thereby causing claspings portion 305 of claspings arms 300 to close, as discussed in more detail herein. Upon release of foot pedal 540 of pedal arm 505, pedal arm 505 will be stably locked into place by pedal latch 605, securing the corresponding degree of closure of claspings arms 300. As shown in this view, an upper claspings arm 300 may be disposed above a lower claspings arm 300. Continuing, FIG. 10E shows a front elevation view of claspings stability device 1300 in accordance with one or more embodiments of the present invention. Continuing, FIG. 10F shows a rear elevation view of claspings stability device 1300 in accordance with one or more embodiments of the present invention.

[0103] FIG. 11A shows a top plan view of a claspings stability device 1300 in an opened state in accordance with one or more embodiments of the present invention. Base plate assembly 1200 may include base plate 1205, an arcuate travel cutout 1237 for a lower claspings arm 300, and a travel cutout 1240 for an actuating portion 510 of a pedal arm 505. A pivoting attachment portion 310 of an upper claspings arm 300 may be aligned with a pivoting attachment portion 310 of a lower claspings arm 300 and secured to base plate 1205 with a bolt 1230. A rotating attachment portion (317, not shown in this view) of upper claspings arm 300 may be attached to a first end 1410 of a first actuating plate 1405. A rotating attachment portion (317, not shown in this view) of lower claspings arm 300 may be attached to a first end 1410 of second actuating plate 1405. A top side of a second end 1410 of first actuating plate 1405 may be aligned and attached to a bottom side of a second end 1410 of second actuating plate 1405 by a bolt 1415, with a slip attachment 1430 disposed in between first actuating plate 1405 and second actuating plate 1405. Slip attachment 1430 may include a cutout for actuating portion 510.

[0104] Continuing, FIG. 11B shows a bottom plan view of claspings stability device 1300 in the opened state in accordance with one or more embodiments of the present invention. Base plate 1205 may include a plurality of pedal mounting plates 255 attached to the bottom side of base plate 1205. Continuing, FIG. 11C shows a top plan view of

clasp stability device **1300** in a closed state in accordance with one or more embodiments of the present invention. When a human operator wishes to engage the clasp mechanism to close on material (not shown), the operator may depress foot pad **540** of the pedal arm (**505**, not shown in this view), the extent to which it is depressed corresponding to the extent to which the clasp arms **300** close. The depression of foot pad **540** causes the pedal arm (**505**, not shown in this view) to pivot, such that actuating portion **510** of the pedal arm (**505**, not shown in this view) travels toward the rear of base plate **1205**. The travel of actuating portion **510** causes the attached ends (by bolt **1415**) of actuator plates **1405** to travel towards the rear of base plate **1205**. As the rotating attachment portions of clasp arms **300** rotate, the pivoting attachment portions of clasp arms **300** pivot, such that clasp portions **305** of clasp arms **300** begin to close. While not shown in this view, when the human operator releases foot pedal **540**, pedal latch **605** latches onto pedal arm **505**, locking clasp arms **300** in their present degree of closure. In this way, clasp stability device **1300** may provide stable clasp with any desired amount of closure from fully open to fully closed, thereby accommodating a large variety of materials. In certain embodiments, clasp stability device **1300** may be removably attached to existing hand trucks (not shown). A plurality of bolts **1215** may be used to removably attach clasp stability device **1300** to a transverse support member (not shown) of the hand truck (not shown). Continuing, FIG. **11D** shows a bottom plan view of clasp stability device **1300** in the closed state in accordance with one or more embodiments of the present invention.

[**10105**] Continuing, FIG. **11E** shows a rear facing top-side perspective view of clasp stability device **1300** in the opened state in accordance with one or more embodiments of the present invention. A portion of pedal arm assembly **500** and pedal latch assembly **600** may be disposed in between a pair of pedal mounting plates **255** disposed on a bottom side of base plate **1205**. For purposes of illustration only, the right-side pedal mounting plate **255** is transparent to more clearly show the interaction of pedal arm assembly **500** and pedal latch assembly **600**. Pedal arm assembly **500** may include a pedal arm **505** having an engagement portion **520**, a pivoting attachment portion (**535**, not shown in this view), an index latch track **530**, and actuating portion **510**. Pedal latch assembly **600** may include a pedal latch **605** having a release portion (**610**, not shown in this view), a pivoting attachment portion (**615**, not shown in this view), and an index latch **620**. In the opened state, actuating portion **510** of pedal arm **505** may be positioned towards the front of base plate **1205**. Index latch track **530** of pedal arm **505** may include an arcuate track of stairs disposed about the pivot point of pedal arm **505**. Index latch **620** of pedal latch **605** may have a complimentary shape to that of index latch track **530**, such that index latch **620** may engage each stair of index latch track **530** and securely maintain the position of pedal arm **505**.

[**10106**] Continuing, FIG. **11F** shows a rear facing top-side perspective view of clasp stability device **1300** in the closed state in accordance with one or more embodiments of the present invention. When a human operator wishes to engage the clasp mechanism of clasp stability device **1300**, the operator may depress foot pedal **540** of pedal arm **505**, causing pedal arm **505** to pivot about its pivoting attachment point (**535**, not shown in this view) such that

actuating portion **510** of pedal arm **505** to travel toward the rear of base plate **1205**, thereby causing clasp arms **300** to close in a corresponding amount. As foot pedal **540** is being depressed, index latch **620** travels through successive stairs of index latch track **530**, against the force of bias springs **285**, until such time as the operator disengages foot pedal **540**. At that point, index latch **620** securely maintains its position in index latch track **530**, maintaining the degree of closure against the force of bias springs **285**. Index latch **620** may have a complimentary shape to that of index latch track **530**, such that when index latch **620** engages index latch track **530**, index latch **620** is capable of maintaining the current position of clasp arms **300**. Showing a different angle, FIG. **11G** shows a rear facing bottom-side perspective view of clasp stability device **1300** in the opened state and FIG. **11H** shows a rear facing bottom-side perspective view of clasp stability device **1300** in the closed state in accordance with one or more embodiments of the present invention.

[**10107**] FIG. **12A** shows a front facing top-side perspective view of a clasp stabilized hand truck **1500** in accordance with one or more embodiments of the present invention. Clasp stabilized hand truck **1500** may include a hand truck **1100** having one or more handles **1105**, a plurality of longitudinal support members **1110** that are typically rectangular in shape, a plurality of transverse support members **1112**, a nose plate **1115**, and a plurality of wheels **1120**. The plurality of longitudinal support members **1110** and transverse support members **1112** form the wheeled frame of hand truck **1500**. Clasp stability device **1300** may be directly attached to a transverse support member **1112**. Continuing, FIG. **12B** shows a rear facing top-side perspective view of clasp stabilized hand truck **1500** in accordance with one or more embodiments of the present invention. Because the clasp stability device **1300** includes controls disposed at the rear of the device **1300**, a human operator (not shown) may fully operate hand truck **1500** from the rear, without having to walk around to the front or use straps (not shown) or ties (not shown). Continuing, FIG. **12C** shows a top plan view of clasp stabilized hand truck **1500** in an opened state and FIG. **12D** shows a top plan view of clasp stabilized hand truck **1500** in a closed state in accordance with one or more embodiments of the present invention.

[**10108**] FIG. **13A** shows a front facing top-side perspective view of a clasp stabilized hand truck **1500** in an opened state showing an environment of use in accordance with one or more embodiments of the present invention. Hand trucks are commonly used to transport tanks and containers that have a substantially cylindrical shape. These tanks and containers vary in size, shape, and weight, and often present problems for transport. In one or more embodiments of the present invention, a clasp stabilized hand truck **1500** may safely transport tanks and containers in a safe manner that protects the safety of the operator as well as the environment. In operative use, the operator may wheel hand truck **1500** into position in front of material, such as, for example, a large container **850**, with one or more hands on the one or more handles **1105**. Hand truck **1500** may be positioned in front of container **850** and then, using a foot, the operator may wedge the nose plate **1115** under container **850** while pushing hand truck **1500** forward. Continuing, FIG. **13B** shows a front facing top-side perspective view of clasp stabilized hand truck **1500** in a closed state showing an

environment of use in accordance with one or more embodiments of the present invention. Once container 850 is well positioned with respect to nose plate 1115, the operator may use a foot to engage foot pedal 540 to close clasp arms 300 around container 850. Once sufficient closure is achieved, the operator may remove the foot from the foot pedal 540, and pedal latch 605 may latch pedal arm 505 into place, securing the degree of closure of clasp arms 300, providing stable support for container 850. Advantageously, the operator is able to perform all of these operations from the rear of hand truck 1500, without having to walk to the front of hand truck 800, and without the use of straps (not shown) or ties (not shown).

[0109] FIG. 14A shows a top plan view of a base plate 1200 of a clasp stability device 1300 in accordance with one or more embodiments of the present invention. Base plate assembly 1200 includes base plate 1205 and a plurality of pedal mounting plates 255 disposed on a bottom side of base plate 1205. Base plate 205 may include a travel cutout for the actuating portion (e.g., 510) of the pedal arm (e.g., 500). Continuing, FIG. 14B shows a bottom plan view of base plate 1200 of clasp stability device 1300 in accordance with one or more embodiments of the present invention. Base plate 1205 includes a plurality of pedal mounting plates 255 disposed on the bottom-side of base plate 1205. In certain embodiments, base plate 1205 may be composed of stainless steel. In other embodiments, base plate 1205 may be composed of carbon steel. In still other embodiments, base plate 1205 may be composed of aluminum. In still other embodiments, base plate 1205 may be composed of any other metal or alloy. In still other embodiments, base plate 1205 may be composed of plastic, composites, or any other lightweight material. One of ordinary skill in the art will recognize that the composition of material used to form base plate 1205 may vary in accordance with one or more embodiments of the present invention.

[0110] Continuing, FIG. 14C shows a top plan view of an actuator plate 1405 of clasp stability device 1300 in accordance with one or more embodiments of the present invention. Actuator plate 1405 includes a first attachment end 1410 and a second attachment end 1410. In certain embodiments, actuator plate 1405 may be composed of stainless steel. In other embodiments, actuator plate 1405 may be composed of carbon steel. In still other embodiments, actuator plate 1405 may be composed of aluminum. In still other embodiments, actuator plate 1405 may be composed of any other metal or alloy. In still other embodiments, actuator plate 1405 may be composed of plastic, composites, or any other lightweight material. One of ordinary skill in the art will recognize that the composition of material used to form actuator plate 1405 may vary in accordance with one or more embodiments of the present invention.

[0111] FIG. 15 shows assembly of a clasp stability device 1300 in accordance with one or more embodiments of the present invention. A bolt 1230 may be disposed through a washer 1320, pivoting attachment portion 310 of an upper clasp arm 300, washer 1320, pivoting attachment portion 310 of a lower clasp arm 300, washer 1320, mounting hole 1225 of base plate 1205, and secured in place by nut 1235. A bolt 1315 may be disposed through a washer 1320, first end 1410 of first actuating plate 1405, washer 1320, rotating attachment portion 317, washer 1320, and secured by nut 1325. A bolt 1315 may be disposed through

a washer 1320, rotating attachment portion 317 of lower clasp arm 300, washer 1320, first end 1410 of second actuator plate 1405, washer 1320, and secured by nut 1325. A second end 1410 of first actuator plate 1405 may be attached to a second end 1410 of second actuator plate 1405. A bolt 1315 may be disposed through a washer 1320, second end 1410 of second actuator plate 1405, slip attachment 1430, second end 1410 of first actuator plate 1405, washer 1320, and secured by nut 1325.

[0112] Advantages of one or more embodiments of the present invention may include one or more of the following:

[0113] In one or more embodiments of the present invention, a clasp stability device provides a stable material handling platform safely operable by a single human operator. The human operator may load and secure the material to the hand truck entirely from the rear without the use of straps or ties.

[0114] In one or more embodiments of the present invention, a clasp stability device eases loading material onto a hand truck at the source location, stabilizes the material during transport, and eases unloading the material from the hand truck at the destination location.

[0115] In one or more embodiments of the present invention, a clasp stability device includes a clasp mechanism that assists in pulling material toward the rear of the nose plate of the hand truck, and onto the nose plate, while the clasp mechanism is closing.

[0116] In one or more embodiments of the present invention, a clasp stability device includes a clasp mechanism that locks into place once the clasp arms are closed to a sufficient degree to secure the material. The locking mechanism is automatically engaged upon release of the engagement portion of the pedal arm. The locking mechanism remains locked stabilizing the material on the hand truck until the release portion of the pedal latch is engaged.

[0117] In one or more embodiments of the present invention, a clasp stability device includes a clasp mechanism that assists in releasing material toward the front of the nose plate while the clasp mechanism is opening.

[0118] In one or more embodiments of the present invention, a clasp stability device provides a single stroke clasp mechanism that automatically locks.

[0119] In one or more embodiments of the present invention, a clasp stability device provides a single stroke release mechanism.

[0120] In one or more embodiments of the present invention, a clasp stability device improves the safety of a hand truck operated by a single human operator.

[0121] In one or more embodiments of the present invention, a clasp stability device does not require an external power source and does not require substantial strength on the part of the human operator. The clasp mechanism uses leverage on an inverted index latch track to reduce the amount of force required to engage the clasp mechanism.

[0122] In one or more embodiments of the present invention, a clasp stability device improves the safety of transporting chemicals, flammable materials, hazardous materials, kegs, tanks, barrels, and other substantially cylindrical objects.

[0123] In one or more embodiments of the present invention, a clasp stability device may be composed of lightweight materials or spark-resistant materials.

[0124] In one or more embodiments of the present invention, a clasp stability device may be retrofitted onto an

existing hand truck having either tubular longitudinal support members or a rectangular transverse support member. Alternatively, the clasp stability device may be integrated with a new hand truck build.

[0125] While the present invention has been described with respect to the above-noted embodiments, those skilled in the art, having the benefit of this disclosure, will recognize that other embodiments may be devised that are within the scope of the invention as disclosed herein. Accordingly, the scope of the invention should only be limited by the appended claims.

What is claimed is:

1. A clasp stability device comprising:
  - a pair of clasp arms each comprising a clasp portion, a pivoting attachment portion, and a rotating attachment portion;
  - a base plate assembly comprising a base plate, a plurality of actuator travel positioner receivers disposed on top side of the base plate, and a plurality of pedal mounting plates disposed on a bottom side of the base plate;
  - an actuator assembly comprising an actuator plate and a plurality of actuator travel positioners attached to a bottom side of the actuator plate;
  - a pedal arm disposed in between the pedal mounting plates comprising an engagement portion, a pivot attachment portion, an index latch track, and an actuating portion; and
  - a pedal latch disposed in between the pedal mounting plates comprising a release portion, a pivot attachment portion, and an index latch,
 wherein the clasp arms are controllably closed by pushing the engagement portion of the pedal arm causing the pedal arm to travel such that the actuating portion of the pedal arm disposed within a cutout of the actuator plate causes the actuator plate assembly to travel in the actuator travel positioner receivers toward a rear of the base plate, and
  - wherein the travel of the actuator plate assembly causes the rotating attachment portion of the clasp arms to travel within arcuate travel cutouts in the actuator plate while the pivot attachment portion of the clasp arms pivot causing the clasp arms to close and upon release of the engagement portion the index latch engages the index latch track to stably retain a degree of closure of the clasp arms.
2. The clasp stability device of claim 1, further comprising a plurality of bias springs each having a first end removably attached to the base plate and a second end removably attached to the actuator plate.
3. The clasp stability device of claim 2, wherein the clasp arms are opened by pushing the release portion of the pedal latch to disengage the index latch from the index latch track and the plurality of bias springs causes the actuator plate assembly to travel in the actuator travel positioner receivers toward a front of the base plate.
4. The clasp stability device of claim 3, wherein the travel of the actuator plate towards the front of the base plate causes the rotating attachment portion of the clasp arms to travel within arcuate travel cutouts in the actuator plate while the pivot attachment portion of the clasp arms pivot causing the clasp arms to open.
5. The clasp stability device of claim 1, further comprising a plurality of clamping assemblies removably attached to the base plate.

6. The clasp stability device of claim 5, wherein each clamping assembly comprises a front member having a radiused portion that is removably attached a rear member having a radiused portion, such that the radiused portions of the front member and rear members secure the clasp stability device to a longitudinal support member of a hand truck.

7. The clasp stability device of claim 1, wherein the base plate comprises a plurality of direct mounting holes for directly attached the clasp stability device to a transverse support member of a hand truck.

8. A clasp stabilized hand truck comprising:

- a hand truck comprising a plurality of longitudinal support members; and
  - a clasp stability device removably attached to the hand truck by a plurality of clamping assemblies wherein each clamping assembly comprises a front member having a radiused portion and a rear member having a radiused portion, and wherein the front member is removably attached to the rear member such that the radiused portions secure the clasp stability device to the longitudinal support members of the hand truck,
- wherein the clasp stability device comprises:

- a pair of clasp arms each comprising a clasp portion, a pivoting attachment portion, and a rotating attachment portion,
  - a base plate assembly comprising a base plate, a plurality of actuator travel positioner receivers disposed on top side of the base plate, and a plurality of pedal mounting plates disposed on a bottom side of the base plate,
  - an actuator assembly comprising an actuator plate and a plurality of actuator travel positioners attached to a bottom side of the actuator plate,
  - a pedal arm disposed in between the pedal mounting plates comprising an engagement portion, a pivot attachment portion, an index latch track, and an actuating portion; and
  - a pedal latch disposed in between the pedal mounting plates comprising a release portion, a pivot attachment portion, and an index latch,
- wherein the clasp arms are controllably closed by pushing the engagement portion of the pedal arm causing the pedal arm to travel such that the actuating portion of the pedal arm disposed within a cutout of the actuator plate causes the actuator plate assembly to travel in the actuator travel positioner receivers toward a rear of the base plate, and

wherein the travel of the actuator plate assembly causes the rotating attachment portion of the clasp arms to travel within arcuate travel cutouts in the actuator plate while the pivot attachment portion of the clasp arms pivot causing the clasp arms to close and upon release of the engagement portion the index latch engages the index latch track to stably retain a degree of closure of the clasp arms.

9. The clasp stabilized hand truck of claim 8, wherein the clasp stability device further comprises a plurality of bias springs each having a first end removably attached to the base plate and a second end removably attached to the actuator plate.

10. The clasp stabilized hand truck of claim 9, wherein the clasp arms of the clasp stability device are opened by pushing the release portion of the pedal latch to disengage the index latch from the index latch track and the plurality

of bias springs causes the actuator plate assembly to travel in the actuator travel positioner receivers toward a front of the base plate.

**11.** The claspings stabilized hand truck of claim **10**, wherein the travel of the actuator plate towards the front of the base plate causes the rotating attachment portion of the claspings arms to travel within arcuate travel cutouts in the actuator plate while the pivot attachment portion of the claspings arms pivot causing the claspings arms to open.

**12.** The claspings stabilized hand truck of claim **8**, further comprising a plurality of clamping assemblies removably attached to the base plate.

**13.** The claspings stabilized hand truck of claim **12**, wherein each clamping assembly comprises a front member having a radiused portion that is removably attached a rear member having a radiused portion, such that the radiused portions of the front member and rear members secure the claspings stability device to a longitudinal support member of a hand truck.

**14.** The claspings stabilized hand truck of claim **8**, wherein the base plate comprises a plurality of direct mounting holes for directly attached the claspings stability device to a transverse support member of a hand truck.

**15.** A claspings stabilized hand truck comprising:

a hand truck comprising a plurality of transverse support members; and

a claspings stability device removably attached to the hand truck by a plurality of mounting bolts that secure the claspings stability device to the transverse support member of the hand truck,

wherein the claspings stability device comprises:

a pair of claspings arms each comprising a claspings portion, a pivoting attachment portion, and a rotating attachment portion,

a base plate assembly comprising a base plate, a plurality of actuator travel positioner receivers disposed on top side of the base plate, and a plurality of pedal mounting plates disposed on a bottom side of the base plate,

an actuator assembly comprising an actuator plate and a plurality of actuator travel positioners attached to a bottom side of the actuator plate,

a pedal arm disposed in between the pedal mounting plates comprising an engagement portion, a pivot attachment portion, an index latch track, and an actuating portion; and

a pedal latch disposed in between the pedal mounting plates comprising a release portion, a pivot attachment portion, and an index latch,

wherein the claspings arms are controllably closed by pushing the engagement portion of the pedal arm causing the pedal arm to travel such that the actuating portion of the pedal arm disposed within a cutout of the actuator plate causes the actuator plate assembly to travel in the actuator travel positioner receivers toward a rear of the base plate, and

wherein the travel of the actuator plate assembly causes the rotating attachment portion of the claspings arms to travel within arcuate travel cutouts in the actuator plate while the pivot attachment portion of the claspings arms pivot causing the claspings arms to close and upon release of the engagement portion the index latch engages the index latch track to stably retain a degree of closure of the claspings arms.

**16.** The claspings stabilized hand truck of claim **15**, wherein the claspings stability device further comprises a plurality of bias springs each having a first end removably attached to the base plate and a second end removably attached to the actuator plate.

**17.** The claspings stabilized hand truck of claim **16**, wherein the claspings arms of the claspings stability device are opened by pushing the release portion of the pedal latch to disengage the index latch from the index latch track and the plurality of bias springs causes the actuator plate assembly to travel in the actuator travel positioner receivers toward a front of the base plate.

**18.** The claspings stabilized hand truck of claim **17**, wherein the travel of the actuator plate towards the front of the base plate causes the rotating attachment portion of the claspings arms to travel within arcuate travel cutouts in the actuator plate while the pivot attachment portion of the claspings arms pivot causing the claspings arms to open.

**19.** The claspings stabilized hand truck of claim **15**, further comprising a plurality of clamping assemblies removably attached to the base plate.

**20.** The claspings stabilized hand truck of claim **19**, wherein each clamping assembly comprises a front member having a radiused portion that is removably attached a rear member having a radiused portion, such that the radiused portions of the front member and rear members secure the claspings stability device to a longitudinal support member of a hand truck.

**21.** The claspings stabilized hand truck of claim **15**, wherein the base plate comprises a plurality of direct mounting holes for directly attached the claspings stability device to a transverse support member of a hand truck.

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