

(19) United States

(12) Patent Application Publication (10) Pub. No.: US 2017/0338720 A1 Mayor

Nov. 23, 2017 (43) **Pub. Date:**

(54) ENHANCED CONVECTIVE ROTOR **COOLING**

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(21) Appl. No.: 15/480,607

(22) Filed: Apr. 6, 2017

Related U.S. Application Data

(60) Provisional application No. 62/318,845, filed on Apr. 6, 2016.

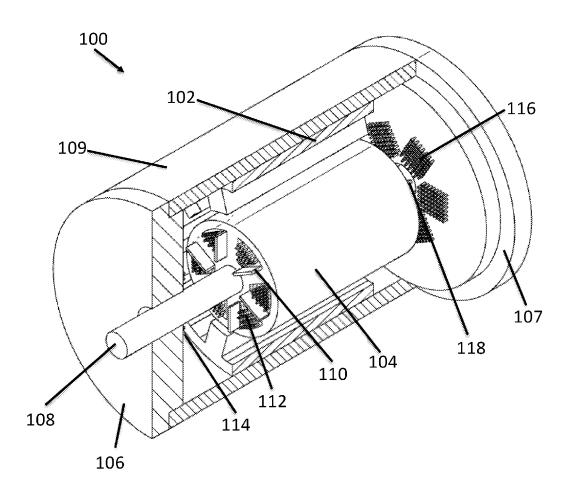
Publication Classification

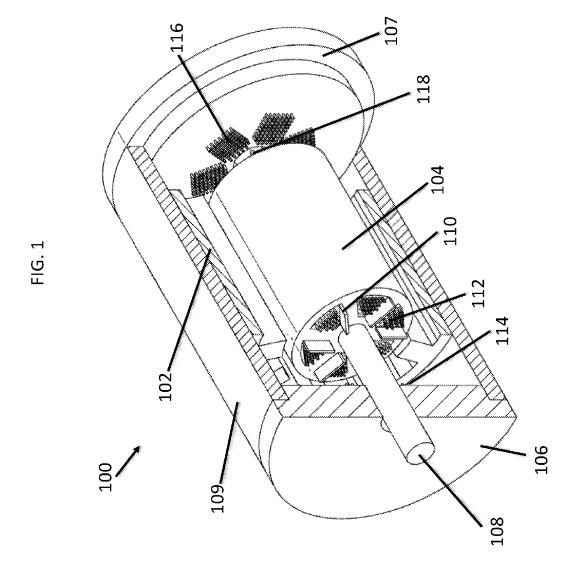
(51) Int. Cl. H02K 9/06 (2006.01)H02K 9/22 (2006.01)H02K 1/32 (2006.01) (52) U.S. Cl. CPC H02K 9/06 (2013.01); H02K 9/22 (2013.01); H02K 1/32 (2013.01)

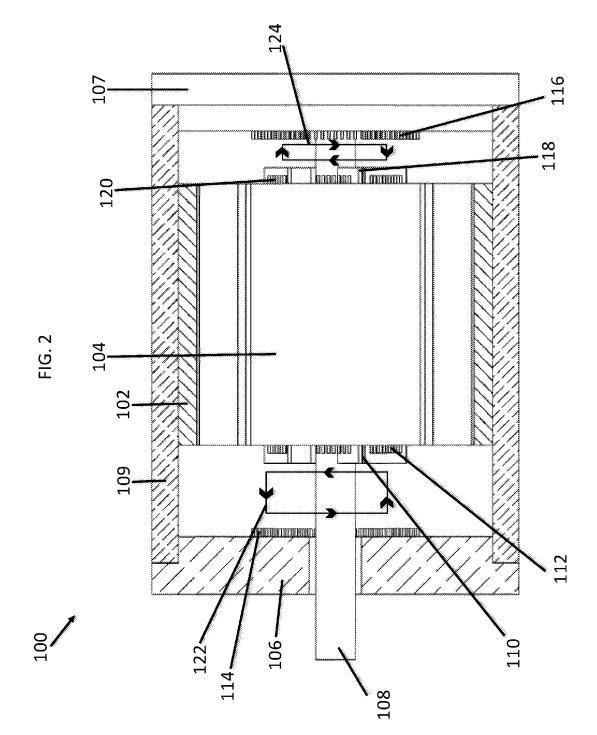
ABSTRACT (57)

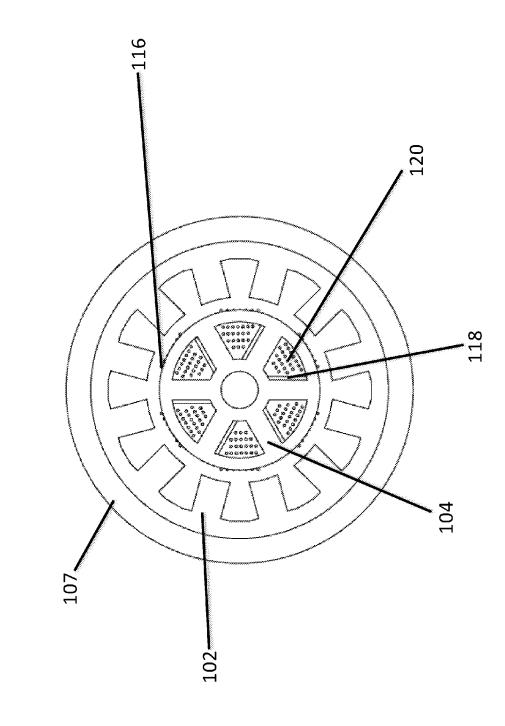
According to various aspects, exemplary embodiments of an electric motor are provided herein. In one embodiment of this disclosure, an electric motor includes a rotor, at least one end of the rotor includes at least one blade and at least one array of micro-features, wherein heat generated by the rotor is dissipated by the at least one blade and the at least one array of micro-features.

In another embodiment, a method of manufacturing an electric motor having a rotor, the method comprising machining a piece of conductive material to create microfeatures on at least one end of the conductive material; and inserting the conductive material into the rotor.

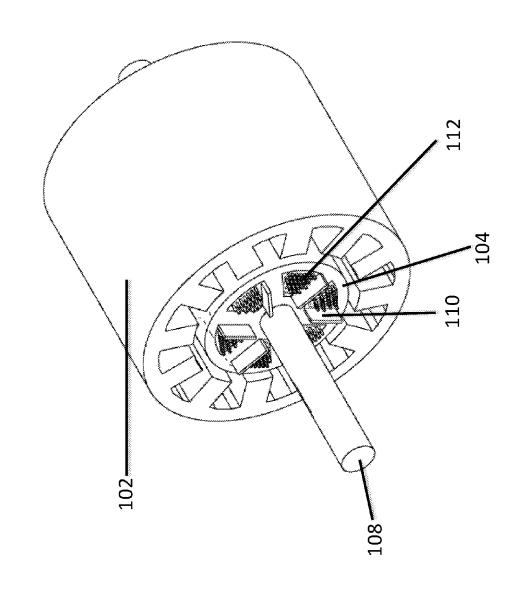




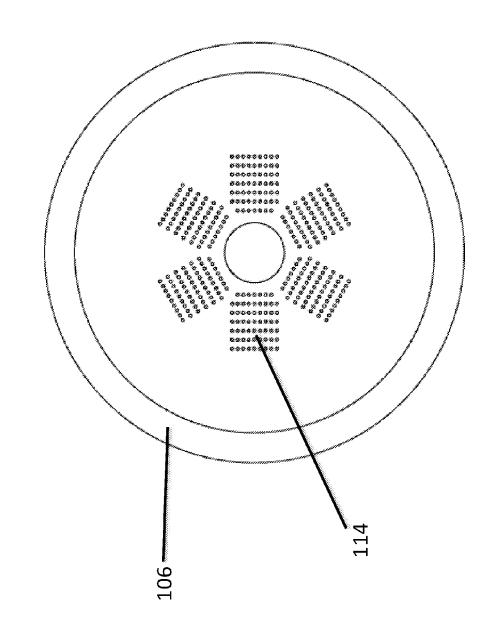




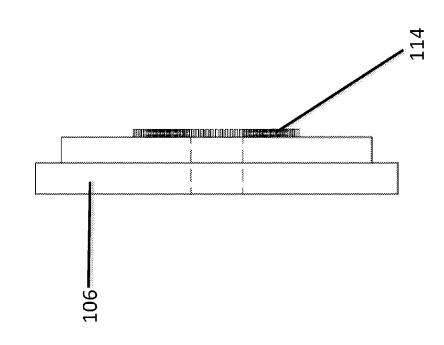


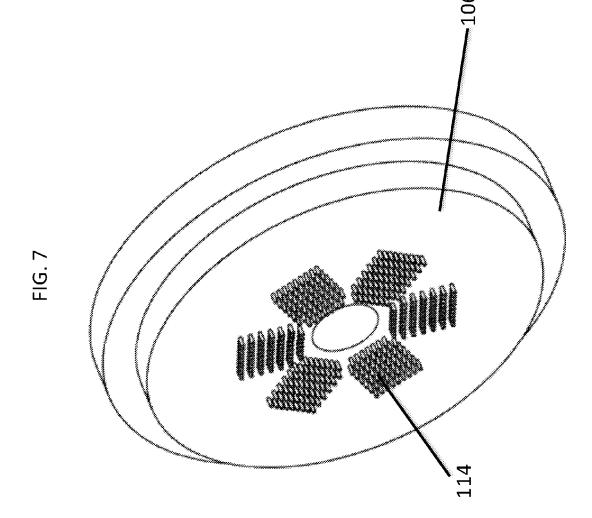


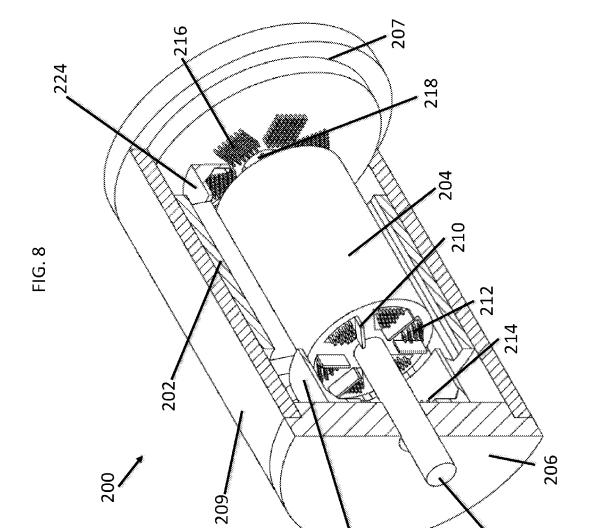




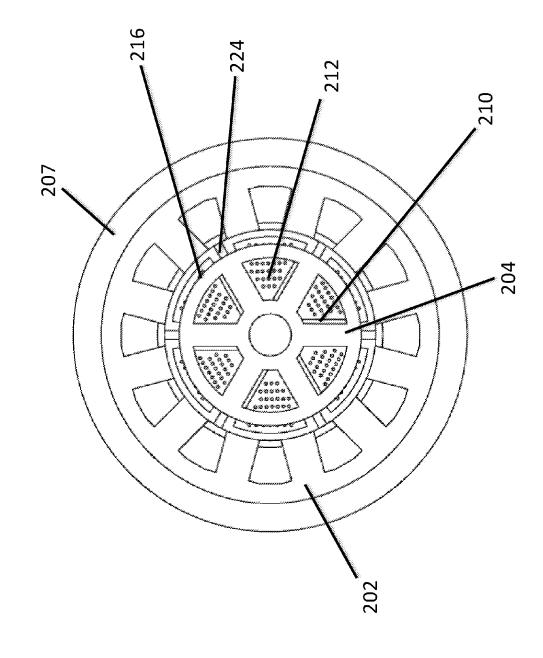


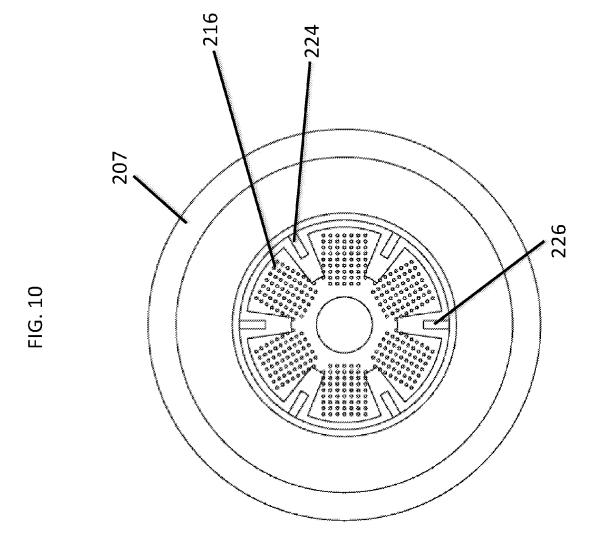


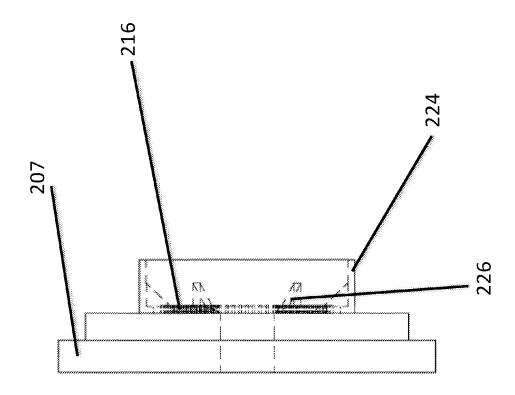


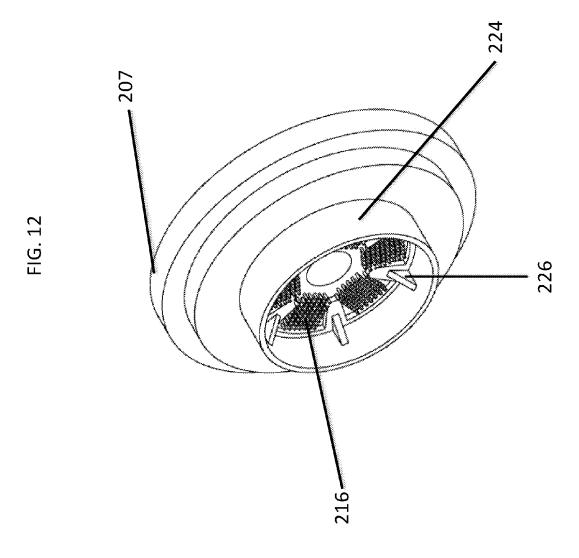












ENHANCED CONVECTIVE ROTOR COOLING

RELATED APPLICATION DATA

[0001] This application claims priority from U.S. Provisional Patent Application No. 62/318,845, which was filed on Apr. 6, 2016, which application is hereby incorporated herein by reference in its entirety.

BACKGROUND

[0002] Electric motors typically include two parts, a rotor and a stator. The stator is a stationary component, while the rotor rotates based on the relationship between the magnetic fields of the rotor and stator. The magnetic fields of the stator and rotor can be created in different ways including installing conductive windings around the teeth of a stator or rotor, using permanent magnets on rotors or stators, or employing rotor bars which are made of a conductor such as aluminum or copper.

[0003] During operation, the rotor and stator generate heat, which if not dissipated, can lead to motor failure. In induction machines where rotor bars are employed, some designs include end rings on each end of the rotor. The end rings can include molded tabs, which are referred to as wafters. As the rotor rotates, heat will generate in the rotor bars. Because the wafters are molded on the end rings, the wafters will rotate along with the rotor and will work to cool the rotor bars and the end windings of the stator.

[0004] In this setup, there are disadvantages. First, where the rotor includes rotor bars of aluminum or copper, heat generated in the rotor can move to the ends of the rotor because these materials are good thermal conductors. But for rotors constructed out of materials that are not good thermal conductors, such as permanent magnets, this design is not effective because it cannot effectively draw out the heat generated by the magnetics. Moreover, the wafters described herein, are not optimal; cooling of electric motors, including induction machines, can be enhanced. And this is desirable because enhanced cooling will allow the motor to receive more current and produce a higher power output.

SUMMARY

[0005] According to various aspects, exemplary embodiments of an electric motor are provided herein. In one embodiment of this disclosure, an electric motor includes a rotor, at least one end of the rotor includes at least one blade and at least one array of micro-features, wherein heat generated by the rotor is dissipated by the at least one blade and the at least one array of micro-features.

[0006] In another embodiment, a method of manufacturing an electric motor having a rotor, the method comprising machining a piece of conductive material to create microfeatures on at least one end of the conductive material; and inserting the conductive material into the rotor.

[0007] According to another embodiment, a method of manufacturing an electric motor having a rotor, the method comprising pouring and casting a piece of conductive material into the rotor, with the casting forming the conductive material into a conductive material having at least one end, wherein the at least one end includes micro-features.

DESCRIPTION OF THE DRAWINGS

[0008] FIG. 1 is a perspective view of an electric motor.

[0009] FIG. 2 is a side view of an electric motor.

 $\ensuremath{[0010]}$ FIG. 3 is an axial view of components of an electric motor.

[0011] FIG. 4 is a perspective view of components of an electric motor.

[0012] FIG. 5 is an axial view of an end cap of an electric motor.

[0013] FIG. 6 is a side view of an end cap of an electric motor.

[0014] FIG. 7 is a perspective view of an end cap of an electric motor.

[0015] FIG. 8 is a perspective view of an electric motor.

 $\mbox{\bf [0016]} \quad \mbox{FIG. 9}$ is an axial view of components of an electric motor.

[0017] FIG. 10 is an axial view of components of an electric motor.

[0018] FIG. 11 is a side view of components of an electric motor.

[0019] FIG. 12 is a perspective view of components of an electric motor.

DETAILED DESCRIPTION

[0020] FIG. 1 is a perspective view of an electric motor 100. The electric motor 100 includes a stator 102, a rotor 104, end caps 106 and 107, a shaft 108 to which the rotor 104 delivers torque during operation, and a casing 109. The left end of the rotor includes a plurality of blades 110 in between which are a plurality of arrays of micro-features 112. Each of the arrays includes projections that are arranged in a trapezoidal fashion, but can be in other configurations such as rectangular, circular, or triangular. The configurations could also be staggered or aligned. The projections of the micro-features 112 have a circular cross-section, but the cross-section of the micro-features 112 could be other shapes such as rectangular, circular, ovular, rhomboidal, or the shape of a hydrofoil or an airfoil. The right side of the rotor 104 also includes a plurality of blades 118 and a plurality of arrays of micro-features, which cannot be observed in this perspective view but will be shown in subsequent figures. Each array of micro-features 112 on the left side of the rotor 104 corresponds with an array of micro-features on the right side of the rotor. Specifically, each corresponding pair of micro-feature arrays are two ends of an insert made of conductive material, referred to herein as a spreader and described in more detail below. In the embodiment of FIG. 1, there are six spreaders inserted into the rotor 104, and as a result, there are six corresponding pairs of micro-feature arrays. Additionally, the blades 110 and 118 can be integral with the spreaders, or alternatively the blades 110 and 118 can be integral with the rotor 104. The blades 110 and 118 could also be discrete components attached to either the rotor 104 or the spreaders.

[0021] The end caps 106 and 107 includes a plurality of arrays of micro-features 114 and 116 respectively. Each array of micro-features 114 and 116 is arranged in a rectangular fashion but can be in other configurations such as circular, triangular, or trapezoidal. Like the micro-features 112, the micro-features 114 and 116 have a circular cross-section, but the cross-section of the micro-features 114 and 116 could be other shapes such as rectangular, circular, ovular, or rhomboidal.

[0022] During operation of the motor 100, the rotor 104 rotates and because the blades 110 and 118 and the microfeatures 112 (and the corresponding micro-features on the right side of the rotor) are on the rotor, they also will rotate. Overtime, the rotor and stator will generate heat. The heat generated by the rotor will be conducted to the ends of the rotor 104 via the spreader. When the heat reaches the ends of the rotor, the blades 110 and 118 and the micro-features 112 (and the corresponding micro-features on the right side of the rotor 104) will cool the rotor and stator by dissipating the heat generated in the rotor.

[0023] More specifically, the rotation of the blades 110 and 118 causes an axisymmetric circulation of air that goes from the rotor 104, to the stator 102, to the end caps 106 and 107, and back to the rotor 104. In this circulation, the heat from the rotor gets dissipated by flowing from the rotor along the described axisymmetric circulation. When the heat reaches the end caps 106 and 107, the micro-features 114 and 116 of the end caps will cause the heat to dissipate to the ambient air outside the motor 100.

[0024] The micro-features described enhance the cooling of the motor 100. As described, heat generated by the rotor 104 will be thermally conducted to the ends of the rotor 104 via the spreaders. The blades 110 and 118 generate the axisymmetrical circulation of air, which will flow in between the gaps of, and around individual micro-features. The surface of the micro-features increases the area of the ends of the rotor (where generated heat is conducted to via the spreaders) and the flow of the circulating air increases its velocity as it flows in between and around individual micro-features. The increase in area and velocity enhances the heat dissipation from the rotor 104.

[0025] Similarly, when the heat dissipated from the rotor flows along the axisymmetric airflow and reaches the microfeatures 114 and 116 on the end caps 106 and 107, the micro-features 114 and 116 will enhance the cooling of the motor 100 by dissipating the heat out to the ambient air outside the motor 100 due to the surface area of the micro-features and the increased velocity of the air flow in between and around the micro-features.

[0026] The arrangement of micro-features and blades described are useful in rotors that comprise permanent magnets. In permanent magnet machines, magnets can generate heat through eddy currents. These eddy currents generate heat on the magnets that can degrade their function. One problem is that magnets are not good thermal conductors, so the generated heat tends to stay with the magnet. When used in permanent magnet machines, the spreader acts as a thermal capacitance that conducts the heat from the magnets and moves it to the ends of the rotor, where it is dissipated as described.

[0027] FIG. 2 is a side view of motor 100 so that internal parts of the motor 100 can be observed. FIG. 2 illustrates the stator 102, a rotor 104, end caps 106 and 107, a shaft 108, and a casing 109. On the left side of the rotor are blades 110 and micro-features 112, and on the right side of the rotor are blades 118 and micro-features 120. On the end caps 106 and 107 are micro-features 114 and 116 respectively. FIG. 2 shows arrows 122 and 124 which illustrate the generally axisymmetric circulation created by the blades 110 and 118. [0028] FIG. 3 is an axial view of components of the electric motor 100. This figure shows the stator 102 inside of which is the rotor 104. One of the ends of the rotor 104 includes blades 110 and micro-features 112. FIG. 3 also

shows end cap 107 having micro-features 116. FIG. 4 is a perspective view of components of the electric motor 100. This figure shows the stator 102, rotor 104, and the shaft 108. On the rotor 104 are the blades 110 and micro-features 112

[0029] FIG. 5 is an axial view of end cap 106 and FIG. 6 is a side view of end cap 106. FIG. 5 shows the array of micro-features 114 and FIG. 6 shows from the side, the projection of the micro-features 114. FIG. 7 shows the micro-features on the end cap 106 from a perspective view, showing micro-features 114.

[0030] FIG. 8 is a perspective view of an electric motor 200. The electric motor 200 includes a stator 202, a rotor 204, end caps 206 and 207, a shaft 208 to which the rotor 204 delivers torque during operation, and a casing 209. The left end of the rotor includes a plurality of blades 210 in between which are a plurality of arrays of micro-features 212. Each of the arrays include projections that are arranged in a trapezoidal fashion, but can be in other configurations such as rectangular, circular, or triangular. The projections of the micro-features 212 have a circular cross-section, but the cross-section of the micro-features 212 could be other shapes such as rectangular, circular, ovular, or rhomboidal. The right side of the rotor 204 also includes a plurality of blades 218 and a plurality of arrays of micro-features, which cannot be observed in this perspective view. The microfeatures on the right side of the rotor 204 are symmetrical to those on the left side, as described in FIG. 1. Each array of micro-features 212 on the left side of the rotor 204 corresponds with an array of micro-features on the right side of the rotor. Specifically, each corresponding pair of microfeature arrays are two ends of an insert made of conductive material, referred to herein as a spreader and described in more detail below. In the embodiment of FIG. 8, there are six spreaders inserted into the rotor 204, and as a result, there are six corresponding pairs of micro-feature arrays. Additionally, the blades 210 and 218 can be integral with the spreaders, or alternatively the blades 210 and 218 can be integral with the rotor 204. The blades 210 and 218 could also be discrete components attached to either the rotor 204 or the spreaders.

[0031] The end caps 206 and 207 includes a plurality of arrays of micro-features 214 and 216 respectively. Each array of micro-features 214 and 216 is arranged in a rectangular fashion but can be in other configurations such as circular, triangular, or trapezoidal. Like the micro-features 212, the micro-features 214 and 216 have a circular cross-section, but the cross-section of the micro-features 214 and 216 could be other shapes such as rectangular, circular, ovular, or rhomboidal.

[0032] During operation, the heat generated in rotor 204 is conducted to the ends of the rotor via the spreaders wherein the heat is dissipated via the blades and micro-features on the rotor 204, similar to that described in FIG. 1. In FIG. 8, however, the motor 200 also includes ducts 222 and 224. During operation, the blades 210 and 218 rotate to create a circulation of air. In FIG. 1, the circulation created by the blades directed airflow axisymmetrically from the rotor to the stator and then to the end caps. In the embodiment in FIG. 8, the circulated air does not flow to the stator due to the ducts 222 and 224. Instead, in FIG. 8, due to the ducts, the air circulates from the rotor 204 to the end caps 206 and 207. With the ducts 222 and 224, there is a close coupling convection between the rotor 204 and the end caps 206 and

207 such that the heat dissipated from the rotor 204 is directed to the micro-features 214 and 216 of the end caps 206 and 207.

[0033] FIG. 9 is an axial view of components of the electric motor 200. This figure shows the stator 202 inside of which is the rotor 204. One of the ends of the rotor 204 includes blades 210 and micro-features 212. FIG. 9 also shows the duct 224 and end cap 207 having micro-features 216

[0034] FIG. 10 is another axial view of components of the electric motor 200, which shows the end cap 207 having micro-features 216, and also shows the duct 224. The duct 224 includes ribs 226. The ribs 226 provide structural support for the duct 224 and also direct airflow to the micro-features 216. During operation, some of the air flow from the rotor (via the blades 210 and 218) will contact the ribs 226 at which point the ribs 226 will assist in direct the airflow to the micro-features 216. The ribs 226, therefore, increase the efficiency of the heat transfer from the rotor to the end caps and ultimately out of the motor 200. While end cap 207 is shown in FIG. 10, it will be appreciated that ribs, like ribs 226, can be included on duct 222 on end cap 206. [0035] FIG. 11 is a side view of the end cap 207 showing the micro-features 216 and duct 224 and ribs 226, and FIG. 12 is a perspective view showing these features. The ribs 226 are triangular, but it will be appreciated that other geometries such as cubical or pyramidal can be applied without departing from the scope of this disclosure.

[0036] The rotors described herein may be manufactured where the spreaders are machined to include the microfeatures on each end; alternatively the micro-features and the

- 1. An electric motor comprising:
- a rotor having a first end;
- at least one blade; and
- at least one array of micro-features;
- wherein the at least one blade and at least one array of micro-features is located on the first end of the rotor; wherein heat generated by the rotor is dissipated by the at least one blade and the at least one array of microfeatures
- 2. The electric motor of claim 1, wherein the motor includes a plurality of blades and a plurality of arrays of micro-features, and the rotor further includes a second end, wherein the one of the plurality of arrays of micro-features and one of the plurality of blades is positioned on each of the first and second ends of the rotor.
- 3. The electric motor of claim 1 further comprising a first end cap, the first end cap including an array of microfeatures.

- **4**. The electric motor of claim **3** further comprising a second end cap, the second end cap including an array of micro-features.
- 5. The electric motor of claim 1, wherein the motor is a permanent magnet machine.
- **6**. The electric motor of claim **5**, wherein the permanent magnet machine includes a segmented magnet.
- 7. The electric motor of claim 7, wherein the motor is an induction machine.
- 8. The electric motor of claim 1 wherein the rotor includes a spreader, the at least one array of micro-features positioned on the spreader.
- 9. The electric motor of claim 8 wherein the rotor includes a plurality of arrays of micro-features, the spreader has two ends, wherein one of the plurality of arrays of micro-features are positioned on each end of the spreader.
- 10. The electric motor of claim 8 wherein the spreader is a discrete part from the rotor.
- 11. The electric motor of claim 9, further comprising a plurality of blades, positioned on each end of the rotor to waft heat dissipated from the plurality of arrays microfeatures.
- 12. The electric motor of claim 9 wherein the plurality of blades is integral with the spreader.
- 13. The electric motor of claim 9 wherein the plurality of blades is integral with the rotor.
- 14. The electric motor of claim 1 wherein the cross-section of the micro-features in the at least one array of micro-features has the shape of an airfoil.
- 15. The electric motor of claim 1 wherein the cross-section of the micro-features in the at least one array of micro-features has a circular shape.
- **16.** The electric motor of claim **1** wherein the at least one array of micro-features has a trapezoidal shape.
- 17. The electric motor of claim 1 wherein the at least one array of micro-features has a rectangular shape.
- **18**. A method of manufacturing an electric motor having a rotor, the method comprising:
 - machining a piece of conductive material to create microfeatures on at least one end of the conductive material; and inserting the conductive material into the rotor.
- 19. The method of claim 18 further comprising, machining an end cap for the motor to create micro-features on the end cap.
- 20. A method of manufacturing an electric motor having a rotor, the method comprising pouring and a casting a piece of conductive material into the rotor, with the casting forming the conductive material into a conductive material having at least one end, wherein the at least one end includes micro-features.

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