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(54) **IMAGING-BASED SIZING OPTIMIZATION OF ENDOTRACHEAL TUBE FOR MECHANICAL VENTILATION**

BILDGEBUNGSBASIERTE GRÖSSENOPTIMIERUNG EINES ENDOTRACHEALTUBUS FÜR MECHANISCHE BEATMUNG

OPTIMISATION DE DIMENSIONNEMENT BASÉE SUR L'IMAGERIE D'UN TUBE ENDOTRACHÉAL POUR VENTILATION MÉCANIQUE

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Description

[0001] The following relates generally to the respiratory therapy arts, tracheal intubation arts, endotracheal tube sizing arts, and related arts.

BACKGROUND

[0002] Mechanical ventilation of a patient typically entails placement of an endotracheal tube (ETT) into a trachea of the patient, in a process known as tracheal intubation. The desired position of the tip of an ETT is approximately 5.0 cm (\pm 2.0 cm) above a carina (i.e., a location where the trachea splits into the main right and left bronchi). Tracheal intubation is usually performed by an anesthesiologist or other qualified medical professional, and in a common sequence the head is moved backward to access the airway, and a laryngoscope is used to facilitate proper placement of the ETT between the vocal cords and into the trachea, without misplacement into the esophagus.

[0003] Common situations where mechanical ventilation is required can include intensive care unit (ICU) cases and during major surgery. Such patients often have images (i.e., computed tomography (CT) images) obtained of the thorax before being sent to the ICU, in particular if the patient's condition is a lung-related disease (e.g., Covid-19), or trauma.

[0004] However, the ETT may be incorrectly positioned (such as in the esophagus or one of the bronchi), or there may be an air-leak in the ETT. Although uncommon, when these situations occur, it may lead to severe complications with long term consequences due to cerebral hypoxia.

[0005] An important consideration when intubating a patient is proper selection of the ETT size. ETTs are available in various sizes, e.g., from 2 mm to 10.5 mm internal diameter in some sizing schemes, with the smallest sizes being used for intubating infants. For patients older than one year, one formula for selecting the internal diameter

$$\frac{Age+16}{4}$$

in millimeters is $\frac{Age+16}{4}$. In addition to selecting ETT diameter, the depth of insertion of the ETT is another important sizing parameter. The end of the ETT is preferably positioned above the carina, that is, where the trachea branches into the left and right bronchial tubes leading into the respective lungs, in order to ensure a wellsealed fit while ventilating both the left and right lungs equally. The ETT usually has marks along its length (e.g., tick marks every 1 cm or the like) so that the tube insertion depth can be tracked visually during the tracheal intubation process. A formula for selecting the depth of insertion

$$\frac{Age+12}{2}$$

in centimeters is $\frac{Age+12}{2}$. While these are general rules, patient-specific anatomy can significantly impact ETT sizing (optimal tube diameter and depth of insertion), as well as the difficulty in performing the tracheal intubation.

Improper tracheal intubation can lead to serious complications, such as perforation of the trachea (or of the esophagus if the ETT is misplaced), nerve damage, spinal damage, vocal cord damage, inadequate mechanical ventilation via the inserted ETT, bronchial intubation (insertion of the ETT too deeply so that it enters the left or right bronchial tube), accidental dislodgment of the ETT, and so forth. Performing the tracheal intubation with a tube of the wrong size can directly or indirectly lead to many such complications. Intubation with an ETT of too-small diameter can lead to inadequate ventilation and possible dislodgement; whereas, using a too-large diameter can lead to excessive force being applied to the airway potentially leading to damage to nerves, vocal cords, or other airway tissue. Similarly, insufficient depth of insertion can lead to inadequate ventilation and possible dislodgement, whereas excessive depth of insertion can lead to bronchial intubation. The laryngoscope permits visual observation only of the upper airway structures (glottis and larynx), so that tracheal intubation is a partially "blind" procedure.

[0006] The US patent application n° US2016/022943 discloses a method and apparatus for determining the optimal endotracheal tube size for the intubation of a patient based upon both optimal tube length and optimal tube diameter which are determined by using either direct or indirect measurement devices or techniques to measure the patient's glottis aperture and tracheal length. The apparatus may include a maneuverable arm, a fiber optic video guidance system and an introducer guide to maneuver an end of the apparatus around obstructions in a patient who has a difficult airway to facilitate insertion of either an optimally sized endotracheal tube or a standard endotracheal tube into the patient's airway.

[0007] The following discloses certain improvements to overcome these problems and others.

SUMMARY

[0008] The invention is defined in the appended set of claims.

[0009] In one aspect, an intubation assistance device includes an electronic controller configured to: identify, from one or more images of a patient, information about the patient including at least a diameter of a trachea and a length of an intubation pathway; determine a recommended ETT size including an ETT diameter and an ETT depth of insertion from the determined diameter of the trachea and the determined length of the intubation pathway; and display the recommended ETT size on a display device.

[0010] In another aspect not forming part of the invention, an intubation assistance method includes, using an electronic controller: identifying, from one or more images of a patient, information about the patient including at least a diameter of a trachea and a length of an intubation pathway; determining a recommended ETT size including an ETT diameter and an ETT depth of insertion from

the determined diameter of the trachea and the determined length of the intubation pathway; and displaying the recommended ETT size on a display device.

[0011] One advantage resides in providing mechanical ventilation therapy to a patient with an ETT of suitable diameter sizing inserted into the patient's trachea.

[0012] Another advantage resides in providing mechanical ventilation therapy to a patient with an ETT of suitable insertion depth sizing into the patient's trachea.

[0013] Another advantage resides in determining a suitable size of the ETT that takes into account the individualized anatomy of the patient.

[0014] Another advantage resides in determining a suitable ETT size for a patient based on one or more images of the patient.

[0015] Another advantage resides in using one or more models of the ETT and/or a patient geometry of the patient to determine a suitable size of the ETT.

[0016] Another advantage resides in using one or more models of the ETT and/or a patient geometry of the patient to determine an insertion depth of the ETT into the patient's trachea.

[0017] A given embodiment may provide none, one, two, more, or all of the foregoing advantages, and/or may provide other advantages as will become apparent to one of ordinary skill in the art upon reading and understanding the present disclosure.

BRIEF DESCRIPTION OF THE DRAWINGS

[0018] The disclosure may take form in various components and arrangements of components, and in various steps and arrangements of steps. The drawings are only for purposes of illustrating the preferred embodiments and are not to be construed as limiting the disclosure.

FIGURE 1 diagrammatically shows an illustrative mechanical ventilation-imaging system in accordance with the present disclosure.

FIGURE 2 shows an example flow chart of operations suitably performed by the system of FIGURE.

FIGURE 3 shows an image with an intubation pathway determined by the system of FIGURE 1.

DETAILED DESCRIPTION

[0019] As used herein, the singular form of "a", "an", and "the" include plural references unless the context clearly dictates otherwise. As used herein, statements that two or more parts or components are "coupled," "connected," or "engaged" shall mean that the parts are joined, operate, or co-act together either directly or indirectly, i.e., through one or more intermediate parts or components, so long as a link occurs. Directional phrases used herein, such as, for example and without limitation, top, bottom, left, right, upper, lower, front, back, and derivatives thereof, relate to the orientation of the elements

shown in the drawings and are not limiting upon the scope of the disclosure unless expressly recited therein. The word "comprising" or "including" does not exclude the presence of elements or steps other than those described herein and/or listed in a claim. In a device comprised of several means, several of these means may be embodied by one and the same item of hardware.

[0020] With reference to FIGURE 1, a mechanical ventilator **2** for providing ventilation therapy to an associated patient **P** is shown. As shown in FIGURE 1, the mechanical ventilator **2** includes an outlet **4** connectable with a patient breathing circuit **5** to deliver mechanical ventilation to the patient **P**. The patient circuit **5** includes typical components for a mechanical ventilator, such as an inlet line **6**, an optional outlet line **7** (this may be omitted if the ventilator employs a single-limb patient circuit), a connector or port **8** for connecting with an ETT, and one or more breathing sensors (not shown), such as a gas flow meter, a pressure sensor, end-tidal carbon dioxide (etCO₂) sensor, and/or so forth. The mechanical ventilator **2** is designed to deliver air, an airoxygen mixture, or other breathable gas (supply not shown) to the outlet **4** at a programmed pressure and/or flow rate to ventilate the patient via an ETT.

[0021] FIGURE 1 also shows a medical imaging device **15** (also referred to as an image acquisition device, imaging device, and so forth). The image acquisition device **15** can be a Computed Tomography (CT) image acquisition device, a C-arm imager, or other X-ray imaging device; Magnetic Resonance (MR) image acquisition device; an ultrasound (US) image acquisition device; or a medical imaging device of another modality. As primarily described herein, the medical imaging device **15** comprises a CT medical imaging device **15**. As described herein, the medical imaging device **15** is used to acquire images of the patient **P** based upon which ETT sizing is performed. It should be noted that the imaging device **15** may not be located in the same room, or even the same department, as the mechanical ventilator **2**. For example, the medical imaging device **15** may be located in a radiology laboratory while the mechanical ventilator **2** may be located in an intensive care unit (ICU), cardiac care unit (CCU), in a hospital room assigned to the patient **P**, or so forth. This is diagrammatically indicated in FIGURE 1 by separator line **L**.

[0022] FIGURE 1 diagrammatically illustrates the patient **P** intubated with an endotracheal tube (ETT) **16** (the lower portion of which is inside the patient **P** and hence is shown in phantom). The connector or port **8** connects with the ETT **16** to operatively connect the mechanical ventilator **2** to deliver breathable air to the patient **P** via the ETT **16**. The mechanical ventilation provided by the mechanical ventilator **2** via the ETT **16** may be therapeutic for a wide range of conditions, such as various types of pulmonary conditions like emphysema or pneumonia, viral or bacterial infections impacting respiration such as a COVID-19 infection or severe influenza, cardiovascular conditions in which the patient **P** receives breathable gas

enriched with oxygen, or so forth.

[0023] FIGURE 1 shows the patient **P** already intubated. That is, FIGURE 1 shows the patient after a tracheal intubation has been performed to insert the ETT **16** into the patient. However, to safely perform the tracheal intubation, the anesthesiologist or other qualified medical professional first performs an assessment of the patient **P** to select the ETT size of the ETT **16**, and then inserts an ETT of the selected size into the patient **P** by a tracheal intubation procedure.

[0024] As a further note, as used herein the "ETT size" includes an ETT diameter and a depth of insertion. The length of the ETT **16** is longer than the depth of insertion, and the depth of insertion is not a characteristic metric of the ETT *per se*. However, the depth of insertion is typically determined for a given patient prior to performing the tracheal intubation. Thus, the ETT sizing for the patient **P** includes sizing both the ETT diameter and the depth of insertion. That is, the ETT size as used herein includes a tube diameter (specified by an inner diameter (ID) an outer diameter (OD), or both an ID and an OD) and a depth of insertion.

[0025] FIGURE 1 further shows an intubation assistance device **18** configured to assist with intubation of the ETT **16** by providing a recommended ETT size (e.g., diameter and depth of insertion) prior to performing the tracheal intubation. The intubation assistance device **18** can comprise an electronic processing device, such as a workstation computer (more generally, a computer), a smart device (e.g., a smartphone, a tablet, and so forth), or server computer or a plurality of server computers, (e.g., interconnected to form a server cluster, cloud computing resource, or so forth). The intubation assistance device **18** includes typical components, such as an electronic controller **20** (e.g., an electronic processor or a microprocessor), at least one user input device (e.g., a mouse, a keyboard, a trackball, a finger swipe on a touchscreen of a smart device, and/or the like) **22**, and at least one display device **24** (e.g., an LCD display, plasma display, cathode ray tube display, and/or so forth). In some embodiments, the display device **24** can be a separate component from the electronic processing device **18**. The display device **24** may also comprise two or more display devices.

[0026] The electronic controller **20** is operatively connected with one or more non-transitory storage media **26**. The non-transitory storage media **26** may, by way of non-limiting illustrative example, include one or more of a magnetic disk, RAID, or other magnetic storage medium; a solid state drive, flash drive, electronically erasable read-only memory (EEROM) or other electronic memory; an optical disk or other optical storage; various combinations thereof; or so forth; and may be for example a network storage, an internal hard drive of the intubation assistance device **18**, various combinations thereof, or so forth. It is to be understood that any reference to a non-transitory medium or media **26** herein is to be broadly construed as encompassing a single medium or multiple

media of the same or different types. Likewise, the electronic controller **20** may be embodied as a single electronic processor or as two or more electronic processors. The non-transitory storage media **26** stores instructions executable by the at least one electronic controller **20**. The instructions include instructions to generate a graphical user interface (GUI) **28** for display on the remote operator display device **24**.

[0027] In some embodiments, one or more cameras are disposed in an area where the medical imaging device **15** is located. For example, as shown in FIGURE 1, a three-dimensional (3D) camera **30** can be positioned to image the patient **P**. Although only one 3D camera **30** is shown in FIGURE 1, any suitable number of 3D cameras **30** can be used. Any suitable 3D camera **30** can be used (see, e.g., FAST Integrated Workflow (siemens-healthineers.com)).

[0028] Furthermore, as disclosed herein, the non-transitory storage media **26** stores instructions executable by the at least one electronic controller **20** to perform an intubation assistance method or process **100** determining a suitable size and/or insertion depth of the ETT **16** to be used with the mechanical ventilator **2** to provide ventilation therapy to the patient **P**.

[0029] It will be appreciated that, as previously noted, the mechanical ventilator **2** (and the 3D camera **30**) can be disposed in a first room of a medical facility, while the image acquisition device **15** and the electronic processing device **18** can be disposed in a second, different room of the medical facility. This is depicted by the dashed line **L** in the generally "middle" portion of FIGURE 1. In another example, the mechanical ventilator **2** and the electronic processing device **18** can be disposed in the first room, while the image acquisition device **15** is disposed in the second room of the medical facility. In a further example, each of the mechanical ventilator **2**, the image acquisition device **15** and the electronic processing device **18** can be disposed in separate rooms of the medical facility. These are merely illustrative examples.

[0030] There may also be substantial temporal separation between (i) the acquisition of the images of the patient **P** using the imaging device **15** and determination of the ETT size recommendation for the patient **P** using the intubation assistance device **18**, and (ii) the actual tracheal intubation of the patient **P**. For example, the patient **P** may first be transported on a gurney to a radiology lab housing the imaging device **15** for imaging and ETT sizing, and then transported on the gurney from the radiology lab to the location of the mechanical ventilator **2**. In some embodiments described herein, the temporal separation may be even larger than this. For example, if the patient **P** undergoes a thoracic CT examination for some routine or diagnostic medical purpose, then as disclosed herein the acquired images may be used for that routine or diagnostic medical purpose and may also be secondarily leveraged to generate an ETT recommendation that may be stored in the Electronic Health Record (EHR) or other medical record of the patient **P**. Thereaf-

ter, if at some point (possibly weeks, months, or even years later) the patient **P** comes under medical care and requires mechanical ventilation, the ETT recommendation can be retrieved from the EHR or other medical record of the patient **P** and referenced by the anesthesiologist or other qualified medical professional performing the tracheal intubation.

[0031] With reference to FIGURE 2, and with continuing reference to FIGURE 1, an illustrative embodiment of the intubation assistance method **100** is diagrammatically shown as a flowchart. At an operation **102**, one or more images **34** of the patient are obtained by the medical imaging device **15**. In a particular example, the acquired images **34** are CT images **34**. In some examples, to acquire the CT images **34**, the electronic controller **20** is configured to control the medical imaging device **15** (i.e., a CT scanner) to acquire the CT images **34** of the upper airway (e.g., from the mouth to the carina) of the patient **P**. In some embodiments, the electronic controller **20** is configured to control the medical imaging device **15** to acquire a diagnostic torso CT image of the patient **P** at a first Xray level, and an extended upper CT image extending upward from the diagnostic torso CT image of the patient **P** at a second Xray level that is lower than the first Xray level. In other embodiments, a single CT image **34** may be acquired along a patient axis that covers both the diagnostic torso CT image and the extended upper CT image. The electronic controller **20** is then configured to combine the diagnostic torso CT image and the extended upper CT image to generate the CT images **34** of the upper airway of the patient **P**. This approach of lowering the X-ray level for the extended upper CT image can be advantageous as the throat area, like other parts of the human anatomy, is sensitive to radiation damage, so that a lower X-ray level in this area provides lower dosage. Additionally, the amount of image detail required for performing the disclosed ETT sizing may be less than usually required for the diagnostic or screening task for which the torso CT examination was ordered, so that the lower X-ray level used for the extended upper CT image is sufficient for this purpose. This type of imaging sequence workflow may be particularly advantageous when performing the ETT sizing as a secondary result of a torso CT examination ordered for a specific diagnostic or screening task unrelated to ETT sizing.

[0032] At an operation **104**, information about the patient **P** is identified from the acquired CT images **34**. The identified information can include, for example, the upper airways of the patient **P**, a diameter of trachea of the patient **P**, and a length of an intubation pathway of the patient **P**. In some embodiments, the electronic controller **20** is configured to identify the upper airways of the patient **P** by segmenting the CT images **34** to identify an upper airway landmark (i.e., 5.0 cm above the carina), the trachea, and the carina of the patient. A length of the intubation pathway can be identified based on a distance from the upper airway landmark through the trachea to the carina of the patient **P**. In some examples, the seg-

mentation might also include the centerline of the trachea. The segmentation can additionally provide a length measurement from the teeth to the point where the trachea and the esophagus enter the throat. This information might also be useful for a medical professional to select the depth of insertion of the ETT so as not to enter the esophagus during ETT placement. In other examples, a length starting from lips of the patient **P** to the carina is measured.

[0033] Any suitable segmentation algorithm can be used in performing the operation **104** (see, e.g., Automatic 3D segmentation of human airway tree in CT image | IEEE Conference Publication | IEEE Xplore, DOI: 10.1109/BMEI.2010.5639658; Automatic segmentation of airway tree based on local intensity filter and machine learning technique in 3D chest CT volume | SpringerLink, DOI 10.1007/s11548-016-1492-2; and Airway Segmentation and Centerline Extraction from Thoracic CT - Comparison of a New Method to State of the Art Commercialized Methods (plos.org), DOI 10.1371/journal.pone.0144282).

[0034] The identification of the length of the intubation pathway can also include identifying an entry point (i.e., the front teeth) for the ETT **16**. The intubation pathway is identified from the front teeth to a desired endpoint (e.g., 5.0 cm above the carina). Any suitable algorithm can be used for this process (see, e.g., Assessment of automatic segmentation of teeth using a watershed-based method (nih.gov), doi: 10.1259/dmfr.20170220; ToothNet: Automatic Tooth Instance Segmentation and Identification From Cone Beam CT Images (researchgate.net), DOI: 10.1109/CVPR.2019.00653; and Rapid Automatic Segmentation and Visualization of Teeth in CT-Scan Data (scialert.net), DOI: 10.3923/jas.2009.2031.2044).

[0035] In some embodiments, during acquisition of the CT images **34**, the head of the patient **P** may not be in a desired position (i.e., bent backwards, as is the usual positioning of the head during tracheal intubation). When this occurs, the electronic controller **20** is optionally configured to retrieve a patient anatomical model **36** (which contains the head and neck, and optionally at least the upper part of the thorax) from the non-transitory computer readable media **26**. The electronic controller **20** may use the patient anatomical model **36** to deform the image of the head and neck of the patient **P** shown in the CT images **34** into a desired position resulting in deformed CT images **34d** (e.g., with the head bent backwards). The patient anatomical model **36** represents the anatomy and, optionally biomechanical properties, of humans. The patient anatomical model **36** can be relatively simple (e.g., allowing an elastic deformation of the CT image(s) **34**) or detailed (e.g., it can consider surrounding anatomical structures (e.g., rigid bones, contractable muscles, tendons, and soft tissue)). With respect to the head and neck part of the patient anatomical model **36**, any suitable patient anatomical model **36** can be used (see, e.g., "Biomechanical modelling of neck flexion for deformable

alignment of the salivary glands in head and neck cancer images", Phys Med Biol. 2019 Sep 5;64(17):175018. doi: 10.1088/1361-6560/ab2f13).

[0036] In other embodiments, the acquired CT images **34** do not depict at least a portion of the upper airway of the patient **P** (e.g., due to the patient **P** moving during image acquisition, the patient **P** being incorrectly positioned for imaging, and so forth). In such instances, the electronic controller **20** is configured to adapt or modify the patient anatomical model **36** based on one or more 3D images **38** of the patient **P**, acquired via the 3D camera **30**. The 3D images **38** show an exterior (e.g., head and thorax) of the patient **P**. In one embodiment, the electronic controller **20** is configured to generate the 3D images **38** by generating a 3D model **40** from the CT images **34**, and by generating the 3D images **38** of the exterior of the patient **P** from the 3D model **40**. In another embodiment, the 3D images **38** of the exterior of the patient **P** are obtained by the 3D camera(s) **30** and transmitted to the electronic processing device **18**. The electronic controller **20** is then configured to register the patient anatomical model **36** with the CT images **34** to obtain a hybrid imaging data set, which is used to determine the intubation pathway. The identifying information about the patient **P** is further based on the extracted patient anatomical model **36**.

[0037] In other embodiments, the acquired CT images **34** do not depict at least a portion of the upper airway of the patient **P** (e.g., due to the patient **P** moving during image acquisition, the patient **P** being incorrectly positioned for imaging, and so forth). In such instances, the electronic controller **20** is configured to retrieve a patient anatomical (head, neck, and optionally thorax) model **36** from the non-transitory computer readable media **26**. The electronic controller **20** is further configured to identify the region where the patient anatomical model **36** and the CT image **34** overlap and to adjust parameters of the model such that the adjusted patient anatomical model **36a** fits in the overlapping region to the CT images **34**. The electronic controller **20** is further configured to generate a hybrid imaging data set from the measured CT images **34** (where available) and the adjusted patient anatomical model **36a** (where desired information from images **34** are missing). The hybrid imaging data set is subsequently used to determine the intubation pathway.

[0038] Once the intubation pathway is determined at the operation **104**, the method **100** proceeds to an operation **106**, in which the electronic controller **20** is configured to determine a recommended ETT size for the patient **P** from the determined diameter of the trachea and the determined length of the intubation pathway. To do so, an ETT model **42** can be retrieved from the non-transitory computer readable media **26**. The electronic controller **20** is configured to use the ETT model **42** to determine a desired stiffness of the ETT **16** by inputting the determined diameter of the trachea and the determined length of the intubation pathway to the ETT model **42**, which then outputs the recommended size of the ETT **16**

for the patient **P** including a recommended depth of insertion of the ETT **16**. The identification of the intubation pathway length is further based on the stiffness of the ETT **16**. In some examples, since the center line of the trachea and the upper airway do not conform to the shape of the ETT **16**, the ETT **16** may touch or contact a tracheal wall at different sides. The ETT model **42** can be used to account for a difference between the actual required depth of insertion of the ETT **16** and the length of the center line of the determined length of the intubation pathway.

[0039] At an operation **108**, the recommended ETT size for the patient **P** is displayed, via the GUI **28**, on the display device **24** of the electronic processing device **18**. Additionally or alternatively, the recommended ETT size can be transmitted to the mechanical ventilator **2** for display on the display device **14** thereof. Advantageously, a medical professional in the room where the mechanical ventilator **2** can quickly see the recommended ETT size for the patient **P** on the mechanical ventilator **2**.

[0040] At an operation **110**, the ETT **16** having the recommended ETT size for the patient **P** is inserted into the trachea of the patient **P**. The medical professional can use markings conventionally included on the ETT **16** to determine progress of the insertion depth of the ETT. The ETT **16** is inserted into the trachea to the recommended depth of insertion so as to place the tip of the ETT **16** at a desired point (e.g., 5.0 cm above the carina). In some embodiments, a headsup display (HUD), such as augmented reality (AR) glasses or headset (e.g., a Microsoft HoloLens, Bellevue, WA, United States) (not shown) can be used to guide the medical professional during placement (and subsequent removal) of the ETT **16**. In particular, the AR device can be used to indicate the position of the ETT **16** in relation to relevant anatomical structures within the patient's body derived from the CT images **34** and/or from the patient anatomical model **36**. This further aids in improving the accuracy of positioning of the ETT **16** and thereby decrease the risk of complications.

[0041] At an operation **112**, the ETT **16** is connected to the mechanical ventilator **2** (e.g., at the port or connector **8**). The medical professional then operates the mechanical ventilator **2** to deliver ventilation therapy to the patient **P** with the mechanical ventilator **2**.

[0042] Since the information can be obtained from any thorax CT image **34** (optionally in combination with the patient anatomical model **36**), the CT image acquisition and the ventilation therapy can be separated in time by days, weeks, months, or even years. For example, if a patient gets a thorax CT image **34** for some unrelated medical purpose, the optimal ETT size for the patient including the ETT diameter and depth of insertion can be calculated routinely and stored in the EHR (e.g., similar to a blood type of the patient). If the patient requires at any time later mechanical ventilation (e.g., after a car accident) then the information can be retrieved from the EHR. This may be particularly useful since the ETT **16**

may be placed by an emergency medicine technician rather than a consultant anesthetist, and often in a situation where time pressures and clinical issues (e.g., blood in the airway) may make ETT placement more difficult.

[0043] FIGURE 3 shows an example of the planning of the intubation pathway (e.g., operation **102**) and the recommended size of the ETT **16** (e.g., operation **104**). FIGURE 3 shows side and front views of a CT image **34** of the patient's head and neck. The intubation pathway is shown in both views extends from the front teeth of the patient **P** (depicted by reference character **50**) to the desired endpoint (depicted by reference character **52**) (e.g., 5.0 cm above the carina).

[0044] The disclosure has been described with reference to the preferred embodiments. Modifications and alterations may occur to others upon reading and understanding the preceding detailed description. It is intended that the exemplary embodiment be construed as including all such modifications and alterations insofar as they come within the scope of the appended claims.

Claims

1. An intubation assistance device (18) comprising an electronic controller (20) configured to:

identify, from one or more images (34) of a patient (P), information about the patient including at least a diameter of a trachea and a length of an intubation pathway;
determine a recommended endotracheal tube ETT (16) size including an ETT diameter and an ETT depth of insertion from the determined diameter of the trachea and the determined length of the intubation pathway; and
display the recommended ETT size on a display device (14).

wherein the electronic controller is configured to identify the upper airways of the patient by:
segmenting the one or more images to identify an upper airway landmark, the trachea, and the carina of the patient.

2. The intubation assistance device (18) of claim 1, wherein the segmenting further includes:
identifying the length of the intubation pathway based on a distance from the upper airway landmark through the trachea to the carina of the patient.
3. The intubation assistance device (18) of claim 1, wherein the electronic controller (20) is configured to determine the ETT size by:
using an ETT model (42) to determine a stiffness of the ETT, the determination of the ETT depth of insertion being further based on the stiffness of the

ETT.

4. The intubation assistance device (18) of claim 1, wherein the electronic controller (20) is further configured to:

adjust the one or more images with a patient anatomical model (36) to deform the one or more images (34) of the patient (P) into a desired position, the information about the patient being identified from the adjusted one or more images (34a).

5. The intubation assistance device (18) of claim 1, wherein the one or more images (34) do not depict at least a portion of the upper airway of the patient (P) and the electronic controller (20) is further configured to:

modify a patient anatomical model (36) based on one or more images of an exterior of the patient;
wherein the identifying information about the patient is further based on the patient anatomical model modified based on the one or more images of the exterior of the patient.

6. The intubation assistance device (18) of claim 5, wherein the electronic controller (20) is further configured to generate the one or more images of the exterior of the patient (P) by:

generating a 3D imaging model (40) from the one or more images (34) of the patient; and
generating the one or more images of the exterior of the patient from the 3D imaging model.

7. The intubation assistance device (18) of claim 5, wherein the images of the exterior of the patient (P) are comprised of one or more 3D images (38) acquired from one or more 3D cameras (30).

8. The intubation assistance device (18) of claim 5, wherein the electronic controller (20) is configured to:

register the patient anatomical model (36) extracted from the one or more images of the exterior of the patient (P) with the one or more images to generate a hybrid imaging data set; and
determine the intubation pathway based on the hybrid imaging data set.

9. The intubation assistance device (18) of claim 1, wherein the electronic controller (20) is further configured to control a computed tomography (CT) scanner to acquire the one or more images of the upper airway of the patient.

10. The intubation assistance device (18) of claim 9, wherein the electronic controller (20) is configured

to control the CT scanner to acquire the one or more images (34) of the upper airway of the patient (P) by operations including:

controlling the CT scanner to acquire a diagnostic torso CT image at a first X-ray level;
controlling the CT scanner to acquire an extended upper CT image extending upward from the diagnostic torso CT image at a second X-ray level that is lower than the first X-ray level; and
combining the diagnostic torso CT image and the extended upper CT image to generate the one or more images of the upper airway of the patient.

Patentansprüche

1. Intubationshilfsvorrichtung (18), die eine elektronische Steuereinheit (20) umfasst, die so konfiguriert ist, dass sie:

anhand eines oder mehrerer Bilder (34) eines Patienten (P) Informationen über den Patienten, die mindestens einen Durchmesser einer Luftröhre und eine Länge eines Intubationsweges beinhalten, identifiziert;
eine empfohlene Größe eines Endotrachealtubus, ETT, (16), die einen ETT-Durchmesser und eine ETT-Einführtiefe beinhaltet, anhand des bestimmten Durchmessers der Luftröhre und der bestimmten Länge des Intubationsweges bestimmt; und
die empfohlene ETT-Größe auf einer Anzeigevorrichtung (14) anzeigt,
wobei die elektronische Steuereinheit so konfiguriert ist, dass sie die oberen Atemwege des Patienten identifiziert durch:
Segmentieren des einen oder der mehreren Bilder, um ein Orientierungsmerkmal der oberen Atemwege, die Luftröhre und die Carina des Patienten zu identifizieren.

2. Intubationshilfsvorrichtung (18) nach Anspruch 1, wobei das Segmentieren weiter beinhaltet:
Identifizieren der Länge des Intubationsweges auf Basis einer Distanz vom Orientierungsmerkmal der oberen Atemwege durch die Luftröhre bis zur Carina des Patienten.

3. Intubationshilfsvorrichtung (18) nach Anspruch 1, wobei die elektronische Steuereinheit (20) so konfiguriert ist, dass sie die ETT-Größe bestimmt durch:
Verwenden eines ETT-Modells (42), um eine Steifheit des ETT zu bestimmen, wobei das Bestimmen der ETT-Einführtiefe weiter auf der Steifheit des ETT basiert.

4. Intubationshilfsvorrichtung (18) nach Anspruch 1, wobei die elektronische Steuereinheit (20) weiter so konfiguriert ist, dass sie:

das eine oder die mehreren Bilder an ein anatomisches Patientenmodell (36) anpasst, um das eine oder die mehreren Bilder (34) des Patienten (P) in eine gewünschte Position zu verformen, wobei die Informationen über den Patienten anhand des einen oder der mehreren angepassten Bilder (34a) identifiziert werden.

5. Intubationshilfsvorrichtung (18) nach Anspruch 1, wobei das eine oder die mehreren Bilder (34) mindestens einen Teil der oberen Atemwege des Patienten (P) nicht abbilden und die elektronische Steuereinheit (20) weiter so konfiguriert ist, dass sie:

ein anatomisches Patientenmodell (36) auf Basis eines oder mehrerer Bilder eines Äußeren des Patienten modifiziert;
wobei das Identifizieren von Informationen über den Patienten weiter auf dem anatomischen Patientenmodell basiert, das auf Basis des einen oder der mehreren Bilder des Äußeren des Patienten modifiziert wurde.

6. Intubationshilfsvorrichtung (18) nach Anspruch 5, wobei die elektronische Steuereinheit (20) weiter so konfiguriert ist, dass sie das eine oder die mehreren Bilder des Äußeren des Patienten (P) erzeugt durch:

Erzeugen eines 3D-Bildgebungsmodells (40) anhand des einen oder der mehreren Bilder (34) des Patienten; und
Erzeugen des einen oder der mehreren Bilder des Äußeren des Patienten anhand des 3D-Bildgebungsmodells.

7. Intubationshilfsvorrichtung (18) nach Anspruch 5, wobei die Bilder des Äußeren des Patienten (P) eines oder mehrere 3D-Bildern (38) umfasst, die von einer oder mehreren 3D-Kameras (30) aufgenommen wurden.

8. Intubationshilfsvorrichtung (18) nach Anspruch 5, wobei die elektronische Steuereinheit (20) so konfiguriert ist, dass sie:

das aus dem einen oder den mehreren Bildern des Äußeren des Patienten (P) extrahierte anatomische Patientenmodell (36) mit dem einen oder den mehreren Bildern registriert, um einen hybriden Bildgebungsdatensatz zu erzeugen; und
den Intubationsweg auf Basis des hybriden Bildgebungsdatensatzes bestimmt.

9. Intubationshilfsvorrichtung (18) nach Anspruch 1,

wobei die elektronische Steuereinheit (20) weiter so konfiguriert ist, dass sie einen Computertomographie- (CT) Scanner steuert, um das eine oder die mehreren Bilder der oberen Atemwege des Patienten aufzunehmen.

10. Intubationshilfsvorrichtung (18) nach Anspruch 9, wobei die elektronische Steuereinheit (20) so konfiguriert ist, dass sie den CT-Scanner steuert, um das eine oder die mehreren Bilder (34) der oberen Atemwege des Patienten (P) durch Operationen aufzunehmen, welche beinhalten:

Steuern des CT-Scanners, um ein diagnostisches CT-Bild des Rumpfes in einer ersten Röntgenebene aufzunehmen;
Steuern des CT-Scanners, um ein erweitertes oberes CT-Bild, das sich vom diagnostischen CT-Bild des Rumpfes nach oben erstreckt, in einer zweiten Röntgenebene aufzunehmen, die niedriger ist als die erste Röntgenebene; und
Kombinieren des diagnostischen CT-Bildes des Rumpfes und des erweiterten oberen CT-Bildes, um das eine oder die mehreren Bilder der oberen Atemwege des Patienten zu erzeugen.

Revendications

1. Dispositif d'assistance à l'intubation (18) comprenant un dispositif de commande électronique (20) configuré pour :

identifier, à partir d'une ou plusieurs images (34) d'un patient (P), des informations concernant le patient incluant au moins un diamètre d'une trachée et une longueur d'une voie d'intubation ;
déterminer une taille de tube endotrachéal TET recommandée (16) incluant un diamètre de TET et une profondeur d'insertion de TET à partir du diamètre déterminé de la trachée et de la longueur déterminée de la voie d'intubation ; et
afficher la taille de TET recommandée sur un dispositif d'affichage (14),
dans lequel le dispositif de commande électronique est configuré pour identifier les voies respiratoires supérieures du patient grâce à :
la segmentation des une ou plusieurs images pour identifier un point de repère des voies respiratoires supérieures, la trachée et l'éperon trachéal du patient.

2. Dispositif d'assistance à l'intubation (18) selon la revendication 1, dans lequel la segmentation inclut en outre :
l'identification de la longueur de la voie d'intubation sur la base d'une distance à partir du point de repère des voies respiratoires supérieures à travers la tra-

chée jusqu'à l'éperon trachéal du patient.

3. Dispositif d'assistance à l'intubation (18) selon la revendication 1, dans lequel le dispositif de commande électronique (20) est configuré pour déterminer la taille de TET grâce à :
l'utilisation d'un modèle de TET (42) pour déterminer une rigidité du TET, la détermination de la profondeur d'insertion de TET étant en outre basée sur la rigidité du TET.

4. Dispositif d'assistance à l'intubation (18) selon la revendication 1, dans lequel le dispositif de commande électronique (20) est en outre configuré pour :
ajuster les une ou plusieurs images avec un modèle anatomique de patient (36) pour déformer les une ou plusieurs images (34) du patient (P) dans une position souhaitée, les informations concernant le patient étant identifiées à partir des une ou plusieurs images ajustées (34a).

5. Dispositif d'assistance à l'intubation (18) selon la revendication 1, dans lequel les une ou plusieurs images (34) ne représentent pas au moins une partie des voies respiratoires supérieures du patient (P) et le dispositif de commande électronique (20) est en outre configuré pour :

modifier un modèle anatomique de patient (36) sur la base d'une ou plusieurs images d'un extérieur du patient ;
dans lequel les informations d'identification concernant le patient sont en outre basées sur le modèle anatomique de patient modifié sur la base des une ou plusieurs images de l'extérieur du patient.

6. Dispositif d'assistance à l'intubation (18) selon la revendication 5, dans lequel le dispositif de commande électronique (20) est en outre configuré pour générer les une ou plusieurs images de l'extérieur du patient (P) grâce à :

la génération d'un modèle d'imagerie 3D (40) à partir des une ou plusieurs images (34) du patient ; et
la génération des une ou plusieurs images de l'extérieur du patient à partir du modèle d'imagerie 3D.

7. Dispositif d'assistance à l'intubation (18) selon la revendication 5, dans lequel les images de l'extérieur du patient (P) sont constituées d'une ou plusieurs images 3D (38) acquises à partir d'une ou plusieurs caméras 3D (30).

8. Dispositif d'assistance à l'intubation (18) selon la revendication 5, dans lequel le dispositif de commande

électronique (20) est configuré pour :

recaler le modèle anatomique de patient (36)
 extrait des une ou plusieurs images de l'exté-
 rieur du patient (P) avec les une ou plusieurs 5
 images pour générer un jeu de données d'ima-
 gerie hybride ; et
 déterminer la voie d'intubation sur la base du
 jeu de données d'imagerie hybride.

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9. Dispositif d'assistance à l'intubation (18) selon la re-
 vendication 1, dans lequel le dispositif de commande
 électronique (20) est en outre configuré pour com-
 mander à un tomodensitomètre d'acquérir les une 15
 ou plusieurs images des voies respiratoires supé-
 rieures du patient.

10. Dispositif d'assistance à l'intubation (18) selon la re-
 vendication 9, dans lequel le dispositif de commande 20
 électronique (20) est configuré pour commander au
 tomodensitomètre d'acquérir les une ou plusieurs
 images (34) des voies respiratoires supérieures du
 patient (P) grâce à des opérations incluant :

la commande au tomodensitomètre d'acquérir 25
 une image tomodensitométrique diagnostique
 du torse à un premier niveau de rayons X ;
 la commande au tomodensitomètre d'acquérir
 une image tomodensitométrique supérieure 30
 étendue s'étendant vers le haut à partir de l'ima-
 ge tomodensitométrique diagnostique du torse
 à un second niveau de rayons X qui est inférieur
 au premier niveau de rayons X ; et
 la combinaison de l'image tomodensitométrique 35
 diagnostique du torse et de l'image tomodensi-
 tométrique supérieure étendue pour générer les
 une ou plusieurs images des voies respiratoires
 supérieures du patient.

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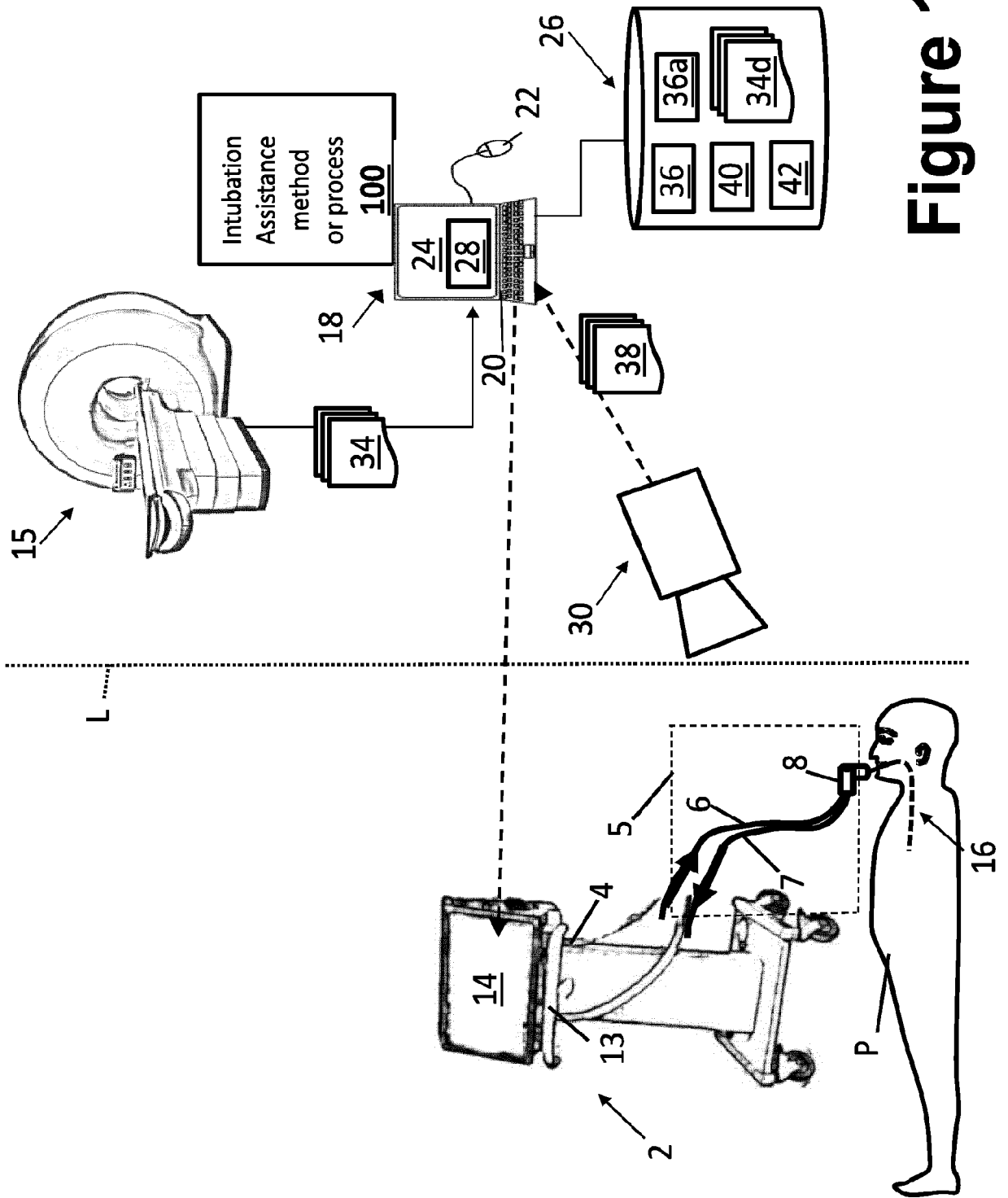


Figure 1

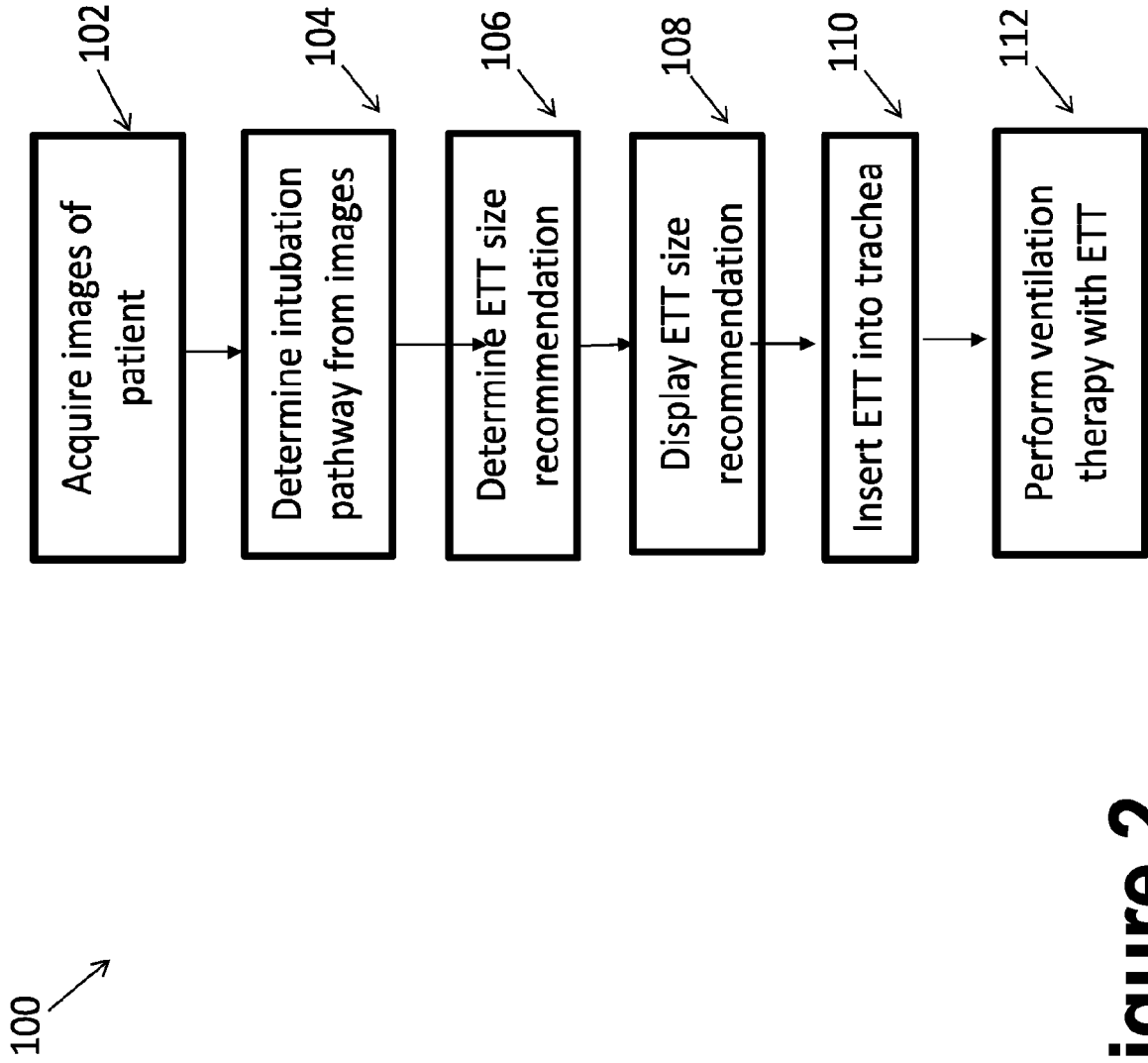


Figure 2

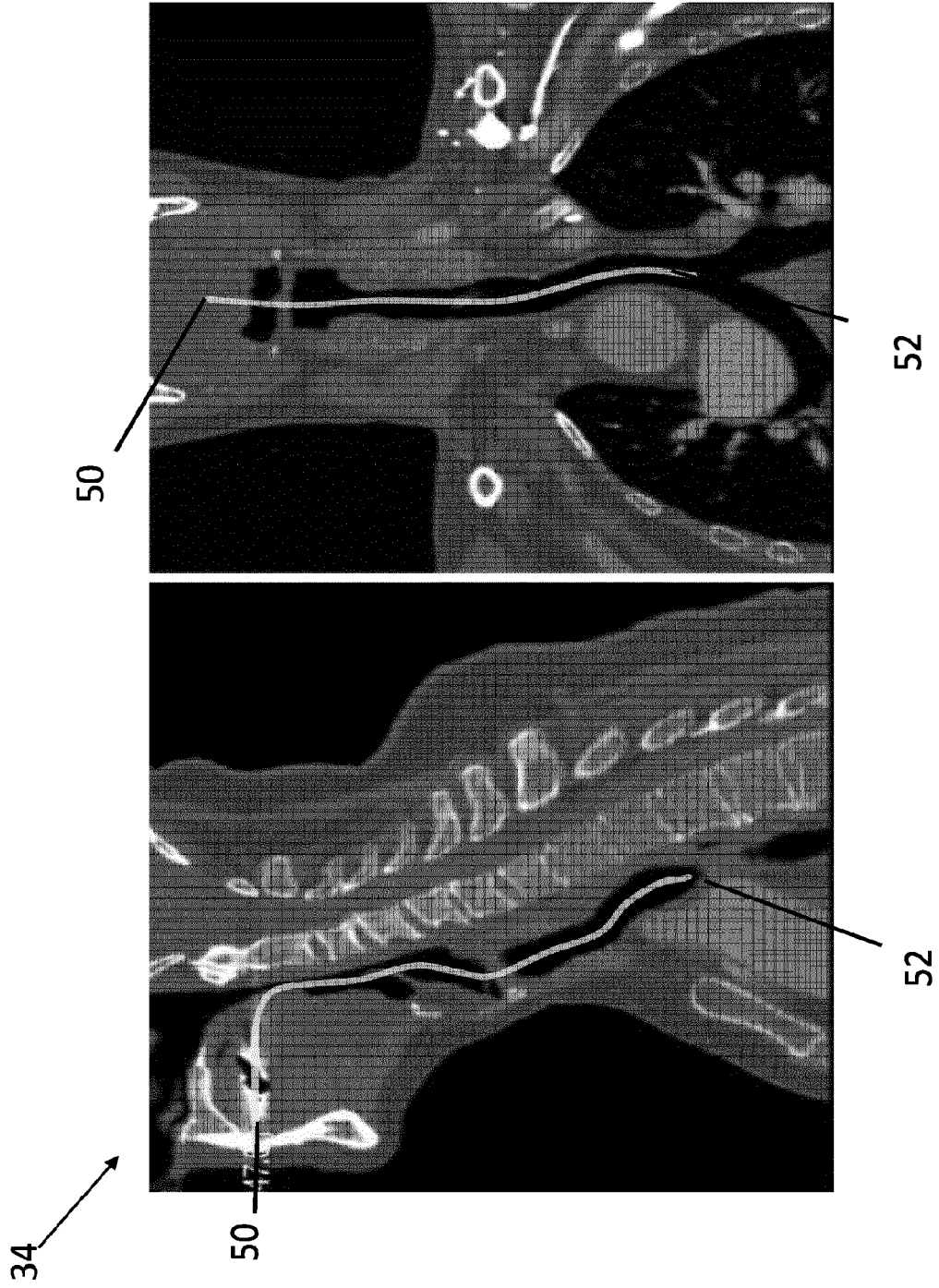


Figure 3

REFERENCES CITED IN THE DESCRIPTION

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Patent documents cited in the description

- US 2016022943 A [0006]

Non-patent literature cited in the description

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