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(54) **ARRAY OF UNIT CELLS HAVING PAD STRUCTURES**

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G01R 31/3185 (2006.01)
G06F 30/392 (2020.01)
G06F 119/02 (2020.01)

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(58) **Field of Classification Search**
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See application file for complete search history.

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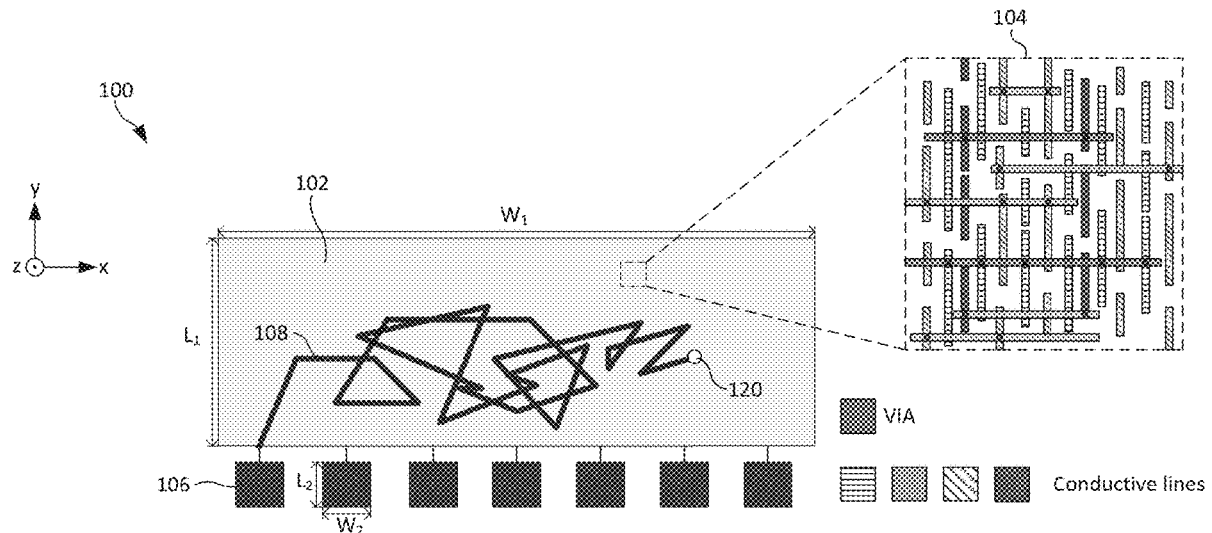
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(57) **ABSTRACT**

The present disclosure describes a method that includes scanning a circuit layout and identifying layout regions of the circuit layout. The method further includes placing unit cells in a layout region of the layout regions and forming a micro pad structure at a border of a unit cell of the unit cells. The micro pad structure includes interconnect structures that are electrically connected to the unit cell.

20 Claims, 7 Drawing Sheets



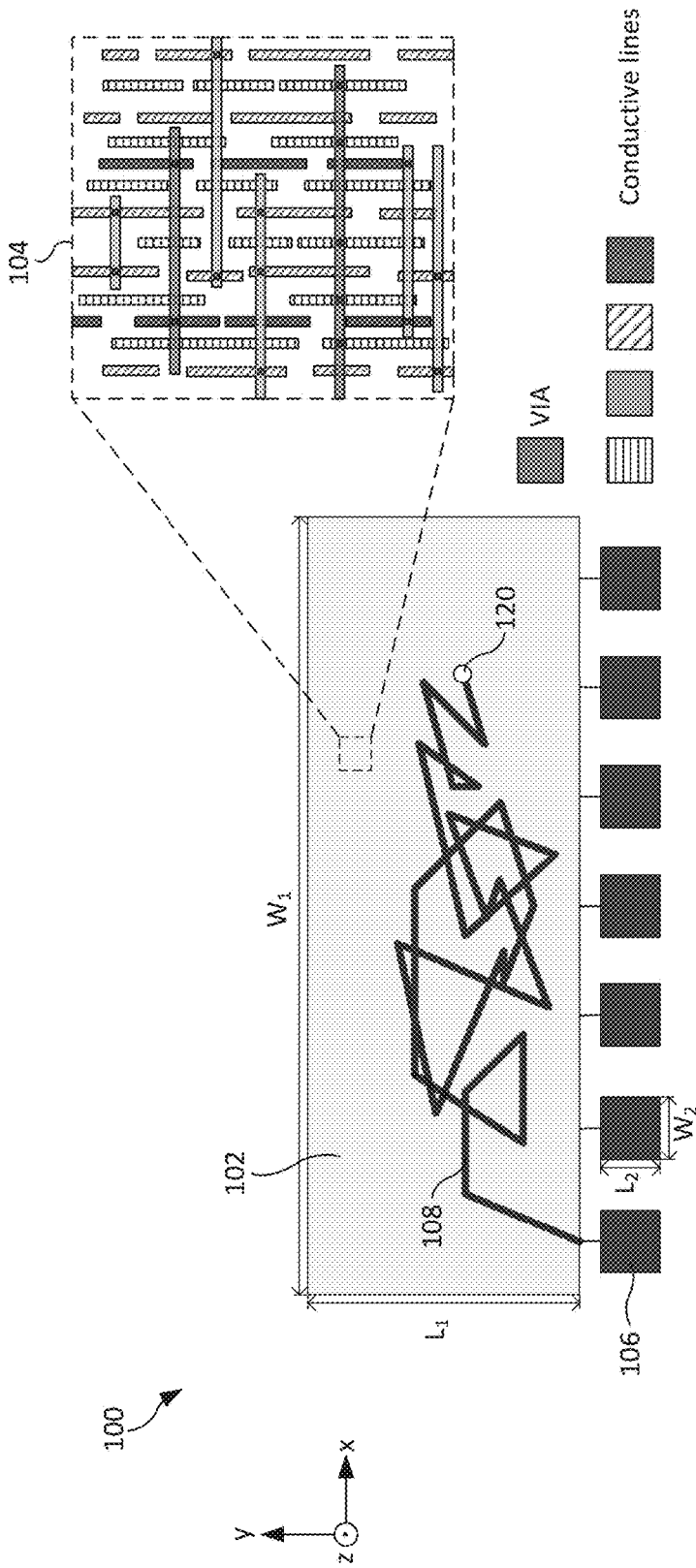


FIG. 1A

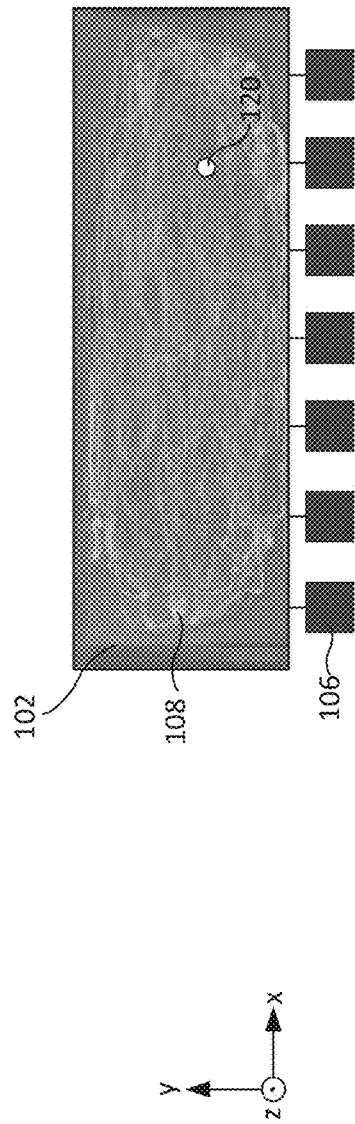


FIG. 1B

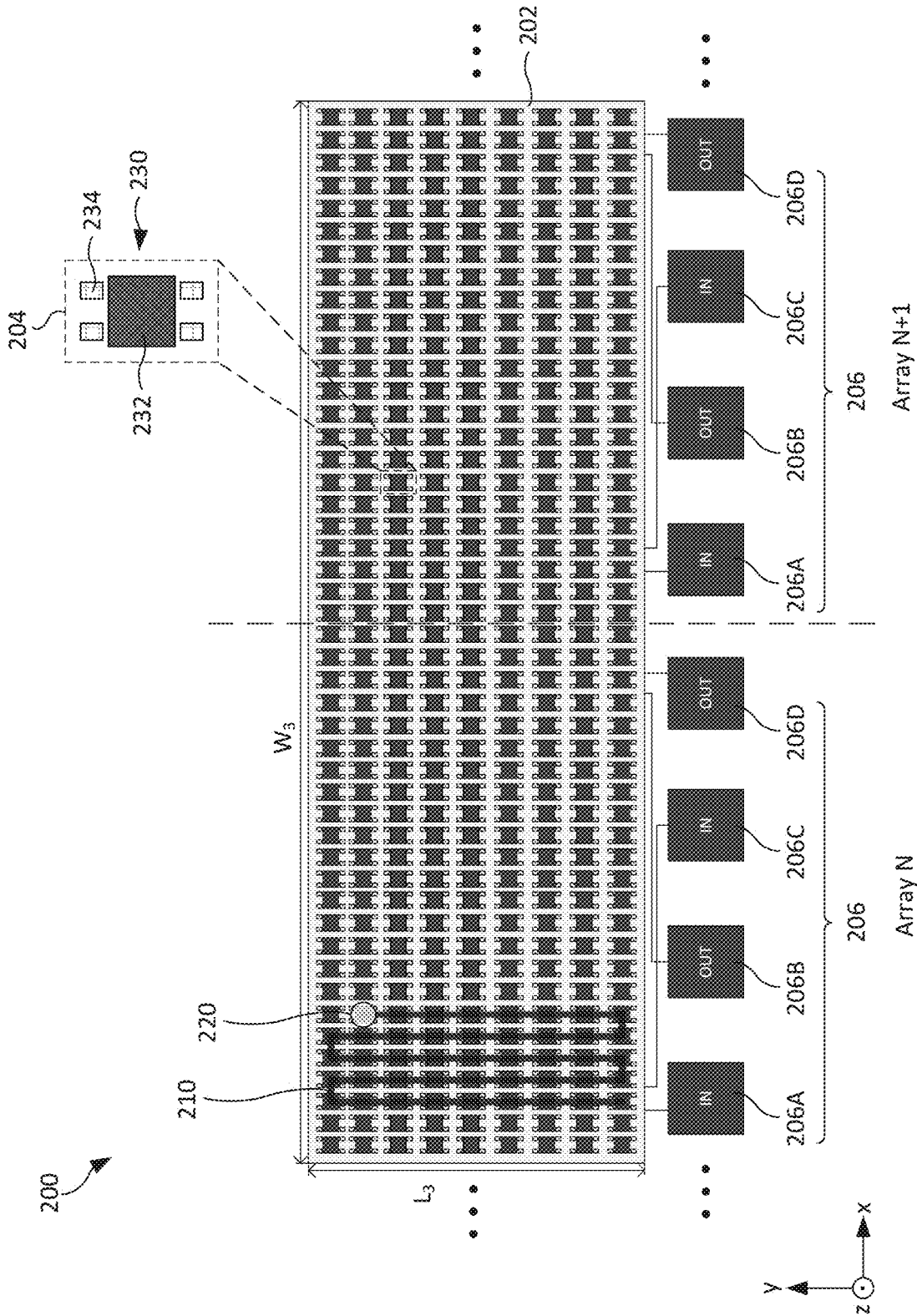


FIG. 2

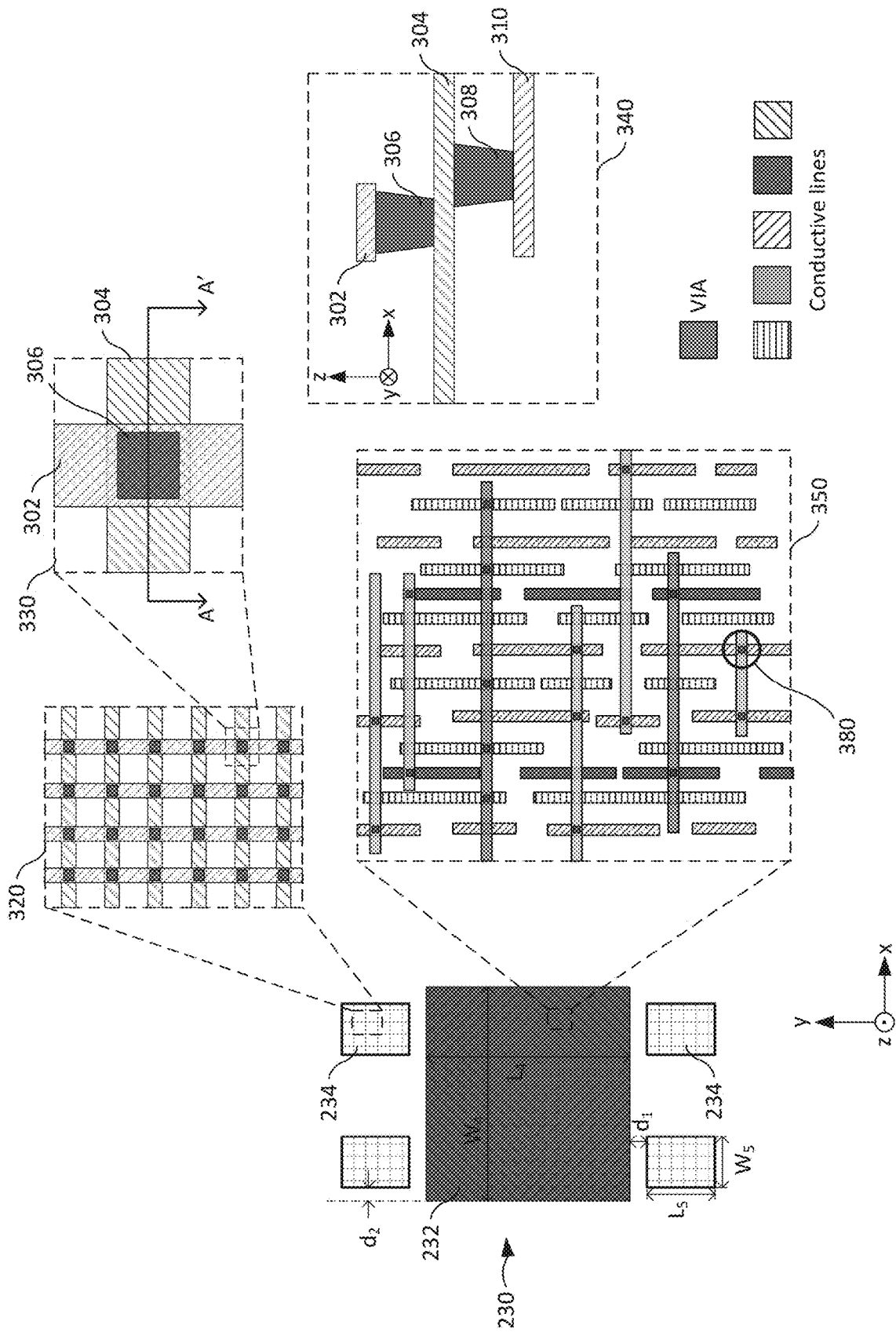


FIG. 3

400

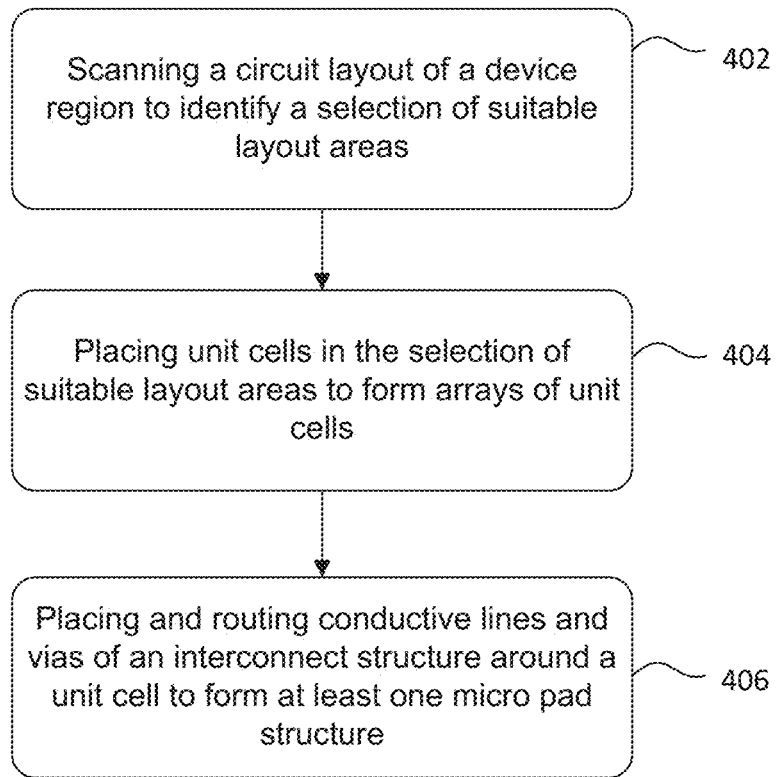


FIG. 4

500

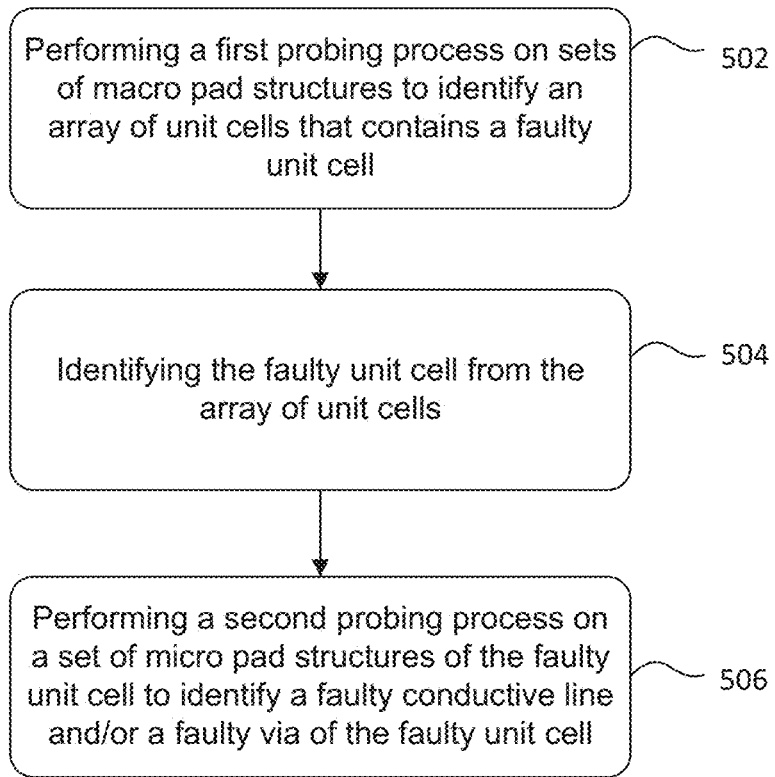


FIG. 5

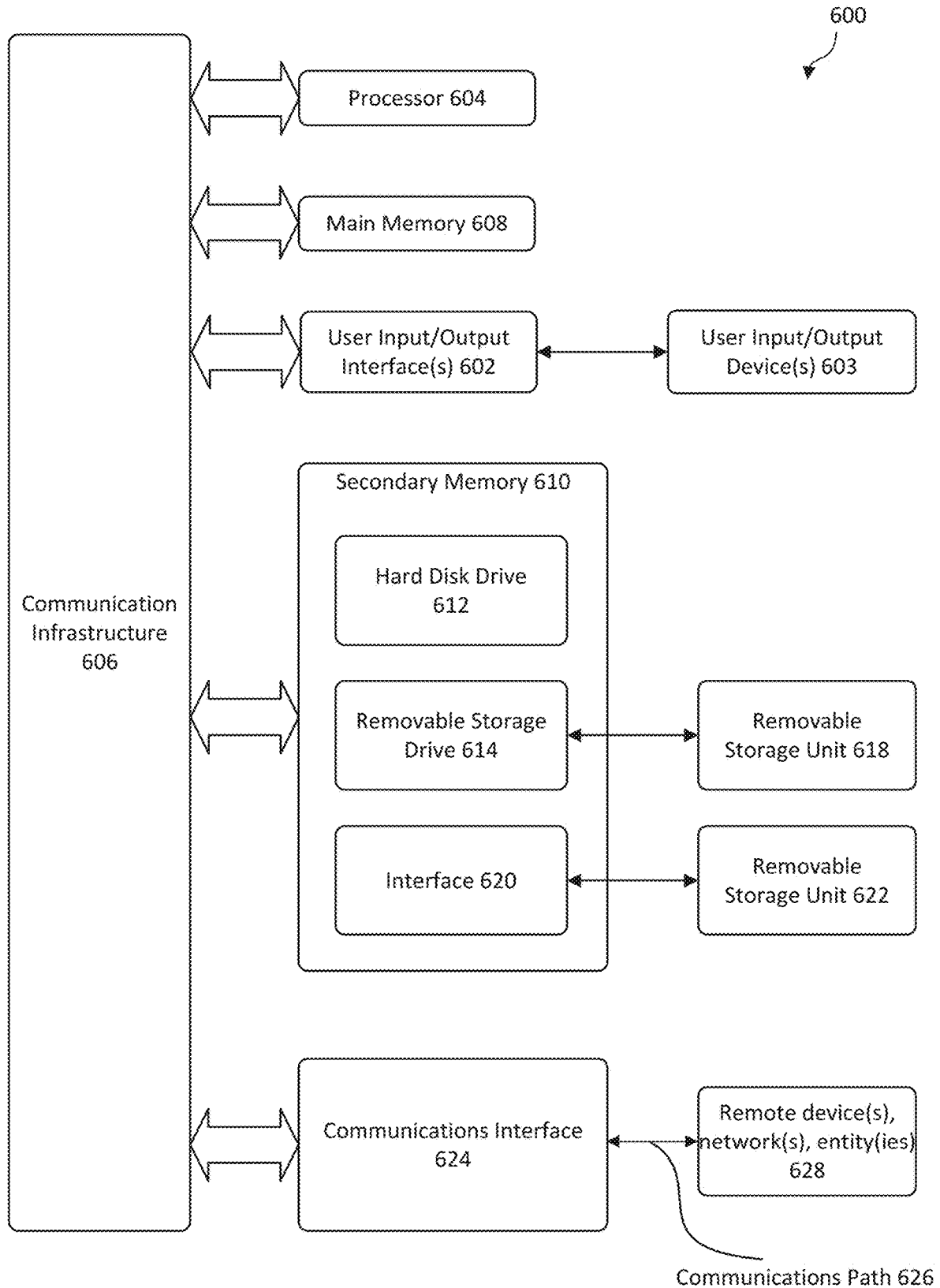


Fig. 6

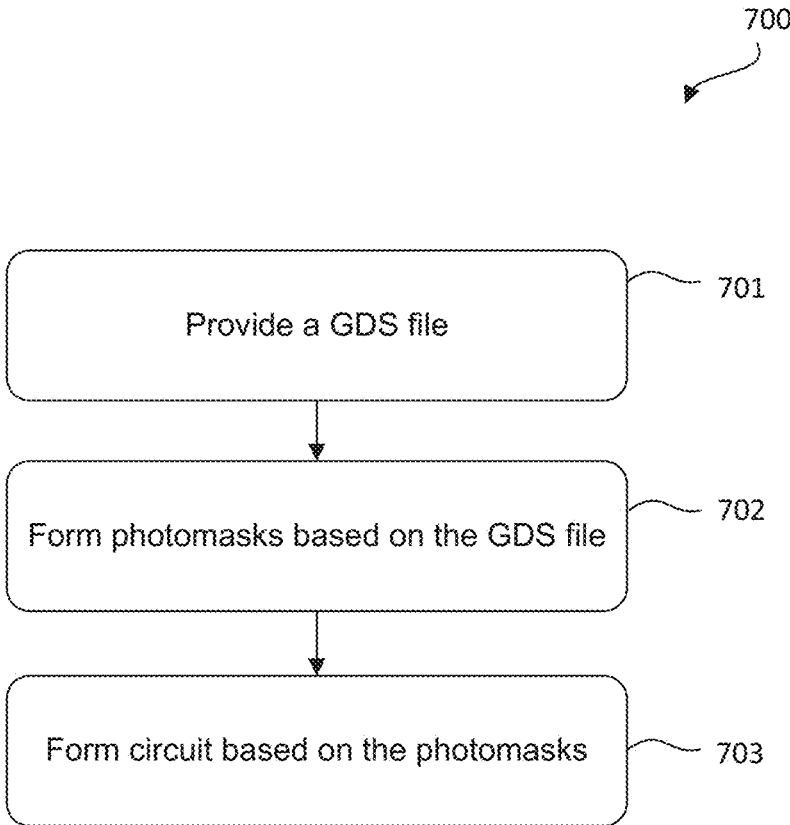


Fig. 7

ARRAY OF UNIT CELLS HAVING PAD STRUCTURES

BACKGROUND

A three-dimensional integrated circuit (“3D IC”) includes a semiconductor device with two or more layers of active electronic components integrated (e.g., vertically stacked and connected) on a substrate to form an integrated circuit. 3D IC technologies include die-on-die stacking, die-on-wafer stacking, and wafer-on-wafer stacking. It’s increasingly challenging to identify faulty circuit components of 3D IC structures.

BRIEF DESCRIPTION OF THE DRAWINGS

Aspects of the present disclosure are best understood from the following detailed description when read with the accompanying figures. It is noted that, in accordance with common practice in the industry, various features are not drawn to scale. In fact, the dimensions of the various features may be arbitrarily increased or reduced for clarity of discussion.

FIG. 1A is a schematic illustration of an integrated circuit layout incorporating macro pad structures, according to some embodiments.

FIG. 1B is a simulated illustration of an integrated circuit layout, according to some embodiments.

FIG. 2 is a schematic illustration of an integrated circuit layout incorporating arrays of unit cells having micro pad structures, according to some embodiments.

FIG. 3 is a schematic illustration of a unit cell having micro pad structures, according to some embodiments.

FIG. 4 is a flow diagram of a method for forming arrays of unit cells having micro pad structures, according to some embodiments.

FIG. 5 is a flow diagram of a method for identifying faulty structures of an integrated circuit, according to some embodiments.

FIG. 6 is an illustration of an exemplary computer system for implementing various embodiments of the present disclosure, according to some embodiments.

FIG. 7 is an illustration of a process to form standard cell structures and conductive line placement and routing based on a graphic database system (GDS) file, according to some embodiments.

DETAILED DESCRIPTION

The following disclosure provides many different embodiments, or examples, for implementing different features of the provided subject matter. Specific examples of components and arrangements are described below to simplify the present disclosure. These are, of course, merely examples and are not intended to be limiting. For example, the formation of a first feature over a second feature in the description that follows may include embodiments in which the first and second features are formed in direct contact, and may also include embodiments in which additional features may be formed that are between the first and second features, such that the first and second features are not in direct contact. In addition, the present disclosure may repeat reference numerals and/or letters in the various examples. This repetition does not in itself dictate a relationship between the various embodiments and/or configurations discussed.

Further, spatially relative terms, such as “beneath,” “below,” “lower,” “above,” “upper,” and the like, may be used herein for ease of description to describe one element or feature’s relationship to another element(s) or feature(s) as illustrated in the figures. The spatially relative terms are intended to encompass different orientations of the device in use or operation in addition to the orientation depicted in the figures. The apparatus may be otherwise oriented (rotated 90 degrees or at other orientations) and the spatially relative descriptors used herein may likewise be interpreted accordingly.

The term “nominal” as used herein refers to a desired, or target, value of a characteristic or parameter for a component or a process operation, set during the design phase of a product or a process, together with a range of values above and/or below the desired value. The range of values can be due to slight variations in manufacturing processes or tolerances.

The term “vertical,” as used herein, means nominally perpendicular to the surface of a substrate.

In some embodiments, the terms “about” and “substantially” can indicate a value of a given quantity that varies within 20% of the value (e.g., +1%, ±2%, ±3%, ±4%, 5%, ±10%, ±20% of the value). These values are merely examples and are not intended to be limiting. The terms “about” and “substantially” can refer to a percentage of the values as interpreted by those skilled in relevant art(s) in light of the teachings herein.

An integrated circuit (“IC”) structure can include a compilation of layers with different functionality, such as interconnects, power distribution network, logic chips, memory chips, radio frequency (RF) chips, and the like. A three-dimensional (3D) integrated circuit (“3D IC”) structure is a non-monolithic vertical structure developed based on the IC structure and can include, for example, a two-dimensional (2D) chip flipped and stacked on a front surface of a carrier chip through various bonding techniques, such as hybrid bonding. In 3D IC structures, each of the layers can be interconnected by micro-bumps, through silicon vias (TSVs), hybrid bonding, other types of interconnect structures, or combinations thereof.

IC structures are subject to variations in the process that can result in latent fabrication defects being formed in the electrical components of the 3D IC structures. When fabrication conditions in the processing chamber deviate from the ideal conditions, abnormalities can be introduced in the physical structure of the electrical components that manifest as faults in the operation of the IC structures. A fault detection system can be used to detect faults of IC structures and provide real-time results on fabrication yield or operation status of semiconductor devices in the IC structures. An exemplary fault detection system includes probes that are electrically connected to external terminals of IC structures, such as conductive pads, and analyzing units that sends, receives, and process testing signals. Testing signals are sent into the IC structure by the fault detection system and return signals are analyzed to identify faulty components of the IC structure. The duration between when a testing signal is sent and when it is analyzed should be under an assigned timing budget for fault detection. However, timing budgets have to be significantly increased as IC structures become more complex.

Various embodiments described in the present disclosure are directed to the placement and routing of unit cells with micro pad structures, according to some embodiments. In some embodiments, an automatic placement and routing (APR) tool can be configured to scan circuit layouts of an IC

structure and identify areas of the circuit layouts that are suitable for implementing unit cells. The identified areas can include interconnect layers, vias, active devices, or passive devices. Each unit cell can include one or more standard cells of a circuit layout and have programmable design parameters. In some embodiments, the APR tool can group and place unit cells into arrays, where each unit cell of an array of unit cells can have similar functional or circuit designs. In some embodiments, the APR tool can group and place unit cells having different functionality or designs. Each unit cell can also include at least one micro pad structure for electrically connecting the unit cell to other adjacent unit cells or to external circuitry. In some embodiments, the micro pad structures can include interconnect structures, such as conductive lines and vias. Adjacent unit cells can be connected by electrically connecting the respective micro pad structures of the adjacent unit cells. In some embodiments, each unit cell can be connected to at least two or more other unit cells. A testing scheme for identifying faulty components, such as faulty metal lines and vias of interconnect structures, can include a first probing process of sending testing signals through a series of unit cells and identifying a faulty unit cell of the series of unit cells by analyzing the received signals and/or determined circuit parameters. A second probing process can include applying testing signals to the identified faulty unit cell and identifying faulty metal conductive lines and/or vias by analyzing the received signals and/or determined circuit parameters of the faulty unit cell. Benefits of implementing arrays of unit cells having micro pad structures can include improved efficiency of identifying faulty components of an IC structure, which in turn lowers circuit fabrication cost.

FIG. 1A is a schematic illustration of an IC layout, according to some embodiments. IC layout **100** can include a layout area **102** and macro pad structures **106** connected to layout area **102**. IC layout **100** can further include other suitable structures and are not illustrated in FIG. 1 for simplicity. Components in IC layout **100** are for illustration purposes and are not drawn to scale.

Layout area **102** can include suitable circuitry components, such as interconnect structures and passive/active devices (e.g., capacitors, inductors, and/or transistors) arranged to be CMOS circuits, RF circuitry, logic circuits, peripheral circuitry, and the like. In some embodiments, layout area **102** can include the placement of fin field-effect transistors (finFETs) with gate terminals and source/drain terminals. In some embodiments, layout area **102** can include the placement of planar transistor devices. In some embodiments, the circuit components can be arranged as standard cells and placed in layout area **102**. Standard cells can be used as base elements for building integrated circuits. The standard cells are placed in layout area **102** and routed to form functional circuits.

Layout area **102** can include device and structures that are formed in “a front-end-of-line (FEOL)” region, “a middle-end-of-line (MEOL)” region, and “a back-end-of-line (BEOL)” region of a semiconductor device. Enlarged view **104** of layout area **102** illustrates interconnect structures are formed in the BEOL region and include various intersecting conductive lines. The conductive lines are connected by vias that are formed at the intersection of the conductive lines. In some embodiments, conductive lines can be metal lines that are formed at different metal levels, such as different metal levels of a BEOL interconnect structure where a metal level is formed above another metal level. For example, a first metallization layer M1 is formed under a second metallization layer M2, the second metallization layer M2 is formed

under a third metallization layer M3, and so on and so forth. Conductive lines from a metallization layer can be electrically connected to other conductive lines from another metallization layer through vias that are formed between the metallization layers. In some embodiments, layout area **102** can have any suitable width W_1 and length L_1 . For example, width W_1 can be between about 400 μm and about 800 μm , between about 500 μm and about 700 μm , between about 550 μm and about 650 μm , or any suitable dimensions. In some embodiments, length L_1 can be between about 200 μm and about 400 μm , between about 250 μm and about 350 μm , between about 275 μm and about 325 μm , or any suitable dimensions.

Macro pad structures **106** are conductive pads that are electrically coupled to devices and structures within layout area **102**. For example, macro pad structures **106** can be electrically coupled to the conductive lines as illustrated in enlarged view **104**. In some embodiments, macro pad structures **106** are electrically coupled to the passive/active devices placed within layout area **102**. In some embodiments, macro pad structures **106** are formed using a single continuous sheet of conductive material that extend substantially in the horizontal directions (e.g., x and y directions). In some embodiments, macro pad structures **106** can have any suitable width W_2 and length L_2 . For example, width W_2 can be between about 20 μm and about 80 μm , between about 15 μm and about 90 μm , between about 10 μm and about 100 μm , or any suitable dimensions. In some embodiments, length L_2 can be between about 20 μm and about 80 μm , between about 15 μm and about 90 μm , between about 10 μm and about 100 μm , or any suitable dimensions.

Performing fault detection to identify faulty conductive lines or vias of structures within layout area **102** includes applying a testing signal through at least one of macro pad structures **106** and analyzing the received signal. For example, a circuit resistance capacitance (RC) constant can be determined by applying an electric signal through macro pad structure **106**. A leakage current can also be determined by applying an electric signal through macro pad structure **106**. The electric testing signal travels a signal path **108** until it reaches location **120**, where a faulty conductor or a faulty via is located. Signal path **108** illustrated in FIG. 1A follows a disorderly path because conductive lines placed in layout area **102** may extend throughout layout area **102**. For example, signal path **108** may travel throughout the majority of regions in layout area **102** before encountering location **120** where a faulty component is located. FIG. 1B is a simulated illustration of layout area **102** after a testing signal is applied and travelled along signal path **108** (shown in light white lines) before encountering location **120** where a faulty component is located. As circuits become more complex, it is increasingly time consuming and challenging for identifying faulty structures.

FIG. 2 is a schematic illustration of an IC layout with unit cells and micro pad structures, according to some embodiments. IC layout **200** can include a layout area **202** that includes arrays of unit cells **230**, such as an array N and an adjacent array N+1. Unit cell **230** can include an active region **232** and micro pad structures **234**. Macro pad structures **206** can be similar to macro pad structures **106** illustrated in FIG. 1. For example, macro pad structures **206** can be connected to layout area **202**. IC layout **200** can further include other suitable structures and are not illustrated in FIG. 2 for simplicity. Components in IC layout **200** are for illustration purposes and are not drawn to scale.

Layout area **202** can be similar to layout area **102** illustrated in FIG. 1. For example, Layout area **202** can also

include interconnect structures and passive and/or active devices. In some embodiments, layout area **202** can have any suitable width W_3 and length L_3 . For example, width W_3 can be between about 200 μm and about 300 μm , between about 220 μm and about 280 μm , between about 240 μm and about 260 μm , or any suitable dimensions. In some embodiments, length L_3 can be between about 100 μm and about 200 μm , between about 120 μm and about 180 μm , between about 140 μm and about 160 μm , or any suitable dimensions.

FIG. 2 illustrates two arrays of unit cell **230**: array N and array N+1. Additional arrays can be included in IC layout **200** and are not illustrated in FIG. 2 for simplicity. Each array includes unit cells **230** arranged in rows and columns as well as macro pad structures **206** electrically coupled to structures in layout area **202**. Each unit cell **230** includes an active region **232** and one or more micro pad structures **234**. Enlarged view **204** illustrates a unit cell **230** with four micro pad structures **234**: two positioned along a top border of active region **232** and two positioned along a bottom border of active region **232**. Additional or fewer number of micro pad structures can be included in each unit cell **230** and are within the scope of the present disclosure. In some embodiments, each unit cell **230** within an array can realize similar or different circuit functions.

Performing fault detection to identify faulty conductive lines or vias of structures within layout area **202** can provide various benefits. First, devices and structures of layout area **202** are divided into arrays, where each array of the array of unit cells can include at least two macro pad structures. Dividing layouts into smaller regions compared to a single region covering the entire layout area can improve fault detecting efficiency. For example, testing can be applied simultaneously and in parallel between different arrays. For example, each array illustrated in IC layout **200** of FIG. 2 includes two pairs of macro pad structures **206** where each pair of macro pad structures **206** includes an IN terminal for applying a testing signal and an OUT terminal for receiving the testing signal. In some embodiments, a voltage bias can be applied to the array of unit cells **230** through the IN and OUT terminals of macro pad structures **206**.

Unit cells **230** can be electrically connected to each other through adjacent micro pad structures **234**. For example, a unit cell **230** from a row can be electrically connected to a unit cell **230** from another row that is immediately below or above. In other words, unit cells **230** from the same column are electrically connected to each other. In addition, unit cells **230** located at a top or bottom of a column are also connected to an adjacent unit cell **230** in the same row. As a result, when a testing signal is applied through one of the IN terminals of macro pad structure **206**, a signal path **210** of the testing signal is pre-determined and predictable. For example, signal path **210** extends substantially in a first horizontal direction (e.g., along the y direction) through columns of unit cells **230** and then in a second horizontal direction (e.g., along the x direction) when the path reaches a top or bottom row of unit cells **230** within the array of unit cells **230**. As shown in FIG. 2, signal path **210** approaches location **220** at which a unit cell **230** having a faulty conductive line or a faulty via is located. In contrast to signal path **108** illustrated in FIGS. 1A and 1B, signal path **210** is more compact. For example, signal path **210** only extends along a much small portion of the width of layout area **202**. In addition, signal path **210** can be pre-determined and predictable compared to signal path **108** since signal path **210** only extends along electrically connected unit cells **230**.

FIG. 3 illustrates a unit cell and its components, according to some embodiments. An example of unit cell can be unit

cell **230** illustrated in FIG. 2. In some embodiments, unit cell **230** can include micro pad structures **234** formed along a top border of active region **232** and along a bottom border of active region **232**. In some embodiments, micro pad structures **234** can be formed along other borders of active region **232**, such as left or right borders that extend along the y direction. In some embodiments, the number of micro pad structures **234** formed along a first border (e.g., a top border) can be different from the number of micro pad structures **234** formed along a second border (e.g., a bottom border). In some embodiments, micro pad structures **234** can be formed along more than two borders of active region **232**. For example, micro pad structures **234** can be formed along top and bottom borders as well as left and right borders of active region **232**. Each micro pad structure **234** is electrically coupled to active region **232**.

Active regions **232** can include interconnect structures and passive/active devices (e.g., capacitors, inductors, and/or transistors) arranged to be CMOS circuits, RF circuitry, logic circuits, peripheral circuitry, and the like. The interconnect structures can include conductive lines formed in various suitable metallization layers and vias formed between the metallization layers. In some embodiments, active region **232** can have a width W_4 that is between about 5 μm and about 50 μm , between about 10 μm and about 45 μm , between about 15 μm and about 40 μm , or any suitable dimensions. In some embodiments, active regions **232** can have a length L_4 that is between about 5 μm and about 50 μm , between about 10 μm and about 45 μm , between about 15 μm and about 40 μm , or any suitable dimensions.

Micro pad structures **234** can be different from macro pad structures **206** in several aspects. First, micro pad structures **234** can be formed using conductive lines and vias of an interconnect structure. As shown in enlarged views **320** and **330**, micro pad structures **234** include conductive lines **302** and **304** as well as vias **306** formed at the intersection of the aforementioned conductive lines. Enlarged view **340** also shows portions of micro pad structures **234** through the A-A' plane of enlarged view **330**. Enlarged view **340** illustrates that micro pad structures **234** also includes conductive lines formed in different metallization layers. For example, portions of conductive line **310** and vias **308** formed between conductive lines **304** and **310** are also formed within micro pad structure **234**. In some embodiments, conductive lines **302**, **304**, and **310** are respectively formed in the M3, M2, and M1 metallization layers. In some embodiments, conductive lines **302**, **304**, and **310** can be formed in other suitable metallization layers, such as M4, M3, and M2, and the like. In some embodiments, widths of conductive lines **302**, **304**, and **310** can be between about 5 nm and about 100 nm, between about 10 nm and about 75 nm, between about 20 nm and about 50 nm, or any suitable dimensions. In some embodiments, widths and lengths of vias **306** and **308** can be between about 5 nm and about 100 nm, between about 10 nm and about 75 nm, between about 20 nm and about 50 nm, or any suitable dimensions. In contrast, macro pad structures **206** are formed using a single continuous sheet of conductive material in a single metallization layer.

Second, dimensions of micro pad structures **234** are orders of magnitude smaller than macro pad structures **206**. For example, micro pad structures **234** can have a width W_5 that is between about 0.1 μm and about 1 μm , between about 0.08 μm and about 1.5 μm , between about 0.05 μm and about 2 μm , or any suitable dimensions. For example, micro pad structures **234** can have a length L_5 that is between about 0.1 μm and about 1 μm , between about 0.08 μm and about 1.5 μm , between about 0.05 μm and about 2 μm , or any suitable

dimensions. In some embodiments, a ratio W_4/W_5 or L_4/L_5 can be between about 10 and about 100, between about 5 and about 500, between about 2 and about 1000, or any suitable ratios. In some embodiments, micro pad structures **234** can be placed away from active region **232** by a distance d_1 . In some embodiments, distance d_1 can be between about 0.5 μm and about 2 μm , between about 0.75 μm and about 1.75 μm , between about 1 μm and about 1.5 μm , or any suitable dimensions. In some embodiments, micro pad structures **234** can be offset from a left or right boundary of active region **232** by a distance d_2 . In some embodiments, distance d_2 can be between about 0.5 μm and about 2 μm , between about 0.75 μm and about 1.75 μm , between about 1 μm and about 1.5 μm , or any suitable dimensions.

FIG. 4 is a flow diagram of a method **400** for forming unit cells and micro pad structures in IC layouts, in accordance with some embodiments of the present disclosure. It should be noted that the operations of method **400** can be performed in a different order and/or vary, and method **400** may include more operations that are not described for simplicity. Although processes for forming unit cells and micro pad structures are described as examples, the formation process can be applied to various suitable semiconductor structures. The described formation processes are exemplary, and alternative processes in accordance with this disclosure may be performed that are not shown in the figures.

At operation **402**, a circuit layout of a device region is scanned to determine a selection of suitable layout areas, according to some embodiments of the present disclosure. Referring to FIG. 2, layout area **202** can be scanned to determine regions of a circuit layout that are suitable for implementing unit cells and micro pad structures. In some embodiments, one or more rules can be used for selecting a region of the circuit layout. For example, an area that is greater than a threshold area can be selected for implementing unit cells and micro pad structures. In some embodiments, the threshold area can be about 2000 μm^2 . For example, the threshold area can be between about 500 μm^2 and about 2500 μm^2 , between about 1000 μm^2 and about 2000 μm^2 , between about 1500 μm^2 and about 1800 μm^2 , or any suitable value. In response to the area being greater than the threshold area, the area is selected as the suitable layout areas. In some embodiments, the selection rule can include layout areas serving a certain circuitry function. For example, circuit layout regions that contain certain functional units of interest, such as latches, switches, adders, comparators, amplifiers, etc. can be selected. In some embodiments, the selection rule can include selecting any region that has certain predetermined characteristics. For example, an area with higher susceptibility of containing faulty conductive lines and/or vias can be selected for implementing unit cells and micro pad structures. For example, the area selected can have a high probability (greater than about 1% of the total circuit elements) of having faulty conductive lines and/or vias.

An automatic routing and placement (APR) tool can be configured to scan layout area **202**. Based on the aforementioned predetermined set of selection rules, the APR tool can be configured to identify and select a region of a circuit layout that satisfies the predetermined set of selection rules. In some embodiments, the set of selection rules can include identifying regions that have areas greater than a threshold area, have certain circuitry function, or have any suitable characteristics.

At operation **404**, unit cells are placed in the selection of suitable layout areas to form arrays of unit cells, according to some embodiments of the present disclosure. An APR tool

can be configured to place unit cells in the selection of suitable layout areas and in the form of rows and columns to form an array of unit cells. The APR tool can further form multiple arrays in the selection of suitable areas if needed. Referring to FIG. 2, the APR tool can be configured to place unit cells **230** in array N regions and array N+1 regions. The APR tool can be further configured to place macro pad structures, such as macro pad structures **206**, in the array regions and electrically couple macro pad structures **206** to structures and devices in layout area **202**.

At operation **406**, at least one micro pad structure is placed around a unit cell by placing and routing conductive lines and vias of an interconnect structure, according to some embodiments of the present disclosure. Referring to FIG. 3, each micro pad structure **234** can include conductive lines formed in any suitable metallization layer and vias that electrically connect the conductive lines. In some embodiments, the conductive lines, such as conductive lines **302**, **304**, and **310**, are electrically connected to suitable devices within active region **232** of unit cell **230**. In some embodiments, additional micro pad structures can be positioned around active region **232** of unit cell **230**.

FIG. 5 is a flow diagram of a method **500** for identifying faulty components of a circuit layout incorporating unit cells and micro pad structures, in accordance with some embodiments of the present disclosure. It should be noted that the operations of method **500** can be performed in a different order and/or vary, and method **500** may include more operations that are not described for simplicity. Although processes for forming unit cells and micro pad structures are described as examples, the formation process can be applied to various suitable semiconductor structures. The described formation processes are exemplary, and alternative processes in accordance with this disclosure may be performed that are not shown in the figures.

At operation **502**, a first probing process is performed on sets of macro pad structures to identify an array of unit cells that contains a faulty unit cell, according to some embodiments of the present disclosure. Referring to FIG. 2, the first probing process can apply testing signals to multiple arrays of unit cells, such as array N and array N+1, or any other suitable arrays, to determine if an array of unit cells contain any faulty unit cells. The first probing process can be performed simultaneously to multiple arrays of unit cells or performed on an array of unit cells at a time. In some embodiments, the first probing process can be applied to a first pair of macro pad structures **206** of an array which includes a first macro pad structure **206A** being used as an input terminal and a second macro pad structure **206B** being used as an output terminal. First macro pad structure **206A** is connected to a voltage potential that is greater than a voltage potential that is connected to second macro pad structure **206B** for determining an RC constant of a signal path of array N. Similarly, a first probing process can be applied to a second pair of macro pad structures **206** that includes macro pad structures **206C** and **206D**.

At operation **504**, a faulty unit cell is identified from within the group of unit cells, according to some embodiments of the present disclosure. Referring to FIG. 2, a faulty unit cell **230** can be located at location **220** by analyzing testing signals that are applied to macro pad structures **206**. The determination of location **220** can be based on any suitable methods, such as comparing a determined RC constant with a desired RC constant and determining the location of faulty unit cell **230** based on the difference between the RC constants. In some embodiments, the loca-

tion of faulty unit cell **230** can be determined by comparing the location of faulty unit cell **230** with a wafer-level or a chip-level map.

At operation **506**, a second probing process is performed on a set of micro pad structures of the identified faulty unit cell to identify faulty conductive lines and/or faulty vias, according to some embodiments of the present disclosure. Referring to FIG. **3**, the second probing process can apply testing signals to micro pad structures **234** of unit cell **230**, to identify the faulty conductive line and/or faulty vias of active region **232**. In some embodiments, the faulty conductive line and/or faulty vias of active region **232** can be determined by performing a scanning electron microscopy (SEM) inspection. In some embodiments, the second probing process can be applied to a micro pad structure **234**, such as one or more micro pad structures positioned at a top or bottom border of active region **232**. In some embodiments, two micro pad structures can be used, in which a first micro pad structure is used as an input terminal and a second micro pad structure is used as an output terminal. In some embodiments, a first micro pad structure is connected to a voltage potential that is greater than a voltage potential that is connected to a second micro pad structure. As shown in FIG. **3**, a faulty via is identified at location **380**.

FIG. **6** is an illustration of an example computer system **600** in which various embodiments of the present disclosure can be implemented, according to some embodiments. Computer system **600** can be any computer capable of performing the functions and operations described herein. For example, and without limitation, computer system **600** can be capable of scanning circuit layout areas, identifying a selection of circuit layout areas, placing and routing unit cells and micro pad structures, performing simulation tests, identifying faulty unit cells, and identifying faulty conductive lines and/or vias. In some embodiments, computer system **600** can be an EDA tool. Computer system **600** can be used, for example, to execute one or more operations in methods **400**, **500**, and **700**, which describe exemplary methods for forming placing and routing unit cells and micro pad structures as well as identifying faulty unit cells and faulty conductive lines and vias within the faulty unit cells.

Computer system **600** includes one or more processors (also called central processing units, or CPUs), such as a processor **604**. Processor **604** is connected to a communication infrastructure or bus **606**. Computer system **600** also includes input/output device(s) **603**, such as monitors, keyboards, pointing devices, etc., that communicate with communication infrastructure or bus **606** through input/output interface(s) **602**. An EDA tool can receive instructions to implement functions and operations described herein—e.g., method **400** of FIG. **4**, method **500** of FIG. **5**, and method **700** of FIG. **7**—via input/output device(s) **603**. Computer system **600** also includes a main or primary memory **608**, such as random access memory (RAM). Main memory **608** can include one or more levels of cache. Main memory **608** has stored therein control logic (e.g., computer software) and/or data. In some embodiments, the control logic (e.g., computer software) and/or data can include one or more of the operations described herein with respect to method **400** of FIG. **4**, method **500** of FIG. **5**, and method **700** of FIG. **7**. For example, main memory **608** can include a non-transitory computer-readable medium having instructions stored thereon that, when executed by computer system **600**, causes computer system **600** to perform operations, such as forming keep-out areas and placing and/or rerouting conductive lines.

Computer system **600** can also include one or more secondary storage devices or memory **610**. Secondary memory **610** can include, for example, a hard disk drive **612** and/or a removable storage device or drive **614**. Removable storage drive **614** can be a floppy disk drive, a magnetic tape drive, a compact disk drive, an optical storage device, tape backup device, and/or any other storage device/drive.

Removable storage drive **614** can interact with a removable storage unit **618**. Removable storage unit **618** includes a computer usable or readable storage device having stored thereon computer software (control logic) and/or data. Removable storage unit **618** can be a floppy disk, magnetic tape, compact disk, DVD, optical storage disk, and/or any other computer data storage device. Removable storage drive **614** reads from and/or writes to removable storage unit **618** in a well-known manner.

According to some embodiments, secondary memory **610** can include other means, instrumentalities or other approaches for allowing computer programs and/or other instructions and/or data to be accessed by computer system **600**. Such means, instrumentalities or other approaches can include, for example, a removable storage unit **622** and an interface **620**. Examples of the removable storage unit **622** and the interface **620** can include a program cartridge and cartridge interface (such as that found in video game devices), a removable memory chip (such as an EPROM or PROM) and associated socket, a memory stick and USB port, a memory card and associated memory card slot, and/or any other removable storage unit and associated interface. In some embodiments, secondary memory **610**, removable storage unit **618**, and/or removable storage unit **622** can include one or more of the operations described herein with respect to method **400** of FIG. **4**, method **500** of FIG. **5**, and method **700** of FIG. **7**.

Computer system **600** can further include a communication or network interface **624**. Communication interface **624** enables computer system **600** to communicate and interact with any combination of remote devices, remote networks, remote entities, etc. (individually and collectively referenced by reference number **628**). For example, communication interface **624** can allow computer system **600** to communicate with remote devices **628** over communications path **626**, which can be wired and/or wireless, and which can include any combination of LANs, WANs, the Internet, etc. Control logic and/or data can be transmitted to and from computer system **600** via communication path **626**.

The operations in the preceding embodiments can be implemented in a wide variety of configurations and architectures. Therefore, some or all of the operations in the embodiments herein—e.g., method **400** of FIG. **4**, method **500** of FIG. **5**, and method **700** of FIG. **7** (described below)—can be performed in hardware, in software, or both. In some embodiments, a tangible apparatus or article of manufacture comprising a tangible computer useable or readable medium having control logic (software) stored thereon is also referred to herein as “a computer program product” or “a program storage device.” This includes, but is not limited to, computer system **600**, main memory **608**, secondary memory **610** and removable storage units **618** and **622**, as well as tangible articles of manufacture embodying any combination of the foregoing. Such control logic, when executed by one or more data processing devices (such as computer system **600**), causes such data processing devices to operate as described herein. In some embodiments, computer system **600** is installed with software to perform operations in the manufacturing of photomasks and circuits, as illustrated in method **700** of FIG. **7** (described below). In

some embodiments, computer system 600 includes hardware/equipment for the manufacturing of photomasks and circuit fabrication. For example, the hardware/equipment can be connected to or be part of remote devices 628 (remote device(s), network(s), entity(ies)) of computer system 600.

FIG. 7 is an illustration of an exemplary method 700 for circuit fabrication, according to some embodiments. In some embodiments, operations/steps of method 700 can be performed in a different order. Variations of method 700 should also be within the scope of the present disclosure.

In operation 701, a GDS file is provided. The GDS file can be generated by an EDA tool and include standard cell structures optimized based on the present disclosure. The operation depicted in operation 701 can be performed by, for example, an EDA tool that operates on a computer system, such as computer system 600 described above.

In operation 702, photomasks are formed based on the GDS file. In some embodiments, the GDS file provided in operation 701 is taken to a tape-out operation to generate photomasks for fabricating one or more integrated circuits. In some embodiments, a circuit layout included in the GDS file can be read and transferred onto a quartz or glass substrate to form opaque patterns that correspond to the circuit layout. The opaque patterns can be made of, for example, chromium or other suitable metals. Operation 702 can be performed by a photomask manufacturer, where the circuit layout is read using a suitable software tool (e.g., an EDA tool) and the circuit layout is transferred onto a substrate using a suitable printing/deposition tool. The photomasks reflect the circuit layout/features included in the GDS file.

In operation 703, one or more circuits are formed based on the photomasks generated in operation 702. In some embodiments, the photomasks are used to form patterns/structures of the circuit contained in the GDS file. In some embodiments, various fabrication tools (e.g., photolithography equipment, deposition equipment, and etching equipment) are used to form features of the one or more circuits.

Various embodiments described in the present disclosure are directed to the placement and routing of unit cells with micro pad structures, according to some embodiments. In some embodiments, an APR tool can be configured to scan circuit layouts of an IC package and identify areas of circuit layouts that are suitable for implementing unit cells. Each unit cell can include one or more standard cells of a circuit layout and have programmable design parameters. In some embodiments, the APR tool can group and place unit cells into arrays, where each unit cell of an array can have similar functional or circuit designs. Each unit cell can also include at least one micro pad structure for electrically connecting the unit cell to other unit cells or to external circuitry. In some embodiments, the micro pad structures can include interconnect structures, such as conductive lines and vias. Adjacent unit cells can be connected by electrically connecting the respective micro pad structures of the adjacent unit cells.

A testing scheme for identifying faulty components, such as faulty metal conductive lines and/or vias of interconnect structures, can include a first probing process of sending testing signals through a series of unit cells of various arrays of unit cells and identifying an array of unit cells that contains a faulty unit cell. Further, a faulty unit cell of the series of unit cells is determined by analyzing the received signals and/or determined circuit parameters. A second probing process can include applying testing signals to the identified faulty unit cell and identifying faulty metal conductive lines and/or vias by analyzing the received signals

and/or determined circuit parameters of the faulty unit cell. Benefits of implementing arrays of unit cells having micro pad structures can include improved efficiency of identifying faulty components of an IC structure, which in turn improves circuit fabrication yield.

In some embodiments, a method includes scanning a circuit layout and identifying layout regions of the circuit layout. The method further includes placing unit cells in a layout region of the layout regions and forming a micro pad structure at a border of a unit cell of the unit cells. The micro pad structure includes interconnect structures that are electrically connected to the unit cell.

In some embodiments, a method includes performing a first probing process on macro pad structures to identify an array of unit cells that contains a faulty unit cell, where each macro pad structure includes a single sheet of conductive material. The method also includes identifying the faulty unit cell from the array of unit cells. The method further includes performing a second probing process on micro pad structures of the faulty unit cell to identify a faulty conductive line or a faulty via of the faulty unit cell. Each micro pad structure includes an interconnect structure of a back-end-of-line (BEOL) semiconductor structure.

In some embodiments, a non-transitory computer-readable medium having instructions stored thereon that, when executed by a computing device, causes the computing device to perform operations including: (i) scanning a circuit layout; (ii) identifying layout regions of the circuit layout; (iii) placing unit cells in a layout region of the layout regions; and (iv) forming a micro pad structure at a border of a unit cell of the unit cells, where the micro pad structure includes interconnect structures that are electrically connected to the unit cell and formed in a back-end-of-line (BEOL) semiconductor structure.

It is to be appreciated that the Detailed Description section, and not the Abstract of the Disclosure section, is intended to be used to interpret the claims. The Abstract of the Disclosure section may set forth one or more but not all possible embodiments of the present disclosure as contemplated by the inventor(s), and thus, are not intended to limit the subjoined claims in any way.

The foregoing disclosure outlines features of several embodiments so that those skilled in the art may better understand the aspects of the present disclosure. Those skilled in the art will appreciate that they may readily use the present disclosure as a basis for designing or modifying other processes and structures for carrying out the same purposes and/or achieving the same advantages of the embodiments introduced herein. Those skilled in the art will also realize that such equivalent constructions do not depart from the spirit and scope of the present disclosure, and that they may make various changes, substitutions, and alterations herein without departing from the spirit and scope of the present disclosure.

What is claimed is:

1. A method, comprising:

scanning a circuit layout;

identifying a plurality of layout regions of the circuit layout, wherein each of the plurality of layout regions is electrically coupled to a plurality of macro pad structures;

placing a plurality of unit cells in a layout region of the plurality of layout regions; and

forming a micro pad structure at a border of a unit cell of the plurality of unit cells, wherein the micro pad structure comprises interconnect structures that are electrically connected to the unit cell.

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2. The method of claim 1, wherein placing the plurality of unit cells comprises arranging the plurality of unit cells into an array.

3. The method of claim 1, wherein identifying the plurality of layout regions comprises selecting layout regions that satisfy a selection rule.

4. The method of claim 3, wherein the selection rule comprises selecting an area of a layout region that is greater than a threshold area.

5. The method of claim 3, wherein the selection rule comprises selecting an area of a layout region that performs a predetermined circuitry function.

6. The method of claim 3, wherein the selection rule comprises selecting an area of a layout region that has a probability of containing faulty unit cells that is greater than 1%.

7. The method of claim 1, wherein forming the micro pad structure comprises placing the micro pad structure at a distance away from an active region of the unit cell.

8. The method of claim 1, wherein forming the micro pad structure further comprises placing and routing conductive lines on different metallization layers of a back-end-of-line (BEOL) semiconductor structure.

9. The method of claim 1, further comprising forming an other micro pad structure at a border of an other unit cell, wherein:

the micro pad structure is between an active region of the unit cell and the other micro pad structure; and

the other micro pad structure is between an other active region of the other unit cell and the micro pad structure.

10. A method, comprising:

performing a first probing process on macro pad structures to identify an array of unit cells that contains a faulty unit cell, wherein each macro pad structure comprises a single sheet of conductive material;

identifying the faulty unit cell from the array of unit cells; and

performing a second probing process on micro pad structures of the faulty unit cell to identify a faulty conductive line or a faulty via of the faulty unit cell, wherein each micro pad structure comprises an interconnect structure of a back-end-of-line (BEOL) semiconductor structure.

11. The method of claim 10, wherein performing the first probing process comprises applying testing signals to the macro pad structures.

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12. The method of claim 11, wherein the macro pad structures comprise an input terminal and an output terminal.

13. The method of claim 10, wherein the interconnect structure comprises conductive lines and vias.

14. The method of claim 10, wherein performing the second probing process comprises performing a scanning electron microscopy inspection on an active region of the faulty unit cell.

15. The method of claim 10, wherein identifying the faulty unit cell comprises comparing a location of the faulty unit cell to a chip-level map.

16. A non-transitory computer-readable medium having instructions stored thereon that, when executed by a computing device, causes the computing device to perform operations comprising:

scanning a circuit layout;

identifying a plurality of layout regions of the circuit layout, wherein each of the plurality of layout regions is electrically coupled to a plurality of macro pad structures;

placing a plurality of unit cells in a layout region of the plurality of layout regions; and

forming a micro pad structure at a border of a unit cell of the plurality of unit cells, wherein the micro pad structure comprises interconnect structures that are electrically connected to the unit cell and formed in a back-end-of-line (BEOL) semiconductor structure.

17. The non-transitory computer-readable medium of claim 16, wherein identifying the plurality of layout regions comprises selecting layout regions that satisfy a selection rule.

18. The non-transitory computer-readable medium of claim 16, wherein forming the micro pad structure comprises placing and routing conductive lines and vias of the interconnect structures.

19. The non-transitory computer-readable medium of claim 18, wherein the conductive lines are formed on different metallization layers of the back-end-of-line (BEOL) semiconductor structure.

20. The non-transitory computer-readable medium of claim 16, wherein the operations further comprise electrically connecting the unit cell to an other unit cell of the plurality of unit cells through the micro pad structure.

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